# FedAvg算法复现

### 1. 准备工作

FedAvg算法过程如下:

**Algorithm 1** FederatedAveraging. The K clients are indexed by k; B is the local minibatch size, E is the number of local epochs, and  $\eta$  is the learning rate.

#### Server executes:

```
initialize w_0

for each round t = 1, 2, \ldots do

m \leftarrow \max(C \cdot K, 1)

S_t \leftarrow (random set of m clients)

for each client k \in S_t in parallel do

w_{t+1}^k \leftarrow ClientUpdate(k, w_t)

w_{t+1} \leftarrow \sum_{k=1}^K \frac{n_k}{n} w_{t+1}^k
```

ClientUpdate(k, w): // Run on client k  $\mathcal{B} \leftarrow (\operatorname{split} \mathcal{P}_k \operatorname{into} \operatorname{batches} \operatorname{of} \operatorname{size} B)$ for each local epoch i from 1 to E do
for batch  $b \in \mathcal{B}$  do  $w \leftarrow w - \eta \nabla \ell(w; b)$ return w to server

#### 数据集介绍:

CIFAR-10是一个更接近普适物体的彩色图像数据集。CIFAR-10 是由Hinton 的学生Alex Krizhevsky 和 Ilya Sutskever 整理的一个用于识别普适物体的小型数据集。一共包含10 个类别的RGB 彩色图片: 飞机(airplane)、汽车(automobile)、鸟类(bird)、猫(cat)、鹿(deer)、狗(dog)、蛙类(frog)、马(horse)、船(ship)和卡车(truck)。每个图片的尺寸为32×32,每个类别有6000个图像,数据集中一共有50000 张训练图片和10000 张测试图片。

