Clustering With DBScans

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```
library(factoextra)

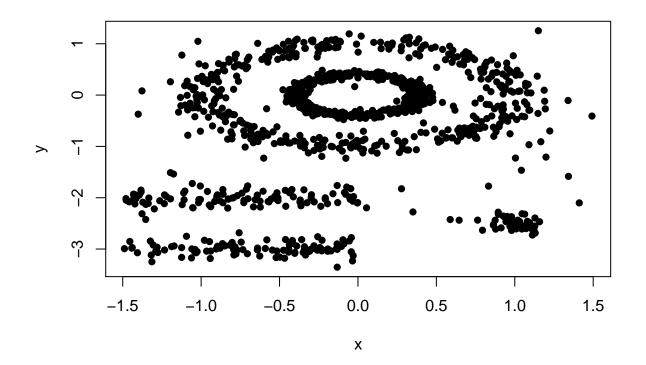
## Warning: package 'factoextra' was built under R version 4.0.3

## Loading required package: ggplot2

## Warning: package 'ggplot2' was built under R version 4.0.3

## Welcome! Want to learn more? See two factoextra-related books at https://goo.gl/ve3WBa

data("multishapes")
df <- multishapes[, 1:2]
plot(df, pch=16)</pre>
```

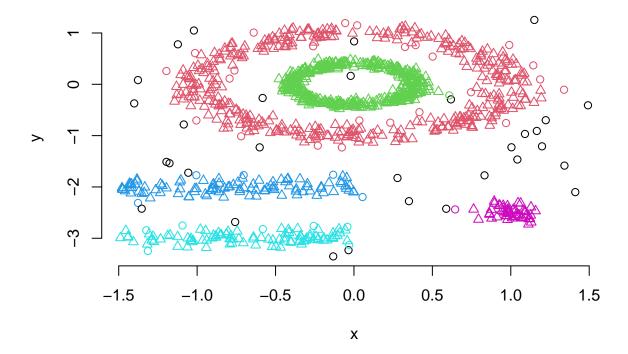


library(fpc)

Warning: package 'fpc' was built under R version 4.0.3

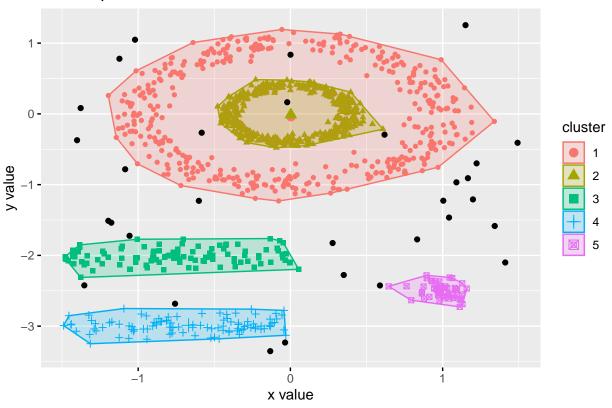
```
set.seed(123)
db <- dbscan(df, eps = 0.15, MinPts = 5)
plot(db, df, main = "DBSCAN", frame = FALSE)</pre>
```

DBSCAN



```
library(factoextra)
fviz_cluster(db, df, stand = FALSE, frame = FALSE, geom = "point")
```

Cluster plot



print(db)

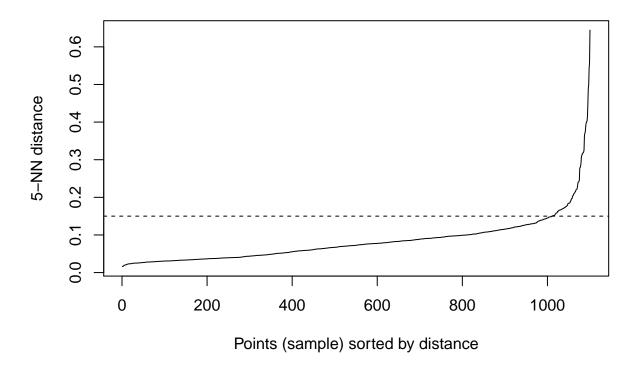
```
## dbscan Pts=1100 MinPts=5 eps=0.15
## 0 1 2 3 4 5
## border 31 24 1 5 7 1
## seed 0 386 404 99 92 50
## total 31 410 405 104 99 51
```

db\$cluster

```
##
 ##
##
 1 1 1 1 1 1 1 1 1 1
##
##
 1
                  1 1 1 1 1 1 1 1 1 1
          1 1 1 1 1 1 1 1 1 1 1 1 1
##
##
          1 1 1 1 1 1 1 1 1
##
##
 [297] 1 1 1 1 1 1
 [371] 1 1 1 1 1 1 1 1 1 1 1 1 1
          1 1 1 1 1 1 1 1 1 1 1 1 1
##
##
 [408] 2 2 2 2 2 2 2 2 2 2 2 2 2
         2
          ##
 ##
```

