Chapter 12

- 12.1 Efficient Gibbs samplers (not part of the course)
- 12.2 Efficient Metropolis jump rules (not part of the course)
- 12.3 Further extensions to Gibbs and Metropolis (not part of the course)
- 12.4 Hamiltonian Monte Carlo (important)
- 12.5 Hamiltonian dynamics for a simple hierarchical model (useful example)
- 12.6 Stan: developing a computing environment (useful intro)

Extra material for dynamic HMC

- Michael Betancourt (2018). A Conceptual Introduction to Hamiltonian Monte Carlo. https://arxiv.org/abs/1701.02434
- Cole C. Monnahan, James T. Thorson, and Trevor A. Branch (2016) Faster estimation of Bayesian models in ecology using Hamiltonian Monte Carlo. https://dx.doi.org/10.1111/2041-210X.12681
- Michael Betancourt (2018). Scalable Bayesian Inference with Hamiltonian Monte Carlo https://www.youtube.com/watch?v=jUSZboSq1zg

Extra material for Stan

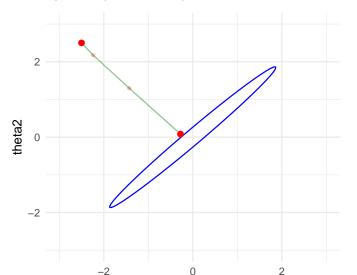
- Andrew Gelman, Daniel Lee, and Jiqiang Guo (2015) Stan:
 A probabilistic programming language for Bayesian inference and optimization. http://www.stat.columbia.edu/~gelman/research/published/stan_jebs_2.pdf
- Carpenter et al (2017). Stan: A probabilistic programming language. Journal of Statistical Software 76(1). https://dox.doi.org/10.18637/jss.v076.i01
- Stan User's Guide, Language Reference Manual, and Language Function Reference (in html and pdf) https://mc-stan.org/users/documentation/
 - easiest to start from Example Models in User's guide
- Basics of Bayesian inference and Stan, part 1 Jonah Gabry & Lauren Kennedy (StanCon 2019 Helsinki tutorial)
 - https://www.youtube.com/watch?v=ZRpo41I02KQ&index= 6&list=PLuwyh42iHquU4hUBQs20hkBsKSMrp6H0J
 - https://www.youtube.com/watch?v=6cc4N1vT8pk&index= 7&list=PLuwyh42iHquU4hUBQs20hkBsKSMrp6H0J

Chapter 12 demos

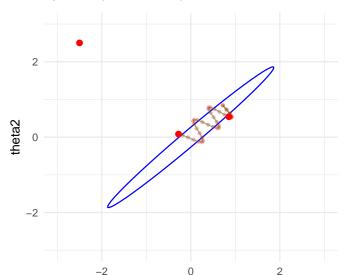
- demo12 1: HMC
- http://elevanth.org/blog/2017/11/28/ build-a-better-markov-chain/
- rstan_demo
- rstanarm_demo
- http://sumsar.net/blog/2017/01/ bayesian-computation-with-stan-and-farmer-jons/
- http://mc-stan.org/documentation/case-studies.html
- https://cran.r-project.org/package=rstan
- https://cran.r-project.org/package=rstanarm

- Uses log density (negative log density is called energy)
- Uses gradient of log density for more efficient sampling
- Augments parameter space with momentum variables

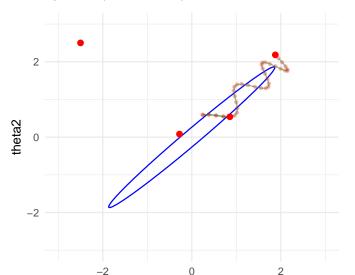
- Uses log density (negative log density is called energy)
- Uses gradient of log density for more efficient sampling
- Augments parameter space with momentum variables



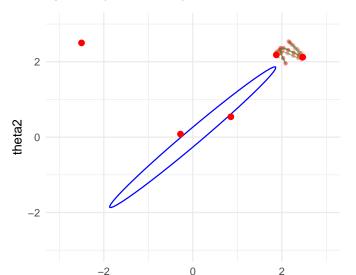
- Uses log density (negative log density is called energy)
- Uses gradient of log density for more efficient sampling
- Augments parameter space with momentum variables



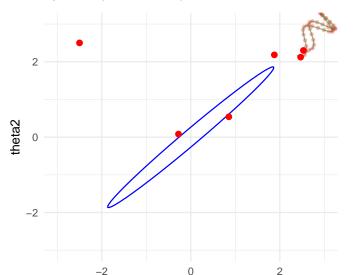
- Uses log density (negative log density is called energy)
- Uses gradient of log density for more efficient sampling
- Augments parameter space with momentum variables



