Chapter 12

- 12.1 Efficient Gibbs samplers (not part of the course)
- 12.2 Efficient Metropolis jump rules (not part of the course)
- 12.3 Further extensions to Gibbs and Metropolis (not part of the course)
- 12.4 Hamiltonian Monte Carlo (important)
- 12.5 Hamiltonian dynamics for a simple hierarchical model (useful example)
- 12.6 Stan: developing a computing environment (useful intro)

Extra material for dynamic HMC

- Michael Betancourt (2018). A Conceptual Introduction to Hamiltonian Monte Carlo. https://arxiv.org/abs/1701.02434
- Cole C. Monnahan, James T. Thorson, and Trevor A. Branch (2016) Faster estimation of Bayesian models in ecology using Hamiltonian Monte Carlo. https://dx.doi.org/10.1111/2041-210X.12681
- Michael Betancourt (2018). Scalable Bayesian Inference with Hamiltonian Monte Carlo https://www.youtube.com/watch?v=jUSZboSq1zg

Extra material for Stan

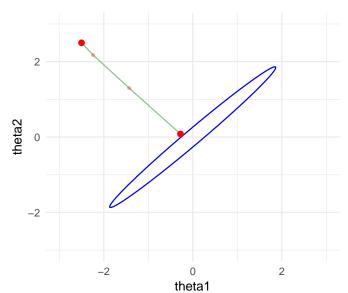
- Andrew Gelman, Daniel Lee, and Jiqiang Guo (2015) Stan:
 A probabilistic programming language for Bayesian inference and optimization. http://www.stat.columbia.edu/~gelman/research/published/stan_jebs_2.pdf
- Carpenter et al (2017). Stan: A probabilistic programming language. Journal of Statistical Software 76(1). https://dox.doi.org/10.18637/jss.v076.i01
- Stan development team (2018). Modeling Language User's Guide and Reference Manual https://github.com/stan-dev/ stan/releases/download/v2.17.0/stan-reference-2.17.0.pdf
 - easiest to start from Part III Example Models
- Basics of Bayesian inference and Stan, part 1 Jonah Gabry & Lauren Kennedy
 - https://www.youtube.com/watch?v=ZRpo41I02KQ&index= 6&list=PLuwyh42iHquU4hUBQs20hkBsKSMrp6H0J
 - https://www.youtube.com/watch?v=6cc4N1vT8pk&index= 7&list=PLuwyh42iHquU4hUBQs20hkBsKSMrp6H0J

Chapter 12 demos

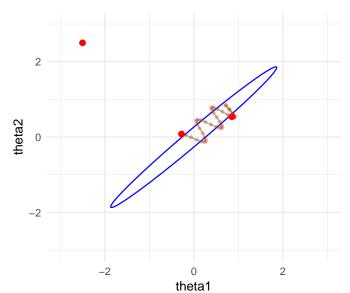
- demo12_1: HMC
- http://elevanth.org/blog/2017/11/28/ build-a-better-markov-chain/
- rstan_demo
- rstanarm_demo
- http://sumsar.net/blog/2017/01/ bayesian-computation-with-stan-and-farmer-jons/
- http://mc-stan.org/documentation/case-studies.html
- https://cran.r-project.org/package=rstan
- https://cran.r-project.org/package=rstanarm

- Uses gradient information for more efficient sampling
- Augments parameter space with momentum variables

