

CptS/EE 555

Project #3 – Reliability with Sliding Window

Instructor: Adam Hahn
Due: 4/13/2019 at 11:59 pm
Points: 50

Deliverable:

Submit the code you developed and any information required to compile and run your program in a .zip/.rar/.gz to the class Blackboard page by the due date.

Test System:

Run your assignment in the `mininet` platform. Your system will run on a basic topology with two hosts, `h1` (IP: `10.0.0.1`), and `h2` (IP: `10.0.0.2`), which communicate through a switch, `s1`.

1. Download the `client_udp.c`, `server_udp.c`, `proj3_555.py` and `tux.txt` from the Github site.
2. Open three different terminal windows.
3. Start `mininet` in terminal #1 with the following command:

```
$ sudo mn -c
$ sudo mn --mac --switch ovsk --controller remote --link
tc,bw=100,delay=40ms
```

4. Now, download POX into your home directory and start the POX SDN controller in terminal #2 utilizing the custom controller program, `proj3_555.py`. Download the controller and copy into the correct directory:

```
$ git clone http://github.com/noxrepo/pox
$ mv proj3_555.py ~/pox/pox/misc/
```

Move to the “pox” directory and start the POX controller

```
$ cd pox
$ ./pox.py misc.proj3_555
```

Or, if `mininet` is listening on port 6653

```
$ ./pox.py openflow.of_01 --port=6653 misc.proj3_555
```

Verify that the controller connects to `mininet`, you should see the following output message:

```
INFO:core:POX 0.2.0 (carp) is up.  
INFO:openflow.of_01:[00-00-00-00-00-01 1] connected
```

5. Compile the template programs and verify that the environment works correctly. Compile the code in the terminal #3 with the following commands:

```
$ gcc -o client_udp client_udp.c  
$ gcc -o server_udp server_udp.c
```

6. Now go back to terminal #1 and run the compiled client and server code

```
mininet> h2 ./server_udp output.txt &  
mininet> h1 ./client_udp 10.0.0.2 tux.txt
```

7. In terminal 3, view the newly created `output.txt` file. To verify it sent correctly, you should use the `diff` command as follows, the results should be empty

```
diff tux.txt output.txt
```

Assignment:

The project will explore how to utilize C sockets to implement a reliable communication over a simulated unreliable link using a *Go-Back-N (GBN) sliding window algorithm* as discussed in class in C to send a text file one line at a time between a client and server using UDP. The template code will unreliably transmit a file from the client to the server using UDP, you must use only UDP to send packets.

Requirements:

- 1) Implement and send a sliding window of 10 lines from the input
- 2) Implement timeouts to resend after dropped packets
- 3) Implement sequence numbers and acknowledgements, ACK/SNs
- 4) Implement a dynamically estimated timeout interval, that will adjust based on measured RTT.

Hints:

The following suggestions may be helpful:

- 1) Timeouts: You may want to implement sockets that only block for a short period of time, therefore allowing you to resend a lost data frames. To do so, please utilize the `setsockopt()` function which enables you to set the amount of time the socket will block for during a `recvfrom()` call.

```
struct timeval tv;  
tv.tv_sec = 0;  
tv.tv_usec = 1000;
```

...

```

    if (setsockopt(s, SOL_SOCKET, SO_RCVTIMEO, &tv, sizeof(tv)) < 0) {
        perror("PError");
    }

```

- 2) Window Size=10: You should keep a sender buffer of 10 previous lines in case resends are needed.
- 3) Sequence Numbers & Acks: You'll need to use sequence numbers and acknowledgements, the number can just be represented by the first byte of each packet's payload.
- 4) Handle drops: The network will both randomly drop packets, so you should test and verify that your reliability mechanism can handle this.
- 5) Termination: To signal the termination of a connection, you can send a special sequence/acknowledgement number (e.g., 0xffff). It is possible that this message is also dropped, but don't worry about acknowledging it.
- 6) Max line lengths: You can safely assume that each line sends at most 80 characters
- 7) Timeout Estimation: As suggested in the Marsic book, timeout interval estimate can be performed using something similar to the following:

```

dev_rtt = .75 * dev_rtt + .25 * abs(rtt - estimated_rtt);
estimated_rtt = .9 * estimated_rtt + .1 * rtt;
timeout_interval = estimated_rtt + 4*dev_rtt;

```