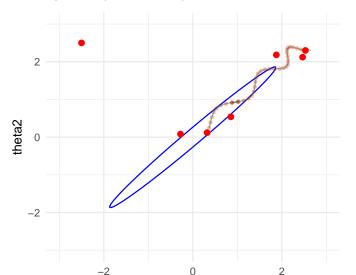
- Uses log density (negative log density is called energy)
- Uses gradient of log density for more efficient sampling
- Augments parameter space with momentum variables



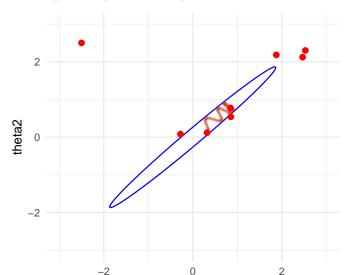
- Uses log density (negative log density is called energy)
- Uses gradient of log density for more efficient sampling
- Augments parameter space with momentum variables



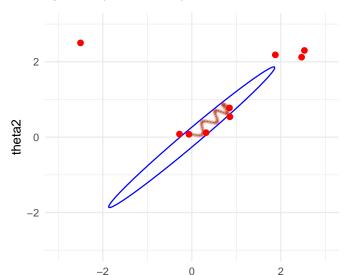
- Uses log density (negative log density is called energy)
- Uses gradient of log density for more efficient sampling
- Augments parameter space with momentum variables



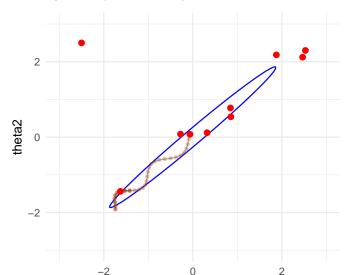
- Uses log density (negative log density is called energy)
- Uses gradient of log density for more efficient sampling
- Augments parameter space with momentum variables



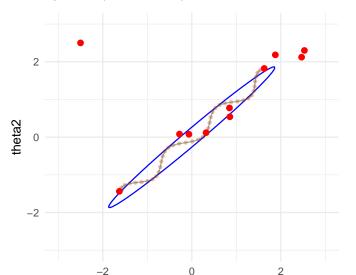
- Uses log density (negative log density is called energy)
- Uses gradient of log density for more efficient sampling
- Augments parameter space with momentum variables



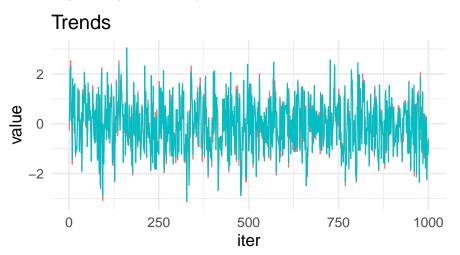
- Uses log density (negative log density is called energy)
- Uses gradient of log density for more efficient sampling
- Augments parameter space with momentum variables



- Uses log density (negative log density is called energy)
- Uses gradient of log density for more efficient sampling
- Augments parameter space with momentum variables

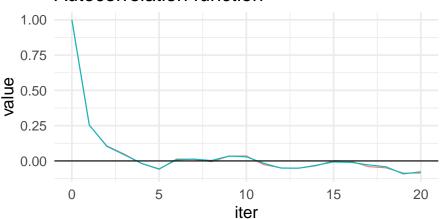


- Uses log density (negative log density is called energy)
- Uses gradient of log density for more efficient sampling
- Augments parameter space with momentum variables

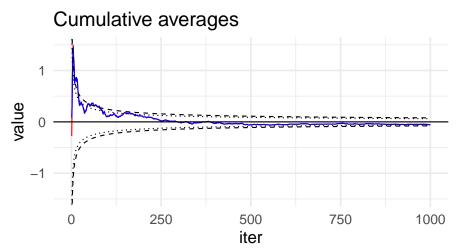


- Uses log density (negative log density is called energy)
- Uses gradient of log density for more efficient sampling
- Augments parameter space with momentum variables

Autocorrelation function



- Uses log density (negative log density is called energy)
- Uses gradient of log density for more efficient sampling
- Augments parameter space with momentum variables



- Uses log density (negative log density is called energy)
- Uses gradient of log density for more efficient sampling
- Augments parameter space with momentum variables
- Simulation of Hamiltonian dynamics reduces random walk
 - Explanation of HMC with black board
 - http:

//elevanth.org/blog/2017/11/28/build-a-better-markov-chain/

- Uses gradient of log density for more efficient sampling
- Alternating dynamic simulation and sampling energy level

- Uses gradient of log density for more efficient sampling
- Alternating dynamic simulation and sampling energy level
- Parameters: step size, number of steps in each chain

- Uses gradient of log density for more efficient sampling
- Alternating dynamic simulation and sampling energy level
- Parameters: step size, number of steps in each chain
- No U-Turn Sampling (NUTS) and dynamic HMC
 - adaptively selects number of steps to improve robustness and efficiency
 - dynamic HMC refers to dynamic trajectory length
 - to keep reversibility of Markov chain, need to simulate in two directions
 - http://elevanth.org/blog/2017/11/28/build-a-better-markov-chain/

