#### Decision making in case of uncertainties



#### Bayesian Analysis

- Based on Bayesian probability theory
  - uncertainty is presented with probabilities
  - probabilities are updated based on new information

#### Bayesian Analysis

- Based on Bayesian probability theory
  - uncertainty is presented with probabilities
  - probabilities are updated based on new information
- Thomas Bayes (170?–1761)
  - English nonconformist, Presbyterian minister, mathematician
  - considered the problem of inverse probability
    - significant part of the Bayesian theory

#### Bayesian Analysis

- Based on Bayesian probability theory
  - uncertainty is presented with probabilities
  - probabilities are updated based on new information
- Thomas Bayes (170?–1761)
  - English nonconformist, Presbyterian minister, mathematician
  - considered the problem of inverse probability
    - significant part of the Bayesian theory
- Bayes did not invent all, but was first to solve problem of inverse probability in special case
- Modern Bayesian theory with rigorous proofs developed in 20th century

#### Term Bayesian used first time in mid 20th century

- Earlier there was just "probability theory"
  - concept of the probability was not strictly defined, although it was close to modern Bayesian interpretation
  - in the end of 19th century there were increasing demand for more strict definition of probability (mathematical and philosophical problem)

#### Term Bayesian used first time in mid 20th century

- Earlier there was just "probability theory"
  - concept of the probability was not strictly defined, although it was close to modern Bayesian interpretation
  - in the end of 19th century there were increasing demand for more strict definition of probability (mathematical and philosophical problem)
- In the beginning of 20th century frequentist view gained popularity
  - accepts definition of probabilities only through frequencies
  - does not accept inverse probability or use of prior
  - gained popularity due to apparent objectivity and "cook book" like reference books

#### Term Bayesian used first time in mid 20th century

- Earlier there was just "probability theory"
  - concept of the probability was not strictly defined, although it was close to modern Bayesian interpretation
  - in the end of 19th century there were increasing demand for more strict definition of probability (mathematical and philosophical problem)
- In the beginning of 20th century frequentist view gained popularity
  - accepts definition of probabilities only through frequencies
  - does not accept inverse probability or use of prior
  - gained popularity due to apparent objectivity and "cook book" like reference books
- R. A. Fisher used in 1950 first time term "Bayesian" to emphasize the difference to general term "probability theory"
  - term became quickly popular, because alternative descriptions were longer



#### Uncertainty and probabilistic modeling

- Two types of uncertainty: aleatoric and epistemic
- Representing uncertainty with probabilities
- Updating uncertainty

# Two types of uncertainty

Aleatoric uncertainty due to randomness

Epistemic uncertainty due to lack of knowledge

#### Two types of uncertainty

- Aleatoric uncertainty due to randomness
  - we are not able to obtain observations which could reduce this uncertainty
- Epistemic uncertainty due to lack of knowledge

#### Two types of uncertainty

- Aleatoric uncertainty due to randomness
  - we are not able to obtain observations which could reduce this uncertainty
- Epistemic uncertainty due to lack of knowledge
  - we are able to obtain observations which can reduce this uncertainty
  - two observers may have different epistemic uncertainty

▶ Probability of red  $\frac{\# \text{red}}{\# \text{red} + \# \text{yellow}} = \theta$ 

- ▶ Probability of red  $\frac{\#\text{red}}{\#\text{red} + \#\text{yellow}} = \theta$
- $p(y = red | \theta) = \theta$  aleatoric uncertainty

- ▶ Probability of red  $\frac{\#\text{red}}{\#\text{red} + \#\text{yellow}} = \theta$
- $p(y = red | \theta) = \theta$  aleatoric uncertainty
- $p(\theta)$  epistemic uncertainty

- ▶ Probability of red  $\frac{\#\text{red}}{\#\text{red} + \#\text{yellow}} = \theta$
- ▶  $p(y = red|\theta) = \theta$  aleatoric uncertainty
- $p(\theta)$  epistemic uncertainty
- Picking many chips updates our uncertainty about the proportion
- $\triangleright$   $p(\theta|y = red, yellow, red, red, ...) =?$

