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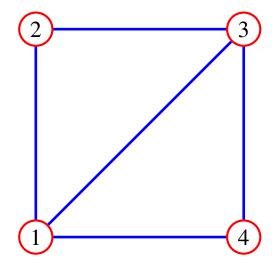
# 7. Spectral clustering

- Laplacian matrix
- graph partitioning
- spectral clustering

### **Undirected graph**

$$G = (V, E)$$

- V is a finite set of *vertices*; we will assume  $V = \{1, 2, ..., n\}$
- $E \subseteq \{\{i,j\} \mid i,j \in V\}$  is the set of (undirected) *edges*
- two vertices i and j are adjacent if  $\{i, j\} \in E$
- the *neighborhood*  $\mathcal{N}(i)$  of vertex i is the set of vertices adjacent to i



$$V = \{1,2,3,4\}$$

$$E = \{\{1,2\},\{1,3\},\{1,4\},\{2,3\},\{3,4\}\}\}$$

$$\mathcal{N}(4) = \{1,3\}$$

### **Edge weights**

**Weights:** each edge  $\{i, j\}$  has a positive weight  $W_{ij} = W_{ji}$ 

- if all the edge weights are one the graph is called unweighted
- we define  $W_{ij} = 0$  if i and j are not adjacent ( $\{i, j\}$  is not an edge) or if i = j
- ullet the symmetric matrix W with elements  $W_{ij}$  is the (weighted) adjacency matrix

edge weights express strength of connection, association, similarity of vertices

Degree: the degree of a vertex is the sum of the weights of the incident edges

$$\deg(i) = \sum_{j \in \mathcal{N}(i)} W_{ij} = \sum_{j=1}^{n} W_{ij} = (W\mathbf{1})_{i}$$

in the example on the previous page,  $deg(4) = W_{14} + W_{34}$ 

## **Graph Laplacian**

**Graph Laplacian:** the symmetric  $n \times n$  matrix

$$L = \operatorname{diag}(W1) - W$$

$$= \begin{bmatrix} \deg(1) & -W_{12} & \cdots & -W_{1n} \\ -W_{21} & \deg(2) & \cdots & -W_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ -W_{n1} & -W_{n2} & \cdots & \deg(n) \end{bmatrix}$$

Normalized graph Laplacian: includes a symmetric scaling of rows and columns

$$L_{\rm n} = {\rm diag}(W1)^{-1/2} L {\rm diag}(W1)^{-1/2}$$

normalized Laplacian has unit diagonal, off-diagonal elements

$$(L_{\rm n})_{ij} = \frac{-W_{ij}}{\sqrt{\deg(i)\deg(j)}}$$

## Laplacian as Gram matrix

the Laplacian can be written as a Gram matrix (page 2.17)

$$L = A \operatorname{diag}(w) A^T$$

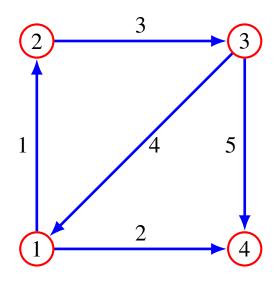
- we number the edges 1 to *m*
- we make the graph directed by giving each edge an (arbitrary) orientation
- A is the  $n \times m$  incidence matrix of the directed graph

$$A_{ik} = \begin{cases} -1 & \text{directed edge } k \text{ points from vertex } i \\ 1 & \text{directed edge } k \text{ points at vertex } i \\ 0 & \text{otherwise} \end{cases}$$

• *w* is the *m*-vector of edge weights

 $w_k = W_{ij}$  if edge k points from vertex j to vertex i

### **Example**



$$A = \begin{bmatrix} -1 & -1 & 0 & 1 & 0 \\ 1 & 0 & -1 & 0 & 0 \\ 0 & 0 & 1 & -1 & -1 \\ 0 & 1 & 0 & 0 & 1 \end{bmatrix}$$

$$A \operatorname{diag}(w) A^{T} = \begin{bmatrix} w_{1} + w_{2} + w_{4} & -w_{1} & -w_{4} & -w_{2} \\ -w_{1} & w_{1} + w_{3} & -w_{3} & 0 \\ -w_{4} & -w_{3} & w_{3} + w_{4} + w_{5} & -w_{5} \\ -w_{2} & 0 & -w_{5} & w_{2} + w_{5} \end{bmatrix}$$

$$= \begin{bmatrix} \deg(1) & -W_{12} & -W_{13} & -W_{14} \\ -W_{21} & \deg(2) & -W_{23} & -W_{24} \\ -W_{31} & -W_{32} & \deg(3) & -W_{34} \\ -W_{41} & -W_{42} & -W_{43} & \deg(4) \end{bmatrix}$$

