



WOMEN IN DATA SCIENCE



#WiDS2019

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- Post graduate from IITB
- Areas of expertise: Deep learning, Statistical Machine Translation
- Hobbies: Travel, Trekking, Painting



Demystifying Convolutional Neural Networks



Convolutional Neural Network

Classification



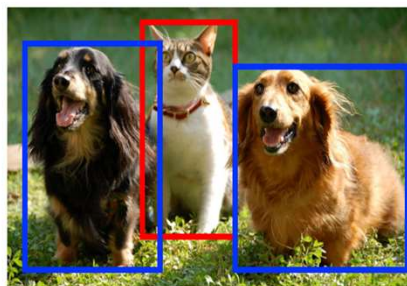
CAT

**Classification
+ Localization**



CAT

Object Detection



CAT, DOG

Instance Segmentation



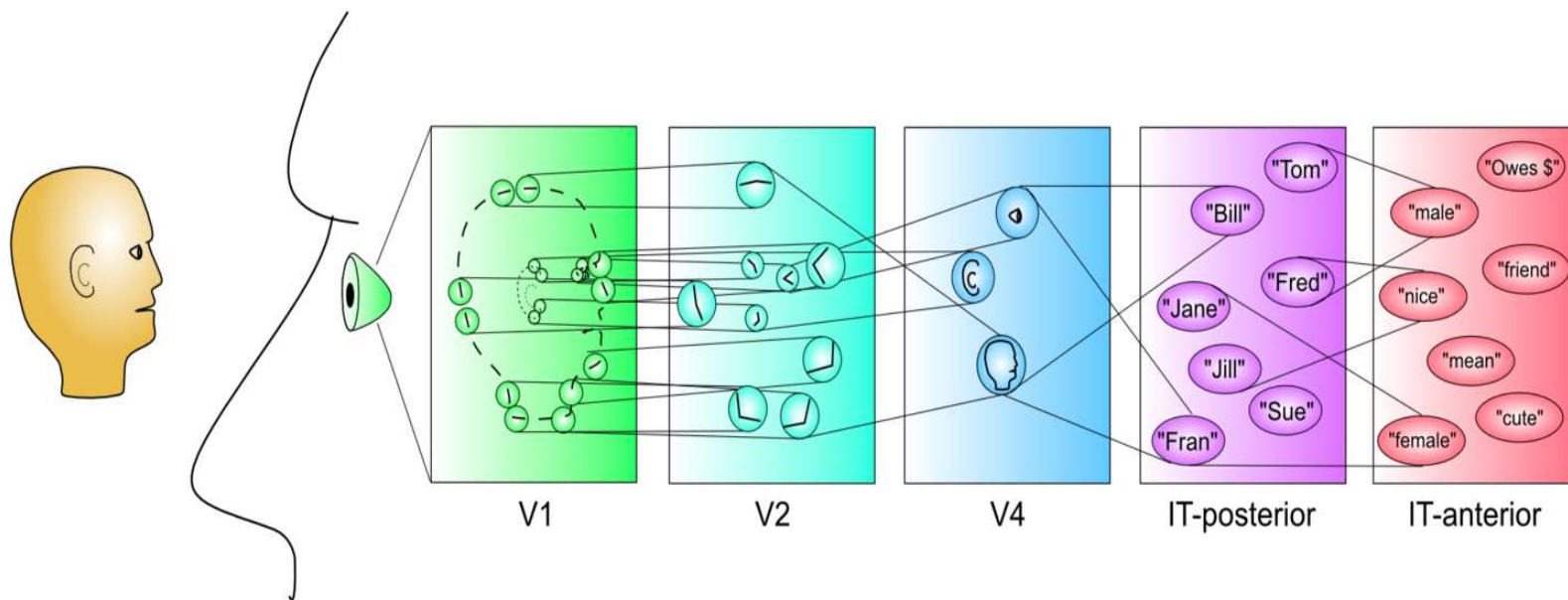
CAT, DOG

Single object

Multiple objects



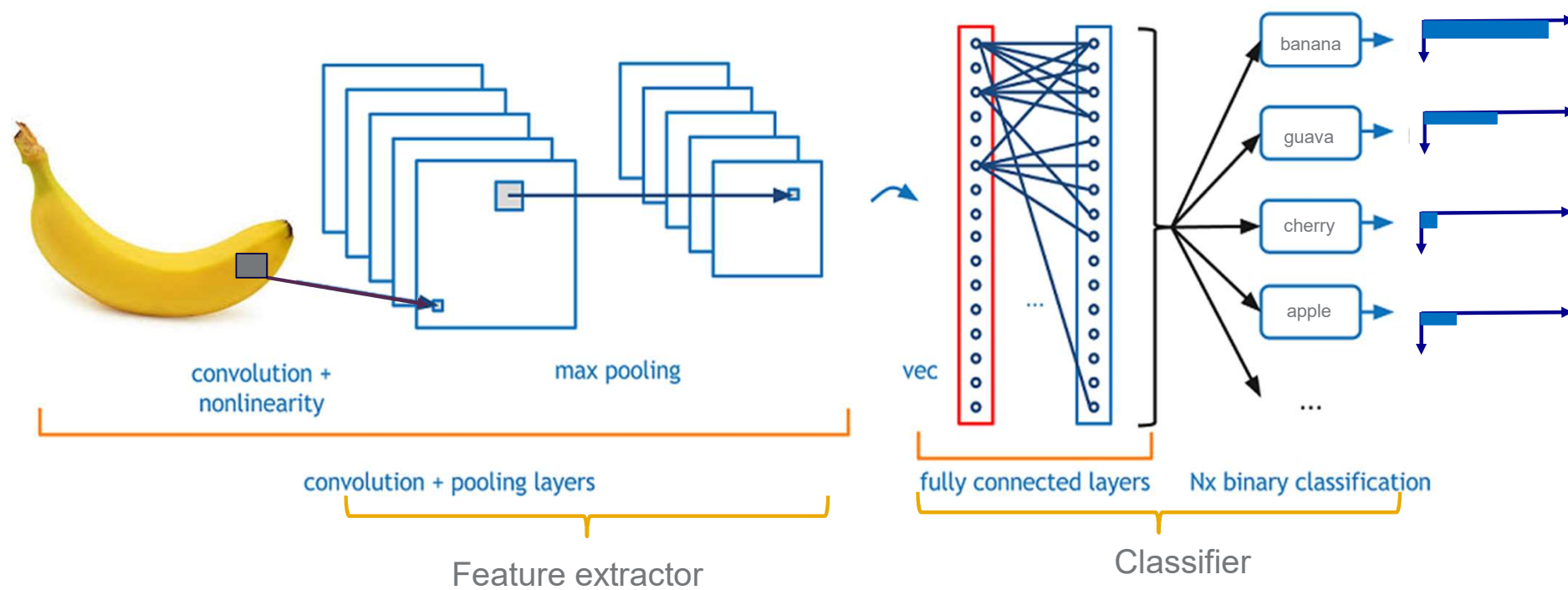
CNN: Biological Motivation



Img src: <https://grey.colorado.edu/CompCogNeuro/index.php/CCNBook/Perception>

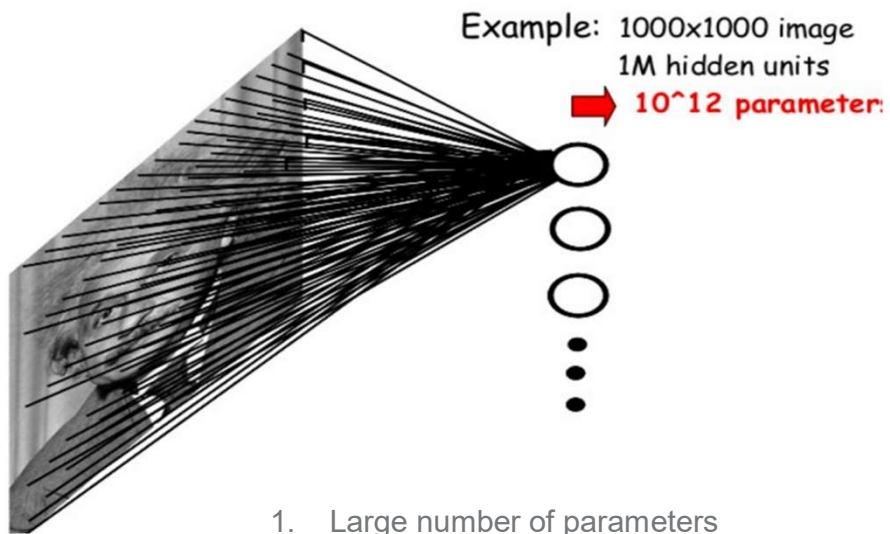