- ▶ Probability of red  $\frac{\#\text{red}}{\#\text{red} + \#\text{yellow}} = \theta$
- $p(y = red | \theta) = \theta$  aleatoric uncertainty
- $p(\theta)$  epistemic uncertainty
- Picking many chips updates our uncertainty about the proportion
- $\triangleright$   $p(\theta|y = red, yellow, red, red, ...) =?$
- ▶ Bayes rule  $p(\theta|y) = \frac{p(y|\theta)p(\theta)}{\int p(y|\theta)p(\theta)d\theta}$

#### Model vs. likelihood

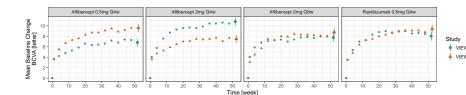
- ▶ Bayes rule  $p(\theta|y) \propto p(y|\theta)p(\theta)$
- ▶ Model:  $p(y|\theta)$  as a function of y given fixed  $\theta$  describes the aleatoric uncertainty
- Likelihood:  $p(y|\theta)$  as a function of  $\theta$  given fixed y provides information about epistemic uncertainty, but is not a probability distribution

#### Model vs. likelihood

- ▶ Bayes rule  $p(\theta|y) \propto p(y|\theta)p(\theta)$
- ▶ Model:  $p(y|\theta)$  as a function of y given fixed  $\theta$  describes the aleatoric uncertainty
- Likelihood:  $p(y|\theta)$  as a function of  $\theta$  given fixed y provides information about epistemic uncertainty, but is not a probability distribution
- ▶ Bayes rule combines the likelihood with prior uncertainty  $p(\theta)$  and transforms them to updated posterior uncertainty

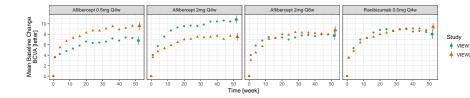
#### Example application

wet age-related macular degeneration (wetAMD)



#### Example application

wet age-related macular degeneration (wetAMD)



Pharmacometric with ordinal differential equations

$$\frac{dR_j(t)}{dt} = k_j^{\text{in}} - k_j^{\text{out}} \left[ R_j(t) - E_{\text{max}j} S_j(C_j(t)) \right].$$

Combining results from different studies

# The art of probabilistic modeling

The art of probabilistic modeling is to describe in a mathematical form (model and prior distributions) what we already know and what we don't know

#### The art of probabilistic modeling

- The art of probabilistic modeling is to describe in a mathematical form (model and prior distributions) what we already know and what we don't know
- "Easy" part is to use Bayes rule to update the uncertainties
  - computational challenges

#### The art of probabilistic modeling

- The art of probabilistic modeling is to describe in a mathematical form (model and prior distributions) what we already know and what we don't know
- "Easy" part is to use Bayes rule to update the uncertainties
  - computational challenges
- Other parts of the art of probabilistic modeling are, for example,
  - model checking: is data in conflict with our prior knowledge?
  - presentation: presenting the model and the results to the application experts

- Galaxy clusters for cosmology
- Coagulation of blood
- Gene regulation
- Pharmacokinetics and -dynamics
- Decision support
- Effects of nutrition for diabetes
- Evolutionary anthropology
- Clinical trial designs
- Daily demand for gas
- Brain structure trees
- School enrollment
- Sports
- Product demand

- Cocoa bean fermentation
- Marine propulsion power
- Alcohol consumption trends
- Flood probability
- Instantaneous heart rate distributions
- Drug dosing regimens in pediatrics
- Human T stem cell memory cells
- Fairness in university admission policies
- Destruction of bacteria and bacterial spores under heat

#### Bayesian data analysis

#### Example analyses

- Treatment/control
  - randomize patients to treatment or control
  - ▶ is the treatment effective?

#### Bayesian data analysis

#### Example analyses

- Treatment/control
  - randomize patients to treatment or control
  - is the treatment effective?
- Continuous valued treatment
  - randomize patients with different dosages
  - which dosage is sufficient without too many side effects?