- Uses gradient of log density for more efficient sampling
- Alternating dynamic simulation and sampling energy level
- Parameters: step size, number of steps in each chain
- No U-Turn Sampling (NUTS) and dynamic HMC
 - adaptively selects number of steps to improve robustness and efficiency
 - dynamic HMC refers to dynamic trajectory length
 - to keep reversibility of Markov chain, need to simulate in two directions
 - http://elevanth.org/blog/2017/11/28/build-a-better-markov-chain/
- · Dynamic simulation is discretized
 - small step size gives accurate simulation, but requires more log density evaluations
 - large step size reduces computation, but increases simulation error which needs to be taken into account in the Markov chain
 - black board explanation of the effect of step size

- Dynamic HMC using growing tree to increase simulation trajectory until no-U-turn criterion stopping
 - max treedepth to keep computation in control

- Dynamic HMC using growing tree to increase simulation trajectory until no-U-turn criterion stopping
 - max treedepth to keep computation in control
 - pick a draw along the trajectory with probabilities adjusted to take into account the error in the discretized dynamic simulation

- Dynamic HMC using growing tree to increase simulation trajectory until no-U-turn criterion stopping
 - max treedepth to keep computation in control
 - pick a draw along the trajectory with probabilities adjusted to take into account the error in the discretized dynamic simulation
 - give bigger weight for treeparts further away to increase probability of jumping further away

- Dynamic HMC using growing tree to increase simulation trajectory until no-U-turn criterion stopping
 - max treedepth to keep computation in control
 - pick a draw along the trajectory with probabilities adjusted to take into account the error in the discretized dynamic simulation
 - give bigger weight for treeparts further away to increase probability of jumping further away
- Mass matrix and step size adaptation in Stan
 - mass matrix refers to having different scaling for different parameters and optionally also rotation to reduce correlations

- Dynamic HMC using growing tree to increase simulation trajectory until no-U-turn criterion stopping
 - max treedepth to keep computation in control
 - pick a draw along the trajectory with probabilities adjusted to take into account the error in the discretized dynamic simulation
 - give bigger weight for treeparts further away to increase probability of jumping further away
- Mass matrix and step size adaptation in Stan
 - mass matrix refers to having different scaling for different parameters and optionally also rotation to reduce correlations
 - mass matrix and step size adjustment and are estimated during initial adaptation phase

- Dynamic HMC using growing tree to increase simulation trajectory until no-U-turn criterion stopping
 - max treedepth to keep computation in control
 - pick a draw along the trajectory with probabilities adjusted to take into account the error in the discretized dynamic simulation
 - give bigger weight for treeparts further away to increase probability of jumping further away
- Mass matrix and step size adaptation in Stan
 - mass matrix refers to having different scaling for different parameters and optionally also rotation to reduce correlations
 - mass matrix and step size adjustment and are estimated during initial adaptation phase
 - step size is adjusted to be as big as possible while keeping discretization error in control (adapt_delta)

- Dynamic HMC using growing tree to increase simulation trajectory until no-U-turn criterion stopping
 - max treedepth to keep computation in control
 - pick a draw along the trajectory with probabilities adjusted to take into account the error in the discretized dynamic simulation
 - give bigger weight for treeparts further away to increase probability of jumping further away
- Mass matrix and step size adaptation in Stan
 - mass matrix refers to having different scaling for different parameters and optionally also rotation to reduce correlations
 - mass matrix and step size adjustment and are estimated during initial adaptation phase
 - step size is adjusted to be as big as possible while keeping discretization error in control (adapt delta)
- After adaptation the algorithm parameters are fixed

- Dynamic HMC using growing tree to increase simulation trajectory until no-U-turn criterion stopping
 - max treedepth to keep computation in control
 - pick a draw along the trajectory with probabilities adjusted to take into account the error in the discretized dynamic simulation
 - give bigger weight for treeparts further away to increase probability of jumping further away
- Mass matrix and step size adaptation in Stan
 - mass matrix refers to having different scaling for different parameters and optionally also rotation to reduce correlations
 - mass matrix and step size adjustment and are estimated during initial adaptation phase
 - step size is adjusted to be as big as possible while keeping discretization error in control (adapt_delta)
- After adaptation the algorithm parameters are fixed
- After warmup store iterations for inference

- Dynamic HMC using growing tree to increase simulation trajectory until no-U-turn criterion stopping
 - max treedepth to keep computation in control
 - pick a draw along the trajectory with probabilities adjusted to take into account the error in the discretized dynamic simulation
 - give bigger weight for treeparts further away to increase probability of jumping further away
- Mass matrix and step size adaptation in Stan
 - mass matrix refers to having different scaling for different parameters and optionally also rotation to reduce correlations
 - mass matrix and step size adjustment and are estimated during initial adaptation phase
 - step size is adjusted to be as big as possible while keeping discretization error in control (adapt delta)
- After adaptation the algorithm parameters are fixed
- After warmup store iterations for inference
- See more details in Stan reference manual

