

$$1. \quad \min [1 \ 1 \ 1 \ 1] \begin{bmatrix} x_1 \\ \vdots \\ x_5 \end{bmatrix}$$

$$\text{s.t.} \quad AX = b \quad x_i \geq 0$$

$$\begin{array}{l} (1) \rightarrow \\ (2) \rightarrow \end{array} \begin{bmatrix} 1 & 2 & 0 & 3 & 1 \\ 0 & 2 & 0 & 1 & 1 \\ 0 & 0 & 1 & 0 & 2 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_5 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 5 \\ 2 \end{bmatrix}$$

$$(1) : \quad x_2 + x_4 = 5$$

$$x_2 + x_4 + 2x_5 = 2$$

$$\therefore 2x_5 = -3$$

$$x_5 = -\frac{3}{2} < 0$$

contradict with  $x_i \geq 0$

$\therefore$  it is not feasible

2. The convex hull for  $(v_i), i \in I$  is

$$S_1 = \left\{ y = \sum_{i \in I} \theta_i v_i \quad \sum \theta_i = 1 \right\}$$

for  $v_j, j \in I$

$$S_2 = \left\{ y = \sum_{j \in I} \theta_j v_j \quad \sum \theta_j = 1 \right\}$$

we need to find a vector  $y'$

s.t  $y'$  could be expressed as  $\sum_{i \in I} \theta_i v_i$   $\sum \theta_i = 1$

and also be expressed as  $\sum_{j \in J} \theta_j v_j$   $\sum \theta_j = 1$

$$\begin{pmatrix} v_1 \\ 1 \end{pmatrix}, \dots, \begin{pmatrix} v_{k+2} \\ 1 \end{pmatrix}$$

$x_i = \begin{pmatrix} v_i \\ 1 \end{pmatrix} \in \mathbb{R}^{k+1}$  and there are  $k+2$  points

$\therefore \begin{pmatrix} v_1 \\ 1 \end{pmatrix}, \dots, \begin{pmatrix} v_{k+2} \\ 1 \end{pmatrix}$  must be linearly dependent

$\therefore$  exists not all-zero coefficients  $a_1, a_2, \dots, a_{k+2}$

$$\text{s.t } a_1 \begin{pmatrix} v_1 \\ 1 \end{pmatrix} + a_2 \begin{pmatrix} v_2 \\ 1 \end{pmatrix} + \dots + a_{k+2} \begin{pmatrix} v_{k+2} \\ 1 \end{pmatrix} = 0$$

$$\therefore a_1 \cdot v_1 + a_2 \cdot v_2 + \dots + a_{k+2} \cdot v_{k+2} = 0$$

$$a_1 + a_2 + \dots + a_{k+2} = 0$$

we just assume that  $a_1, a_2, \dots, a_t$  are not zero

$a_1^+, a_2^+, \dots, a_m^+$  are positive

$a_1^-, a_2^-, \dots, a_n^-$  are negative

$$m+n = t$$

$$\text{let } S^+ = a_1^+ \dots + a_m^+ \\ S^- = a_1^- \dots + a_n^-$$

$$\therefore \vec{0} = \frac{a_1^+}{S^+} V_1^+ + \frac{a_2^+}{S^+} V_2^+ + \dots + \frac{a_m^+}{S^+} V_m^+ \leftarrow \text{corresponding vector of } v$$

$$\vec{0} = \frac{a_1^-}{S^-} V_1^- + \frac{a_2^-}{S^-} V_2^- + \dots + \frac{a_n^-}{S^-} V_n^-$$

$$\therefore S_1 \cap S_2 \neq \emptyset$$

$\therefore$  convex hull intersect

3. friend is right

At the optimal  $x^*$  and  $y^*$

$$c^T x^* + y^{*T} \cdot b = 0$$

$$b = Ax$$

$$\therefore c^T x^* + y^{*T} A x^* = 0$$

$$(c^T + y^{*T} A) x^* = 0$$

$$\therefore (c_i^T + y_i^{*T} a_i) \cdot x_i^* = 0$$

$$\text{if } x_i^* > 0 \Rightarrow (c_i^T + y_i^{*T} a_i) = 0$$

$$\text{if } c_i^T + y_i^{*T} a_i > 0 \Rightarrow x_i^* = 0$$

it is claimed that  $c_i + a_i^T y_I^* > 0$   
for all  $i = 1, \dots, n$

$$\text{for } i \in I \quad x_i^* = x_{Ii}^*$$

$$\text{for } j \notin I \quad x_j^* = 0$$

$\therefore$  Once we know the  $x_I^*$ , we know the  $i \in I$  indices  
that could be non-zero in  $x^*$ , we set all the  
indices that  $j \notin I \quad x_j^* = 0$

Then we can get  $x^*$  from  $x_I$

