

Repast HPC  
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## **Chapter 1**

# **Repast HPC: A High-Performance Agent-Based Modeling Platform**

By Argonne National Laboratory, 2009-2013

### **1.1 What is Repast HPC?**

Repast HPC is an Agent-Based Modeling Platform in the spirit of Repast Symphony. Repast HPC, however, is designed for top-500 high-performance computing systems (supercomputers).



## Chapter 2

# Hierarchical Index

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## Chapter 3

# Class Index

### 3.1 Class List

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## Chapter 4

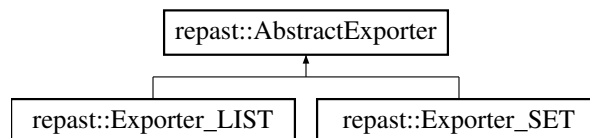
# Class Documentation

### 4.1 repast::AbstractExporter Class Reference

The 'Exporter' class is responsible for keeping a list of the agents that have been requested by other processes and whose data is to be sent to them when agents' states are synchronized, and for packaging and sending that data during synchronization.

```
#include <AgentImporterExporter.h>
```

Inheritance diagram for repast::AbstractExporter:



#### Public Types

- typedef std::map< int, std::set< [AgentStatus](#) > > **StatusMap**

#### Public Member Functions

- virtual void [registerIncomingRequests](#) (std::vector< [AgentRequest](#) > &requests)=0  
*Makes a record of the data receives (in the form of a vector of AgentRequests) so that the agents' data can be sent to the requesting processes.*
- virtual void [incorporateAgentExporterInfo](#) (std::map< int, [AgentRequest](#) \* > info)  
*The set of information received here comprises the information that some other process was using to export information about agents that are now being moved to this process.*
- virtual void [agentRemoved](#) (const [AgentId](#) &id)  
*1) Removes the agent export information from this process 2) Updates the outgoing status change buffer to include the status change for this agent to all procs to which this agent was being exported (except if one of these was the proc to which the agent is now moving; this is omitted)*
- virtual void [agentMoved](#) (const [AgentId](#) &id, int process)  
*1) Removes the agent export information from this process 2) Places a copy of the agent export information into the outgoing buffer 3) Updates the outgoing status change buffer to include the status change for this agent to all procs to which this agent was being exported (except if one of these was the proc to which the agent is now moving; this is omitted)*
- virtual const std::set< int > & [getProcessesExportedTo](#) ()

- Gets the list of processes this exporter is sending information to.*

  - AgentExporterInfo \* [getAgentExportInfo](#) (int destProc)

*Gets the export information that has been placed into the 'outgoing agent export information' buffer because agents that were being exported are being sent to a new process, for the specified process.*
- const StatusMap \* [getOutgoingStatusChanges](#) ()

*Gets the set of status changes for the exported agents.*
- void [clearAgentExportInfo](#) ()

*Clears the outgoing agent export information buffer; should be called after the information is sent.*
- void [clearStatusMap](#) ()

*Clears the outgoing status information buffer; should be called after the information is sent.*
- virtual const std::map< int, [AgentRequest](#) > & [getAgentsToExport](#) ()

*Gets the list of agents being exported by this exported, as a map by ints representing the processes to which information will be sent.*
- **AbstractExporter** (StatusMap \*outgoingStatusMap, [AgentExporterData](#) \*outgoingAgentExporterInfo)
- virtual std::string [getReport](#) ()=0

*Gets a printable report of the state of this object.*
- virtual void **clear** ()
- virtual void **clearExportToSpecificProc** (int rank)

## Protected Attributes

- StatusMap \* **outgoingStatusChanges**
- [AgentExporterData](#) \* **outgoingAgentExporterInformation**
- std::set< int > **processesExportedTo**
- std::map< int, [AgentRequest](#) > **exportedMap**

### 4.1.1 Detailed Description

The 'Exporter' class is responsible for keeping a list of the agents that have been requested by other processes and whose data is to be sent to them when agents' states are synchronized, and for packaging and sending that data during synchronization.

It is also responsible for exchanging this 'export' information when any of the agents that it is exporting are being moved to other processes; when an agent moves, its new home process must be able to assume the same export duties that its original process was performing.

### 4.1.2 Member Function Documentation

#### 4.1.2.1 void AbstractExporter::incorporateAgentExporterInfo ( std::map< int, [AgentRequest](#) \* > *info* ) [virtual]

The set of information received here comprises the information that some other process was using to export information about agents that are now being moved to this process.

This method takes that information and incorporates it into this exporter, so that this exporter can now export the agents' information to the processes that have requested it.

