PROGRAM TITLE 1

8-PUZZLE PROBLEM

AIM:

To write a python program to solve 8-puzzle problem.

PROCEDURE:

- The code implements the A* algorithm to solve the 8-Puzzle problem.
- It defines classes for priority queue and nodes to represent states.
- Functions are provided for calculating costs, creating new nodes, and printing matrices.
- A* search is performed iteratively, exploring possible moves until the goal state is reached.
- The main section initializes the puzzle states and invokes the solver function to find the solution.

CODING:

```
import copy

from heapq import heappush, heappop


n = 3


row = [1, 0, -1, 0] col
= [0, -1, 0, 1]



class priorityQueue:


    def __init__(self):
self.heap = []


    def push(self, k):

        heappush(self.heap, k)
```

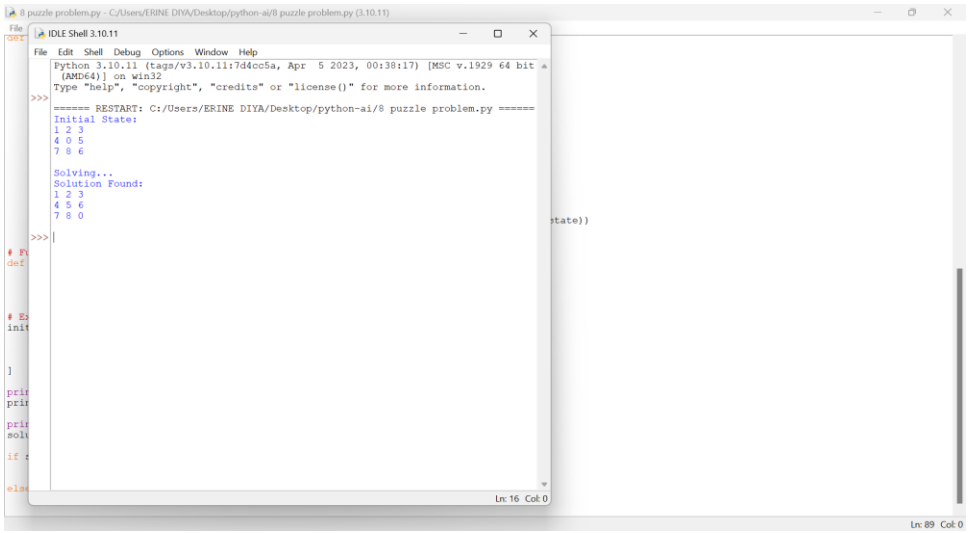
```
    def pop(self):
        return heappop(self.heap)

    def    empty(self):
if    not    self.heap:
return True       else:
            return False


class node:

    def __init__(self, parent, mat, empty_tile_pos,
                 cost, level):
self.parent = parent

        self.mat = mat

        self.empty_tile_pos = empty_tile_pos

        self.cost = cost

        self.level = level

    def __lt__(self, nxt):
        return self.cost < nxt.cost


def calculateCost(mat, final) -> int:
    count = 0     for i in
range(n):         for j in
range(n):             if
((mat[i][j]) and
                  (mat[i][j] != final[i][j])):
```

```
            count += 1

    return count


def newNode(mat, empty_tile_pos, new_empty_tile_pos,
            level, parent, final) -> node:
    new_mat = copy.deepcopy(mat)

    x1 = empty_tile_pos[0]     y1 = empty_tile_pos[1]     x2 =
new_empty_tile_pos[0]     y2 = new_empty_tile_pos[1]     new_mat[x1][y1],
new_mat[x2][y2] = new_mat[x2][y2], new_mat[x1][y1]

    cost = calculateCost(new_mat, final)

    new_node = node(parent, new_mat, new_empty_tile_pos,
                    cost, level)
    return new_node



def printMatrix(mat):
for i in range(n):
for j in range(n):
            print("%d " % (mat[i][j]), end=" ")

print()



def isSafe(x, y):     return x >= 0 and x < n and
y >= 0 and y < n



def printPath(root):
if root == None:
```

```
        return


    printPath(root.parent)
printMatrix(root.mat)     print()



def solve(initial, empty_tile_pos, final):
pq = priorityQueue()


    cost = calculateCost(initial, final)
root = node(None, initial,
empty_tile_pos, cost, 0)


    pq.push(root)


    while not pq.empty():


        minimum = pq.pop()


        if minimum.cost == 0:
printPath(minimum)
            return


        for i in range(4):              new_tile_pos = [
minimum.empty_tile_pos[0] + row[i],
minimum.empty_tile_pos[1] + col[i], ]


            if isSafe(new_tile_pos[0], new_tile_pos[1]):
child = newNode(minimum.mat,
minimum.empty_tile_pos,
new_tile_pos,                               minimum.level +
1,                              minimum, final, )


                pq.push(child)
```

```
initial = [[1, 2, 3],
[5, 6, 0],
          [7, 8, 4]]


final = [[1, 2, 3],

         [5, 8, 6],

         [0, 7, 4]]


empty_tile_pos = [1, 2]


solve(initial, empty_tile_pos, final)
```

OUTPUT:



RESULT:

Hence the program been successfully executed and verified.