CNN Architecture



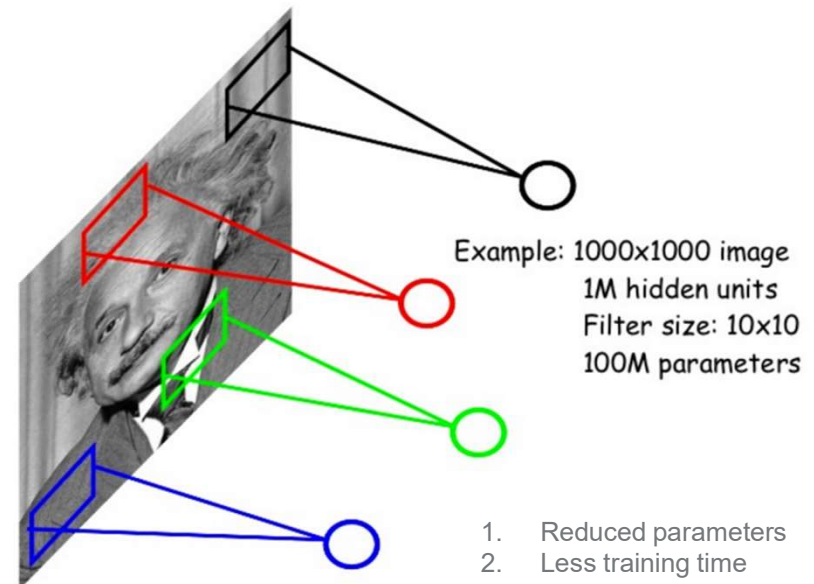
Why Convolution?

FULLY CONNECTED NEURAL NET



1. Large number of parameters
2. More training time

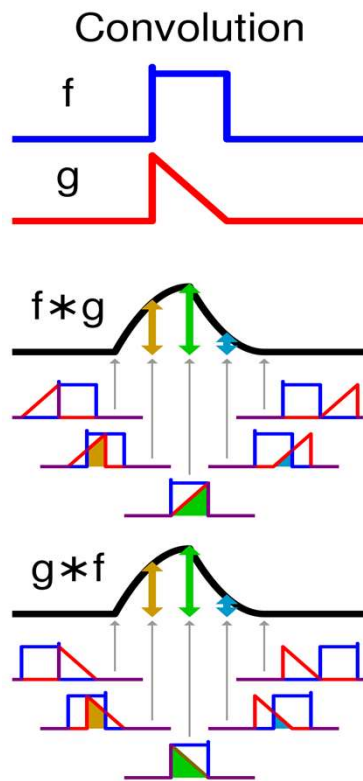
LOCALLY CONNECTED NEURAL NET



1. Reduced parameters
2. Less training time
3. Leverage spatial invariance



What is Convolution?



Img source: Wikipedia

Original Image

7	2	3	3	8
4	5	3	8	4
3	3	2	8	4
2	8	7	2	7
5	4	4	5	4

Filter

1	0	-1
1	0	-1
1	0	-1

*

$$7 \times 1 + 4 \times 1 + 3 \times 1 + 2 \times 0 + 5 \times 0 + 3 \times 0 + 3 \times -1 + 3 \times -1 + 2 \times -1 = 6$$

Convolved image

6		

=



Edge Detection with Convolution

10	10	10	0	0	0
10	10	10	0	0	0
10	10	10	0	0	0
10	10	10	0	0	0
10	10	10	0	0	0
10	10	10	0	0	0