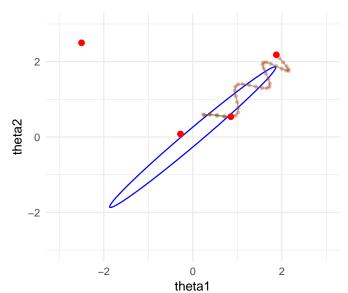
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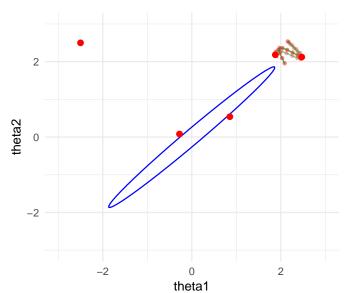
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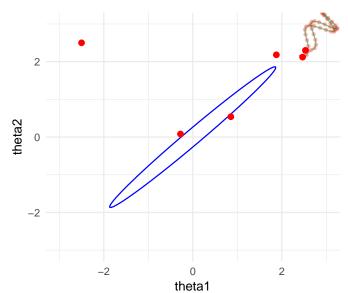
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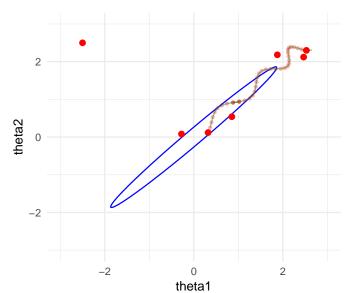
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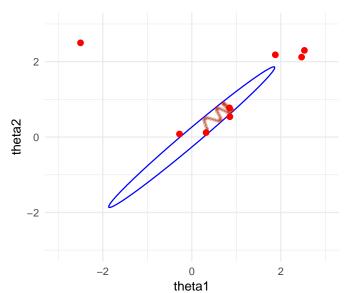
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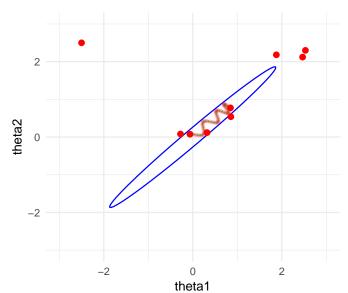
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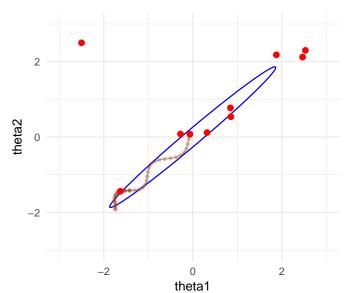
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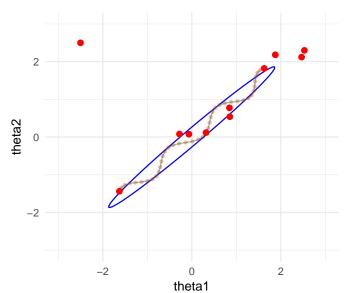
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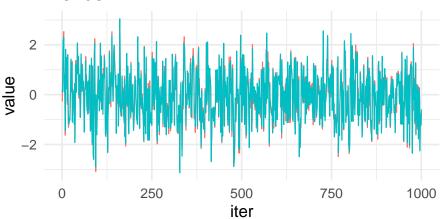


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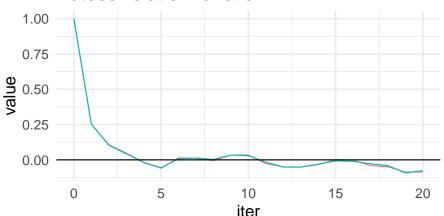
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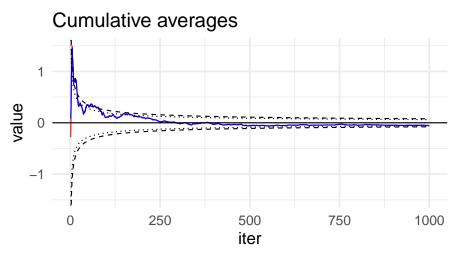


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- Augments parameter space with momentum variables

Autocorrelation function



- Uses gradient information for more efficient sampling
- Augments parameter space with momentum variables



- Uses gradient information for more efficient sampling
- Augments parameter space with momentum variables
- Simulation of Hamiltonian dynamics reduces random walk
 - Explanation of HMC with black board
 - http://elevanth.org/blog/2017/11/28/ build-a-better-markov-chain/

