

10-11-20

Artificial Intelligence Lab Test - 1

- fedham -

GURU NAVMA
IRM18CS031
SA, Batch-2

```
import math
```

```
maze = []
```

```
path = []
```

```
closedPath = []
```

```
neighbours = [[1, 1], [0, 1], [1, 0], [1, -1], [0, -1], [-1, 1], [-1, 0], [-1, -1]]
```

```
def findShortestPath(nentPath, n, m):
```

```
    minDist = 9999
```

```
    nent = []
```

```
    for x in nentPath:
```

```
        if (euclidianDistance(x, n, m) < minDist):
```

```
            minDist = euclidianDistance(n, n, m)
```

```
            nent = x
```

```
    return nent
```

```
def euclidianDistance(x, n, m):
```

```
    dist = math.sqrt((n-1-x[0])**2 + (m-1-x[1])**2)
```

```
    return dist
```

```
def findPath(n, m):
```

```
    path.append([0, 0])
```

```
    curr = [0, 0]
```

```
    while (curr != [m-1, m-1]):
```

```
        nentPath = []
```

```
        for x in neighbours:
```

```
            a = []
```

```
            a.append(curr[0] + x[0])
```

```
            a.append(curr[1] + x[1])
```

if $a[0] > -1$ and $a[0] < n$ and $a[1] > -1$ and $a[1] < m$:

if (maze[a[0]][a[1]]):

if a not in path and a not in closedPath:

newPath.append(a)

if (newPath):

curr = findShortestPath(newPath, n, m)

path.append(curr)

else:

if path:

closedPath.append(curr)

path.pop()

if path:

curr = path[len(path) - 1]

else:

print("No Path available")

exit(0)

else:

print("No Path available")

exit(0)

def main():

n = int(input("\nEnter number of rows: "))

m = int(input("\nEnter number of cols: "))

print("\nEnter the maze: 0 - blocked, 1 - free:")

for i in range(n):

a = list(map(int, input().split(" ")))

maze.append(a)

print("\n\nMaze")

for i in range(n):

for j in range(m):

print(maze[i][j], end=" ")

print()

findPath(n, m)

print("Enter
co-ordinates for
destination")
x = int(input())
y = int(input())
dest = []
dest.append(x)
dest.append(y)

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```

print("In Path")
for i in range(n):
    for j in range(m):
        if (i,j) in path:
            print("-", end=" ")
        else:
            print(maze[i][j], end=" ")
    print()
print()
print(path)

```

main()

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