#### Bayesian data analysis

#### Example analyses

- Treatment/control
  - randomize patients to treatment or control
  - is the treatment effective?
- Continuous valued treatment
  - randomize patients with different dosages
  - which dosage is sufficient without too many side effects?
- Different effects for different patients?
  - Is the treatment effect different for male/female, child/adult, light/heavy, ...

#### Bayesian approach

- Benefits of Bayesian approach
  - integrate over uncertainties to focus to interesting parts
  - use relevant prior information
  - hierarchical models
  - model checking and evaluation

#### Computation

We need to be able to compute expectations with respect to posterior distribution  $p(\theta|y)$ 

$$\mathrm{E}_{ heta|y}\left[g( heta)
ight] = \int 
ho( heta|y)g( heta)d heta$$

- Analytic
  - only for very simple models
- Monte Carlo, Markov chain Monte Carlo
  - generic
- Distributional approximations
  - e.g. Laplace, variational, expectation propagation
  - less generic, but can be much faster with sufficient accuracy

# Probabilistic programming



Enables agile workflow for developing probabilistic models

language - automated inference - diagnostics



#### Binomial model for treatment/control comparison

- Two groups of patients: treatment and control
  - ▶ Binary outcome
  - ▶ Is the treatment useful?

#### Binomial model for treatment/control comparison

```
data {
  int < lower = 0 > N1;
  int < lower = 0 > y1;
  int < lower = 0 > N2;
  int < lower = 0 > y2;
parameters {
  real<lower=0,upper=1> theta1;
  real<lower=0,upper=1> theta2;
model {
  theta1 \sim beta(1,1);
  theta2 \sim beta(1,1);
  y1 ~ binomial(N1, theta1);
  v2 ~ binomial(N2, theta2);
generated quantities {
  real oddsratio;
  oddsratio = (theta2/(1-theta2))/(theta1/(1-theta1));
```

# Binomial model for treatment/control comparison RStanARM

#### Modeling nature

Drop a ball from different heights and measure time

#### Modeling nature

- Drop a ball from different heights and measure time
  - Newton
  - air resistance, air pressure, shape and surface structure of the ball
  - relativity

## Modeling nature

- Drop a ball from different heights and measure time
  - Newton
  - air resistance, air pressure, shape and surface structure of the ball
  - relativity
- ► Taking into account the accuracy of the measurements, how accurate model is needed?

## Modeling nature

- Drop a ball from different heights and measure time
  - Newton
  - air resistance, air pressure, shape and surface structure of the ball
  - relativity
- Taking into account the accuracy of the measurements, how accurate model is needed?
  - often simple models are adequate and useful
  - All models are wrong, but some of them are useful, George P. Box

#### Rest of the course

- Basic models which can be used as building blocks
- Basic computation
- Typical simple scientific data analysis cases
  - e.g. comparison of treatments
- Presentation of the results

## Reminder: Uncertainty and probabilistic modeling

- ► Two types of uncertainty: aleatoric and epistemic
- Representing uncertainty with probabilities
- Updating uncertainty

▶ Pick a number between 1–5

- ▶ Pick a number between 1–5
  - raise as many fingers

- ► Pick a number between 1–5
  - raise as many fingers
  - is the number of fingers raised random (by you or by others)?

- Pick a number between 1–5
  - raise as many fingers
  - is the number of fingers raised random (by you or by others)?
- If we build a robot with very fast vision which can observe the rotating coin accurately, is the throw random for the robot?

- Pick a number between 1–5
  - raise as many fingers
  - is the number of fingers raised random (by you or by others)?
- If we build a robot with very fast vision which can observe the rotating coin accurately, is the throw random for the robot?
- Is the quantum uncertainty aleatoric or epistemic?

- Pick a number between 1–5
  - raise as many fingers
  - is the number of fingers raised random (by you or by others)?
- If we build a robot with very fast vision which can observe the rotating coin accurately, is the throw random for the robot?
- Is the quantum uncertainty aleatoric or epistemic?
- What is your own example with both aleatoric and epistemic uncertainty?