- Uses gradient information for more efficient sampling
- Alternating dynamic simulation and sampling of the energy level

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- Parameters: step size, number of steps in each chain
- No U-Turn Sampling (NUTS) and dynamic HMC
 - adaptively selects number of steps to improve robustness and efficiency
 - dynamic HMC refers to dynamic trajectory length
 - to keep reversibility of Markov chain, need to simulate in two directions
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 - http://elevanth.org/blog/2017/11/28/ build-a-better-markov-chain/
- Dynamic simulation is discretized
 - small step size gives accurate simulation, but requires more log density evaluations
 - large step size reduces computation, but increases simulation error which needs to be taken into account in the Markov chain
 - black board explanation of the effect of step size

- Dynamic HMC using growing tree to increase simulation trajectory until no-U-turn criterion stopping
 - max treedepth to keep computation in control
 - pick a draw along the trajectory with probabilities adjusted to take into account the error in the discretized dynamic simulation

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 - mass matrix refers to having different scaling for different parameters and optionally also rotation to reduce correlations
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- After warmup store iterations for inference

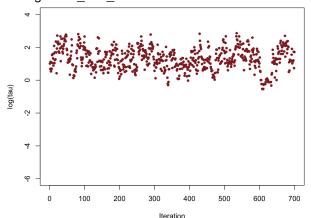
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- See more details in Stan reference manual

Max tree depth diagnostic

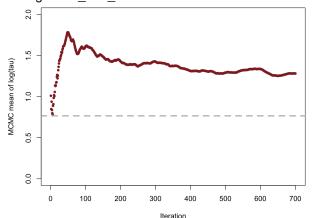
- Dynamic HMC specific diagnostic
- Indicates inefficiency in sampling leading to higher autocorrelations and lower n_{eff}
- Different parameterizations matter

- HMC specific: Indicates that Hamiltonian dynamic simulation has problems going to narrow places
 - indicates possibility of biased estimates
- Different parameterizations matter
- http://mc-stan.org/users/documentation/case-studies/ divergences and bias.html

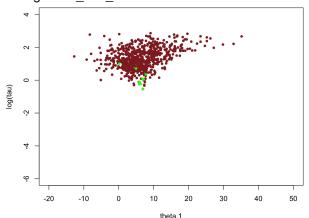
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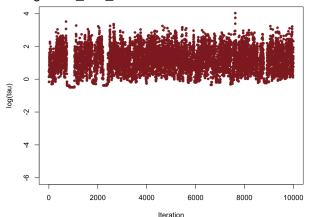


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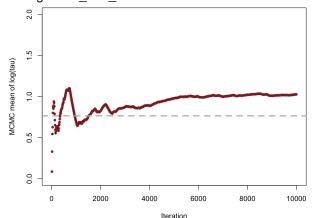
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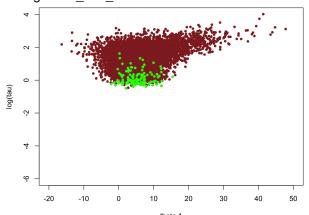


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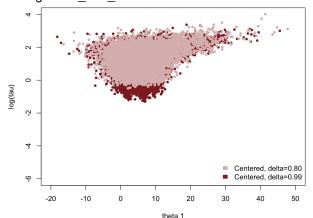
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Divergences

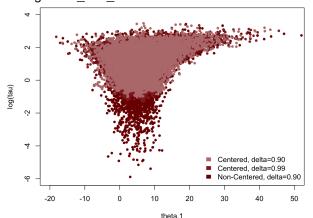
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Probabilistic programming language

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Probabilistic programming language

- Wikipedia "A probabilistic programming language (PPL) is a programming language designed to describe probabilistic models and then perform inference in those models"
- To make probabilistic programming useful
 - inference has to be as automatic as possible
 - diagnostics for telling if the automatic inference doesn't work
 - easy workflow (to reduce manual work)
 - fast enough (manual work replaced with automation)

Probabilistic programming

- Enables agile workflow for developing probabilistic models
 - language
 - automated inference
 - diagnostics
- Many frameworks Stan, PyMC3, Pyro (Uber), Edward (Google), Birch, ELFI, ...

