



## Mathematical Statistics and Data Analysis

Lecture 8: Parameter Estimation

Lyu Ni

DaSE@ECNU (Ini@dase.ecnu.edu.cn)

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#### **Outlines**

1 Point Estimation

Methods of Finding an estimate Method of Moments Method of Maximum Likelihood

# Reading Material

#### Textbook:

• Rice: Chapter 8;

Mao: Chapter 6;

#### Point Estimation

#### Example

On the Error of Counting with a Haemacytometer (1907) by Student.

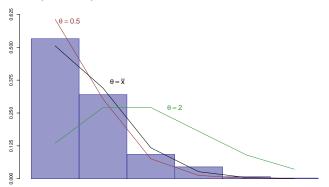
- The famous statistician William Gosset, who worked for Guinness brewery, took measure of the number of yeast cells per square in a hemocytometer. The count of yeast cells could be model with a probability distribution known as 'Poisson distribution'  $P(\theta)$ .
- This distribution  $P(\theta)$  has an unknown parameter  $\theta$ .
- The data is shown as follows:

Containing	0	1	2	3	4	5
Actual	213	128	37	18	3	1

• Problem: What is a guess of  $\theta$ ?

#### Point Estimation

## Example (Con'd)

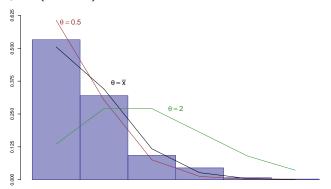


#### Definition

Suppose that  $x_1, x_2, \dots, x_n$  is a sample from a population with unknown parameter  $\theta$ . The statistic  $\hat{\theta} = \hat{\theta}(x_1, x_2, \dots, x_n)$  is called an **point estimate** of  $\theta$ .

#### Point Estimation

## Example (Con'd)



#### Definition

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The kth moment of a random variable X is defined as

$$\mu_k = E(X^k).$$

Suppose that  $x_1, x_2, \dots, x_n$  is a sample. The kth sample moment is defined as

$$a_k = \frac{1}{n} \sum_{i=1}^n x_i^k$$

Then, we can view  $a_k$  as an estimate of  $\mu_k$ , and thus let  $\hat{\mu}_k = a_k$ .

#### Idea

The method of moments estimates parameters by finding expressions for them in terms of the lowest moments and then substitution sample moments into the expressions.

- The p.d.f. or p.m.f. of the population is  $f(x:\theta_1,\cdots,\theta_k)$ ;
- $(\theta_1, \dots, \theta_k) \in \Theta$  is an unknown parameter vector;
- $\Theta$  is a parameter space.
- Suppose that the *i*th moment  $\mu_i$  exists,  $i=1,2,\cdots,k$ ;
- The parameters  $\theta_1, \dots, \theta_k$  can be written as the functions of  $\mu_1, \dots, \mu_k$ , that is  $\theta_j = \theta_j(\mu_1, \dots, \mu_k)$ ;
- The method of moments estimates of  $\theta_i$  is

$$\hat{\theta}_j = \theta_j(\hat{\mu}_1, \cdots, \hat{\mu}_k), j = 1, \cdots, k$$

• Furthermore, if  $\eta=g(\theta_1,\cdots,\theta_k)$  is to be estimated, the method of moment estimate of  $\eta$  is

$$\hat{\eta} = g(\hat{\theta}_1, \cdots, \hat{\theta}_k)$$

### Example: Exponential Distribution

The p.d.f. of an exponential distribution is

$$f(x;\lambda) = \lambda e^{-\lambda x}, x > 0$$

and  $x_1, x_2, \cdots, x_n$  is a sample.

• Consider k=1. Since  $EX=1/\lambda$ , i.e.  $\lambda=1/EX$ , then the method of moment estimate of  $\lambda$  is

$$\hat{\lambda} = 1/\bar{x};$$

• Consider k=2. Since  $Var(X)=1/\lambda^2$ , i.e.  $\lambda=1/\sqrt{Var(X)}$ , then the moment of method estimate of  $\lambda$  is

$$\hat{\lambda} = 1/s$$
.

#### Remark

- The method of moment estimate is straight forward.
- The method of moment estimate is **not unique**.
- Problem: Which one is better?

#### Rule of thumb

The sample moments used in the method of moment should be as **low** as possible.