## Some important terms

- probability
- probability density
- probability mass
- probability density function (pdf)
- probability mass function (pmf)
- probability distribution
- discrete probability distribution
- continuous probability distribution
- cumulative distribution function (cdf)
- likelihood

In  $p(y|\theta)$ 

- y can be variable or value we could clarify by using  $p(Y|\theta)$  or  $p(y|\theta)$ 

- y can be variable or value we could clarify by using  $p(Y|\theta)$  or  $p(y|\theta)$
- $\theta$  can be variable or value we could clarify by using  $p(y|\Theta)$  or  $p(y|\theta)$

- y can be variable or value we could clarify by using  $p(Y|\theta)$  or  $p(y|\theta)$
- $\theta$  can be variable or value we could clarify by using  $p(y|\Theta)$  or  $p(y|\theta)$
- p can be a discrete or continuous function of y or θ
  we could clarify by using P<sub>Y</sub>, P<sub>Θ</sub>, p<sub>Y</sub> or p<sub>Θ</sub>

- y can be variable or value we could clarify by using  $p(Y|\theta)$  or  $p(y|\theta)$
- $\theta$  can be variable or value we could clarify by using  $p(y|\Theta)$  or  $p(y|\theta)$
- p can be a discrete or continuous function of y or θ
  we could clarify by using P<sub>Y</sub>, P<sub>Θ</sub>, p<sub>Y</sub> or p<sub>Θ</sub>
- $P_Y(Y|\Theta=\theta)$  is a probability mass function, sampling distribution, observation model

- y can be variable or value we could clarify by using  $p(Y|\theta)$  or  $p(y|\theta)$
- $\theta$  can be variable or value we could clarify by using  $p(y|\Theta)$  or  $p(y|\theta)$
- p can be a discrete or continuous function of y or θ
  we could clarify by using P<sub>Y</sub>, P<sub>Θ</sub>, p<sub>Y</sub> or p<sub>Θ</sub>
- $P_Y(Y|\Theta=\theta)$  is a probability mass function, sampling distribution, observation model
- $P(Y = y | \Theta = \theta)$  is a probability

- y can be variable or value we could clarify by using  $p(Y|\theta)$  or  $p(y|\theta)$
- $\theta$  can be variable or value we could clarify by using  $p(y|\Theta)$  or  $p(y|\theta)$
- p can be a discrete or continuous function of y or θ
  we could clarify by using P<sub>Y</sub>, P<sub>Θ</sub>, p<sub>Y</sub> or p<sub>Θ</sub>
- $P_Y(Y|\Theta=\theta)$  is a probability mass function, sampling distribution, observation model
- $P(Y = y | \Theta = \theta)$  is a probability
- P<sub>Θ</sub>(Y = y|Θ) is a likelihood function (can be discrete or continuous)

- y can be variable or value we could clarify by using  $p(Y|\theta)$  or  $p(y|\theta)$
- $\theta$  can be variable or value we could clarify by using  $p(y|\Theta)$  or  $p(y|\theta)$
- p can be a discrete or continuous function of y or θ
  we could clarify by using P<sub>Y</sub>, P<sub>Θ</sub>, p<sub>Y</sub> or p<sub>Θ</sub>
- $P_Y(Y|\Theta=\theta)$  is a probability mass function, sampling distribution, observation model
- $P(Y = y | \Theta = \theta)$  is a probability
- P<sub>Θ</sub>(Y = y|Θ) is a likelihood function (can be discrete or continuous)
- $p_Y(Y|\Theta = \theta)$  is a probability density function, sampling distribution, observation model

