The Trampoline Handbook

release 2.0

Jean-Luc Béchennec Mikaël Briday Sébastien Faucou Pierre Molinaro Florent Pavin

CONTENTS

Ι	\mathbf{T} h	ie Rea	al-Time Operating System	5					
1	Porting Trampoline								
	1.1	Addin	g files to the directory structure	7					
	1.2	Using	a target with goil \hdots	8					
	1.3	Archit	tecture specific code and structures	8					
		1.3.1	Functions called by Trampoline	9					
		1.3.2	Data types and structures	9					
П	\mathbf{T}	he G	oil system generator	11					

4 Contents

Part I

The Real-Time Operating System

CHAPTER

ONE

Porting Trampoline



In this chapter *arch* is used to designate the instruction set of the target like PowerPC[®], ARM[®] or AVR[®]; *chip* is used to designate the name of an implementation of the architecture like a PowerPC 5516; *board* is used to designate the name of a development board that uses the chip. *compiler* is used to designate the compiler and *linker* is used to designate the linker used to link the project and produced the executable file.

1.1 Adding files to the directory structure

Doing a port of Trampoline on a new target requires

- data structures
- code, some is in C and some is in assembly language of the target
- code templates
- memory mapping templates (depend on the compiler)
- link scripts templates (depend on the linker)

Data structures declarations and code related to the instruction set are located in the 'machines/arch' directory.

Code templates are located in the 'goil/templates/code/arch' directory.

Memory mapping templates are located in the 'goil/templates/compiler/compiler/arch' directory.

Link scripts templates are located in the 'goil/templates/linker/linker/arch' directory.

For instance, if the goal is to port Trampoline to a Freescale[®] ColdFire[®] CPU with the gcc compiler and the gnu ld linker, you have to create a directory 'coldfire' inside the 'machines' directory, inside the 'goil/templates/code' directory and inside the

'goil/templates/code/gnu_ld' directory. For gcc, memory mapping templates are common to all *arch* and exist already but, for instance, the Metrowerks[®] C compiler uses different #pragma according to the *arch*. So memory mapping templates for the Metrowerks C compiler for PowerPC would be located in 'goil/templates/compiler/mwc/powerpc' and for HCS12 would be located in 'goil/templates/compiler/mwc/hcs12'

In addition, some code or link scripts may be specific to the *chip* or the *board*. In this case, create sub-directories in the various *arch* directories using the pattern 'arch/chip/board' to put the corresponding files.

1.2 Using a target with goil

The -t or --target option of goil selects the target by using a arch/chip/board path. Goil will look at the code, compiler and linker templates in the corresponding paths. Goil looks for a template at the deeper path first and goes up until it find it or gives an error when it does not find it. This way, a generic chip level template may be overridden by a more specific board level template for instance.

If you use the -g or --generate-makefile option, goil generates a Makefile that includes the Makefiles that exist along the path.

The link script templates (linker) and the memory mapping templates (compiler) are used only if a project is built using memory mapping. MEMMAP is a boolean attribute of the OS object in the OIL file. COMPILER and LINKER are sub-attributes of MEMMAP when it is TRUE. For instance, a MEMMAP using gcc and gnu ld would described like that:

```
MEMMAP = TRUE {
   COMPILER = gcc;
   LINKER = gnu_ld { SCRIPT = "script.ld"; };
   ...
};
```

Using this description and the target option, goil will look for link script templates in 'goil/templates/gnu_ld/arch/chip/board' path and for memory mapping templates in 'goil/templates/gcc/arch/chip/board' path.

The SCRIPT sub-attributes gives the name of the generated link script file.

1.3 Architecture specific code and structures



The following informations require you use a software interrupt to call the system services.

This code should be located in the 'machines/arch' directory or in a sub-directory ('chip' or 'board') if you want to implement a feature that rely on a specific chip or board (for instance to put peripheral devices in sleep mode in the tpl_sleep function). Anyway, you should put the relevant code at the corresponding level. If in the rare instances you may need to use conditional compiling, you may use the C macros TARGET_ARCH, TARGET_CHIP and TARGET_BOARD that contains the arch, chip and board respectively as character strings.