Max tree depth diagnostic

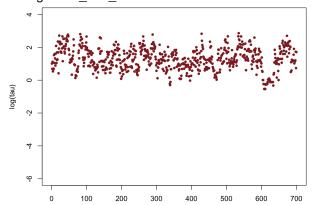
- Dynamic HMC specific diagnostic
- Indicates inefficiency in sampling leading to higher autocorrelations and lower ESS (n_{eff})
- Different parameterizations matter

Divergences

- HMC specific: indicates that Hamiltonian dynamic simulation has problems with unexpected fast changes in log-density
 - indicates possibility of biased estimates
- Different parameterizations matter
- http://mc-stan.org/users/documentation/case-studies/ divergences_and_bias.html

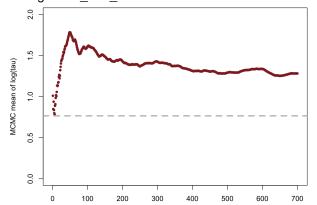
Divergences

- HMC specific: indicates that Hamiltonian dynamic simulation has problems with unexpected fast changes in log-density
 - indicates possibility of biased estimates
- Different parameterizations matter
- http://mc-stan.org/users/documentation/case-studies/ divergences and bias.html

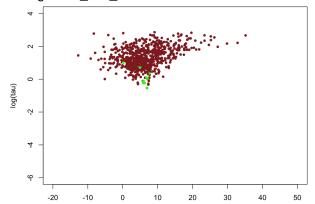


Divergences

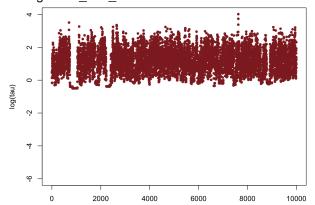
- HMC specific: indicates that Hamiltonian dynamic simulation has problems with unexpected fast changes in log-density
 - indicates possibility of biased estimates
- Different parameterizations matter
- http://mc-stan.org/users/documentation/case-studies/ divergences and bias.html



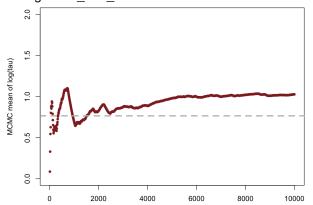
- HMC specific: indicates that Hamiltonian dynamic simulation has problems with unexpected fast changes in log-density
 - indicates possibility of biased estimates
- Different parameterizations matter
- http://mc-stan.org/users/documentation/case-studies/ divergences and bias.html



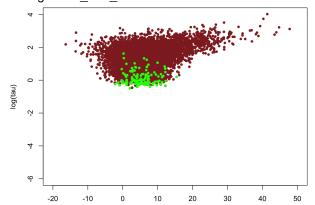
- HMC specific: indicates that Hamiltonian dynamic simulation has problems with unexpected fast changes in log-density
 - indicates possibility of biased estimates
- Different parameterizations matter
- http://mc-stan.org/users/documentation/case-studies/ divergences and bias.html



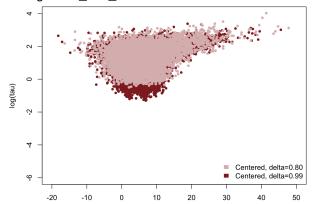
- HMC specific: indicates that Hamiltonian dynamic simulation has problems with unexpected fast changes in log-density
 - indicates possibility of biased estimates
- Different parameterizations matter
- http://mc-stan.org/users/documentation/case-studies/ divergences and bias.html



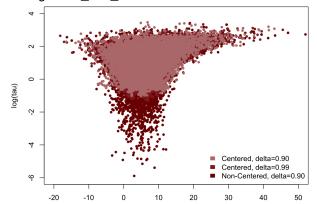
- HMC specific: indicates that Hamiltonian dynamic simulation has problems with unexpected fast changes in log-density
 - indicates possibility of biased estimates
- Different parameterizations matter
- http://mc-stan.org/users/documentation/case-studies/ divergences and bias.html



- HMC specific: indicates that Hamiltonian dynamic simulation has problems with unexpected fast changes in log-density
 - indicates possibility of biased estimates
- Different parameterizations matter
- http://mc-stan.org/users/documentation/case-studies/ divergences and bias.html



- HMC specific: indicates that Hamiltonian dynamic simulation has problems with unexpected fast changes in log-density
 - indicates possibility of biased estimates
- Different parameterizations matter
- http://mc-stan.org/users/documentation/case-studies/ divergences and bias.html



- Nonlinear dependencies
 - simple mass matrix scaling doesn't help

- Nonlinear dependencies
 - simple mass matrix scaling doesn't help
- Funnels
 - optimal step size depends on location

