

CPSC 320: NP-Completeness

Where does this topic fit within the course?

- Up to now:
 - We have been learning “recipes” to design or analyze efficient algorithms.
 - Most of the problems we looked at can be solved in $O(n)$, or $O(n \log n)$, or $O(n^2)$, or maybe $O(n^3)$ time.
 - Every one of these problems was “easy” to solve, that is, has an algorithm that runs in $O(n^k)$ time for some integer $k \geq 0$.

Where does this topic fit within the course?

- Now:
 - We will look at problems that (we think) are hard to solve.
 - It doesn't mean the problems are difficult to describe.
 - Only that we don't know of any efficient algorithms for them.

Where does this topic fit within the course?

- Examples:
 - Find a way to schedule n exams in k time-slots without any exam conflict.
 - Find the cheapest route for a traveling business person to visit n cities and come back to his/her starting point.
 - Find k students, in a class of size n , that (already) all know one another.
 - Divide a group of n people into two teams of equal total strength to play tug-of-war.

Decision problems vs Optimization problems

- Two types of problems:
 - **Optimization problem**: we want to find the solution s that maximizes or minimizes a function $f(s)$.
 - **Decision problem**: we are given a parameter K , and we need to decide if there is a solution s for which
 - ◆ $f(s) \leq K$ [minimization] or
 - ◆ $f(s) \geq K$ [maximization].

So the answer is **True** or **False**.

- They are almost equivalent

Decision problems vs Optimization problems

- Example: **Independent Set**
 - **Definition:** Given a graph $G = (V, E)$, an **independent set** in G is a subset V' of V such that no two vertices of V' are joined by an edge in G .
 - **Optimization Problem:** Given $G = (V, E)$, find the largest independent set in G .
 - **Decision Problem:** Given $G = (V, E)$ and an integer K , does G have an independent set with at least K vertices?

Decision problems vs Optimization problems

- These two problems are very similar in terms of complexity:
 - If we have a solution to the optimization problem, then it gives us an answer to the decision problem.
 - If we can solve the decision problem efficiently, then we can use binary search on K to find the answer to the optimization problem.
- So we will look at decision problems only.

The sets P and NP

- We will consider two sets of problems:
 - **P**: the set of all problems for which we have an efficient **solver**:
 - ◆ Given a problem instance, the solver decides in polynomial time if the answer is **Yes** or **No**.
 - **NP**: the set of all problems for which we have an efficient **verifier**:
 - ◆ For every problem instance whose answer is **Yes**, there is a “proof” that a verifier can check in polynomial time.

The sets P and NP

Is $P = NP$?

- Nobody knows
- Most people think the answer is **No**.

The sets P and NP

- We have
 - Easy problems.
 - Problems that we **think** are hard.
- **Cook's theorem:** if **SAT** can be solved in polynomial time, then **every** problem in **NP** can be solved in polynomial time.
- A problem that belongs to **NP** and has this property is called **NP-complete**.

The sets P and NP

- We have already seen many NP-Complete problems:
 - Satisfiability
 - Graph coloring (tutorial 2)
 - Clique, Independent Set (tutorial 3)
 - Vertex Cover, Dominating set (tutorial 3)
 - Hitting Set (assignment 1)
 - Hamiltonian Path (test 1)
 - Monochromatic Triangle (midterm)

Why do we want to know if a problem is NP-complete?

- Suppose your boss asked you to design an algorithm to solve a problem. You would like to avoid this:

[image deleted to avoid copyright issues]

text: “I can’t find an efficient algorithm. I guess I’m just too dumb.”

Why do we want to know if a problem is NP-complete?

- Ideally, you would like to do this:

[image deleted to avoid copyright issues]

*text: “I can’t find an efficient algorithm,
because no such algorithm is possible!”*

Why do we want to know if a problem is NP-complete?

- But since you can't (we still don't know if **P** = **NP**), at least you might be able to do this, and avoid getting fired:

[image deleted to avoid copyright issues]

“I can't find an efficient algorithm, but neither can all these famous people.”

Proving a new problem NP-Complete

- How do we prove that a problem \mathcal{P} is NP-Complete?
 - First we prove that \mathcal{P} belongs to **NP**. This is (usually) easy:
 - ◆ Show what kind of “proof” for Yes answers can be checked in polynomial time.

Proving a new problem NP-Complete

- Example 1:
 - For SAT:
 - ◆ The proof is an assignment of true/false values to the variables.
 - ◆ We can verify that all clauses are satisfied fairly quickly.