--	--

 $*$

1	0	-1
1	0	-1
1	0	-1

--	--	--

 $=$

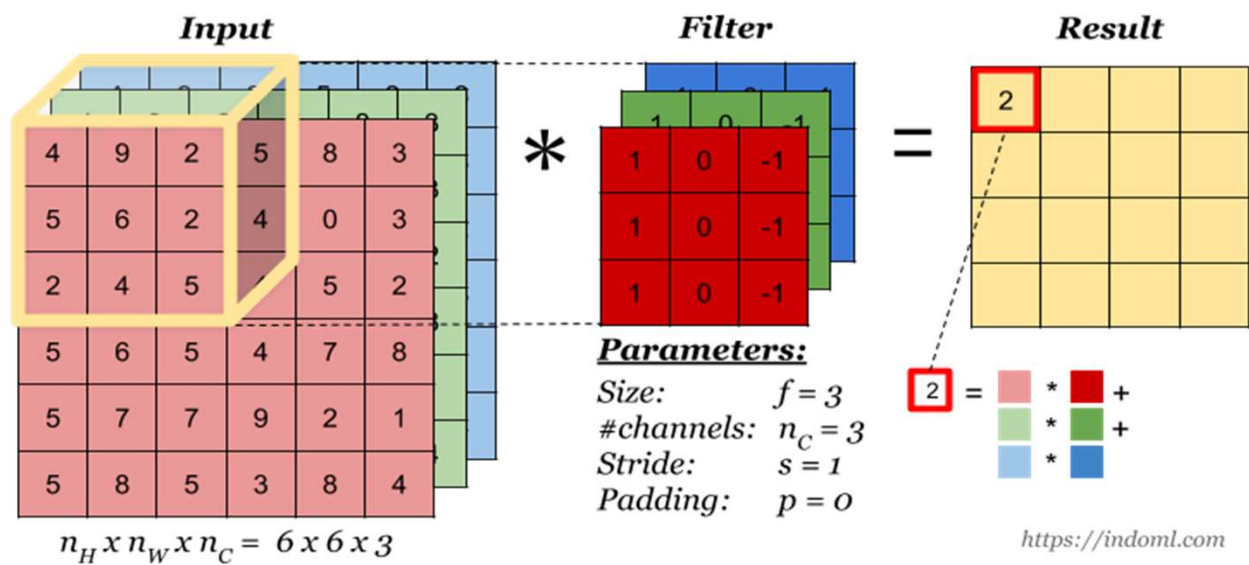
0	30	30	0
0	30	30	0
0	30	30	0
0	30	30	0

--	--	--

Vertical Edge Detection



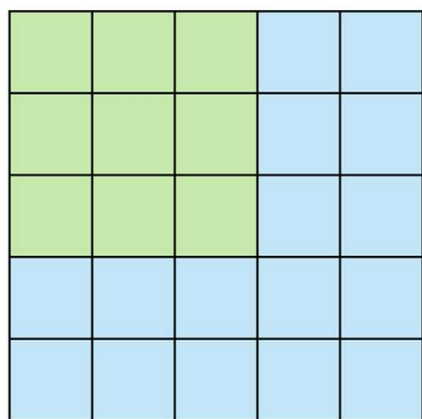
Convolution over Volumes



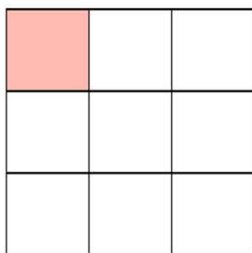
#of parameters: $3 \times 3 \times 3$



Stride

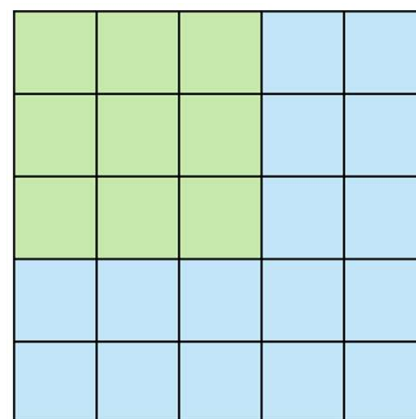


Stride 1

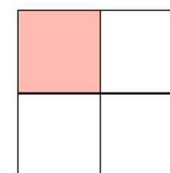


Feature Map

$5 \times 5 \rightarrow 3 \times 3$



Stride 2

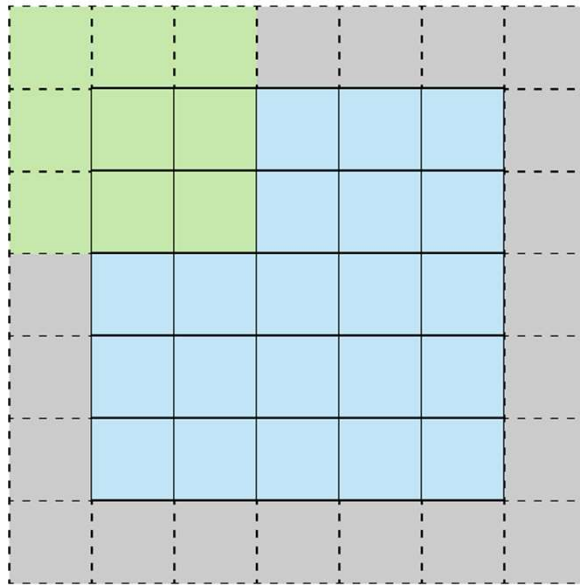


Feature Map