```
##
##
## [1000] 4 1 5 1 2 0 0 0 0 0 1 0 2 0 2 0 1 1 4 0 0 3 0 0 2 0 0 1 0 0 0 0 1 2 0 0 0
library(dbscan)
## Warning: package 'dbscan' was built under R version 4.0.3
## Attaching package: 'dbscan'
## The following object is masked from 'package:fpc':
##
##
 dbscan
```

kNNdistplot(df, k = 5)
abline(h = 0.15, lty = 2)



Latihan

1. Jika radius di ubah dan min Pt
s=5tetap

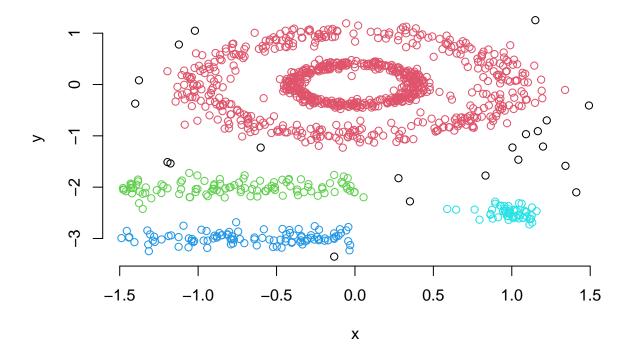
```
library(fpc)
library(factoextra)
set.seed(123)

##Radius Semakin Besar
db <- dbscan(df, eps = 0.20, MinPts = 5)

## Warning in dbscan(df, eps = 0.2, MinPts = 5): converting argument MinPts (fpc)
## to minPts (dbscan)!

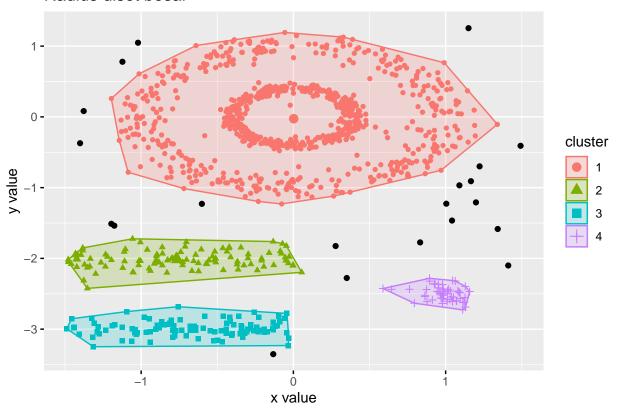
plot(db, df, main = "DBSCAN-RADIUS_SET_BESAR", frame = FALSE)</pre>
```

DBSCAN-RADIUS_SET_BESAR



fviz_cluster(db, df, main = "Radius diset besar", stand = FALSE, frame = FALSE, geom = "point")

Radius diset besar

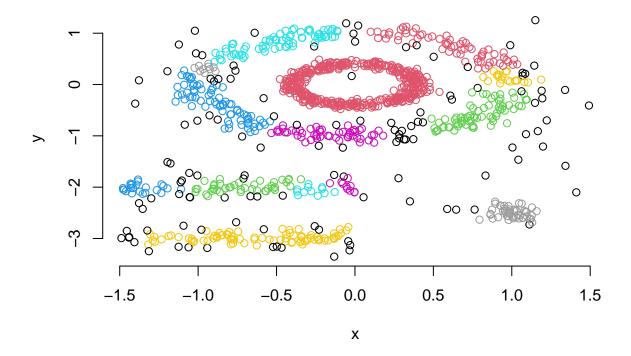


