Chapter 4

- 4.1 Normal approximation (Laplace's method)
- 4.2 Large-sample theory
- 4.3 Counter examples
 - includes examples of difficult posteriors for MCMC, too
- 4.4 Frequency evaluation*
- 4.5 Other statistical methods*

- Often posterior converges to normal distribution when $n \to \infty$
- If posterior is unimodal and close to symmetric
 - we can approximate $p(\theta|y)$ with normal distribution

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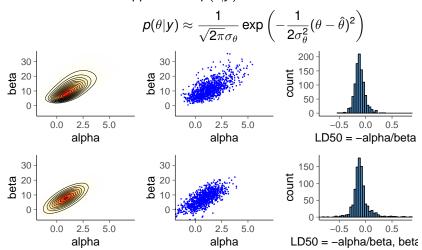
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- A most strict proof by LeCam in 1950's

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• We can approximate $p(\theta|y)$ with normal distribution

$$p(\theta|y) \approx \frac{1}{\sqrt{2\pi}\sigma_{\theta}} \exp\left(-\frac{1}{2\sigma_{\theta}^2}(\theta-\hat{\theta})^2\right)$$

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- if $\hat{\theta}$ is at mode, then $f'(\hat{\theta}) = 0$
- often when $n \to \infty$, $\frac{f^{(3)}(\hat{\theta})}{3!}(\theta \hat{\theta})^3 + \dots$ is small

Multivariate Taylor series

Multivariate series expansion

$$f(\theta) = f(\hat{\theta}) + \frac{df(\theta')}{d\theta'} \Big|_{\theta' = \hat{\theta}} (\theta - \hat{\theta}) + \frac{1}{2!} (\theta - \hat{\theta})^{T} \frac{d^{2}f(\theta')}{d\theta'^{2}} \Big|_{\theta' = \hat{\theta}} (\theta - \hat{\theta}) + \dots$$

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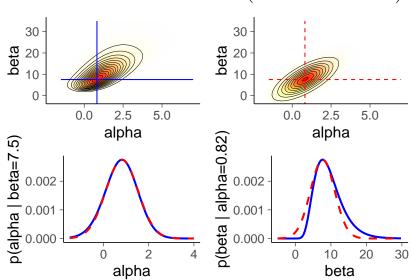
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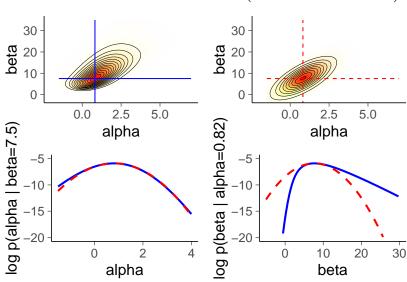
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- Normal approximation

$$p(\theta|y) \approx N(\hat{\theta}, [I(\hat{\theta})]^{-1})$$

where $I(\theta)$ is called *observed information*

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- $I(\hat{\theta})$ is the second derivatives at the mode and thus describes the curvature at the mode
- if the mode is inside the parameter space, $I(\hat{\theta})$ is positive
- if θ is a vector, then $I(\theta)$ is a matrix

 BDA3 Ch 4 has an example where it is easy to compute first and second derivatives and there is easy analytic solution to find where the first derivatives are zero

- Normal distribution, unknown mean and variance
 - uniform prior $(\mu, \log \sigma)$
 - normal approximation for the posterior of $(\mu, \log \sigma)$

$$\log p(\mu, \log \sigma | y) = \operatorname{constant} - n \log \sigma - \frac{1}{2\sigma^2} [(n-1)s^2 + n(\bar{y} - \mu)^2]$$

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from which it is easy to compute the mode

$$(\hat{\mu}, \log \hat{\sigma}) = \left(\bar{y}, \frac{1}{2} \log \left(\frac{n-1}{n} s^2\right)\right)$$

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matrix of the second derivatives at $(\hat{\mu}, \log \hat{\sigma})$

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 Normal distribution, unknown mean and variance posterior mode

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normal approximation

$$p(\mu, \log \sigma | y) \approx N\left(\begin{pmatrix} \mu \\ \log \sigma \end{pmatrix} \middle| \begin{pmatrix} \bar{y} \\ \log \hat{\sigma} \end{pmatrix}, \begin{pmatrix} \hat{\sigma}^2/n & 0 \\ 0 & 1/(2n) \end{pmatrix}\right)$$