### Laplacian quadratic form

$$x^{T}Lx = \sum_{\{i,j\} \in E} W_{ij}(x_i - x_j)^2$$

(see derivation on next page)

- x is an n-vector, x<sub>i</sub> is a scalar quantity associated with vertex i
- $x^T L x$  is small if entries of x at adjacent vertices are close to each other
- each edge appears once in this sum
- other equivalent expressions are

$$x^{T}Lx = \sum_{i=1}^{n} \sum_{j=i+1}^{n} W_{ij}(x_{i} - x_{j})^{2}$$
$$= \frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} W_{ij}(x_{i} - x_{j})^{2}$$

the formula for  $x^T L x$  can be verified in several ways

• from the definition  $L = \operatorname{diag}(W1) - W$ :

$$x^{T}Lx = \sum_{i=1}^{n} (\sum_{j=1}^{n} W_{ij}) x_{i}^{2} - \sum_{i=1}^{n} \sum_{j=1}^{n} W_{ij} x_{i} x_{j}$$

$$= \sum_{i=1}^{n} \sum_{j=1}^{n} W_{ij} (x_{i}^{2} - x_{i} x_{j})$$

$$= \sum_{i=1}^{n} \sum_{j=i+1}^{n} W_{ij} (x_{i}^{2} - 2x_{i} x_{j} + x_{j}^{2})$$

$$= \sum_{i=1}^{n} \sum_{j=i+1}^{n} W_{ij} (x_{i} - x_{j})^{2}$$

• from the Gram matrix expression  $L = A \operatorname{diag}(w)A^T$ :

$$x^{T}Lx = \sum_{k=1}^{m} w_{k} (A^{T}x)_{k}^{2} = \sum_{k=1}^{m} w_{k} (x_{i_{k}} - x_{j_{k}})^{2}$$

if in the directed graph edge k is oriented from vertex  $j_k$  to  $i_k$ 

#### **Matrix extension**

suppose X is an  $n \times p$  matrix with rows  $x_1^T, \ldots, x_n^T$ 

trace
$$(X^T L X) = \sum_{\{i,j\} \in E} W_{ij} ||x_i - x_j||^2$$

- here we associate a vector  $x_i$  with vertex i
- $trace(X^TLX)$  is small if distances of vectors at adjacent vertices are small
- follows from formula for Laplacian quadratic form applied to the columns of X:

trace
$$(X^T L X) = \sum_{k=1}^{p} (X e_k)^T L (X e_k) = \sum_{k=1}^{p} \sum_{\{i,j\} \in E} W_{ij} (X_{ik} - X_{jk})^2$$

other expressions:

trace(
$$X^T L X$$
) =  $\sum_{i=1}^{n} \sum_{j=i+11}^{n} W_{ij} ||x_i - x_j||^2$   
 =  $\frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{n} W_{ij} ||x_i - x_j||^2$ 

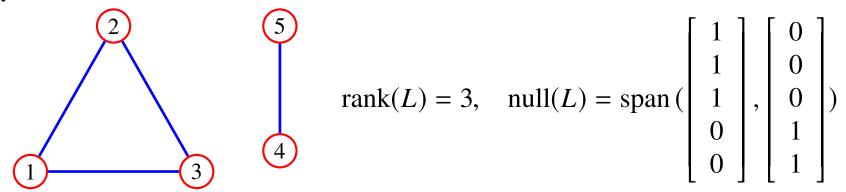
### Rank and nullspace

the following properties were shown in lecture 2 and homework 1

- the graph Laplacian *L* is positive semidefinite
- the rank of *L* is *n* minus the number of connected components in the graph
- if the graph is connected, the nullspace of L is spanned by the n-vector 1
- if the graph has c connected components, nullspace is  $\mathrm{span}\,(y_1,\ldots,y_c)$ , where

$$(y_k)_i = \begin{cases} 1 & \text{vertex } i \text{ is in connected component } k \\ 0 & \text{otherwise} \end{cases}$$

#### **Example**



## **Outline**

- Laplacian matrix
- graph partitioning
- spectral clustering

### **Vertex partition**

### **Vertex partition**

• a vertex partition is a collection of nonempty subsets  $V_1, \ldots, V_K$  of V with

$$V = V_1 \cup \cdots \cup V_K$$
,  $V_i \cap V_j = \emptyset$  for  $i \neq j$ 

• a partition with two subsets  $V_1$  and  $V_2 = V \setminus V_1$  is called a *cut* 