1.3.1 Functions called by Trampoline

The following functions are needed by Trampoline:

```
extern FUNC(void, OS_CODE) tpl_init_context(
   CONST(tpl_proc_id, AUTOMATIC) proc_id);
```

tpl_init_context may be written in C. It is called when an activated task runs for the first time. It initializes the context of the task by setting the 'at start' values of registers. Setting at least the values of the stack pointer at the beginning of the stack zone of the task and the return address at the entry point of the task code are required.

```
extern FUNC(void, OS_CODE) tpl_init_machine(void);
```

tpl_init_machine is called at the beginning of StartOS before calling the StartupHook and starting the scheduling. tpl_init_machine should do the hardware related initializations that are needed to run the OS (for instance starting the timer of the SystemCounter).

```
extern FUNC(void, OS_CODE) tpl_sleep(void);
```

tpl_sleep is called from the idle task. It should implement a loop around an instruction that put the CPU in a waiting for interrupt mode. If the *arch* does not have such an instruction, an empty loop may be used.



tpl_sleep should never return.

```
extern FUNC(void, OS_CODE) tpl_shutdown(void);
```

tpl_shutdown is called from ShutdownOS. It should disable all interrupts and put the CPU in sleep mode. If no sleep mode exists, an empty loop may be used.



tpl_shutdown should never return.

1.3.2 Data types and structures

A file named 'tpl_machine.h' should exists in the 'machines/arch' directory. This file should contain the declarations and definitions of:

- the tpl_stack_word type
- the tpl_stack_size type
- the tpl_context structure
- the tpl_stack structure
- the IDLE_ENTRY macro that should set to tpl_sleep
- the IDLE_STACK macro
- the IDLE_CONTEXT macro

The tpl_stack_word type is used to achieved a correct alignment of the stack

The tpl_context context structure contains one of more pointers to structures where all the registers needed for the execution context are stored. More than one pointer may be needed because on some architectures, contexts may be split in 2 or 3 parts to store the integer context, the floating point context and the vector context for instance. This way a task doing only integer computation needs the integer context only. The other pointers are set to NULL and the context switching code does not save or restore contexts for the NULL pointers. A tpl_context field is included in the static part of a task descriptor which may be stored in ROM. For instance, on an AVR, the context structure is declared as follow:

```
struct TPL_CONTEXT {
   avr_context *ic;
};
typedef struct TPL_CONTEXT tpl_context;

and an avr_context is defined as follow:
struct AVR_CONTEXT {
   u8 *sp;
   u8 regist[33]; // registers: RO-R15,R17-R31,SREG,R16
};
typedef struct AVR_CONTEXT avr_context;
```

The tpl_stack stack structure contains one or more pointers to the stack and one or more stack sizes. Some ABI may use more than one stack (an example is the Infineon C166). A tpl_stack field is included in the static part of a task descriptor. The AVR stack structure is as follow:

```
struct TPL_STACK {
   tpl_stack_word *stack_zone;
   tpl_stack_size stack_size;
};
typedef struct TPL_STACK tpl_stack;
```

The IDLE_STACK macro should expand to a tpl_stack initialization. This macro is used to initialize the stack in the idle task descriptor. For instance, the AVR IDLE_STACK and the component it uses are defined like this:

```
#define SIZE_OF_IDLE_STACK 50

extern VAR(tpl_stack_word, OS_VAR)
   idle_stack[SIZE_OF_IDLE_STACK/sizeof(tpl_stack_word)];

#define IDLE_STACK { idle_stack, SIZE_OF_IDLE_STACK }
```

The IDLE_CONTEXT should expand to a tpl_context initialization. This macro is used to initialize the context in the idle task descriptor. For instance, the AVR IDLE_CONTEXT and the component it uses are defined like this:

```
extern avr_context idle_task_context;
#define IDLE_CONTEXT {&idle_task_context}
```

Part II

The Goil system generator

BIBLIOGRAPHY

- [1] Programming Environments Manual for 32-Bit Implementations of the PowerPCTM Architecture, chapter 8, pages 8–157. Freescale semiconductor, rev. 3 edition, September 2005.
- [2] AUTOSAR. Specification of compiler abstraction. Technical report, AUTOSAR GbR, August 2008. http://autosar.org/download/R3.1/AUTOSAR_SWS_CompilerAbstraction.pdf.
- [3] AUTOSAR. Specification of memory mapping. Technical report, AUTOSAR GbR, June 2008. http://autosar.org/download/R3.1/AUTOSAR_SWS_MemoryMapping.pdf.
- [4] Microcontroller Applications IBM Microelectronics. Developing powerpc embedded application binary interface (eabi) compliant programs. Technical report, IBM, Research Triangle Park, NC, September 1998.
- [5] L. Sha, R. Rajkumar, and J. P. Lehoczky. Priority inheritance protocols: An approach to real-time synchronization. *IEEE Trans. Comput.*, 39(9):1175–1185, 1990.