#### Example: Poisson Distribution

The p.d.f. of a Poisson distribution is

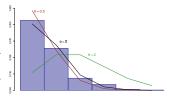
$$f(x; \lambda) = \frac{\lambda^x}{x!} e^{-\lambda}, x = 0, 1, 2, \dots$$

and  $x_1, x_2, \dots, x_n$  is a sample. Since  $E(X) = \lambda$ , the method of moment estimate of  $\lambda$  is

$$\lambda = \bar{x}$$

The data are shown as follows:

Containing	0	1	2	3	4	5
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#### Example: Uniform Distribution

The p.d.f. of a uniform distribution is

$$f(x;\lambda) = \frac{1}{b-a} I_{(a,b)}(x)$$

with two unknown parameter a and b. Suppose that  $x_1, x_2, \cdots, x_n$  is a sample. Since

$$E(X) = \frac{a+b}{2}$$
 and  $Var(X) = \frac{(b-a)^2}{12}$ ,

it is obvious that  $a=EX-\sqrt{3Var(X)}$  and  $b=EX+\sqrt{3Var(X)}$ . Thus, the method of moment estimates of a and b are

$$\hat{a} = \bar{x} - \sqrt{3}s$$
 and  $\hat{b} = \bar{x} + \sqrt{3}s$ .

### Example One

Suppose that it is difficult to distinguish two urns from the appearance. Urn A contains 99 white balls and 1 black ball while Urn B contains 1 white ball and 99 black balls. Here we randomly select an urn and then take a ball. If this ball is a white ball, which urn do you select?

Solution: Let the event

$$A = \{A \text{ white ball is taken}\}.$$

- If Urn A is chosen, the probability P(A) = 0.99.
- If Urn B is chosen, the probability P(A) = 0.01

If A occurs and then we may think that it is likely that this white ball is taken out of  $Urn\ A$ .

#### Example Two

We flip a coin and use a random variable X to represent the result. If it heads up, then X=1; otherwise, X=0. Then, X is distributed as a Bernoulli distribution B(p) with a unknown parameter p.

Suppose that  $x_1, x_2, \dots, x_n$  is a sample. The joint p.m.f. of  $(x_1, x_2, \dots, x_n)$  is

$$f(x_1, x_2, \dots, x_n; p) = \prod_{i=1}^n p^{x_i} (1-p)^{1-x_i} = p^{\sum_{i=1}^n x_i} (1-p)^{n-\sum_{i=1}^n x_i}$$

Since p is unknown, this function could be thought to be a likelihood function of p, denoted as L(p). That is,

$$L(p) = p^{\sum_{i=1}^{n} x_i} (1-p)^{n-\sum_{i=1}^{n} x_i}, p \in (0,1).$$

### Example Two (Con'd)

- How to determine p?
- We would like to choose p so that the probability is as large as possible. Equivalently,

$$\hat{p} = \arg\max_{p} L(p)$$

Then,

$$\frac{\partial \ln L(p)}{\partial n} = \frac{\sum_{i=1}^{n} x_i}{n} - \frac{n - \sum_{i=1}^{n} x_i}{1 - n} = 0.$$

Thus, the maximum likelihood estimate of p is

$$\hat{p} = \hat{p}(x_1, x_2, \dots, x_n) = \frac{\sum_{i=1}^n x_i}{n} = \bar{x}.$$

#### Definition

Suppose that the p.m.f. or p.d.f. of the population is  $p(x;\theta), \theta \in \Theta$ , where  $\theta$  is a unknown parameter (vector) and  $\Theta$  is the parameter space. Let  $x_1, x_2, \cdots, x_n$  be a sample. The joint p.m.f. or p.d.f. of  $x_1, x_2, \cdots, x_n$  could be thought to be a function of  $\theta$ , denoted as  $L(\theta; x_1, \cdots, x_n)$  or  $L(\theta)$ .

- This function  $L(\theta)$  is called as the **likelihood function**.
- A statistic  $\hat{\theta} = \hat{\theta}(x_1, x_2, \dots, x_n)$  is called **maximum likelihood estimate (MLE)** if this statistic  $\hat{\theta}$  satisfies

$$L(\hat{\theta}) = \max_{\theta \in \Theta} L(\theta)$$

#### **Example: Normal Distribution**

Suppose that  $x_1, x_2, \cdots, x_n$  is a sample from a normal distribution  $N(\mu, \sigma^2)$ , where  $\theta = (\mu, \sigma^2)$  is a two-dimensional parameter vector. The likelihood function is

$$L(\mu, \sigma^2) = \prod_{i=1}^n \left( \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left\{ -\frac{(x_i - \mu)^2}{2\sigma^2} \right\} \right)$$
$$= (2\pi\sigma^2)^{-n/2} \exp\left\{ -\frac{1}{2\sigma^2} \sum_{i=1}^n (x_i - \mu)^2 \right\},$$

and its log-likelihood function is

$$l(\mu, \sigma^2) = \ln L(\mu, \sigma^2) = -\frac{1}{2\sigma^2} \sum_{i=1}^{n} (x_i - \mu)^2 - \frac{n}{2} \ln \sigma^2 - \frac{n}{2} \ln(2\pi).$$