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 - e.g. in R, demo4_1.R:

```
\begin{array}{lll} \mbox{bioassayfun} & <- \mbox{ function(w, df) } \{ & z <- \mbox{ w[1] } + \mbox{ w[2]* df$x} \\ & - \mbox{sum(df$y*(z) } - \mbox{ df$n*log1p(exp(z)))} \} \\ \\ \mbox{theta0 } & <- \mbox{ c(0,0)} \\ \mbox{optimres} & <- \mbox{ optim(w0, bioassayfun, gr=NULL, df1, hessian=T)} \\ \mbox{thetahat } & <- \mbox{ optimres$par} \\ \mbox{Sigma} & <- \mbox{ solve(optimres$hessian)} \end{array}
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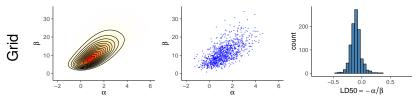
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 - uses finite differences of gradients to compute Hessian
 - second order autodiff coming to Stan

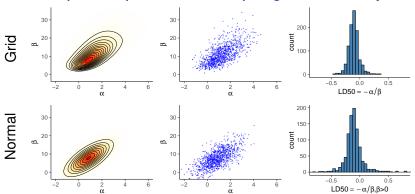
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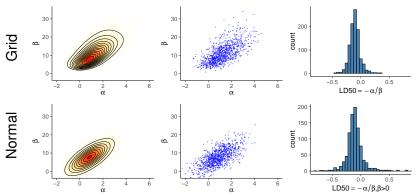
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 - Rasmussen & Williams: Gaussian Processes for Machine Learning

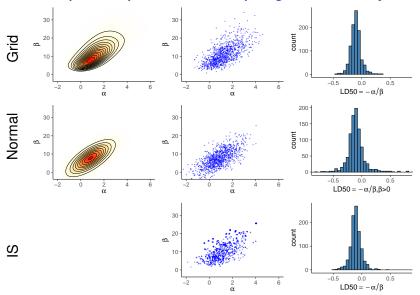
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- Accuracy can be improved by importance sampling (Ch 10)

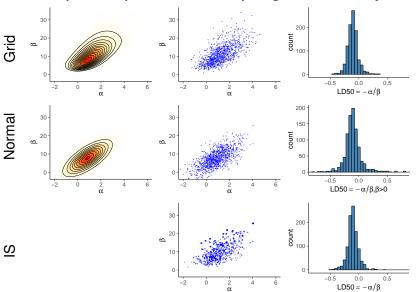






But the normal approximation is not that good here: Grid $sd(LD50) \approx 0.1$, Normal $sd(LD50) \approx .75!$





Grid sd(LD50) \approx 0.1, IS sd(LD50) \approx 0.1

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 - since version 2.19.2 (2019-10-03)
 - + Pareto-k diagnostic
 - + importance resampling (IR)

• Higher order derivatives at the mode can be used

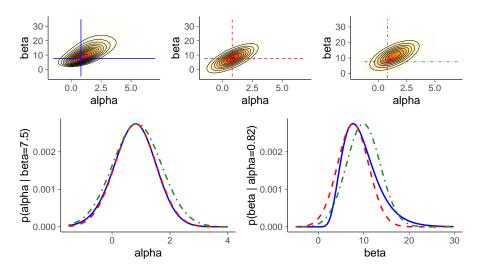
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- Instead of mode and Hessian at mode, e.g.
 - variational inference (Ch 13)
 - CS-E4820 Machine Learning: Advanced Probabilistic Methods
 - Stan has an experimental ADVI algorithm
 - expectation propagation (Ch 13)
 - speed of these is usually between optimization and MCMC

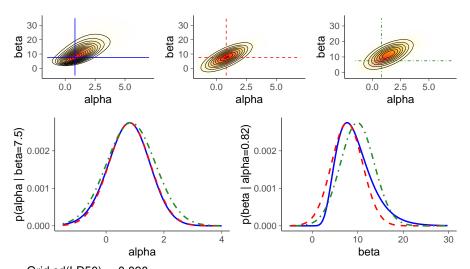
Distributional approximations

Exact, Normal at mode, Normal with variational inference



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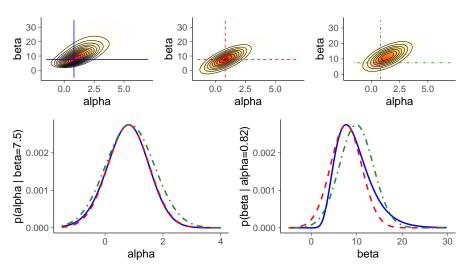
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 - eventually likelihood dominates the prior
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 - see counter examples

- Assume "true" underlying data distribution f(y)
 - observations y_1, \ldots, y_n are independent samples from the joint distribution f(y)
 - "true" data distribution f(y) is not always well defined
 - in the following we proceed as if there were true underlying data distribution
 - for the theory the exact form of f(y) is not important as long at it has certain regularity conditions

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- Problem also for other inference methods like MCMC

- If the number of parameter increases as the number of observation increases
 - in some models number of parameters depends on the number of observations
 - e.g. time series models $y_i \sim N(\theta_i, \sigma^2)$ and θ_i has prior in time
 - posterior of θ_i does not converge to a point, if additional observations do not bring enough information

- Aliasing (FI: valetoisto)
 - special case of under-identifiability where likelihood repeats in separate points
 - e.g. mixture of normals

$$p(y_i|\mu_1, \mu_2, \sigma_1^2, \sigma_2^2, \lambda) = \lambda N(\mu_1, \sigma_1^2) + (1 - \lambda) N(\mu_2, \sigma_2^2)$$

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 For MCMC makes the convergence diagnostics more difficult, as it is difficult to identify aliasing from other multimodality

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 - asymptotic results assume that probability sums to 1
 - e.g. Binomial model, with Beta(0,0) prior and observation
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 - posterior $p(\theta|n,0) = \theta^{n-1}(1-\theta)^{-1}$
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 - if in discrete case $p(\theta_0) = 0$ or in continuous case $p(\theta) = 0$ in the neighborhood of θ_0 , then the convergence results based on the dominance of the likelihood do not hold
- Should have a positive prior probability/density where needed

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 - e.g. $y_i \sim N(\theta, 1)$ with a restriction $\theta \ge 0$ and assume that $\theta_0 = 0$
 - posterior of θ is left truncated normal distribution with $\mu = \bar{y}$
 - in the limit $n \to \infty$ posterior is half normal distribution
- Can be easy or difficult for MCMC

- Tails of the distribution
 - normal approximation may be accurate for the most of the posterior mass, but still be inaccurate for the tails
 - e.g. parameter which is constrained to be positive; given a finite n, normal approximation assumes non-zero probability for negative values

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 - Calibration
 - α %-posterior interval has the true value in α % cases
 - α %-predictive interval has the true future values in α % cases
 - approximate calibration with shorter intervals for likely true values more important than exact calibration with bad intervals for all possible values.