Proving a new problem NP-Complete

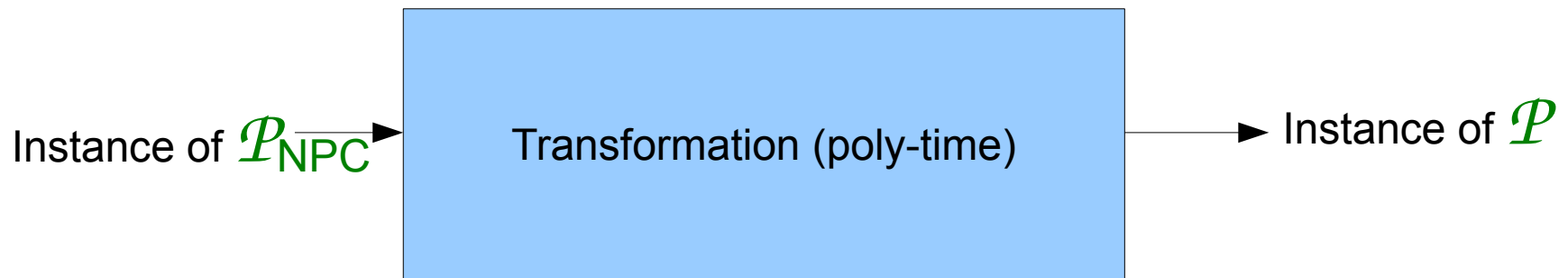
- Example 2:
 - For **Graph k -colorability**:
 - ◆ The proof is the colour assigned to each vertex.
 - ◆ We can count the different colours and verify there are at most **k** of them.
 - ◆ We can verify that every edge has endpoints of different colours.

Proving a new problem NP-Complete

- How do we prove that a problem \mathcal{P} is NP-Complete (continued)?
 - Then we prove that if we can solve \mathcal{P} in polynomial time, then every other problem in NP can be solved in polynomial time. This is (usually) a bit more involved.
 - ◆ The proof of Cook's theorem is ugly (6 pages in Garey & Johnson).
 - ◆ Luckily, now that we know that SAT is NP-complete, we can use a much simpler method.

Proving a new problem NP-Complete

- Polynomial-time reduction:
 - Pick a known NP-complete problem \mathcal{P}_{NPC} .
 - Give a polynomial-time algorithm that transforms instances of \mathcal{P}_{NPC} into instances of \mathcal{P} with the same Yes/No answer.



Proving a new problem NP-Complete

- If you could solve \mathcal{P} efficiently, then you could solve an instance of \mathcal{P}_{NPC} as follows:
 - Transform it into an instance of \mathcal{P} .
 - Solve the instance of \mathcal{P} and return the same answer.
- Since \mathcal{P}_{NPC} is NP-complete, this means you could solve every problem in **NP** in polynomial time!

Coping with NP-completeness

- What do we do if we find the problem we need to solve is NP-Complete?
 - Solving it exactly most likely takes exponential time.
 - Or we can use an **approximation algorithm**: an algorithm for which we have a bound on how bad the solution is.
 - So we don't get the optimal solution, but we know how far off we are from the optimal.

Coping with NP-completeness

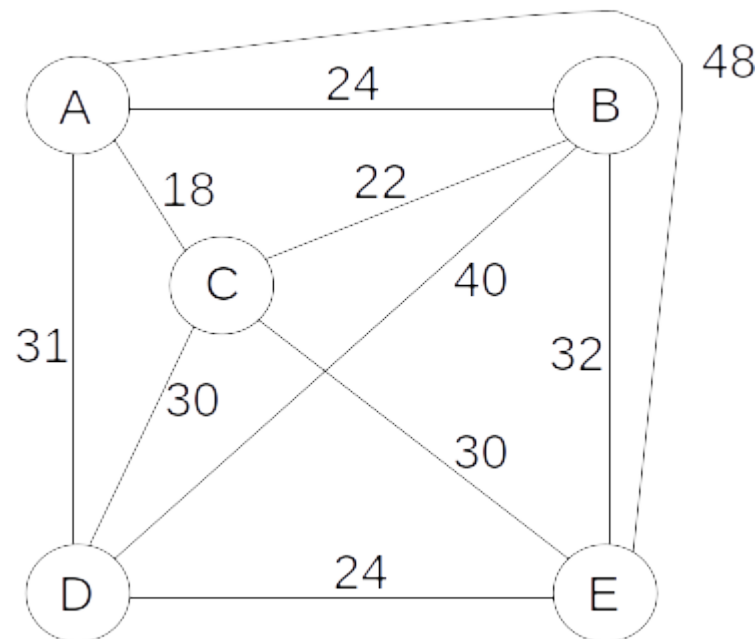
- Example: Traveling salesperson with the triangle inequality.
 - Given:
 - ♦ a graph $G = (V, E)$
 - ♦ a weight function $w: E \rightarrow \mathbb{R}^+$ such that $w(x,z) \leq w(x,y) + w(y,z)$ for all vertices x, y, z .
 - Find a simple cycle that contains every vertex of G , and whose total weight is minimum.