## Example: Normal Distribution (Con'd)

The partials with respect to  $\mu$  and  $\sigma^2$  are

$$\frac{\partial(-l)}{\partial\mu} = -\frac{1}{\sigma^2} \sum_{i=1}^n (x_i - \mu)$$

$$\frac{\partial(-l)}{\partial\sigma^2} = -\frac{1}{2\sigma^4} \sum_{i=1}^n (x_i - \mu)^2 + \frac{n}{2\sigma^2}.$$

Setting the first partial equal to zero and solving for the MLE, we obtain

$$\hat{\mu} = \frac{1}{n} \sum_{i=1}^{n} x_i = \bar{x}$$
 and  $\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^{n} (x_i - \bar{x}) = s_*^2$ .

### Example: Normal Distribution (Con'd)

The second-order partial deviates are, respectively,

$$\frac{\partial^2(-l)}{\partial \mu^2} = \frac{n}{\sigma^2} \text{ and } \frac{\partial^2(-l)}{\partial (\sigma^2)^2} = \frac{1}{\sigma^6} \sum_{i=1}^n (x_i - \mu)^2 - \frac{n}{2\sigma^4}$$

$$\frac{\partial^2 l}{\partial (\sigma^2)\partial \mu} = \frac{\partial^2 l}{\partial \mu \partial (\sigma^2)} = \frac{1}{\sigma^4} \sum_{i=1}^n (x_i - \mu).$$

It is easy to verify the matrix is negative definite since

$$\frac{\partial l}{\partial \mu^2} \Big|_{\mu = \bar{x}, \sigma^2 = s_*^2} = \frac{n}{s_*^2} > 0$$

$$\left(\frac{\partial l}{\partial \mu^2} \cdot \frac{\partial l}{\partial (\sigma^2)^2} - \left(\frac{\partial l}{\partial (\sigma^2)\partial \mu}\right)^2\right) \Big|_{\mu = \bar{x}, \sigma^2 = s_*^2} = \frac{n^2}{2s_*^6} > 0$$

#### Example: Uniform Distribution

Suppose that  $x_1, x_2, \cdots, x_n$  is a sample from a uniform distribution  $U(0, \theta)$ . Find the maximum likelihood estimate of  $\theta$ .

**Solution:** The likelihood function is

$$L(\theta) = \frac{1}{\theta^n} \prod_{i=1}^n I_{\{0 < x_i \le \theta\}} = \frac{1}{\theta^n} I_{\{0 < x_{(n)} \le \theta\}}$$

To maximize the likelihood,

- let  $I_{\{x_{(n)} < \theta\}}$  be 1;
- let  $1/\theta^n$  be as large as possible.

Since  $\frac{1}{\theta^n}$  is decreasing in  $\theta,$  the maximum likelihood estimate of  $\theta$  is

$$\hat{\theta} = x_{(n)}$$

Theorem: Invariance Property

If  $\hat{\theta}$  is the MLE of  $\theta,$  then for any function of  $g(\theta),$  the MLE of  $g(\theta)$  is  $g(\hat{\theta}).$ 

Example: Normal Distribution (Revisit)

Suppose that  $x_1, x_2, \dots, x_n$  is a sample from  $N(\mu, \sigma^2)$ . The MLE of  $\mu$  and  $\sigma^2$  are respectively

$$\hat{\mu} = \bar{x}$$
 and  $\hat{\sigma^2} = s_*^2$ .

From the invariance property, find the MLE:

- The standard deviation  $\sigma$ :
- The probability  $P(X < 3) = \Phi\left(\frac{3-\mu}{\sigma}\right)$ .;
- The 90% quantile  $x_{0.90} = \mu + \sigma u_{0.90}$ , where  $u_{0.90}$  is the 90% quantile of a standard normal r.v.

#### Theorem: Invariance Property

If  $\hat{\theta}$  is the MLE of  $\theta$ , then for any function of  $g(\theta)$ , the MLE of  $g(\theta)$  is  $g(\hat{\theta})$ .

## Example: Normal Distribution (Revisit)

Suppose that  $x_1, x_2, \dots, x_n$  is a sample from  $N(\mu, \sigma^2)$ . The MLE of  $\mu$  and  $\sigma^2$  are respectively

$$\hat{\mu} = \bar{x}$$
 and  $\hat{\sigma^2} = s_*^2$ .

From the invariance property, we have

- The MLE of  $\sigma$  is  $\hat{\sigma} = s_*$ :
- The MLE of P(X < 3) is  $\Phi\left(\frac{3-\bar{x}}{s_*}\right)$ ;
- The MLE of the 90% quantile  $x_{0.90}$  is  $\bar{x} + s_* u_{0.90}$ .