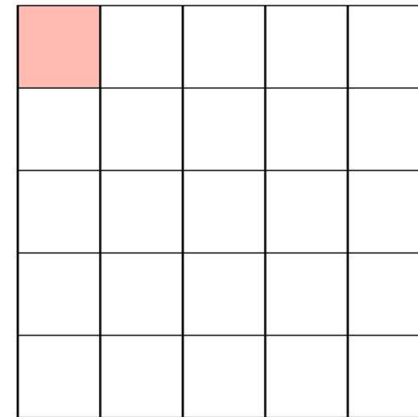
$5 \times 5 \rightarrow 2 \times 2$



Padding



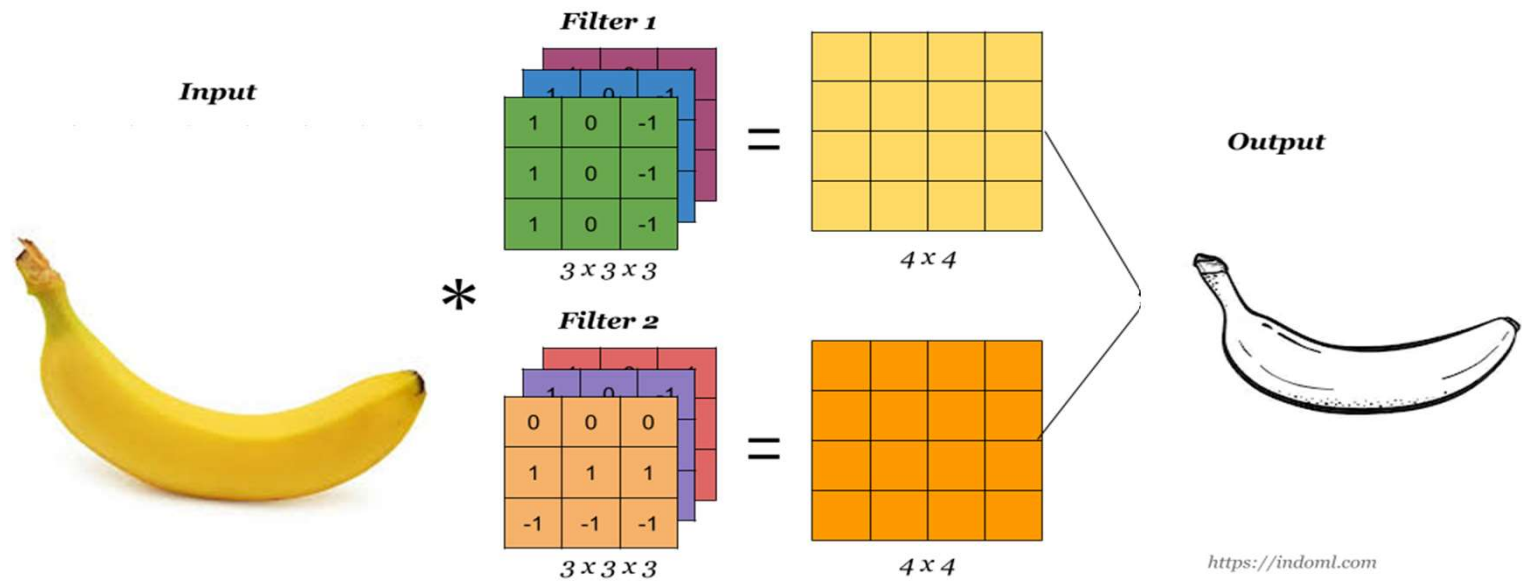
Stride 1 with Padding



Feature Map



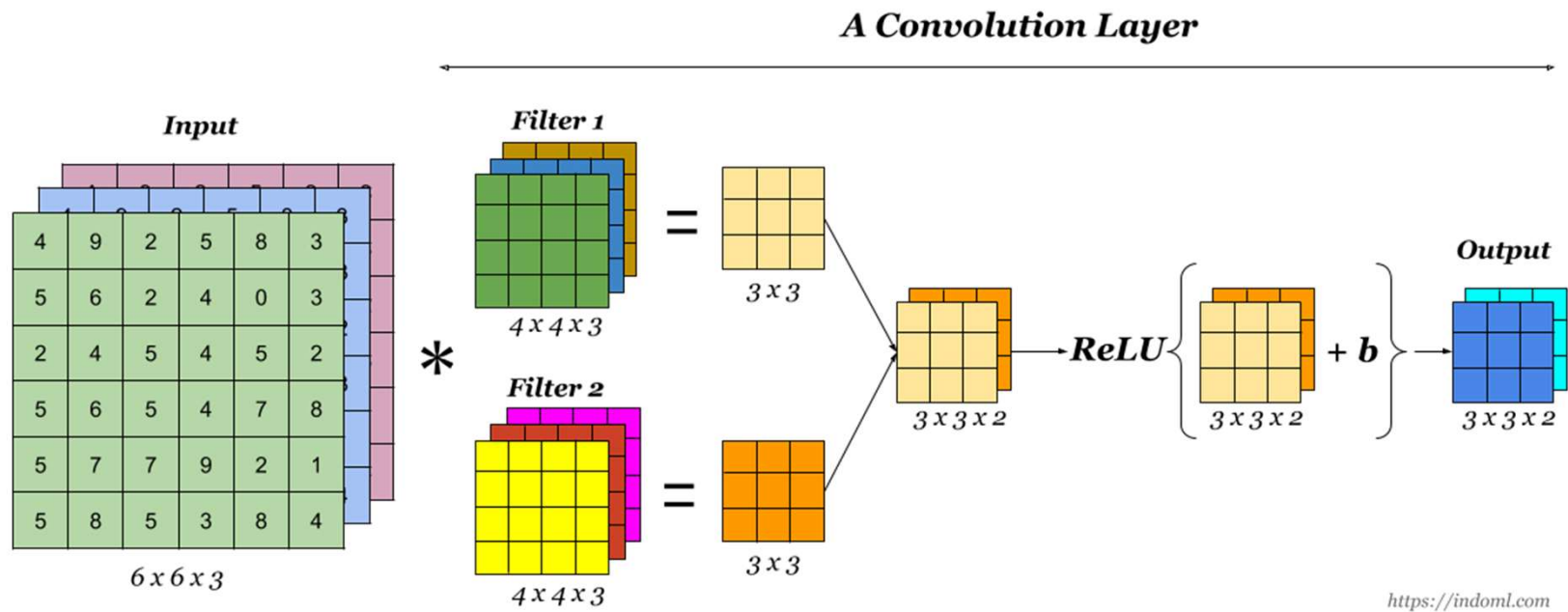
Convolution with multiple filters



of parameters: $3 \times 3 \times 3 \times 2$ (# of filters)



Convolution Layer



of parameters: $4 \times 4 \times 3 \times 2 + 1$ (bias)



Pattern Detection with Convolution



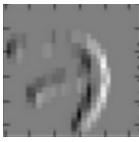
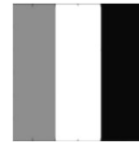
-1	-1	-1
1	1	1
0	0	0