## 2. 分割数据集

```
def get_datasets(data_name, dataroot, normalize=True, val_size=10000):
    """

get_datasets returns train/val/test data splits of CIFAR10/100 datasets
:param data_name: name of dataset, choose from [cifar10, cifar100]
:param dataroot: root to data dir
```

```
6
        :param normalize: True/False to normalize the data
 7
        :param val_size: validation split size (in #samples)
 8
        :return: train_set, val_set, test_set (tuple of pytorch dataset/subset)
 9
10
11
        if data_name =='cifar10':
12
            normalization = transforms.Normalize((0.4914, 0.4822, 0.4465),
    (0.2023, 0.1994, 0.2010))
13
            data_obj = CIFAR10
14
        elif data_name == 'cifar100':
15
            normalization = transforms.Normalize((0.5071, 0.4865, 0.4409),
    (0.2673, 0.2564, 0.2762))
16
            data_obj = CIFAR100
17
        else:
18
            raise ValueError("choose data_name from ['mnist', 'cifar10',
    'cifar100']")
19
20
        trans = [transforms.ToTensor()]
21
22
        if normalize:
            trans.append(normalization)
23
24
25
        transform = transforms.Compose(trans)
26
27
        dataset = data_obj(
28
            dataroot,
29
            train=True,
30
            download=True,
31
            transform=transform
32
        )
33
34
        test_set = data_obj(
35
            dataroot,
36
            train=False.
37
            download=True,
38
            transform=transform
39
        )
40
41
        train_size = len(dataset) - val_size
42
        train_set, val_set = torch.utils.data.random_split(dataset,
    [train_size, val_size]) # 切割数据集伟训练集与验证集
43
44
        return train_set, val_set, test_set
45
46
47
    def get_num_classes_samples(dataset):
48
49
        extracts info about certain dataset
50
        :param dataset: pytorch dataset object
51
        :return: dataset info number of classes, number of samples, list of
    labels
52
53
        # ----#
54
        # Extract labels #
55
        # ----#
56
        if isinstance(dataset, torch.utils.data.Subset):
57
            if isinstance(dataset.dataset.targets, list):
```

```
5.8
                data_labels_list = np.array(dataset.dataset.targets)
     [dataset.indices]
 59
            else:
 60
                data_labels_list = dataset.dataset.targets[dataset.indices]
 61
         else:
            if isinstance(dataset.targets, list):
 62
 63
                data_labels_list = np.array(dataset.targets)
 64
            else:
                data_labels_list = dataset.targets
 65
 66
         classes, num_samples = np.unique(data_labels_list, return_counts=True)
         num_classes = len(classes)
 67
 68
         return num_classes, num_samples, data_labels_list
 69
 70
 71
     def gen_classes_per_node(dataset, num_users, classes_per_user=2,
     high_prob=0.6, low_prob=0.4):
        0.000
 72
 73
        creates the data distribution of each client
 74
        :param dataset: pytorch dataset object
 75
        :param num_users: number of clients
 76
        :param classes_per_user: number of classes assigned to each client
 77
         :param high_prob: highest prob sampled
 78
         :param low_prob: lowest prob sampled
 79
         :return: dictionary mapping between classes and proportions, each entry
     refers to other client
 80
         num_classes, num_samples, _ = get_num_classes_samples(dataset)
 81
 82
         # -----#
 83
 84
         # Divide classes + num samples for each user #
 85
         # -----#
 86
         assert (classes_per_user * num_users) % num_classes == 0, "equal
     classes appearance is needed"
 87
         count_per_class = (classes_per_user * num_users) // num_classes
 88
         class_dict = {}
 89
         for i in range(num_classes):
             # sampling alpha_i_c
 90
 91
            probs = np.random.uniform(low_prob, high_prob,
     size=count_per_class)
 92
            # normalizing
             probs_norm = (probs / probs.sum()).tolist()
 93
 94
             class_dict[i] = {'count': count_per_class, 'prob': probs_norm}
 95
96
         # -----#
 97
         # Assign each client with data indexes #
 98
99
         class_partitions = defaultdict(list)
100
        for i in range(num_users):
101
            c = []
102
             for _ in range(classes_per_user):
103
                class_counts = [class_dict[i]['count'] for i in
     range(num_classes)]
104
                max_class_counts = np.where(np.array(class_counts) ==
     max(class_counts))[0]
105
                c.append(np.random.choice(max_class_counts))
106
                class_dict[c[-1]]['count'] -= 1
107
             class_partitions['class'].append(c)
```

```
108
            class_partitions['prob'].append([class_dict[i]['prob'].pop() for i
     in c])
109
        return class_partitions
110
111
112
     def gen_data_split(dataset, num_users, class_partitions):
113
114
        divide data indexes for each client based on class_partition
115
        :param dataset: pytorch dataset object (train/val/test)
116
        :param num_users: number of clients
        :param class_partitions: proportion of classes per client
117
        :return: dictionary mapping client to its indexes
118
119
120
        num_classes, num_samples, data_labels_list =
     get_num_classes_samples(dataset)
121
122
         # ----- #
123
        # Create class index mapping #
         # ----- #
124
125
         data_class_idx = {i: np.where(data_labels_list == i)[0] for i in
     range(num_classes)}
126
127
        # ----- #
128
        # Shuffling #
129
        # ----- #
130
        for data_idx in data_class_idx.values():
131
             random.shuffle(data_idx)
132
133
        # ----- #
134
        # Assigning samples to each user #
135
         # ----- #
        user_data_idx = [[] for i in range(num_users)]
136
137
         for usr_i in range(num_users):
138
            for c, p in zip(class_partitions['class'][usr_i],
     class_partitions['prob'][usr_i]):
139
                end_idx = int(num_samples[c] * p)
                user_data_idx[usr_i].extend(data_class_idx[c][:end_idx])
140
141
                data_class_idx[c] = data_class_idx[c][end_idx:]
142
143
        return user_data_idx
144
145
146
     def gen_random_loaders(data_name, data_path, num_users, bz,
     classes_per_user):
        0.00
147
        generates train/val/test loaders of each client
148
149
        :param data_name: name of dataset, choose from [cifar10, cifar100]
150
        :param data_path: root path for data dir
151
        :param num_users: number of clients
152
        :param bz: batch size
153
         :param classes_per_user: number of classes assigned to each client
         :return: train/val/test loaders of each client, list of pytorch
154
     dataloaders
        0.00
155
156
         loader_params = {"batch_size": bz, "shuffle": False, "pin_memory":
     True, "num_workers": 0}
157
         dataloaders = []
158
         datasets = get_datasets(data_name, data_path, normalize=True)
```

```
159
         for i, d in enumerate(datasets):
160
             # ensure same partition for train/test/val
             if i == 0:
161
162
                 cls_partitions = gen_classes_per_node(d, num_users,
     classes_per_user)
163
                 loader_params['shuffle'] = True
164
             usr_subset_idx = gen_data_split(d, num_users, cls_partitions)
165
             # create subsets for each client
             subsets = list(map(lambda x: torch.utils.data.Subset(d, x),
166
     usr_subset_idx))
             # create dataloaders from subsets
167
             dataloaders.append(list(map(lambda x:
168
     torch.utils.data.DataLoader(x, **loader_params), subsets)))
169
170
         return dataloaders
171
```