Coping with NP-completeness

- Traveling salesperson with the triangle inequality (continued):
 - Algorithm:
 - Compute a minimum spanning tree of G .
 - Starting from a vertex v , go around the tree.
 - The second (or more) time a vertex w is visited, remove it from the tour.

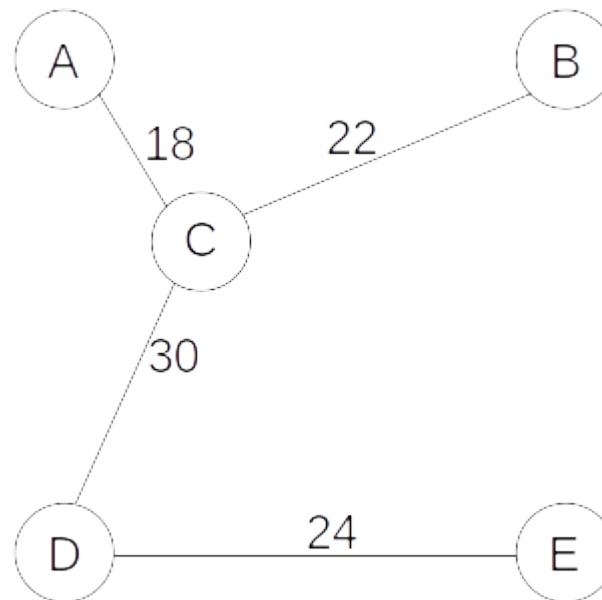
Coping with NP-completeness

- Example: the graph and distances



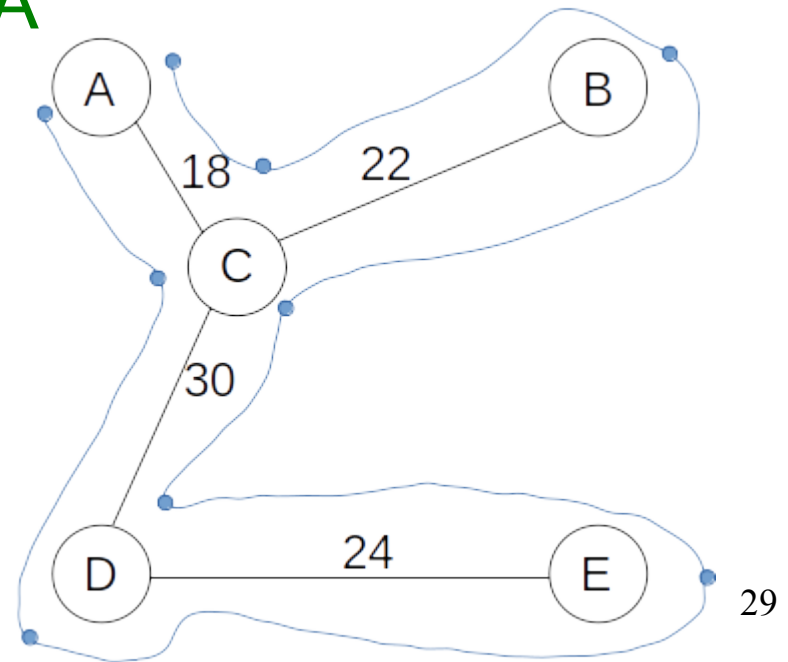
Coping with NP-completeness

- Example: a minimum spanning tree



Coping with NP-completeness

- Example: going around the minimum spanning tree
 - ACDEDCBCA →
ACDEBA (total weight: 128)
 - Minimum tour: ACBEDA
(total weight 127)



Coping with NP-completeness

- Traveling salesperson with the triangle inequality (continued):
 - Let
 - W be the weight of the tour produced by this algorithm.
 - $MST(G)$ be the weight of the minimum spanning tree of G .
 - $OPT(G)$ be the weight of the minimum TSP tour.

Coping with NP-completeness

- Traveling salesperson with the triangle inequality (continued):
 - Fact 1: $MST(G) \leq OPT(G)$
 - ◆ Proof: Take the minimum weight TSP tour. We get a spanning tree T by removing one edge. So $MST(G)$ is \leq the weight of T , which is $\leq OPT(G)$.

Coping with NP-completeness

- Traveling salesperson with the triangle inequality (continued):
 - Fact 2: $W \leq 2 \text{MST}(G)$
 - ◆ Proof: the initial tour (the one that goes around the tree) has weight exactly twice that of $\text{MST}(G)$ (it follows every edge twice). Because of the triangle inequality the shortcuts can only reduce the weight of the tour.
 - Corollary: $W \leq 2 \text{OPT}(G)$.