-1	1	0
-1	1	0
-1	1	0

0	0	0
1	1	1
-1	-1	-1

0	1	-1
0	1	-1
0	1	-1

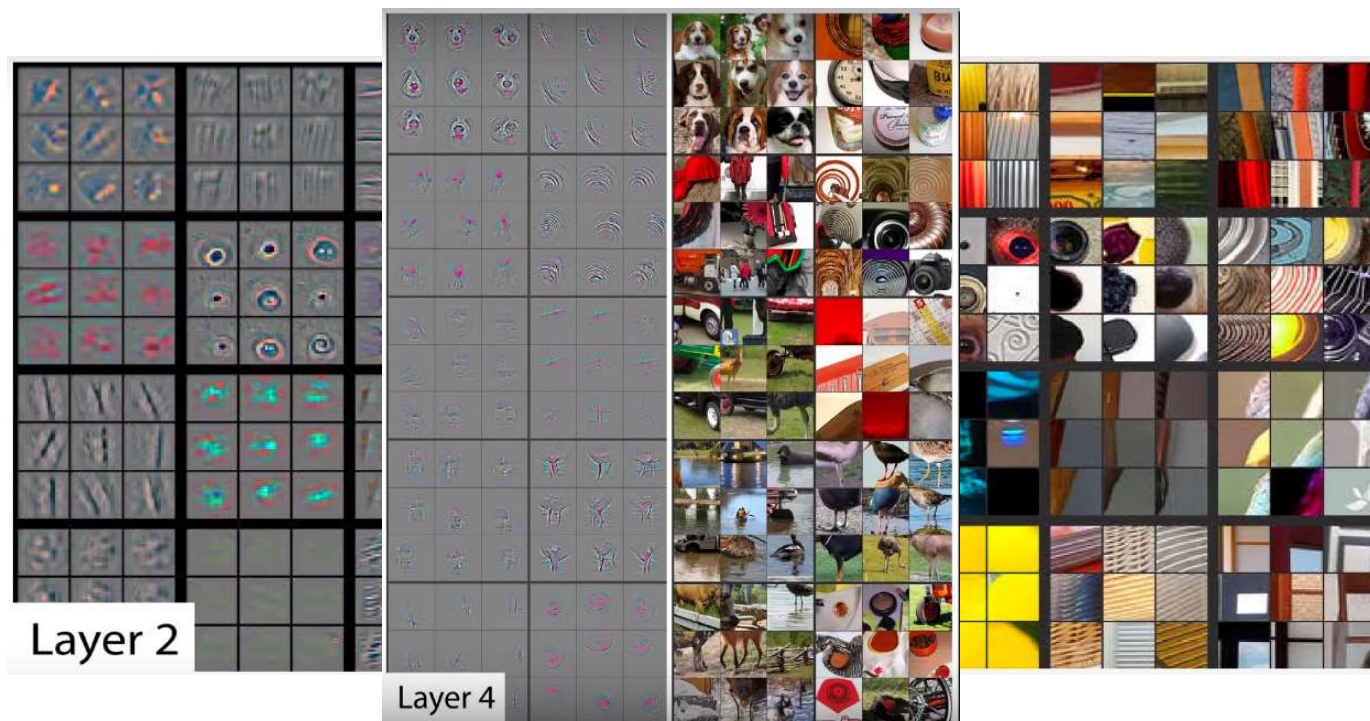
} Feature detectors



} Output activation maps



Pattern Detection with Convolution



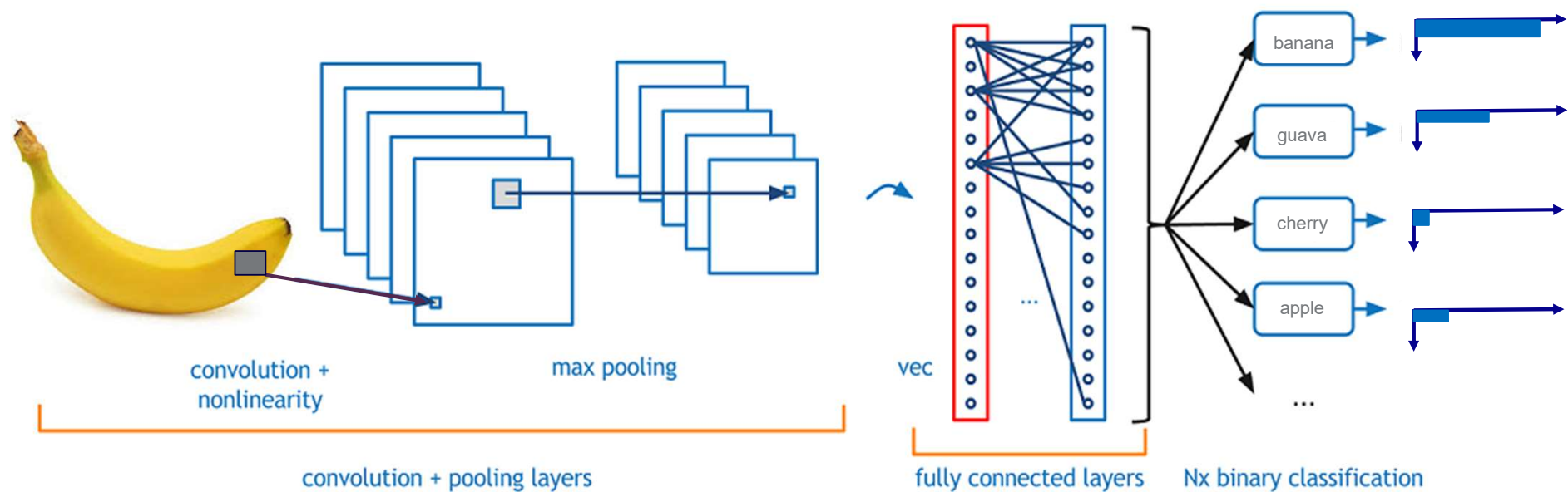
Convolution Hyperparameters

- Filter size and number of filters
- Type of padding
- Stride size

Small filter size (3X3, 5X5) with stride 1 and zeros padding