## 3. 数据节点类

```
from experiments.dataset import gen_random_loaders
 1
 2
 3
 4
    class BaseNodes:
 5
        def __init__(
 6
                 self,
                 data_name,
 7
 8
                 data_path,
 9
                 n_nodes,
10
                 batch_size=128,
                 classes_per_node=2
11
        ):
12
13
14
            self.data_name = data_name
15
            self.data_path = data_path
            self.n_nodes = n_nodes
16
17
            self.classes_per_node = classes_per_node
18
            self.batch_size = batch_size
19
20
21
            self.train_loaders, self.val_loaders, self.test_loaders = None,
    None, None
22
            self._init_dataloaders()
23
24
        def _init_dataloaders(self):
             self.train_loaders, self.val_loaders, self.test_loaders =
25
    gen_random_loaders(
26
                 self.data_name,
                 self.data_path,
27
28
                 self.n_nodes,
29
                 self.batch_size,
                 self.classes_per_node
30
31
            )
32
33
        def __len__(self):
34
             return self.n_nodes
```

## 4. CNN模型类

```
import torch.nn.functional as F
 1
 2
    from torch import nn
    import numpy as np
    import torch
    from torch.utils.data import TensorDataset
    from torch.utils.data import DataLoader
 6
 7
 8
 9
    class CNN(nn.Module):
10
        def __init__(self, in_channels=3, n_kernels=16, out_dim=10):
            super(CNN, self).__init__()
11
12
            self.conv1 = nn.Conv2d(in_channels=in_channels,
13
    out_channels=n_kernels, kernel_size=5)
14
            self.pool = nn.MaxPool2d(2, 2)
            self.conv2 = nn.Conv2d(in_channels=n_kernels, out_channels=2 *
15
    n_kernels, kernel_size=5)
            self.fc1 = nn.Linear(in_features=2 * n_kernels * 5 * 5,
16
    out_features=120)
17
            self.fc2 = nn.Linear(in_features=120, out_features=84)
            self.fc3 = nn.Linear(in_features=84, out_features=out_dim)
18
19
        def forward(self, x):
20
            x = self.pool(F.relu(self.conv1(x)))
21
22
            x = self.pool(F.relu(self.conv2(x)))
23
            x = x.view(x.shape[0], -1)
24
            x = F.relu(self.fc1(x))
25
            x = F.relu(self.fc2(x))
26
            x = self.fc3(x)
27
            return x
28
29
30
    class Client(object):
31
        def __int__(self, trainDataSet, dev):
32
            self.train_ds = trainDataSet
33
            self.dev = dev
34
            self.train_dl = None
35
            self.local_parameter = None
```