- Nonlinear dependencies
 - simple mass matrix scaling doesn't help
- Funnels
 - optimal step size depends on location
- Multimodal
 - difficult to move from one mode to another

- Nonlinear dependencies
 - simple mass matrix scaling doesn't help
- Funnels
 - optimal step size depends on location
- Multimodal
 - · difficult to move from one mode to another
- Long-tailed with non-finite variance and mean
 - · effciency of exploration is reduced
 - central limit theorem doesn't hold for mean and variance

Probabilistic programming language

 Wikipedia "A probabilistic programming language (PPL) is a programming language designed to describe probabilistic models and then perform inference in those models"

Probabilistic programming language

- Wikipedia "A probabilistic programming language (PPL) is a programming language designed to describe probabilistic models and then perform inference in those models"
- To make probabilistic programming useful
 - inference has to be as automatic as possible
 - diagnostics for telling if the automatic inference doesn't work
 - easy workflow (to reduce manual work)
 - fast enough (manual work replaced with automation)

Probabilistic programming

- Enables agile workflow for developing probabilistic models
 - language
 - automated inference
 - diagnostics
- Many frameworks Stan, PyMC3, Pyro (Uber), Edward (Google), Birch, ELFI, ...

- Language, inference engine, user interfaces, documentation, case studies, diagnostics, packages, ...
 - · autodiff to compute gradients of the log density



- Language, inference engine, user interfaces, documentation, case studies, diagnostics, packages, ...
 - autodiff to compute gradients of the log density
- More than ten thousand users in social, biological, and physical sciences, medicine, engineering, and business



- Language, inference engine, user interfaces, documentation, case studies, diagnostics, packages, ...
 - autodiff to compute gradients of the log density
- More than ten thousand users in social, biological, and physical sciences, medicine, engineering, and business
- Several full time developers, 38 in dev team, more than 100 contributors



- Language, inference engine, user interfaces, documentation, case studies, diagnostics, packages, ...
 - autodiff to compute gradients of the log density
- More than ten thousand users in social, biological, and physical sciences, medicine, engineering, and business
- Several full time developers, 38 in dev team, more than 100 contributors
- R, Python, Julia, Scala, Stata, Matlab, command line interfaces
- More than 100 R packages using Stan



Stan

- Stanislaw Ulam (1909-1984)
 - · Monte Carlo method
 - H-Bomb

```
data {
  int < lower = 0 > N; // number of experiments
  int <lower = 0, upper = N> y; // number of successes
parameters {
  real < lower = 0, upper = 1 > theta; // parameter of the binor
model
  theta \sim beta(1,1); //prior
  y ~ binomial(N, theta); // observation model
```

```
data
  int < lower = 0 > N;  // number of experiments
  int <lower = 0, upper = N> y; // number of successes
parameters {
  real < lower = 0, upper = 1 > theta; // parameter of the binor
model
  theta \sim beta(1,1); //prior
  y ~ binomial(N, theta); // observation model
```

```
data
  int < lower = 0 > N;  // number of experiments
  int <lower = 0, upper = N> y; // number of successes
parameters {
  real < lower = 0, upper = 1 > theta; // parameter of the binor
model {
  theta \sim beta(1,1); //prior
  y ~ binomial(N, theta); // observation model
```

- Data type and size are declared
- Stan checks that given data matches type and constraints

- Data type and size are declared
- Stan checks that given data matches type and constraints
 - If you are not used to strong typing, this may feel annoying, but it will reduce the probability of coding errors, which will reduce probability of data analysis errors

```
parameters {
   real <lower = 0, upper = 1 > theta;
}
```

- Parameters may have constraints
- Stan makes transformation to unconstrained space and samples in unconstrained space
 - e.g. log transformation for <lower=a>
 - e.g. logit transformation for <lower=a,upper=b>

```
parameters {
   real < lower = 0, upper = 1 > theta;
}
```

- Parameters may have constraints
- Stan makes transformation to unconstrained space and samples in unconstrained space
 - e.g. log transformation for <lower=a>
 - e.g. logit transformation for <lower=a,upper=b>
- For these declared transformation Stan automatically takes into account the Jacobian of the transformation (see BDA3 p. 21)

```
model {
  theta ~ beta(1,1); // prior
  y ~ binomial(N,theta); // likelihood
}
```

```
model {
  theta ~ beta(1,1);  // prior
  y ~ binomial(N,theta); // likelihood
}

• ~ is syntactic sugar and this is equivalent to

model {
  target += beta_lpdf(theta | 1, 1);
  target += binomial_lpmf(y | N, theta);
}
```

```
model {
  theta \sim beta(1,1); // prior
  y ~ binomial(N, theta); // likelihood
  \bullet \sim is syntactic sugar and this is equivalent to
model {
  target += beta lpdf(theta | 1, 1);
  target += binomial_lpmf(y | N, theta);

    target is the log posterior density
```

```
model {
  theta \sim beta(1,1); // prior
  y ~ binomial(N, theta); // likelihood
  \bullet \sim is syntactic sugar and this is equivalent to
model {
  target += beta lpdf(theta | 1, 1);
  target += binomial lpmf(y | N, theta);

    target is the log posterior density

    lpdf for continuous, lpmf for discrete distributions

    (discrete for the left hand side of |)
```

```
model {
  theta ~ beta(1,1); // prior
  y ~ binomial(N, theta); // likelihood
  \bullet \sim is syntactic sugar and this is equivalent to
model {
  target += beta lpdf(theta | 1, 1);
  target += binomial lpmf(y | N, theta);
```