Stan - probabilistic programming framework

- Language, inference engine, user interfaces, documentation, case studies, diagnostics, packages, ...
 - autodiff to compute gradients of the log density



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- Language, inference engine, user interfaces, documentation, case studies, diagnostics, packages, ...
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- More than ten thousand users in social, biological, and physical sciences, medicine, engineering, and business
- Several full time developers, 35 in dev team, more than 100 contributors



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- R, Python, Julia, Scala, Stata, Matlab, command line interfaces
- More than 100 R packages using Stan



Stan

- Stanislaw Ulam (1909-1984)
 - Monte Carlo method
 - H-Bomb

```
data {
  int < lower = 0 > N; // number of experiments
  int <lower = 0, upper = N> y; // number of successes
parameters {
  real < lower = 0, upper = 1 > theta; // parameter of the binor
model
  theta \sim beta(1,1); //prior
  y ~ binomial(N, theta); // observation model
```

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data
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```

- Data type and size are declared
- Stan checks that given data matches type and constraints

```
parameters {
   real < lower = 0, upper = 1 > theta;
}
```

- Parameters may have constraints
- Stan makes transformation to unconstrained space and samples in unconstrained space
 - e.g. log transformation for <lower=a>
 - e.g. logit transformation for <lower=a,upper=b>
- For these declared transformation Stan automatically takes into account the Jacobian of the transformation (see BDA3 p. 21)

```
model {
  theta ~ beta(1,1); // prior
  y ~ binomial(N,theta); // likelihood
}
```

```
model {
  theta ~ beta(1,1); // prior
  y ~ binomial(N,theta); // likelihood
}
```

ullet \sim is syntactic sugar and this could be also written as

```
model {
  target += beta_lpdf(theta | 1, 1);  // prior
  target += binomial_lpmf(y | N, theta); // likelihood
}
```

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target is the log posterior density (usually)

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- target is the log posterior density (usually)
- _lpdf for continuous, _lpmf for discrete distributions

Stan

- Stan compiles (transplies) the model written in Stan language to C++
 - this makes the sampling for complex models and bigger data faster
 - also makes Stan models easily portable, you can use your own favorite interface

RStan and PyStan

RStan

```
library(rstan)
rstan_options(auto_write = TRUE)
options(mc.cores = parallel::detectCores())
source('stan_utility.R')

d_bin <- list(N = 10, y = 7)
fit_bin <- stan(file = 'binom.stan', data = d_bin)</pre>
```

RStan and PyStan

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Stan

- Compilation (unless previously compiled model available)
- Adaptation
- Warm-up
- Sampling
- Generated quantities
- Save posterior draws
- Report divergences, n_{eff}, R̂

- An experiment was performed to estimate the effect of beta-blockers on mortality of cardiac patients
- A group of patients were randomly assigned to treatment and control groups:
 - out of 674 patients receiving the control, 39 died
 - out of 680 receiving the treatment, 22 died

```
data {
  int < lower = 0 > N1:
  int < lower = 0 > y1;
  int < lower = 0 > N2;
  int < lower = 0 > v2;
parameters {
  real<lower=0,upper=1> theta1;
  real<lower=0,upper=1> theta2;
model {
  theta1 \sim beta(1,1);
  theta2 \sim beta(1,1);
  y1 ~ binomial(N1, theta1);
  y2 ~ binomial(N2, theta2);
generated quantities {
  real oddsratio:
  oddsratio = (theta2/(1-theta2))/(theta1/(1-theta1));
```