```
##Radius Semakin Kecil
db <- dbscan(df, eps = 0.10, MinPts = 5)</pre>
```

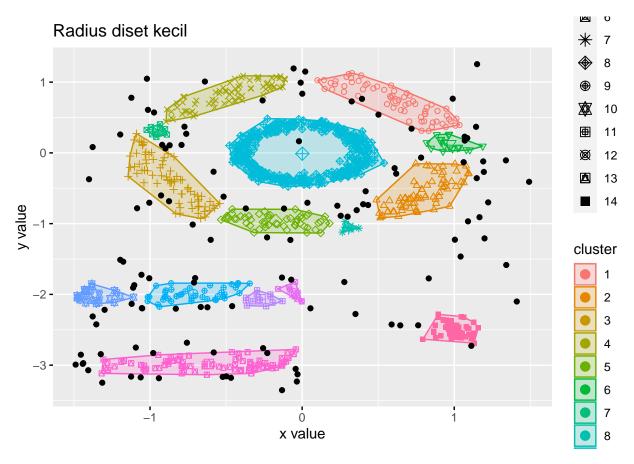
Warning in dbscan(df, eps = 0.1, MinPts = 5): converting argument MinPts (fpc)
to minPts (dbscan)!

plot(db, df, main = "DBSCAN-RADIUS_SET_KECIL", frame = FALSE)

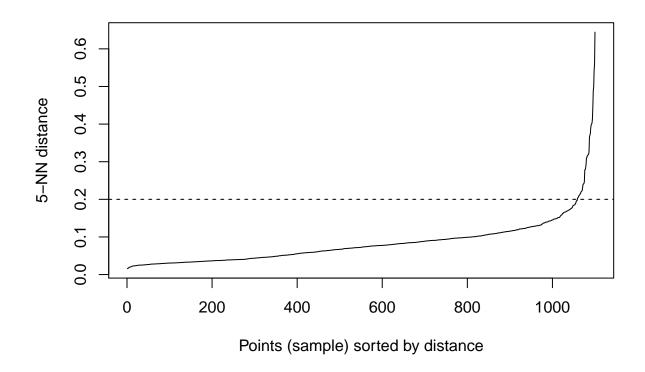
DBSCAN-RADIUS_SET_KECIL



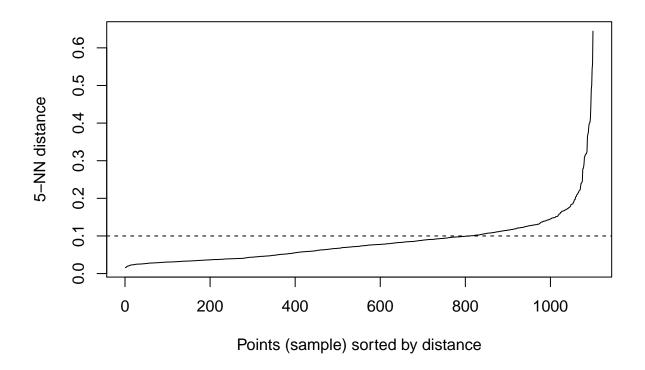
fviz_cluster(db, df, main = "Radius diset kecil", stand = FALSE, frame = FALSE, geom = "point")



```
##Radius Semakin Besar
kNNdistplot(df, k = 5)
abline(h = 0.20, lty = 2)
```



```
##Radius Semakin Kecil
kNNdistplot(df, k = 5)
abline(h = 0.10, lty = 2)
```



2. Jika min Pts di ubah dan radius = 0.15 tetap

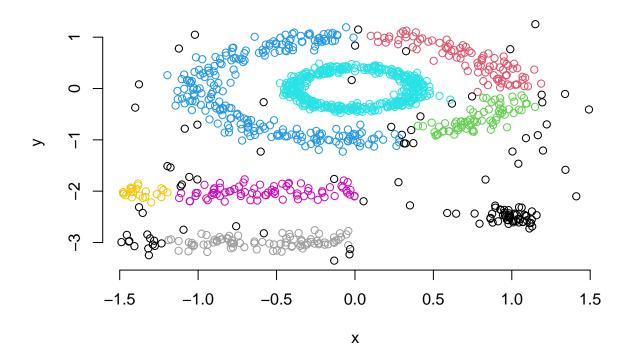
```
library(fpc)
library(factoextra)
set.seed(123)

##Minimal Point Semakin Besar
db <- dbscan(df, eps = 0.15, MinPts = 10)

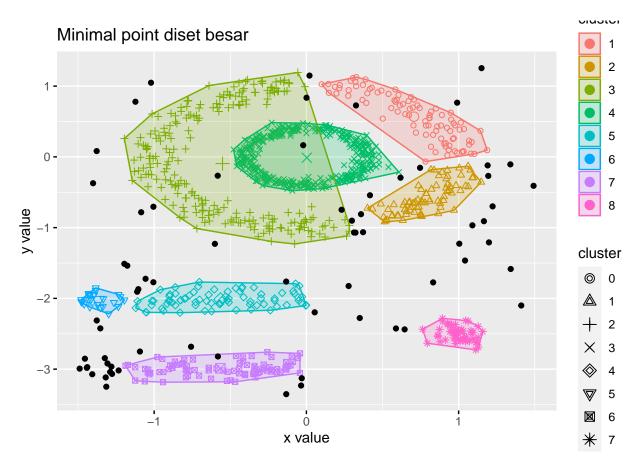
## Warning in dbscan(df, eps = 0.15, MinPts = 10): converting argument MinPts (fpc)
## to minPts (dbscan)!