#### Value of a cut

$$\operatorname{cut}(V_k) = \sum_{i \in V_k, j \notin V_k} W_{ij}$$

- ullet sum of the weights of the edges connecting vertices in  $V_k$  to vertices outside  $V_k$
- with this notation, the total weight of edges between subsets of the partition is

$$\frac{1}{2} \sum_{k=1}^{K} \operatorname{cut}(V_k)$$

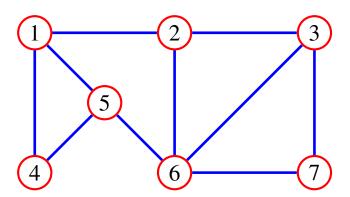
### Weight of a subgraph

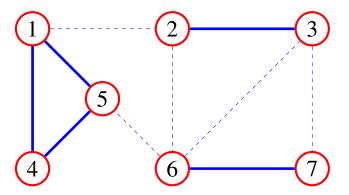
- we give a positive weight  $d_i$  to each vertex i
- the total weight of a subset  $V_k$  in the partition is denoted by

$$\operatorname{size}(V_k) = \sum_{i \in V_k} d_i$$

- if  $d_i = 1$ , then  $size(V_k)$  is simply the number of vertices in  $V_k$
- another common choice of vertex weight is the degree:  $d_i = \deg(i)$

### **Example**





vertex partition with three sets  $V_1 = \{1, 4, 5\}, V_2 = \{2, 3\}, V_3 = \{6, 7\}$ 

$$cut(V_1) = W_{12} + W_{56}$$

$$cut(V_2) = W_{12} + W_{26} + W_{36} + W_{37}$$

$$cut(V_3) = W_{56} + W_{26} + W_{36} + W_{37}$$
  $size(V_3) = d_6 + d_7$ 

$$size(V_1) = d_1 + d_4 + d_5$$

$$size(V_2) = d_2 + d_3$$

$$size(V_3) = d_6 + d_7$$

### **Clustering objective**

to evaluate the quality of a partition  $V_1, \ldots, V_k$  we define the cost function

$$\sum_{k=1}^{K} \frac{\operatorname{cut}(V_k)}{\operatorname{size}(V_k)}$$

- $\operatorname{cut}(V_k)$  is the total weight of edges between  $V_k$  and  $V \setminus V_k$
- dividing by  $size(V_k)$  discourages using small sets  $V_k$  in the partition
- with vertex weights  $d_i = 1$ , this is called the *ratio cut* objective
- with vertex weights  $d_i = \deg(i)$ , it is called the *normalized cut* objective

- finding a partition with minimum cost is a hard combinatorial problem
- spectral clustering uses eigendecompositions to find approximate solutions

## **Outline**

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### **Indicator vector**

#### Indicator vector

- an *n*-vector with elements 0 and 1
- indicator vector x indicates membership of a subset  $S \subseteq V$ :

$$x_i = \left\{ \begin{array}{ll} 1 & i \in S \\ 0 & i \notin S \end{array} \right.$$

#### **Normalization**

- we'll call a positive multiple of an indicator vector a scaled indicator vector
- the scaling of a scaled indicator vector *x* will be defined via a normalization

$$x^{T} \operatorname{diag}(d)x = \sum_{i=1}^{n} d_{i}x_{i}^{2} = 1$$

• with this normalization (and using notation size(S) =  $\sum_{i \in S} d_i$ ),

$$x_i = \begin{cases} 1/\sqrt{\operatorname{size}(S)} & i \in S \\ 0 & i \notin S \end{cases}$$

### **Indicator matrix**

we represent a vertex partition by an  $n \times K$  indicator matrix X:

- 1. columns are scaled indicator vectors (defining K subsets  $V_1, \ldots, V_K$  of V)
- 2. columns are scaled so that nonzero in column k is  $1/\sqrt{\operatorname{size}(V_k)}$

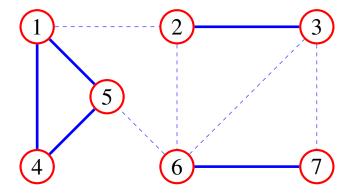
$$X_{ik} = \begin{cases} 1/\sqrt{\operatorname{size}(V_k)} & i \in V_k \\ 0 & \text{otherwise} \end{cases}$$