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```
data
  int < lower = 0 > N1:
  int <lower=0> y1;
  int <lower=0> N2;
  int < lower = 0 > v2;
parameters
  real<lower=0,upper=1> theta1;
  real < lower = 0, upper = 1 > theta2;
model
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```

oddsratio = (theta2/(1-theta2))/(theta1/(1-theta1));

```
generated quantities {
  real oddsratio;
  oddsratio = (theta2/(1-theta2))/(theta1/(1-theta1));
}
```

generated quantities is run after the sampling

```
d bin2 \leftarrow list (N1 = 674, y1 = 39, N2 = 680, y2 = 22)
fit bin2 <- stan(file = 'binom2.stan', data = d bin2)
starting worker pid=10151 on localhost:11783 at 10:03:27.872
starting worker pid=10164 on localhost:11783 at 10:03:28.087
starting worker pid=10176 on localhost:11783 at 10:03:28.295
starting worker pid=10185 on localhost:11783 at 10:03:28.461
SAMPLING FOR MODEL 'binom2' NOW (CHAIN 1).
Gradient evaluation took 6e-06 seconds
1000 transitions using 10 leapfrog steps per transition would take 0.06 seconds.
Adjust your expectations accordingly!
Iteration: 1 / 2000 [ 0%] (Warmup)
Iteration: 200 / 2000 [ 10%] (Warmup)
Iteration: 1000 / 2000 [ 50%] (Warmup)
Iteration: 1001 / 2000 [ 50%] (Sampling)
Iteration: 2000 / 2000 [100%] (Sampling)
Elapsed Time: 0.012908 seconds (Warm-up)
              0.017027 seconds (Sampling)
              0.029935 seconds (Total)
SAMPLING FOR MODEL 'binom2' NOW (CHAIN 2).
```

```
monitor(fit_bin2, probs = \mathbf{c}(0.1, 0.5, 0.9))
```

Inference for the input samples
(4 chains: each with iter=1000; warmup=0):

	mean	se_mean	sd	10%	50%	90%	n_eff	Rhat
theta1	0.1	0	0.0	0.0	0.1	0.1	3280	1
theta2	0.0	0	0.0	0.0	0.0	0.0	3171	1
oddsratio	0.6	0	0.2	0.4	0.6	0.8	3108	1
lp	-253.5	0	1.0	-254.8	-253.2	-252.6	1922	1

For each parameter, n_eff is a crude measure of effective sample size, and Rhat is the potential scale reduction factor on split chains (at convergence, Rhat=1).

```
monitor(fit_bin2, probs = \mathbf{c}(0.1, 0.5, 0.9))
```

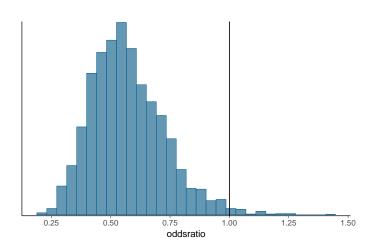
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	mean	se_mean	sd	10%	50%	90%	n_eff	Rhat
theta1	0.1	0	0.0	0.0	0.1	0.1	3280	1
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oddsratio	0.6	0	0.2	0.4	0.6	0.8	3108	1
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For each parameter, n_{eff} is a crude measure of effective sample size, and Rhat is the potential scale reduction factor on split chains (at convergence, Rhat=1).

lp__ is the log density, ie, same as "target"

```
draws <- as.data.frame(fit_bin2)
mcmc_hist(draws, pars = 'oddsratio') +
  geom_vline(xintercept = 1) +
  scale_x_continuous(breaks = c(seq(0.25,1.5,by=0.25)))</pre>
```



HMC specific diagnostics

```
check_treedepth(fit_bin2)
check_energy(fit_bin2)
check_div(fit_bin2)
```

