

附加题

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$$H) a_{k+1}(i) = P(O_1, O_2, \dots, O_{k+1}, q_{k+1} = s_i)$$

$$= \sum_j P(O_1, O_2, \dots, O_k, q_k = s_j, q_{k+1} = s_i)$$

$$= \sum_j P(O_1, O_2, \dots, O_k, q_k = s_j) a_{ji} b_i(O_{k+1}) \quad \text{式①}$$

N : 状态空间, k : 样本总次数

$$\rightarrow a_i(i) = P(O_1, q_1 = s_i) = \pi_i b_i(O_1), \quad i \in [1, N]$$

$q = s_i$ 即状态值为 s_i

$a_{ji}(i)$ 为观测 O , 状态 s 的概率, 因为齐次 Markov,

$$\therefore a_{k+1}(i) = \sum_{j=1}^N a_k(j) \cdot a_{ji} \cdot b_i(O_{k+1}) \quad \text{式②}$$

即第 $k+1$ 次观测 O_{k+1} , 状态为 s_i 的概率。 a_{k+1} 等于第 k 次所有 $a_k(j)$ 的概率, 乘从 j 转移到 i 的概率, 乘观测与状态对应概率。 因为对于第 k 次, 有

$$\therefore a_k(j) = P(O_1, O_2, \dots, O_k, q_k = s_j)$$

代入式①

$$a_{k+1}(i) = \sum_{j=1}^N P(O_1, O_2, \dots, O_k, q_k = s_j) \cdot a_{ji} \cdot b_i(O_{k+1})$$

$$= \sum_{j=1}^N (a_k(j) \cdot a_{ji}) \cdot b_i(O_{k+1})$$

= 式②

代入结果与式②使用 HMM 的齐次 Markov 假设得到结果一致, 得证

2. 推导 $\delta_k(s)$,

$$\begin{aligned}\delta_k(s) &= \max P(q_1 \dots q_{k-1}, q_k = s, o_1, o_2 \dots o_k) \\ &= \max [\max P(q_1 \dots q_{k-1}, q_{k-1} = s_i, o_1, o_2 \dots o_{k-1}) \cdot P(s_j | s_i) \cdot P(s_j | o_k)]\end{aligned}$$

2. 推导 $\delta_k(s)$, 由于是次 Markov 假设

$$\begin{aligned}\delta_k(s) &= \max P(q_1 \dots q_{k-1}, q_k = s, o_1, o_2 \dots o_k) \\ &= \max (\delta_{k-1}(s_i) \cdot P(s_j | s_i) \cdot P(s_j | o_k)) \\ &= \max_i (\max P(q_1 \dots q_{k-1} = s_i, o_1 \dots o_{k-1}) \cdot a_{ij} \cdot b_j(o_k))\end{aligned}$$

3. 推导 BW

$$\xi_k(i, j) = P(q_k = s_i, q_{k+1} = s_j | o_1, o_2 \dots o_k)$$

$$\gamma_k(i) = P(q_k = s_i | o_1 \dots o_k)$$

① from state s_i to state s_j equals to

$$\begin{aligned}&P(q_1 = s_i, q_2 = s_j | o_1, o_2 \dots o_k) + \dots + P(q_{k-1} = s_i, q_k = s_j | o_1, o_2 \dots o_k) \\ &= \xi_1(i, j) + \xi_2(i, j) + \dots + \xi_{k-1}(i, j) \\ &= \sum_{k=1}^{K-1} \xi_k(i, j)\end{aligned}$$

② ~~see~~ one of state s_i , 从该状态转移到别的状态的概率

$$\begin{aligned}&P(q_{k+1} = s_j | o_1, o_2 \dots o_k) + \dots + P(q_{k+K-1} = s_j | o_1, o_2 \dots o_k) \\ &= \gamma_{k+1}(j) + \dots + \gamma_{k+K-1}(j) = \sum_{k=1}^{K-1} \gamma_k(j)\end{aligned}$$

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(3) When V_m occurs in state s_i , $O_k = O_m$.

~~The~~ V_m means the observation is V_m .

$\therefore \sum_{k=1}^K P(q_k = s_i | O_1 \dots O_m)$, $k \leq m$ when $O_k = V_m$

$$R = \sum_{k=1}^K \Gamma_k(i)$$

(4) Expected frequency of in state s_i at time $K = \Gamma_k(i)$

$\Gamma_k(i)$ is a probability, and k is a integer, k can not equals to $\Gamma_k(i)$,

I find the paper in

"cse.buffalo.edu/~jcorso/t/CSE555/files/lecture_hmm.pdf"

and he is

"Expected frequency in state s_i at time $K=1: \Gamma_1(i)$ "

$$\begin{aligned} \text{So, } \pi_i &= P(q_1 = s_i | O_1, O_2 \dots O_K) \\ &= \Gamma_1(i) \end{aligned}$$

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