

BOW

2018年2月17日 10:46

```
import numpy as np
import pandas as pd
import sqlite3
import pickle
import cv2
from sklearn.cluster import KMeans
```

```
if __name__ == '__main__':
    resizeImgData=getImgPath()
    training_data=load_training_data(resizeImgData)
    scaling_size=100
    kmeans,centroids=FeatureBuilder().get_codewords(training_data,scaling_size)
```

```
with open('featK.pkl','wb') as f1: # 使用with结构避免手动的文件关闭操作
    pickle.dump((kmeans,centroids),f1) #存储kmeans模型, 以及聚类中心点
```

```
feature_map=get_feature_map(training_data,kmeans,centroids,scaling_size)
with open('feature_map.pkl','wb') as f2:
    pickle.dump(feature_map,f2) #存储特征
```

'''提取网页图像打分存储到服务器SQLite数据库中的数据'''

```
def getImgPath():
    connPred = sqlite3.connect('local_data.db') # 连接数据库
    sql = "select * from imageseval"
    data = pd.read_sql(sql=sql, con=connPred) #根据pandas读取SQLite数据库参数要求配置参数

    print(data)

    return data
```

'''根据图像打分评价标志'好', '中'和'差'分离数据, 提取对应的图像路径'''

```
def load_training_data(imgPD):
    training_data=[]
    # print(input_folder)
    goodPD=imgPD[imgPD['eval']=='好'] #先判断获取bool值mask后提取数据
    mediumPD = imgPD[imgPD['eval']=='中']
    poorPD = imgPD[imgPD['eval']=='差']
    training_data.append([( {'object_class': 'good', 'image_path':i} for i in goodPD['imagename']).tolist()]) #根据评价类标提取对应的图像路径名
    training_data.append([( {'object_class': 'moderate', 'image_path': i} for i in mediumPD['imagename']).tolist()])
    training_data.append([( {'object_class': 'poor', 'image_path': i} for i in poorPD['imagename']).tolist()])
    training_dataFlat=flatten_lam(training_data)
    print(training_dataFlat[5])
    return training_dataFlat
```

'''图像特征提取'''

class FeatureBuilder(object):
'''计算图像特征, 返回关键点及特征向量'''

```
def extract_features(self, img):
    keypoints=StarFeatureDetector().detect(img)

    print(len(keypoints),keypoints[:5])

    keypoints,feature_vectors=compute_sift_features(img,keypoints)

    print(len(keypoints),keypoints[:5])

    print(len(feature_vectors),[len(i)for i in feature_vectors[:5]],feature_vectors[0])

    return feature_vectors
```

'''提取指定采样图像数量的图像特征, 此时图像评价指标有3类'good','moderate'和'poor'。'''

```
def get_codewords(self, input_map, scaling_size, max_samples=200): #max_samples为采样数量, 例如键为'good','moderate','poor'的分别各自取12个图像, 当程序调试正确后, 调大该值
    keypoints_all=[]
    count=0
    cur_class=''
    for item in input_map:
        if count>=max_samples:
            if cur_class != item['object_class']:
                count=0
            else:
                continue
        count+=1

        if count==max_samples:
            print("Build centroid for",item['object_class'])

            cur_class=item['object_class']
            img=cv2.imread(item['image_path'])

            num_dims=128
            feature_vectors=self.extract_features(img)
            keypoints_all.extend(feature_vectors) #提取每一图像特征, 并追加在列表中

    print(len(keypoints_all),keypoints_all[0])
    kmeans,centroids=BagOfWords().cluster(keypoints_all) #聚类特征
    print(kmeans,centroids.shape,centroids)
    return kmeans,centroids
```

```
def get_feature_map(input_map,kmeans,centroids,scaling_size):
    feature_map=[]
    for item in input_map:
        temp_dict={}
        temp_dict['object_class']=item['object_class']
        print("Extracting feature for",item['image_path'])
        img=cv2.imread(item['image_path'])
        # img=resize_image(img,scaling_size)

        temp_dict['feature_vector']=BagOfWords().construct_feature(img,kmeans,centroids)
        if temp_dict['feature_vector'] is not None:
            feature_map.append(temp_dict)
        print(feature_map[0]['feature_vector'].shape,feature_map[0])
    return feature_map
```