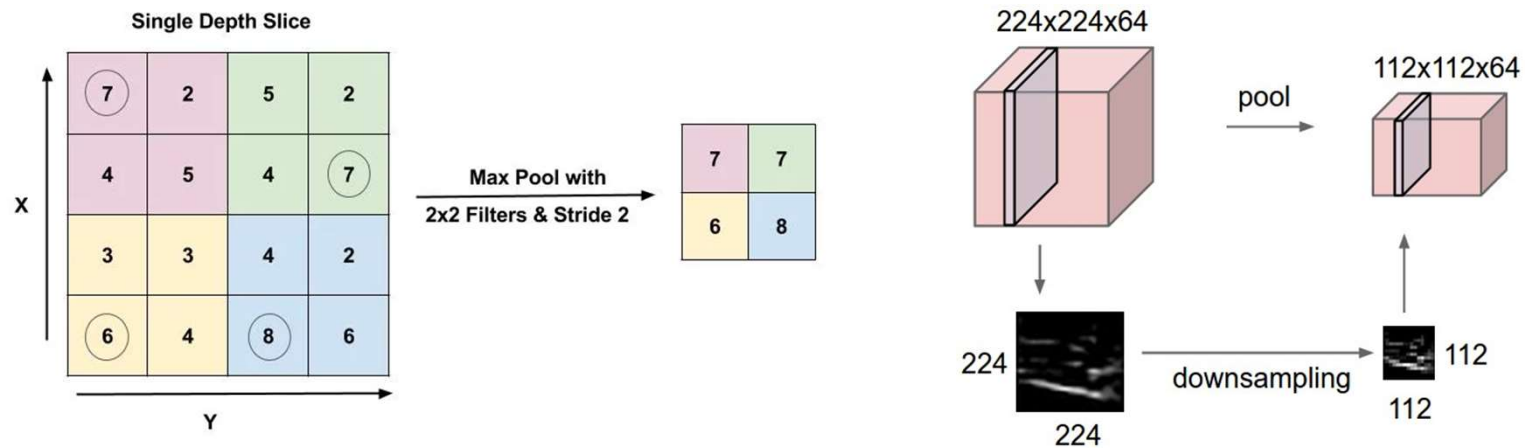


CNN Architecture

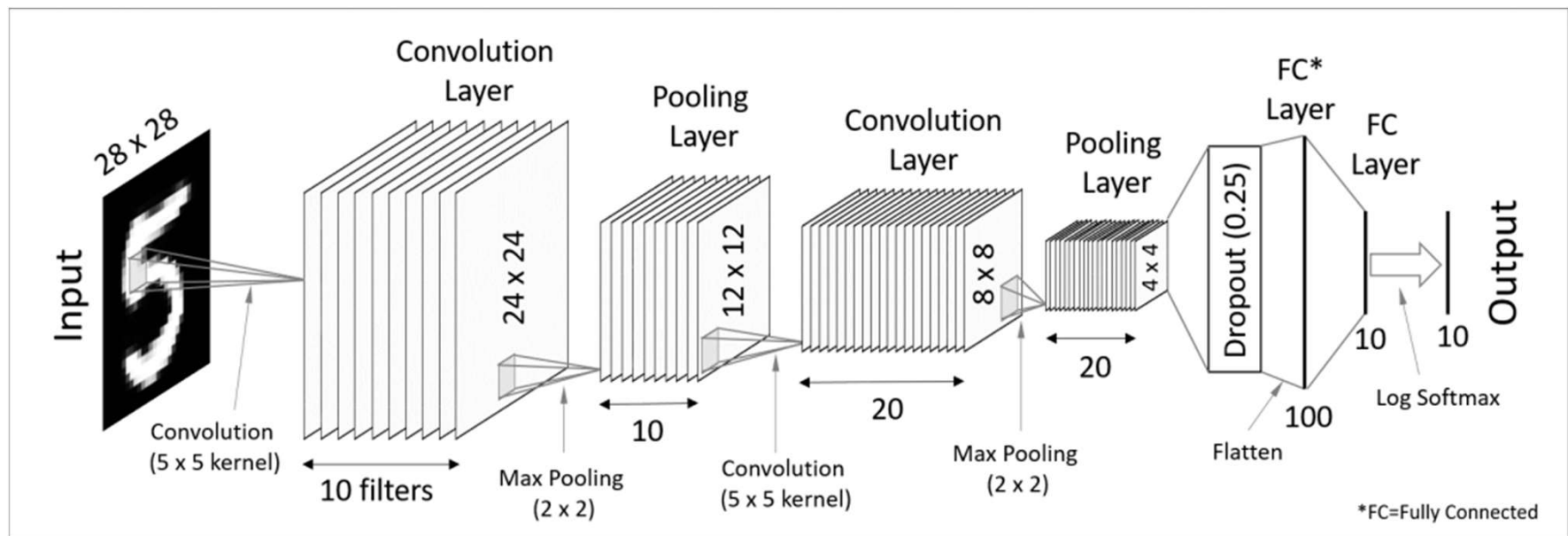


Pooling Layer

- Downsample the input to reduce parameters



End-to-End Network



CNN Hyperparameters

- Filter size and number of filters
- Padding type, stride size
- Pooling size and type
- Number of conv-pool layers, learning rate etc.