The documentation for this class was generated from the following files:

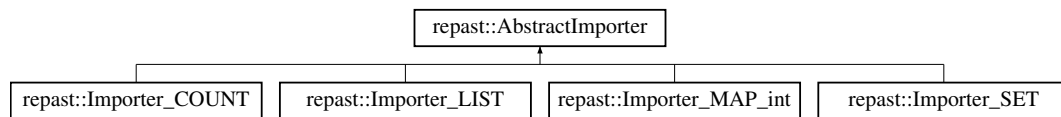
- repast\_hpc/AgentImporterExporter.h
- repast\_hpc/AgentImporterExporter.cpp

## 4.2 repast::AbstractImporter Class Reference

This class manages importing agent information; primarily this means constructing the appropriate mpi receives when agent information is to be exchanged.

```
#include <AgentImporterExporter.h>
```

Inheritance diagram for repast::AbstractImporter:



### Public Member Functions

- virtual const std::set< int > & [getExportingProcesses](#) ()  
*Gets a const reference to the set of ints representing the processes that are sending this process agent information.*
- virtual void [registerOutgoingRequests](#) ([AgentRequest](#) &req)=0  
*Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.*
- virtual void [importedAgentsRemoved](#) (const [AgentId](#) &id)=0  
*Notifies this importer that the agent that it (presumably) has been importing has been removed from the simulation on its home process, and the information for that agent will no longer be sent.*
- virtual void [importedAgentsMoved](#) (const [AgentId](#) &id, int newProcess)=0  
*Notifies this importer that the agent that it (presumably) has been importing from another process has been moved; its information will now be received from its new home process (unless the agent was moved to this process)*
- void [importedAgentsNowLocal](#) (const [AgentId](#) &id)  
*Some semantic sugar; operationally this is the same as 'importedAgentsRemoved'.*
- virtual std::string [getReport](#) ()=0  
*Get a printable indication of the data in this object.*
- virtual void [getSetOfAgentsBeingImported](#) (std::set< [AgentId](#) > &set)=0
- virtual void [clear](#) ()

### Protected Attributes

- std::set< int > [exportingProcesses](#)

#### 4.2.1 Detailed Description

This class manages importing agent information; primarily this means constructing the appropriate mpi receives when agent information is to be exchanged.

However, this class can also define specific semantics that can apply to agent requests- what to do in the case that an agent is requested twice, for example.

#### 4.2.2 Member Function Documentation

##### 4.2.2.1 virtual void repast::AbstractImporter::registerOutgoingRequests ( [AgentRequest](#) & req ) [pure virtual]

Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.

The record must at a minimum indicate which other processes are sending agent information, but may include other information, such as how many times a particular agent has been requested.

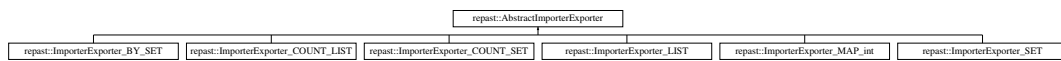
Implemented in [repass::Importer\\_MAP\\_int](#), [repass::Importer\\_SET](#), [repass::Importer\\_LIST](#), and [repass::Importer\\_COUNT](#).

The documentation for this class was generated from the following files:

- [repass\\_hpc/AgentImporterExporter.h](#)
- [repass\\_hpc/AgentImporterExporter.cpp](#)

### 4.3 repass::AbstractImporterExporter Class Reference

Inheritance diagram for [repass::AbstractImporterExporter](#):



#### Public Member Functions

- **AbstractImporterExporter** ([AbstractImporter](#) \*i, [AbstractExporter](#) \*e)
- virtual const std::set< int > & **getExportingProcesses** ()
- virtual void **registerOutgoingRequests** ([AgentRequest](#) &req)
- virtual void **importedAgentsRemoved** (const [AgentId](#) &id)
- virtual void **importedAgentsMoved** (const [AgentId](#) &id, int newProcess)
- virtual void **importedAgentsNowLocal** (const [AgentId](#) &id)
- virtual void **getSetOfAgentsBeingImported** (std::set< [AgentId](#) > &set)
- virtual const  
AbstractExporter::StatusMap \* **getOutgoingStatusChanges** ()
- virtual const std::set< int > & **getProcessesExportedTo** ()
- virtual void **registerIncomingRequests** (std::vector< [AgentRequest](#) > &requests)
- virtual void **agentRemoved** (const [AgentId](#) &id)
- virtual void **agentMoved** (const [AgentId](#) &id, int process)
- virtual void **incorporateAgentExporterInfo** (std::map< int, [AgentRequest](#) \* > info)
- virtual void **clearStatusMap** ()
- virtual [AgentExporterInfo](#) \* **getAgentExportInfo** (int destProc)
- virtual void **clearAgentExportInfo** ()
- virtual const std::map< int,  
[AgentRequest](#) > & **getAgentsToExport** ()
- virtual void **exchangeAgentStatusUpdates** (boost::mpi::communicator world, std::vector< std::vector< [Agent-Status](#) > \* > &statusUpdates)  
*Exchanges the contents of the 'statusMap' with the destination processes, updating the status (moved or removed) for all agents being exported.*
- virtual std::string **version** ()=0  
*Returns the version of this [AbstractImporterExporter](#).*
- virtual std::string **getReport** ()  
*Gets a printable report of the state of this object.*
- virtual void **clear** ()
- virtual void **clearExporter** ()
- virtual void **clearExportToSpecificProc** (int rank)