# 5. 利用FedAvg算法训练

```
# init nodes, hnet, local net #
8
        #################################
9
        steps = 5
10
        node_iter = 5
11
        nodes = BaseNodes(data_name, data_path, num_nodes,
    classes_per_node=classes_per_node,
12
                          batch_size=bs)
13
        net = CNN(n_kernels=n_kernels)
        # hnet = hnet.to(device)
14
15
        net = net.to(device)
16
17
        ###################
18
        # init optimizer #
        ##################
19
20
        # embed_lr = embed_lr if embed_lr is not None else lr
        optimizer = torch.optim.SGD(
21
22
            net.parameters(), lr=inner_lr, momentum=.9, weight_decay=inner_wd
23
24
        criteria = torch.nn.CrossEntropyLoss()
25
        ################
26
27
        # init metrics #
28
        ###############
29
        # step_iter = trange(steps)
30
        step_iter = range(steps)
31
        # train process
        # record the global parameters
32
33
        global_parameters = {}
34
        for key, parameter in net.state_dict().items():
            global_parameters[key] = parameter.clone()
35
36
        for step in step_iter:
37
            local_parameters_list = {}
38
39
            # 需要训练的node数目
40
            for i in range(node_iter):
41
                # 随机选择一个客户端
                node_id = random.choice(range(num_nodes))
42
43
                # 用全局模型参数训练当前客户端
44
                local_parameters = local_upload(nodes.train_loaders[node_id], 5,
    net, criteria, optimizer,
45
                                                 global_parameters, dev='cpu')
                print("\nEpoch: {}, Node Count: {}, Node ID: {}".format(step +
46
    1, i + 1, node_id), end="")
47
                evaluate(net, local_parameters, nodes.val_loaders[node_id],
    'cpu')
                local_parameters_list[i] = local_parameters
48
49
50
            # 更新当前轮次模型的参数
51
            sum_parameters = None
            for node_id, parameters in local_parameters_list.items():
52
53
                if sum_parameters is None:
54
                    sum_parameters = parameters
55
                else:
56
                    for key in parameters.keys():
                         sum_parameters[key] += parameters[key]
57
58
            for var in global_parameters:
59
                global_parameters[var] = (sum_parameters[var] / node_iter)
60
```

```
61
        net.load_state_dict(global_parameters, strict=True)
62
        net.eval()
        for data_set in nodes.test_loaders:
63
            running_correct = 0
64
65
            running\_samples = 0
            for data, label in data_set:
66
67
                 pred = net(data)
68
                 running_correct += pred.argmax(1).eq(label).sum().item()
                 running_samples += len(label)
69
            print("\t" + 'accuracy: %.2f' % (running_correct / running_samples),
70
    end="")
```

## 6. client训练函数

```
def local_upload(train_data_set, local_epoch, net, loss_fun, opt,
   global_parameters, dev):
2
       # 加载当前通信中最新全局参数
       net.load_state_dict(global_parameters, strict=True)
4
       # 设置迭代次数
5
       net.train()
6
       for epoch in range(local_epoch):
7
           for data, label in train_data_set:
8
               data, label = data.to(dev), label.to(dev)
9
               # 模型上传入数据
10
               predict = net(data)
               loss = loss_fun(predict, label)
11
12
               # 反向传播
13
               loss.backward()
14
               # 计算梯度,并更新梯度
15
               opt.step()
               # 将梯度归零,初始化梯度
16
17
               opt.zero_grad()
18
       # 返回当前Client基于自己的数据训练得到的新的模型参数
19
       return net.state_dict()
```

## 7. 模型评估函数

```
1
    def evaluate(net, global_parameters, testDataLoader, dev):
 2
        net.load_state_dict(global_parameters, strict=True)
 3
        running_correct = 0
 4
        running\_samples = 0
 5
        net.eval()
 6
        # 载入测试集
 7
        for data, label in testDataLoader:
            data, label = data.to(dev), label.to(dev)
 8
9
            pred = net(data)
            running_correct += pred.argmax(1).eq(label).sum().item()
10
11
            running_samples += len(label)
12
        print("\t" + 'accuracy: %.2f' % (running_correct / running_samples),
    end="")
```