- target is the log posterior density
- _lpdf for continuous, _lpmf for discrete distributions (discrete for the left hand side of |)
- for Stan sampler there is no difference between prior and likelihood, all that matters is the final target

```
target += binomial_lpmf(y | N, theta);
}
```

- target is the log posterior density
- _lpdf for continuous, _lpmf for discrete distributions (discrete for the left hand side of |)
- for Stan sampler there is no difference between prior and likelihood, all that matters is the final target
- you can write in Stan language any program to compute the log density (Stan language is Turing complete)

Stan

- Stan compiles (transplies) the model written in Stan language to C++
 - this makes the sampling for complex models and bigger data faster
 - also makes Stan models easily portable, you can use your own favorite interface

RStan

RStan

```
library(rstan)
rstan_options(auto_write = TRUE)
options(mc.cores = parallel::detectCores())
source('stan_utility.R')

d_bin <- list(N = 10, y = 7)
fit_bin <- stan(file = 'binom.stan', data = d_bin)</pre>
```

RStan

RStan

```
library(rstan)
rstan_options(auto_write = TRUE)
options(mc.cores = parallel::detectCores())
source('stan_utility.R')

d_bin <- list(N = 10, y = 7)
fit_bin <- stan(file = 'binom.stan', data = d_bin)</pre>
```

PyStan

PyStan

```
import pystan
import stan_utility
```

```
data = dict(N=10, y=8)
model = stan_utility.compile_model('binom.stan')
fit = model.sampling(data=data)
```

PyStan

```
PyStan
import pystan
import stan_utility

data = dict(N=10, y=8)
model = stan_utility.compile_model('binom.stan')
fit = model.sampling(data=data)
```

Stan

- Compilation (unless previously compiled model available)
- Warm-up including adaptation
- Sampling
- Generated quantities
- Save posterior draws
- Report divergences, $n_{\rm eff}$, \hat{R}

- An experiment was performed to estimate the effect of beta-blockers on mortality of cardiac patients
- A group of patients were randomly assigned to treatment and control groups:
 - · out of 674 patients receiving the control, 39 died
 - out of 680 receiving the treatment, 22 died

data {

int <lower = 0 > N1; int <lower = 0 > y1;

```
int < lower = 0 > N2;
  int < lower = 0 > v2;
parameters {
  real<lower=0,upper=1> theta1;
  real<lower=0,upper=1> theta2;
model {
  theta1 \sim beta(1,1);
  theta2 \sim beta(1,1);
  y1 ~ binomial(N1, theta1);
  y2 ~ binomial(N2, theta2);
generated quantities {
  real oddsratio:
  oddsratio = (theta2/(1-theta2))/(theta1/(1-theta1));
                                                          26/50
```

```
data
  int < lower = 0 > N1:
  int <lower=0> y1;
  int <lower=0> N2;
  int < lower = 0 > v2;
parameters
  real < lower = 0, upper = 1 > theta1;
  real < lower = 0, upper = 1 > theta2;
model
  theta1 \sim beta(1,1);
  theta2 \sim beta(1,1);
  y1 ~ binomial(N1, theta1);
  y2 ~ binomial(N2, theta2);
generated quantities {
  real oddsratio:
  oddsratio = (theta2/(1-theta2))/(theta1/(1-theta1));
```

26/50

```
generated quantities {
  real oddsratio;
  oddsratio = (theta2/(1-theta2))/(theta1/(1-theta1));
}
```

generated quantities is run after the sampling

```
d bin2 \leftarrow list (N1 = 674, y1 = 39, N2 = 680, y2 = 22)
fit bin2 <- stan(file = 'binom2.stan', data = d bin2)
starting worker pid=10151 on localhost:11783 at 10:03:27.872
starting worker pid=10164 on localhost:11783 at 10:03:28.087
starting worker pid=10176 on localhost:11783 at 10:03:28.295
starting worker pid=10185 on localhost:11783 at 10:03:28.461
SAMPLING FOR MODEL 'binom2' NOW (CHAIN 1).
Gradient evaluation took 6e-06 seconds
1000 transitions using 10 leapfrog steps per transition would take 0.06 seconds.
Adjust your expectations accordingly!
Iteration: 1 / 2000 [ 0%] (Warmup)
Iteration: 200 / 2000 [ 10%] (Warmup)
Iteration: 1000 / 2000 [ 50%] (Warmup)
Iteration: 1001 / 2000 [ 50%] (Sampling)
Iteration: 2000 / 2000 [100%] (Sampling)
Elapsed Time: 0.012908 seconds (Warm-up)
              0.017027 seconds (Sampling)
              0.029935 seconds (Total)
SAMPLING FOR MODEL 'binom2' NOW (CHAIN 2).
```

```
monitor(fit_bin2, probs = \mathbf{c}(0.1, 0.5, 0.9))
```