Extracting feature for static/images/imresize/img_0334.jpg
[31 31 31 5 20 20 5 5 5 20 20 5 5 20 20 5 5 5 5 20 5 5 5 5 5 5 31 5 5 5 20 31 31 20 20 20 16 20 20 11 23 23 9 0 0 13]

	id	imagename	good	medium	poor	eval	eval_time	image_id
1	1	static/images/imresize/img_0321.jpg	4	0	0	好	2018-01-28 17:43:47.808424	<null>
2	2	static/images/imresize/img_0323.jpg	0	0	1	差	2018-01-28 17:43:55.915705	<null>
3	3	static/images/imresize/img_0326.jpg	0	2	0	中	2018-01-28 17:44:05.366660	<null>
4	4	static/images/imresize/img_0327.jpg	1	0	0	好	2018-01-28 17:44:14.690694	<null>
5	5	static/images/imresize/img_0331.jpg	1	0	0	好	2018-01-28 17:44:21.485299	<null>
6	6	static/images/imresize/img_0332.jpg	0	0	1	差	2018-01-28 17:44:28.395802	<null>
7	7	static/images/imresize/img_0333.jpg	0	1	0	中	2018-01-28 17:44:35.023523	<null>
8	8	static/images/imresize/img_0334.jpg	2	0	0	好	2018-01-28 17:44:41.900496	<null>
9	9	static/images/imresize/img_0336.jpg	1	0	0	好	2018-01-28 17:44:47.083740	<null>
10	10	static/images/imresize/img_0339.jpg	2	0	0	好	2018-01-28 17:44:54.997002	<null>

	id	imagename	good	medium	poor	eval	eval_time	image_id
0	1	static/images/imresize/img_0321.jpg	4	0	0	好	2018-01-28 17:43:47.808424	None
1	2	static/images/imresize/img_0323.jpg	0	0	1	差	2018-01-28 17:43:55.915705	None
2	3	static/images/imresize/img_0326.jpg	0	2	0	中	2018-01-28 17:44:05.366660	None
3	4	static/images/imresize/img_0327.jpg	1	0	0	好	2018-01-28 17:44:14.690694	None
4	5	static/images/imresize/img_0331.jpg	1	0	0	好	2018-01-28 17:44:21.485299	None

'''定义类, 用于处理Star特征检测相关函数'''

```
class StarFeatureDetector(object):
    def __init__(self):
        self.detector = cv2.xfeatures2d.StarDetector_create()
    def detect(self, img):
        return self.detector.detect(img) #对输入图像运行检测器
```

194 [<KeyPoint 11D2E610>,<KeyPoint 11D2E750>,<KeyPoint 11D2E5C0>,<KeyPoint 11D2E110>,<KeyPoint 11D2E598>]
294 [<KeyPoint 11D2E138>,<KeyPoint 11D3F318>,<KeyPoint 11D3F340>,<KeyPoint 11D3F368>,<KeyPoint 11D3F390>]
831 [<KeyPoint 11D3F2F0>,<KeyPoint 11E021D8>,<KeyPoint 11E02200>,<KeyPoint 11E02228>,<KeyPoint 11E02250>]
48 [<KeyPoint 11E021B0>,<KeyPoint 11E10598>,<KeyPoint 11E105C0>,<KeyPoint 11E105E8>,<KeyPoint 11E10610>]
367 [<KeyPoint 11E10570>,<KeyPoint 11E10A70>,<KeyPoint 11E10A98>,<KeyPoint 11E10AC0>,<KeyPoint 11E10AE8>]

'''提取SIFT特征'''

```
def compute_sift_features(img,keypoints):
    if img is None:
        raise TypeError('Invalid input image')
    img_gray=cv2.cvtColor(img,cv2.COLOR_BGR2GRAY) #将图像转为灰度
    keypoints,descriptors=cv2.xfeatures2d.SIFT_create().compute(img_gray,keypoints) #SIFT特征提取器提取特征
    return keypoints,descriptors
```