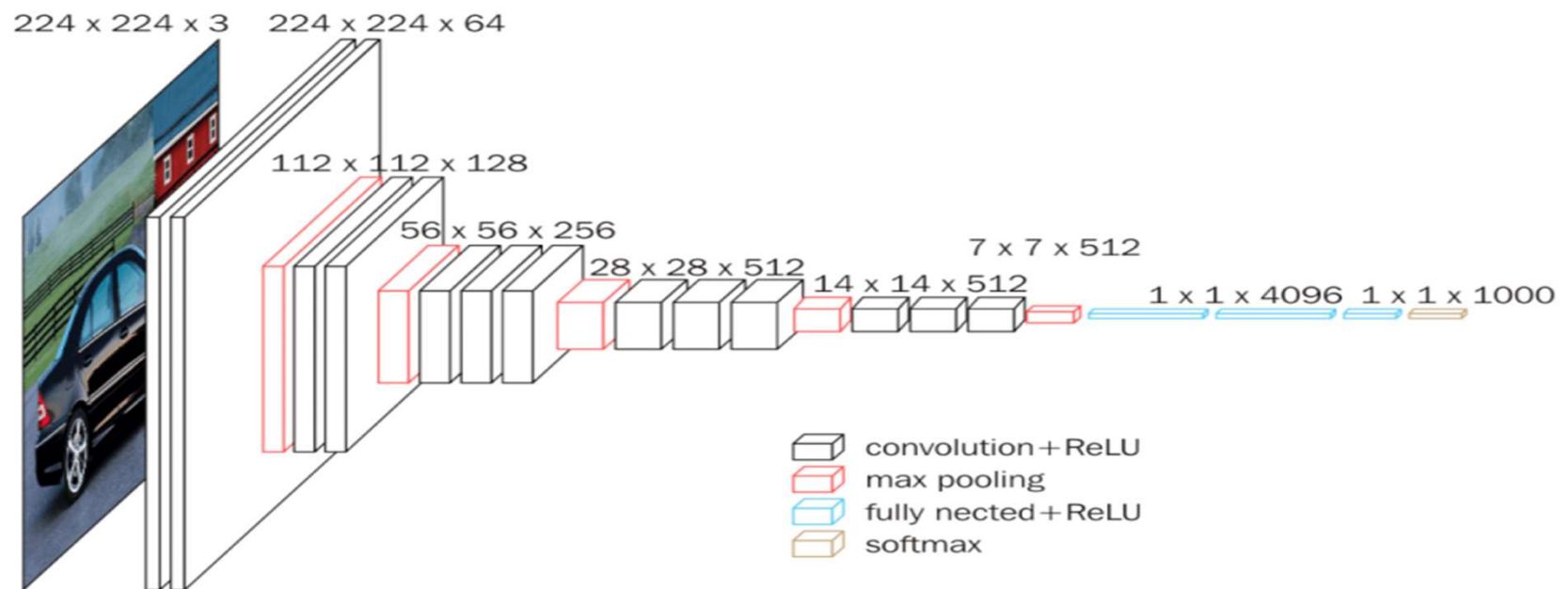


Classic CNN models

- VGG-16
- LeNet-5
- AlexNet



VGG-16 Architecture

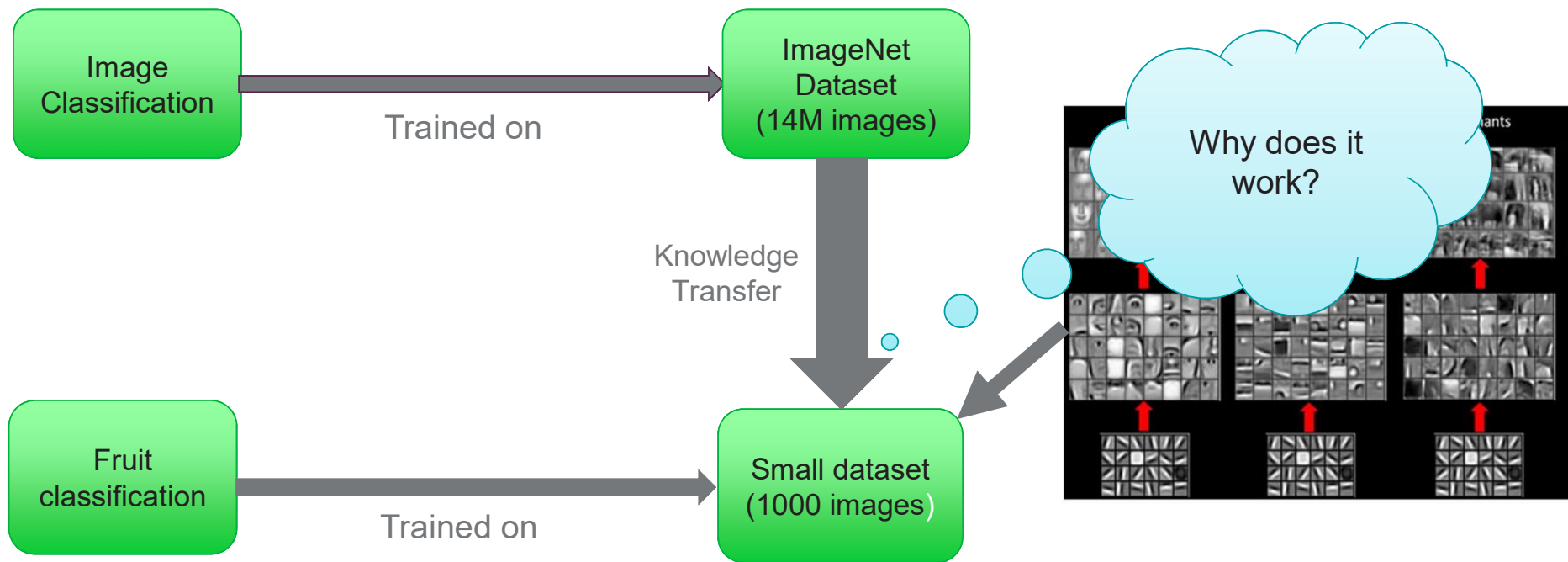


Improving CNN model

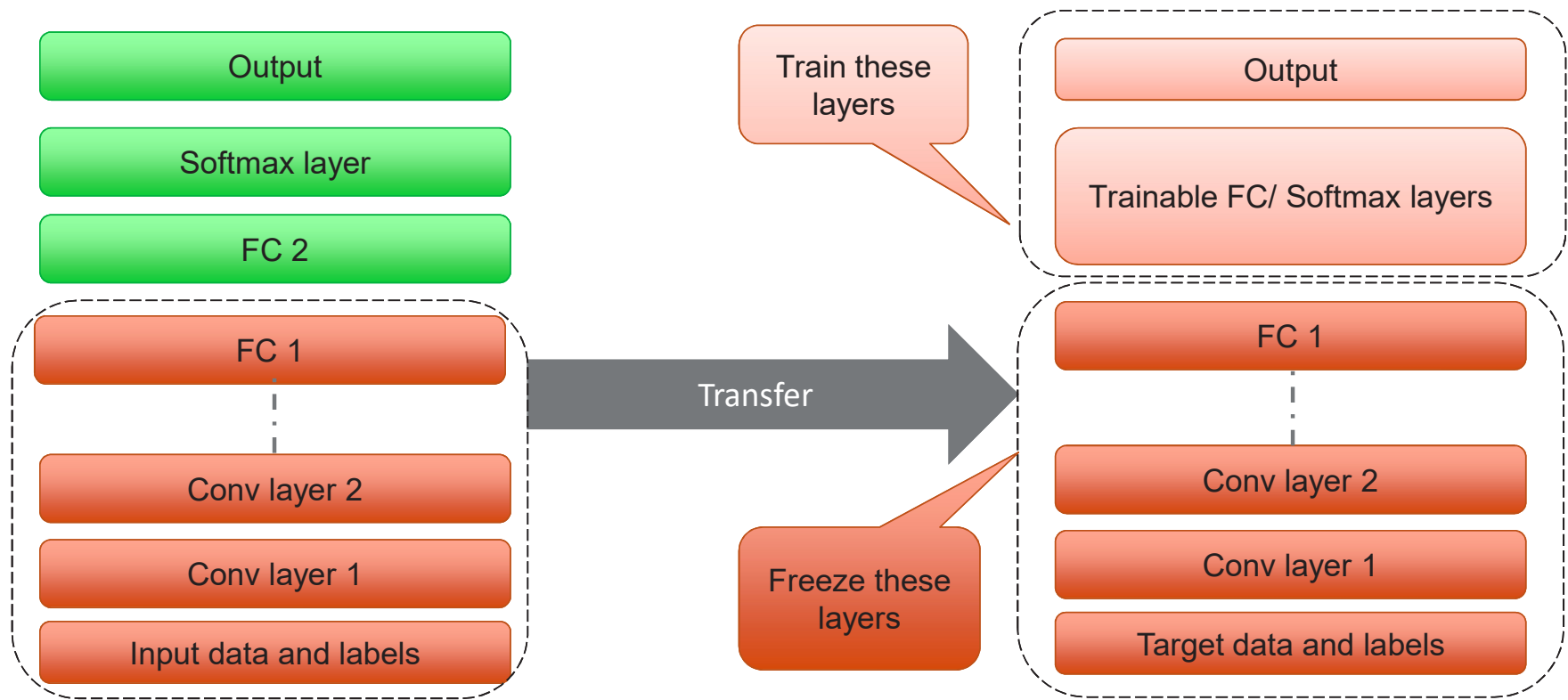
- Transfer learning
- Data augmentation



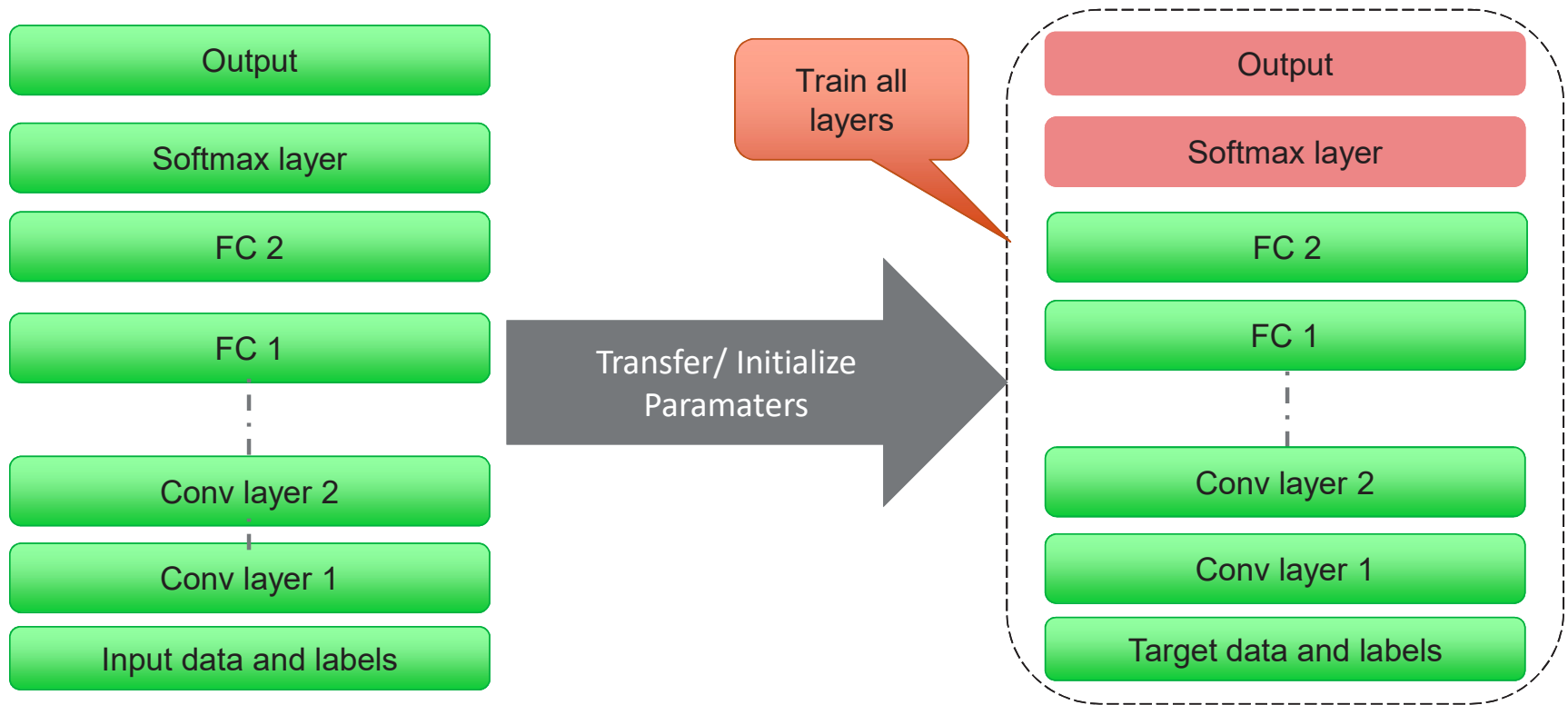
Transfer Learning



Transfer Learning scenarios – Feature extraction