## Protected Attributes

- [AbstractImporter](#) \* **importer**
- [AbstractExporter](#) \* **exporter**

### 4.3.1 Member Function Documentation

4.3.1.1 void AbstractImporterExporter::exchangeAgentStatusUpdates ( boost::mpi::communicator *world*, std::vector< std::vector< [AgentStatus](#) > \* > & *statusUpdates* ) [virtual]

Exchanges the contents of the 'statusMap' with the destination processes, updating the status (moved or removed) for all agents being exported.

Returns this information in the statusUpdates vector.

The documentation for this class was generated from the following files:

- repast\_hpc/AgentImporterExporter.h
- repast\_hpc/AgentImporterExporter.cpp

## 4.4 repast::Agent Class Reference

Interface for agent classes.

```
#include <AgentId.h>
```

### Public Member Functions

- virtual [AgentId](#) & [getId](#) ()=0  
*Gets the [AgentId](#) for this [Agent](#).*
- virtual const [AgentId](#) & [getId](#) () const =0  
*Gets the [AgentId](#) for this [Agent](#).*

#### 4.4.1 Detailed Description

Interface for agent classes.

### 4.4.2 Member Function Documentation

4.4.2.1 virtual [AgentId](#)& repast::Agent::getId ( ) [pure virtual]

Gets the [AgentId](#) for this [Agent](#).

Returns

the [AgentId](#) for this [Agent](#).

4.4.2.2 virtual const [AgentId](#)& repast::Agent::getId ( ) const [pure virtual]

Gets the [AgentId](#) for this [Agent](#).

**Returns**

the [AgentId](#) for this [Agent](#).

The documentation for this class was generated from the following file:

- repast\_hpc/AgentId.h

## 4.5 repast::AgentExporterData Class Reference

Data structure for exporter data that is to be sent to other processes when the agents being exported are moved.

```
#include <AgentImporterExporter.h>
```

**Public Member Functions**

- void [addData](#) (const [AgentId](#) &id, const int destProc, const int sourceProc, const int numberOfCopies=1)  
*Adds an agent ID to this list of data that is being exported to a specific processor (destProc), so that the agent's information will be exported to another processor (sourceProc).*
- AgentExporterInfo \* [dataForProc](#) (int destProc)  
*Gets the packaged set of information to be sent to a specific processor.*
- void [clear](#) ()  
*Clears this data structure.*
- void [removeAllDataForAgent](#) ([AgentId](#) &id)  
*Remove all the data for a specific agent; useful when the agent is removed.*
- void [selectSet](#) (std::string setName)  
*Specifies that add and retrieve actions are to be performed on the subset of data identified by the given set name.*

### 4.5.1 Detailed Description

Data structure for exporter data that is to be sent to other processes when the agents being exported are moved.

Note that the internal data structure is protected; classes can use this data without knowing its actual internal structure.

### 4.5.2 Member Function Documentation

#### 4.5.2.1 void AgentExporterData::selectSet ( std::string setName )

Specifies that add and retrieve actions are to be performed on the subset of data identified by the given set name.

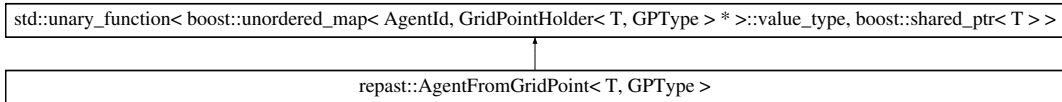
(Does not affect 'clear' or 'removeAllDataForAgent')

The documentation for this class was generated from the following files:

- repast\_hpc/AgentImporterExporter.h
- repast\_hpc/AgentImporterExporter.cpp

## 4.6 repast::AgentFromGridPoint< T, GPType > Struct Template Reference

Inheritance diagram for repast::AgentFromGridPoint< T, GPType >:



### Public Member Functions

- `boost::shared_ptr< T > operator()` (const typename boost::unordered\_map< [AgentId](#), [GridPointHolder](#)< T, GPType > \* >::value\_type &value) const

The documentation for this struct was generated from the following file:

- `repast_hpc/BaseGrid.h`

## 4.7 repast::AgentHashId< AgentType > Struct Template Reference

`operator()` implementation that returns the hashcode of an agent via its [AgentId](#).

```
#include <AgentId.h>
```

### Public Member Functions

- `std::size_t operator()` (const AgentType \*agent) const

#### 4.7.1 Detailed Description

```
template<typename AgentType>struct repast::AgentHashId< AgentType >
```

`operator()` implementation that returns the hashcode of an agent via its [AgentId](#).