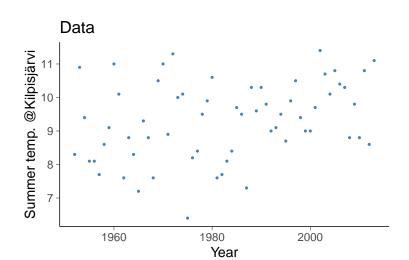
```
[1] "0 of 4000 iterations saturated the maximum tree depth of 10 (0\%)" [1] "0 of 4000 iterations ended with a divergence (0\%)"
```

Shinystan

Graphical user interface for analysing MCMC results

Kilpisjärvi summer temperature

- Temperature at Kilpisjärvi in June, July and August from 1952 to 2013
- Is there change in the temperature?



Gaussian linear model

```
data {
    int <lower = 0 > N; // number of data points
    vector[N] x; //
    vector[N] y; //
parameters {
    real alpha;
    real beta;
    real < lower = 0 > sigma;
transformed parameters {
    vector[N] mu;
    mu <- alpha + beta *x;
model {
    y ~ normal(mu, sigma);
```

Gaussian linear model

```
data {
    int <lower=0> N; // number of data points
    vector[N] x; //
    vector[N] y; //
}
```

difference between "vector[N] x" and "real x[N]"

Gaussian linear model

```
parameters {
    real alpha;
    real beta;
    real <lower=0> sigma;
}
transformed parameters {
    vector[N] mu;
    mu <- alpha + beta*x;
}</pre>
```

 transformed parameters are deterministic transformations of parameters and data

Priors for Gaussian linear model

```
data {
    int <lower = 0 > N; // number of data points
    vector[N] x: //
    vector[N] v: //
    real pmualpha; // prior mean for alpha
    real psalpha; // prior std for alpha
    real pmubeta; // prior mean for beta
    real psbeta; // prior std for beta
transformed parameters {
    vector[N] mu;
    mu <- alpha + beta *x;
model {
    alpha ~ normal(pmualpha, psalpha);
    beta ~ normal(pmubeta, psbeta);
    y ~ normal(mu, sigma);
```

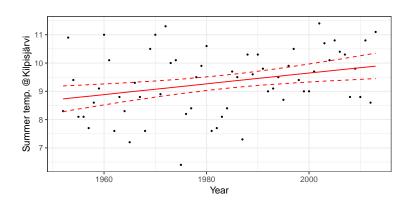
Student-t linear model

```
parameters {
  real alpha;
  real beta:
  real < lower = 0 > sigma;
  real < lower = 1, upper = 80 > nu;
transformed parameters {
  vector[N] mu;
  mu <- alpha + beta *x;
model {
  nu ~ qamma(2,0.1);
  y ~ student t(nu, mu, sigma);
```

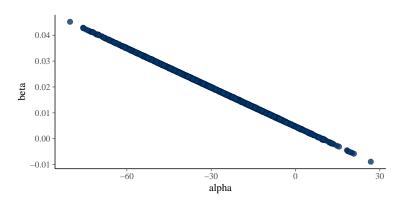
Priors

• Prior for temperature increase?

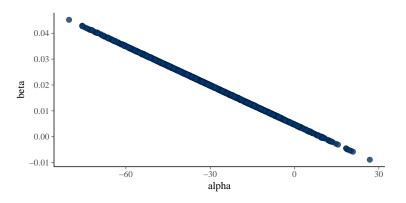
Kilpisjärvi summer temperature



Kilpisjärvi summer temperature



Kilpisjärvi summer temperature



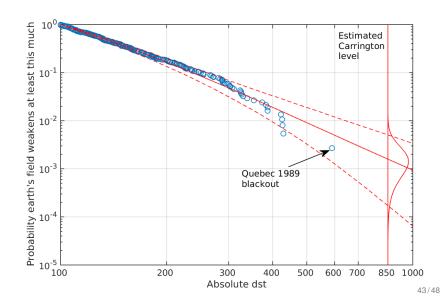
There were 14 transitions after warmup that exceeded the maximum treedepth. Increase max_treedepth above 10. See http://mc-stan.org/misc/warnings.html#maximum-treedepth-exceeded Examine the pairs() plot to diagnose sampling problems