Fine-Tuning Pre-trained model

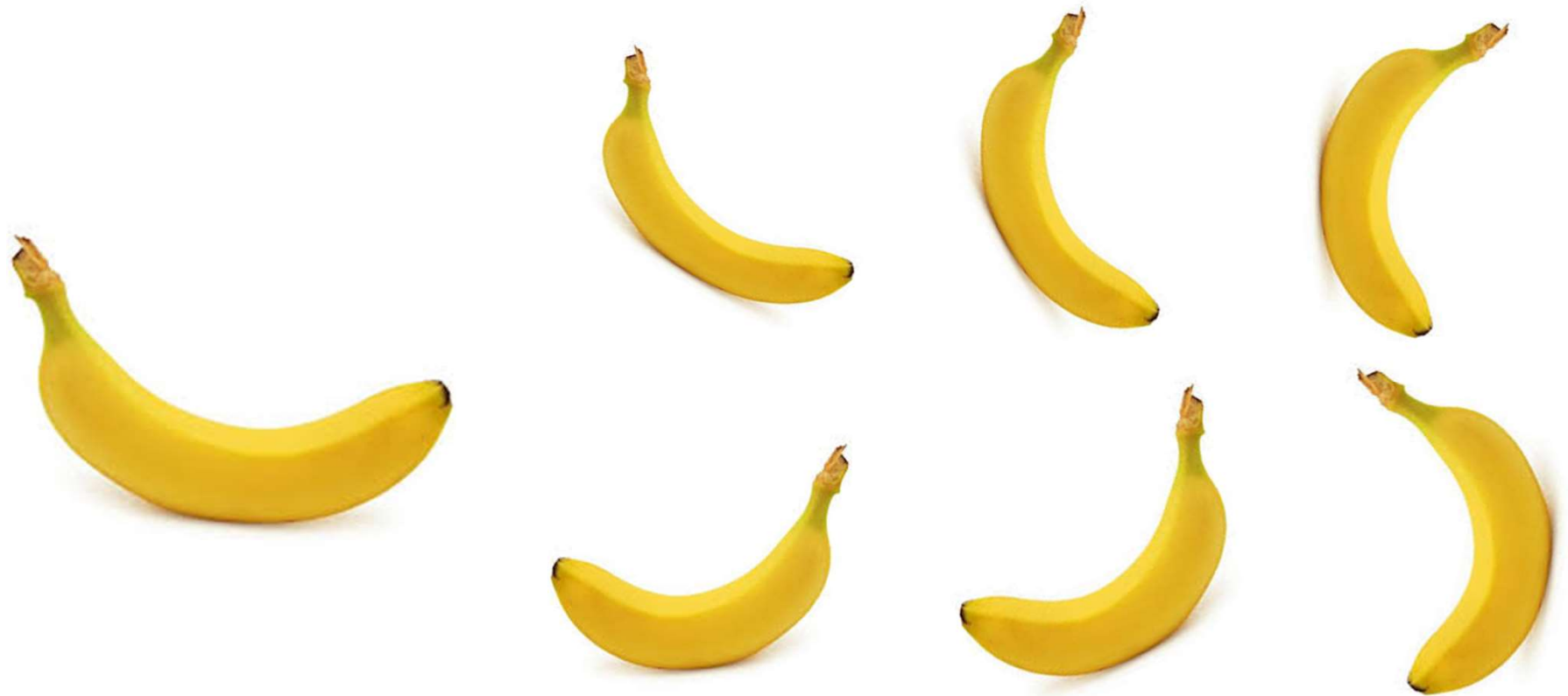


When to use transfer learning?

- Limited labeled data to train
- Availability of pre-trained model on similar data



Data Augmentation



Conclusion

- What is convolutional neural network.
- How it works.
- How to use pre-trained networks.



Any Questions?



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