194 [<KeyPoint 11D3E340>,<KeyPoint 11D3E368>,<KeyPoint 11D3E390>,<KeyPoint 11D3E3B8>,<KeyPoint 11D3E3E0>]
194 [128,128,128,128,128] [2. 1. 12. 9. 1. 0. 23.106. 0. 0. 52. 28. 4. 6. 19. 13. 2. 1. 46.117.15. 6. 4. 5. 6. 0. 15. 77. 30. 7. 34. 42. 0. 0. 14. 39. 21. 3. 1. 5. 5. 2. 98.117.117. 9. 1. 4.117. 27.117.117. 19. 4. 2. 91. 77. 4. 5. 10. 0. 11. 32.115. 0. 0. 7. 47. 36. 18. 3. 1. 6. 1. 6. 62.117.117. 79. 26.117. 5. 5. 14. 22. 39. 88.117. 68. 26. 33. 7. 5. 6. 2. 31. 0. 0. 0. 0. 0. 1. 13. 24. 18. 6. 0. 0. 0. 0. 1. 22. 85. 21. 3. 0. 0. 0. 1. 13. 82. 43. 1. 3. 20. 9. 12. 52. 31. 5.]

1734 [2. 1. 12. 9. 1. 0. 23.106. 0. 0. 52. 28. 4. 6. 19. 13. 2. 1. 46.117.15. 6. 4. 5. 6. 0. 15. 77. 30. 7. 34. 42. 0. 0. 14. 39. 21. 3. 1. 5. 5. 2. 98.117.117. 9. 1. 4.117. 27.117.117. 19. 4. 2. 91. 77. 4. 5. 10. 0. 11. 32.115. 0. 0. 7. 47. 36. 18. 3. 1. 6. 1. 6. 62.117.117. 79. 26.117. 5. 5. 14. 22. 39. 88.117. 68. 26. 33. 7. 5. 6. 2. 31. 0. 0. 0. 1. 13. 24. 18. 6. 0. 0. 0. 0. 1. 22. 85. 21. 3. 0. 0. 0. 1. 13. 82. 43. 1. 3. 20. 9. 12. 52. 31. 5.]

KMeans(algorithm='auto', copy_x=True, init='k-means++', max_iter=10, n_clusters=32, n_init=10, n_jobs=1, compute_distances='auto', random_state=None, tol=1.0, verbose=0)
(32, 128)
[[17.5 27.56060606 60.8030303 ... 27.53030303 33.39393939 20.01515152]
[29.26785714 12.48214286 12.85714286 ... 14.58928571 15.125 22.26785714]
[16.12658228 22.01265823 33.74683544 ... 30.5443038 48.73417722 27.93670886]
...
[3.66666667 2.96296296 8.62962963 ... 22.85185185 41.2962963 28.81481481]
[12.24657534 16.28767123 30.01369863 ... 20.79452055 24.45205479 22.64383562]
[21.50704225 15.11267606 21.30985915 ... 11.16901408 15.94366197 16.63380282]]

'''调整图像大小, 因已经处理过图像大小, 此处定义函数未使用。一般直接使用misc.imresize()方法调整图像大小更加简便'''

```
def resize_image(input_img, new_size):
    h, w = input_img.shape[:2]
    scaling_factor = new_size / float(h)
    if w < h:
        scaling_factor = new_size / float(w)
    new_shape = (int(w * scaling_factor), int(h * scaling_factor))
    return cv2.resize(input_img, new_shape) #使用cv2.resize()方法调整图像大小
```

(1, 32) {'object_class': 'good', 'feature_vector': array([[0.05154639, 0.01030928, 0.01030928, 0. , 0.05670103, 0.11340206, 0. , 0.01030928, 0. , 0.01030928, 0.05154639, 0.00515464, 0.06185567, 0.06701031, 0.01030928, 0. , 0.01030928, 0.09793814, 0.02061856, 0.01030928, 0.11340206, 0. , 0. , 0.01030928, 0.02061856, 0.03608247, 0.0257732, 0.1185567, 0. , 0.07216495, 0. , 0.00515464]])}