Inference for the input samples
(4 chains: each with iter=1000; warmup=0):

	mean	se_mean	sd	10%	50%	90%	n_eff	Rhat
theta1	0.1	0	0.0	0.0	0.1	0.1	3280	1
theta2	0.0	0	0.0	0.0	0.0	0.0	3171	1
oddsratio	0.6	0	0.2	0.4	0.6	0.8	3108	1
lp	-253.5	0	1.0	-254.8	-253.2	-252.6	1922	1

For each parameter, n_eff is a crude measure of effective sample size, and Rhat is the potential scale reduction factor on split chains (at convergence, Rhat=1).

```
monitor(fit_bin2, probs = \mathbf{c}(0.1, 0.5, 0.9))
```

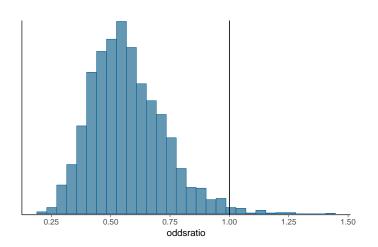
Inference for the input samples
(4 chains: each with iter=1000; warmup=0):

	mean	se_mean	sd	10%	50%	90%	n_eff	Rhat
theta1	0.1	0	0.0	0.0	0.1	0.1	3280	1
theta2	0.0	0	0.0	0.0	0.0	0.0	3171	1
oddsratio	0.6	0	0.2	0.4	0.6	0.8	3108	1
lp	-253.5	0	1.0	-254.8	-253.2	-252.6	1922	1

For each parameter, n_{eff} is a crude measure of effective sample size, and Rhat is the potential scale reduction factor on split chains (at convergence, Rhat=1).

• lp__ is the log density, ie, same as target

```
draws <- as.data.frame(fit_bin2)
mcmc_hist(draws, pars = 'oddsratio') +
  geom_vline(xintercept = 1) +
  scale_x_continuous(breaks = c(seq(0.25,1.5,by=0.25)))</pre>
```



HMC specific diagnostics

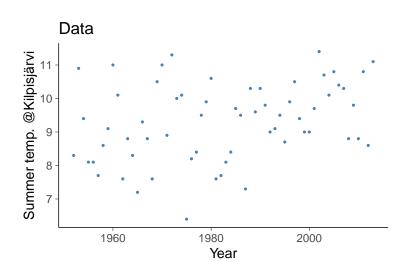
```
check_treedepth(fit_bin2)
check_energy(fit_bin2)
check_div(fit_bin2)
```

```
[1] "O of 4000 iterations saturated the maximum tree depth of 10 (0%)" [1] "O of 4000 iterations ended with a divergence (0%)"
```

Shinystan

• Graphical user interface for analysing MCMC results

- Temperature at Kilpisjärvi in June, July and August from 1952 to 2013
- Is there change in the temperature?



Gaussian linear model

```
data {
    int <lower = 0 > N; // number of data points
    vector[N] x; //
    vector[N] y; //
parameters {
    real alpha;
    real beta;
    real < lower = 0 > sigma;
transformed parameters {
    vector[N] mu;
    mu <- alpha + beta *x;
model {
    y ~ normal(mu, sigma);
```

Gaussian linear model

```
data {
    int <lower=0> N; // number of data points
    vector[N] x; //
    vector[N] y; //
}
```

• difference between vector[N] x and real x[N]

Gaussian linear model

```
parameters {
    real alpha;
    real beta;
    real <lower=0> sigma;
}
transformed parameters {
    vector[N] mu;
    mu <- alpha + beta*x;
}</pre>
```

 transformed parameters are deterministic transformations of parameters and data

Priors for Gaussian linear model

```
data {
    int <lower = 0 > N; // number of data points
    vector[N] x: //
    vector[N] v: //
    real pmualpha; // prior mean for alpha
    real psalpha; // prior std for alpha
    real pmubeta; // prior mean for beta
    real psbeta; // prior std for beta
transformed parameters {
    vector[N] mu;
    mu <- alpha + beta *x;
model {
    alpha ~ normal(pmualpha, psalpha);
    beta ~ normal(pmubeta, psbeta);
    y ~ normal(mu, sigma);
```