Linear regression model in Stan

```
data {
  int <lower=0> N; // number of data points
  vector[N] x; //
  vector[N] y; //
  real xpred; // input location for prediction
}
transformed data {
  vector[N] x_std;
  vector[N] y_std;
  real xpred_std;
  x_std = (x - mean(x)) / sd(x);
  y_std = (y - mean(y)) / sd(y);
  xpred_std = (xpred - mean(x)) / sd(x);
}
```

Extreme value analysis

Geomagnetic storms



Extreme value analysis

```
data {
  int < lower = 0 > N;
  vector<lower=0>[N] y;
  int < lower = 0 > Nt:
  vector<lower=0>[Nt] yt;
transformed data {
  real ymax;
  ymax <- max(y);
parameters {
  real < lower = 0 > sigma;
  real < lower = - sigma / ymax > k;
model {
  y ~ gpareto(k, sigma);
generated quantities {
  vector[Nt] predccdf;
  predccdf<-gpareto_ccdf(yt,k,sigma);</pre>
```

Functions

```
functions {
  real gpareto_lpdf(vector y, real k, real sigma) {
    // generalised Pareto log pdf with mu=0
    // should check and give error if k<0
    // and max(y)/sigma > -1/k
    int N;
    N \leftarrow dims(y)[1];
    if (fabs(k) > 1e-15)
      return -(1+1/k)*sum(log1pv(y*k/sigma)) -N*log(sigma);
    else
      return -sum(y/sigma) -N*log(sigma); // limit k->0
  vector gpareto ccdf(vector y, real k, real sigma) {
    // generalised Pareto log ccdf with mu=0
    // should check and give error if k<0
    // and max(y)/sigma < -1/k
    if (fabs(k) > 1e-15)
      return exp((-1/k)*log1pv(y/sigma*k));
    else
      return \exp(-y/\text{sigma}); // limit k \rightarrow 0
```

RStanARM

- RStanARM provides simplified model description with pre-compiled models
 - no need to wait for compilation
 - a restricted set of models

```
 \begin{aligned} & \text{d\_bin2} < - \text{ data.frame} (\text{N} = \text{c}(674, 680), \text{y} = \text{c}(39,22), \text{ grp2} = \text{c}(0,1)) \\ & \text{fit\_bin2} < - \text{ stan\_glm}(\text{y/N} \sim \text{grp2}, \text{ family} = \text{binomial}(), \text{ data} = \text{d\_bin2}, \\ & \text{weights} = \text{N}) \end{aligned}   \begin{aligned} & \text{draws\_bin2} < - \text{ as.data.frame} (\text{fit\_bin2}) \%\% \\ & \text{mutate} (\text{theta1} = \text{plogis}(`(\text{Intercept})`), \\ & \text{theta2} = \text{plogis}(`(\text{Intercept})` + \text{grp2}), \\ & \text{oddsratio} = (\text{theta2/(1-theta2}))/(\text{theta1/(1-theta1)})) \end{aligned}   \end{aligned}   \begin{aligned} & \text{mcmc} \quad \text{hist} (\text{draws} \quad \text{bin2}, \quad \text{pars='oddsratio'}) \end{aligned}
```

BRMS

- BRMS provides simplified model description
 - a larger set of models than RStanARM, but still restricted
 - need to wait for the compilation

Other packages

- R
- shinystan interactive diagnostics
- bayesplot visualization and model checking (see model checking in Ch 6)
- loo cross-validation model assessment, comparison and averaging (see Ch 7)
- projpred projection predictive variable selection

Python

 ArviZ — visualization, and model checking and assessment (see Ch 6 and 7)