plot(db, df, main = "DBSCAN-MINIMAL_POINT_SET_BESAR", frame = FALSE)</pre>
```

DBSCAN-MINIMAL_POINT_SET_BESAR



fviz_cluster(db, df, main = "Minimal point diset besar", stand = FALSE, frame = FALSE, geom = "point")

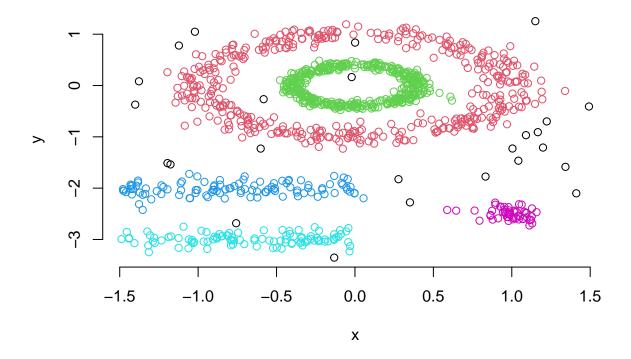


```
##Minimal Point Semakin Kecil
db <- dbscan(df, eps = 0.15, MinPts = 3)</pre>
```

Warning in dbscan(df, eps = 0.15, MinPts = 3): converting argument MinPts (fpc)
to minPts (dbscan)!

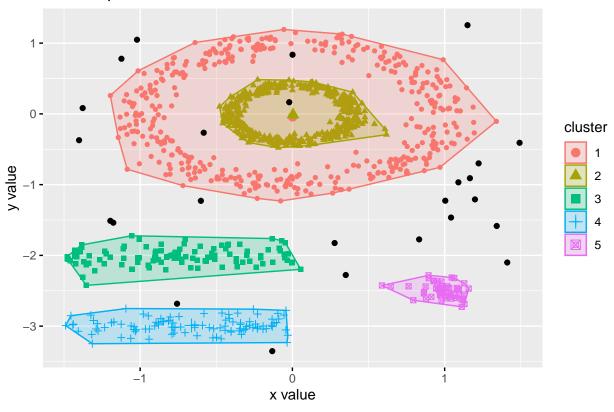
plot(db, df, main = "DBSCAN-MINIMAL_POINT_SET_KECIL", frame = FALSE)

DBSCAN-MINIMAL_POINT_SET_KECIL

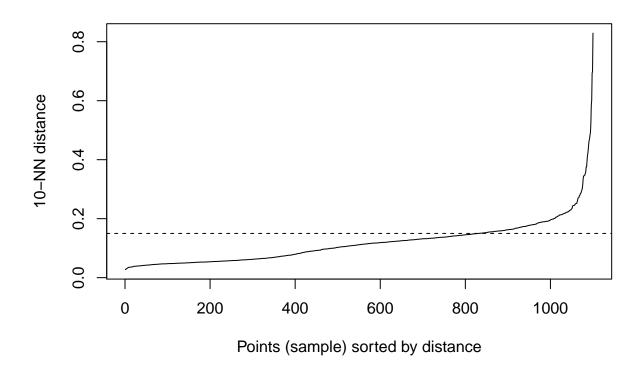


fviz_cluster(db, df, main = "Minimal point diset kecil", stand = FALSE, frame = FALSE, geom = "point")

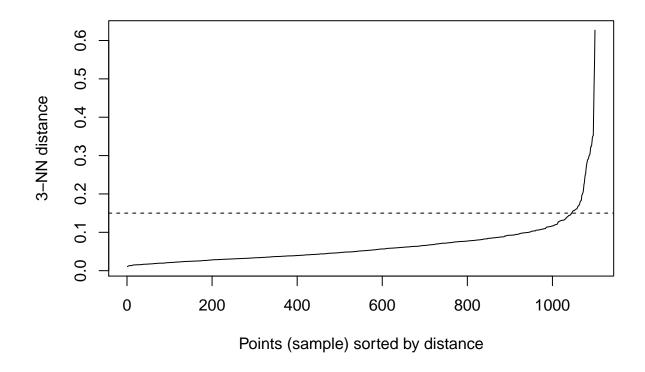
Minimal point diset kecil



```
library(dbscan)
##Minimal Point Semakin Besar
kNNdistplot(df, k = 10)
abline(h = 0.15, lty = 2)
```



```
##Minimal Point Semakin Kecil
kNNdistplot(df, k = 3)
abline(h = 0.15, lty = 2)
```



Kesimpulan

Jika radius di set semakin besar maka beberapa noise akan ikut menjadi bagian dari claster sedangkan jika radius di set semakin kecil maka noise akan bertambah begitupun dengan banyaknya claster yang terbentuk.

Jika minimal point di set semakin besar maka akan terbentuk beberapa claster baru dan noise nya bertambah sedangkan jika minimal point di set semakin kecil maka claster dan noise akan berkurang.