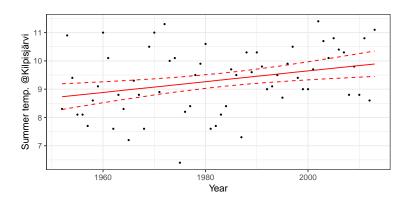
Student-t linear model

```
parameters {
  real alpha;
  real beta:
  real < lower = 0 > sigma;
  real < lower = 1, upper = 80 > nu;
transformed parameters {
  vector[N] mu;
  mu <- alpha + beta *x;
model {
  nu ~ qamma(2,0.1);
  y ~ student t(nu, mu, sigma);
```

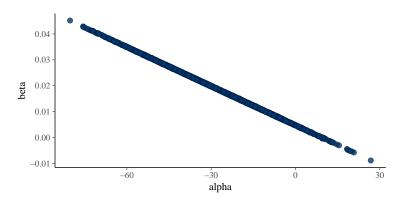
Priors

• Prior for temperature increase?

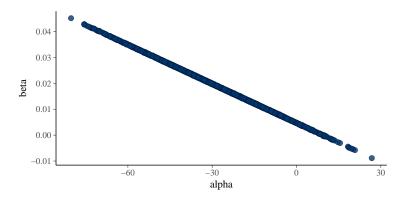
Posterior fit



Posterior draws of alpha and beta



Posterior draws of alpha and beta



There were 14 transitions after warmup that exceeded the maximum treedepth. Increase max_treedepth above 10. See http://mc-stan.org/misc/warnings.html#maximum-treedepth-exceeded Examine the pairs() plot to diagnose sampling problems

Linear regression model in Stan

```
data {
   int < lower = 0 > N; // number of data points
   vector[N] x; //
   vector[N] y; //
   real xpred; // input location for prediction
}
transformed data {
   vector[N] x_std;
   vector[N] y_std;
   real xpred_std;
   x_std = (x - mean(x)) / sd(x);
   y_std = (y - mean(y)) / sd(y);
   xpred_std = (xpred - mean(x)) / sd(x);
}
```

RStanARM

- RStanARM provides simplified model description with pre-compiled models
 - no need to wait for compilation
 - a restricted set of models

Two group Binomial model:

RStanARM

- RStanARM provides simplified model description with pre-compiled models
 - no need to wait for compilation
 - · a restricted set of models

Two group Binomial model:

Gaussian linear model

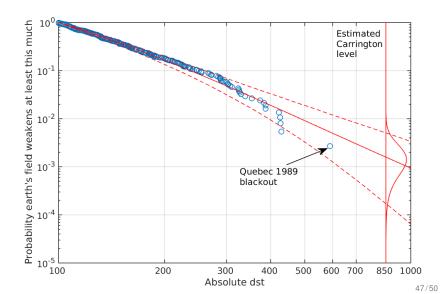
```
fit_lin \leftarrow stan_glm(temp \sim year, data = d_lin)
```

BRMS

- BRMS provides simplified model description
 - a larger set of models than RStanARM, but still restricted
 - need to wait for the compilation

Extreme value analysis

Geomagnetic storms



Extreme value analysis

```
data {
  int < lower = 0 > N;
  vector<lower=0>[N] y;
  int < lower = 0 > Nt:
  vector<lower=0>[Nt] yt;
transformed data {
  real ymax;
  ymax <- max(y);
parameters {
  real < lower = 0 > sigma;
  real < lower = - sigma / ymax > k;
model {
  y ~ gpareto(k, sigma);
generated quantities {
  vector[Nt] predccdf;
  predccdf<-gpareto_ccdf(yt,k,sigma);</pre>
```

Functions

```
functions {
  real gpareto_lpdf(vector y, real k, real sigma) {
    // generalised Pareto log pdf with mu=0
    // should check and give error if k<0
    // and max(y)/sigma > -1/k
    int N;
    N \leftarrow dims(y)[1];
    if (fabs(k) > 1e-15)
      return -(1+1/k)*sum(log1pv(y*k/sigma)) -N*log(sigma);
    else
      return -sum(y/sigma) -N*log(sigma); // limit k->0
  vector gpareto ccdf(vector y, real k, real sigma) {
    // generalised Pareto log ccdf with mu=0
    // should check and give error if k<0
    // and max(y)/sigma < -1/k
    if (fabs(k) > 1e-15)
      return exp((-1/k)*log1pv(y/sigma*k));
    else
      return \exp(-y/\text{sigma}); // limit k \rightarrow 0
```

Other packages

- R
- shinystan interactive diagnostics
- bayesplot visualization and model checking (see model checking in Ch 6)
- loo cross-validation model assessment, comparison and averaging (see Ch 7)
- projpred projection predictive variable selection
- Python
 - ArviZ visualization, and model checking and assessment (see Ch 6 and 7)