## 8. 模型训练结果

#### 因为设备原因, 暂时无法训练出论文中的模型

```
Epoch: 2, Node Count: 35, Node ID: 39
                                        accuracy: 0.7173376083374023
Epoch: 2, Node Count: 36, Node ID: 43
                                        accuracy: 0.5102083086967468
Epoch: 2, Node Count: 37, Node ID: 41
                                        accuracy: 0.6944901347160339
Epoch: 2, Node Count: 38, Node ID: 4
                                        accuracy: 0.4871794879436493
Epoch: 2, Node Count: 39, Node ID: 47
                                        accuracy: 0.46875
Epoch: 2, Node Count: 40, Node ID: 25
                                        accuracy: 0.7411221265792847
Epoch: 2, Node Count: 41, Node ID: 39
                                        accuracy: 0.6196151375770569
Epoch: 2, Node Count: 42, Node ID: 40
                                        accuracy: 0.7840402126312256
Epoch: 2, Node Count: 43, Node ID: 16
                                        accuracy: 0.7732007503509521
Epoch: 2, Node Count: 44, Node ID: 8
                                        accuracy: 0.7512019276618958
Epoch: 2, Node Count: 45, Node ID: 27
                                        accuracy: 0.6020998954772949
Epoch: 2, Node Count: 46, Node ID: 5
                                        accuracy: 0.4984374940395355
Epoch: 2, Node Count: 47, Node ID: 40
                                        accuracy: 0.7109375
Epoch: 2, Node Count: 48, Node ID: 49
                                        accuracy: 0.7680289149284363
```

### 附录:关键函数记录

#### torch.nn.Module.load\_state\_dict

#### load\_state\_dict(state\_dict, strict=True)

使用 state\_dict 反序列化模型参数字典。用来加载模型参数。将 state\_dict 中的 parameters 和 buffers 复制到此 module 及其子节点中。

概况: 给模型对象加载训练好的模型参数, 即加载模型参数

state\_dict (字典类型) - 一个包含参数和持续性缓冲的字典,往往是pytorch模型pth文件

strict (布尔类型, 可选) – 该参数用来指明是否需要强制严格匹配, 即:state\_dict中的关键字是否需要和该模块的state\_dict()方法返回的关键字强制严格匹配.默认值是True

#### nn.utils.clip\_grad\_norm\_

#### nn.utils.clip\_grad\_norm\_(parameters, max\_norm, norm\_type=2)

这个函数是根据参数的范数来衡量的

#### Parameters:

parameters (Iterable[Variable]) – 一个基于变量的迭代器,会进行归一化(原文:an iterable of Variables that will have gradients normalized)

max\_norm (float or int) - 梯度的最大范数 (原文: max norm of the gradients)

norm\_type(float or int) – 规定范数的类型,默认为L2(原文: type of the used p-norm. Can be'inffor infinity norm)

Returns:参数的总体范数(作为单个向量来看)(原文: Total norm of the parameters (viewed as a single vector).)

#### torch.nn.Embedding

```
torch.nn.Embedding(num_embeddings, embedding_dim, padding_idx=None,
max_norm=None, norm_type=2.0, scale_grad_by_freq=False, sparse=False,
_weight=None, device=None, dtype=None)
```

一个简单的查找表,用于存储固定字典和大小的嵌入。该模块通常用于存储词嵌入并使用索引检索它们。模块的输入是索引列表,输出是相应的词嵌入。

```
CNNTarget(
  (conv1): Conv2d(3, 16, kernel_size=(5, 5), stride=(1, 1))
  (pool): MaxPool2d(kernel_size=2, stride=2, padding=0, dilation=1,
    ceil_mode=False)
  (conv2): Conv2d(16, 32, kernel_size=(5, 5), stride=(1, 1))
  (fc1): Linear(in_features=800, out_features=120, bias=True)
  (fc2): Linear(in_features=120, out_features=84, bias=True)
  (fc3): Linear(in_features=84, out_features=10, bias=True)
)
```