- y can be variable or value we could clarify by using  $p(Y|\theta)$  or  $p(y|\theta)$
- $\theta$  can be variable or value we could clarify by using  $p(y|\Theta)$  or  $p(y|\theta)$
- p can be a discrete or continuous function of y or θ
  we could clarify by using P<sub>Y</sub>, P<sub>Θ</sub>, p<sub>Y</sub> or p<sub>Θ</sub>
- P<sub>Y</sub>(Y|Θ = θ) is a probability mass function, sampling distribution, observation model
- $P(Y = y | \Theta = \theta)$  is a probability
- P<sub>Θ</sub>(Y = y|Θ) is a likelihood function (can be discrete or continuous)
- $p_Y(Y|\Theta = \theta)$  is a probability density function, sampling distribution, observation model
- $p(Y = y | \Theta = \theta)$  is a density

- y can be variable or value we could clarify by using  $p(Y|\theta)$  or  $p(y|\theta)$
- $\theta$  can be variable or value we could clarify by using  $p(y|\Theta)$  or  $p(y|\theta)$
- p can be a discrete or continuous function of y or θ
   we could clarify by using P<sub>Y</sub>, P<sub>Θ</sub>, p<sub>Y</sub> or p<sub>Θ</sub>
- P<sub>Y</sub>(Y|Θ = θ) is a probability mass function, sampling distribution, observation model
- $P(Y = y | \Theta = \theta)$  is a probability
- P<sub>Θ</sub>(Y = y|Θ) is a likelihood function (can be discrete or continuous)
- $p_Y(Y|\Theta = \theta)$  is a probability density function, sampling distribution, observation model
- $p(Y = y | \Theta = \theta)$  is a density
- p<sub>Θ</sub>(Y = y|Θ) is a likelihood function (can be discrete or continuous)

- y can be variable or value we could clarify by using  $p(Y|\theta)$  or  $p(y|\theta)$
- $\theta$  can be variable or value we could clarify by using  $p(y|\Theta)$  or  $p(y|\theta)$
- p can be a discrete or continuous function of y or θ
  we could clarify by using P<sub>Y</sub>, P<sub>Θ</sub>, p<sub>Y</sub> or p<sub>Θ</sub>
- $P_Y(Y|\Theta=\theta)$  is a probability mass function, sampling distribution, observation model
- $P(Y = y | \Theta = \theta)$  is a probability
- $P_{\Theta}(Y = y | \Theta)$  is a likelihood function (can be discrete or continuous)
- $p_Y(Y|\Theta = \theta)$  is a probability density function, sampling distribution, observation model
- $p(Y = y | \Theta = \theta)$  is a density
- p<sub>Θ</sub>(Y = y|Θ) is a likelihood function (can be discrete or continuous)
- y and  $\theta$  can also be mix of continuous and discrete



- y can be variable or value we could clarify by using  $p(Y|\theta)$  or  $p(y|\theta)$
- $\theta$  can be variable or value we could clarify by using  $p(y|\Theta)$  or  $p(y|\theta)$
- p can be a discrete or continuous function of y or θ
  we could clarify by using P<sub>Y</sub>, P<sub>Θ</sub>, p<sub>Y</sub> or p<sub>Θ</sub>
- P<sub>Y</sub>(Y|Θ = θ) is a probability mass function, sampling distribution, observation model
- $P(Y = y | \Theta = \theta)$  is a probability
- $P_{\Theta}(Y = y | \Theta)$  is a likelihood function (can be discrete or continuous)
- $p_Y(Y|\Theta = \theta)$  is a probability density function, sampling distribution, observation model
- $p(Y = y | \Theta = \theta)$  is a density
- $p_{\Theta}(Y = y|\Theta)$  is a likelihood function (can be discrete or continuous)
- y and  $\theta$  can also be mix of continuous and discrete
- Due to the sloppines sometimes likelihood is used to refer  $P_{Y,\theta}(Y|\Theta),\,p_{Y,\theta}(Y|\Theta)$

## Chapter 1

#### Reading instructions

- ▶ 1.1-1.3 important terms
- 1.4 a useful example
- 1.5 foundations
- ▶ 1.6 & 1.7 examples (can be skipped, but may be useful to read)
- 1.8 & 1.9 background material, good to read before doing the exercises
- ▶ 1.10 a point of view for using Bayesian inference