- 3. columns are mutually orthogonal  $(V_i \cap V_j = \emptyset \text{ for } i \neq j)$
- 4. no row is zero  $(V_1 \cup \cdots \cup V_K = V)$

if property 1 holds, properties 2 and 3 can be summarized as

$$X^T \operatorname{diag}(d)X = I$$

### **Example**



indicator matrix for this partition, with unit vertex weights  $d_i = 1$ 

$$X = \begin{bmatrix} 1/\sqrt{3} & 0 & 0\\ 0 & 1/\sqrt{2} & 0\\ 0 & 1/\sqrt{2} & 0\\ 1/\sqrt{3} & 0 & 0\\ 1/\sqrt{3} & 0 & 0\\ 0 & 0 & 1/\sqrt{2}\\ 0 & 0 & 1/\sqrt{2} \end{bmatrix}$$

### **Clustering objective**

suppose X is an indicator matrix (satisfying the four properties on page 7.16)

• if  $x_i^T$  and  $x_j^T$  are two rows of X, then

$$||x_i - x_j||^2 = \begin{cases} 0 & \text{vertices } i \text{ and } j \text{ are in the same subset} \\ \frac{1}{\text{size}(V_k)} + \frac{1}{\text{size}(V_l)} & i \in V_k, j \in V_l, \text{ and } k \neq l \end{cases}$$

• the clustering objective of page 7.14 can be written as  $trace(X^TLX)$ :

trace(
$$X^T L X$$
) = 
$$\sum_{\{i,j\} \in E} W_{ij} ||x_i - x_j||^2$$
= 
$$\sum_{k=1}^K \sum_{i \in V_k, j \notin V_k} \frac{W_{ij}}{\text{size}(V_k)}$$
= 
$$\sum_{k=1}^K \frac{\text{cut}(V_k)}{\text{size}(V_k)}$$

### **Optimal partition**

to summarize, optimal partitions are solutions X of the optimization problem

minimize  $\operatorname{trace}(X^T L X)$ 

subject to  $X^T \operatorname{diag}(d)X = I$ 

columns of *X* are scaled indicator vectors

X has no zero rows

- the  $n \times K$  matrix X is an indicator matrix of the partition
- the second constraint makes this a difficult combinatorial problem
- to simplify the problem we omit the difficult constraints
- the simpler problem is called a *relaxation* of the difficult problem
- ullet we solve the relaxation and round its solution to a suboptimal indicator matrix X

### Spectral clustering for ratio cut objective

first consider the relaxed problem with vertex weights  $d_i = 1$ :

minimize 
$$\operatorname{trace}(X^T L X)$$
  
subject to  $X^T X = I$ 

solution follows from eigendecomposition of Laplacian

$$L = Q\Lambda Q^T = \sum_{i=1}^n \lambda_i q_i q_i^T$$

ullet columns of optimal  $\tilde{X}$  are last K eigenvectors (for smallest K eigenvalues):

$$X = \left[ \begin{array}{ccc} q_{n-K+1} & \cdots & q_n \end{array} \right]$$

• if the graph is connected, 1 is in the range of X, so X has no zero rows

optimal solution of relaxed problem is not necessarily a valid indicator matrix

### *k*-means rounding

to find a valid partition  $V_1, \ldots, V_K$  from the solution X of the relaxed problem:

- apply the k-means algorithm (with k = K) to the n rows of X
- the result is a clustering of the rows in K groups with representatives  $s_1, \ldots, s_K$
- assign vertex i to set  $V_k$  if row i of X is assigned to the cluster of  $s_k$

### Motivation for k-means rounding

the k-means rounding method may be justified as follows

• *k*-means applied to the rows of *X* computes an approximate factorization

$$X \approx \tilde{X}\tilde{S}$$

- $\tilde{X}$  is an  $n \times K$  indicator matrix (elements in column k are 0 and  $1/\sqrt{\operatorname{size}(V_k)}$ )
- $\tilde{S}$  is a  $K \times K$  matrix; rows are scaled representatives  $\sqrt{\operatorname{size}(V_k)} s_k^T$
- since  $X^TX = I$ , the matrix  $\tilde{S}$  is approximately orthogonal:

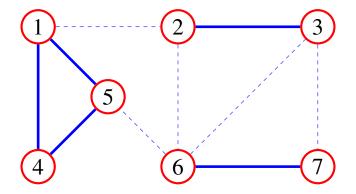
$$I = X^T X \approx \tilde{S}^T \tilde{X}^T \tilde{X} \tilde{S} = \tilde{S}^T \tilde{S}$$

ullet therefore  $ilde{X} pprox X ilde{S}^T$  is an indicator matrix with clustering objective

$$\operatorname{trace}(\tilde{X}^T L \tilde{X}) \approx \operatorname{trace}(\tilde{S} X^T L X \tilde{S}^T) \approx \operatorname{trace}(X^T L X)$$

i.e., close to the optimal value of the relaxed optimization problem

### **Example**



suppose k-means applied to the rows of the solution X of the relaxation gives

$$X \approx \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} s_1^T \\ s_2^T \\ s_3^T \end{bmatrix} = \tilde{X}\tilde{S}, \quad \tilde{X} = \begin{bmatrix} 1/\sqrt{3} & 0 & 0 \\ 0 & 1/\sqrt{2} & 0 \\ 0 & 1/\sqrt{2} & 0 \\ 1/\sqrt{3} & 0 & 0 \\ 1/\sqrt{3} & 0 & 0 \\ 0 & 0 & 1/\sqrt{2} \\ 0 & 0 & 1/\sqrt{2} \end{bmatrix}, \quad \tilde{S} = \begin{bmatrix} \sqrt{3}s_1^T \\ \sqrt{2}s_1^T \\ \sqrt{2}s_3^T \end{bmatrix}$$

we take partition indicated by  $\tilde{X}$  as approximate solution of partitioning problem

### Spectral clustering for normalized cut

the relaxed problem with vertex weights  $d_i = \deg(i)$  is

minimize 
$$\operatorname{trace}(X^T L X)$$
  
subject to  $X^T \operatorname{diag}(d)X = I$ 

- solution follows from generalized eigendecomposition of L,  $\operatorname{diag}(d)$
- solution is  $X = \operatorname{diag}(d)^{-1/2}Y$  where Y is the solution of

minimize 
$$\operatorname{trace}(Y^T L_n Y)$$
  
subject to  $Y^T Y = I$ 

and  $L_n$  is the normalized Laplacian (page 7.4)

$$L_{\rm n} = {\rm diag}(d)^{-1/2} L {\rm diag}(d)^{-1/2}$$

- columns of optimal Y are the last K eigenvectors of L<sub>n</sub>
- we can use k-means to round solution X of relaxation to valid indicator matrix

### **Example**

- participants in a study are asked to score 24 animals on a list of 764 properties
- the result is a 764 × 24 table of scores from 0 to 4

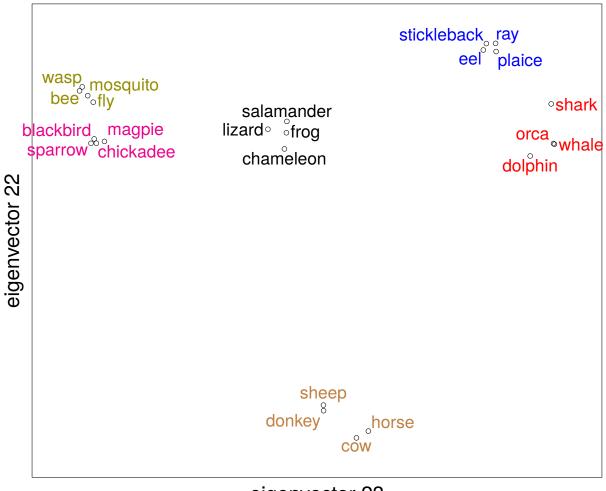
	bee	donkey	shark	frog	sparrow	
is dangerous	2	0	4	0	0	• • •
has a tail	0	4	2	1	2	• • •
lives in the woods	3	0	0	2	3	• • •
is beautiful	0	2	1	0	2	• • •
:	•	•	•	•	:	

- cosine similarities of columns give a semantic similarity between the 24 names
- we define a graph with 24 vertices and the cosine similarities as edge weights

<sup>&</sup>lt;sup>1</sup>Liuzzi, A. G. et al., Cross-modal representation of spoken and written word meaning in left pars triangularis, NeuroImage (2017).

### Spectral clustering with normalized ratio cut

- the figure shows the entries of the generalized eigenvectors 22 and 23 of L
- the six clusters are found by k-means with K=6



eigenvector 23

#### References

 Ulrike von Luxburg, A tutorial on spectral clustering, Statistics and Computing (2007).

the methods we discussed are algorithms 1 and 2 on page 399

Jianbo Shi and Jitendra Malik, Normalized cuts and image segmentation, IEEE
Transactions on Pattern Analysis and Machine Intelligence (2000).

discusses the generalized eigenvalue method for normalized cut objective

Spectral clustering 7.27