The documentation for this struct was generated from the following file:

- `repast_hpc/AgentId.h`

## 4.8 repast::AgentId Class Reference

[Agent](#) identity information.

```
#include <AgentId.h>
```

### Public Member Functions

- [AgentId](#) ()  
*No-arg constructor necessary for serialization.*
- [AgentId](#) (int [id](#), int startProc, int [agentType](#), int currentProc=-1)  
*Creates an [AgentId](#).*
- int [id](#) () const  
*Gets the id component of this [AgentId](#).*
- int [startingRank](#) () const  
*Gets the starting rank component of this [AgentId](#).*
- int [agentType](#) () const

- *Gets the agent type component of this [AgentId](#).*
- `int currentRank () const`  
*Gets the current process rank of this [AgentId](#).*
- `void currentRank (int val)`  
*Sets the current process rank of this [AgentId](#).*
- `std::size_t hashCode () const`  
*Gets the hashcode for this [AgentId](#).*

## Friends

- class **boost::serialization::access**
- `std::ostream & operator<< (std::ostream &os, const AgentId &id)`  
*Writes the agent id to the ostream.*
- `bool operator== (const AgentId &one, const AgentId &two)`  
*Equality operator.*
- `bool operator< (const AgentId &one, const AgentId &two)`  
*A comparison operator for use with std::set.*

### 4.8.1 Detailed Description

[Agent](#) identity information.

Each agent should be uniquely identified by an [AgentId](#).

### 4.8.2 Constructor & Destructor Documentation

#### 4.8.2.1 `repast::AgentId::AgentId ( int id, int startProc, int agentType, int currentProc = -1 )`

Creates an [AgentId](#).

The combination of the three parameters should uniquely identify the agent.

Parameters

<i>id</i>	the agent's id
<i>startProc</i>	the rank of the agent's starting process
<i>agentType</i>	the agent's type (user defined)

### 4.8.3 Member Function Documentation

#### 4.8.3.1 `int repast::AgentId::agentType ( ) const` `[inline]`

Gets the agent type component of this [AgentId](#).

Returns

the agent type component of this [AgentId](#).

#### 4.8.3.2 `int repast::AgentId::currentRank ( ) const` `[inline]`

Gets the current process rank of this [AgentId](#).

The current rank identifies which process the agent with this [AgentId](#) is currently on.



**Returns**

the current process rank of this [AgentId](#).

**4.8.3.3** `void repast::AgentId::currentRank ( int val ) [inline]`

Sets the current process rank of this [AgentId](#).

The current rank identifies which process the agent with this [AgentId](#) is currently on.

**Parameters**

<i>val</i>	the current process rank
------------	--------------------------

**4.8.3.4** `std::size_t repast::AgentId::hashCode ( ) const [inline]`

Gets the hashcode for this [AgentId](#).

**Returns**

the hashcode for this [AgentId](#).

**4.8.3.5** `int repast::AgentId::id ( ) const [inline]`

Gets the id component of this [AgentId](#).

**Returns**

the id component of this [AgentId](#).

**4.8.3.6** `int repast::AgentId::startingRank ( ) const [inline]`

Gets the starting rank component of this [AgentId](#).

**Returns**

the starting rank component of this [AgentId](#).

The documentation for this class was generated from the following files:

- repast\_hpc/AgentId.h
- repast\_hpc/AgentId.cpp

## 4.9 repast::AgentRequest Class Reference

Encapsulates a request made by one process for agents in another.

```
#include <AgentRequest.h>
```

## Public Member Functions

- [AgentRequest](#) (int [sourceProcess](#))  
*Creates an [AgentRequest](#) that comes from the specified process.*
- [AgentRequest](#) (int [sourceProcess](#), int [targetProcess](#))  
*Creates an [AgentRequest](#) made from the source process to the target process.*
- void [addAll](#) (const [AgentRequest](#) &req)  
*Adds all the agent ids (both requests and cancellations) in req to this [AgentRequest](#).*
- void [addAllRequests](#) (const [AgentRequest](#) &req)  
*Adds all the agent ids in req to this request, including only the ids that are requests and not those that are cancellations.*
- void [addAllCancellations](#) (const [AgentRequest](#) &req)  
*Adds all the agent ids in req to this request, including only the ids that are cancellations and not those that are requests.*
- const std::vector< [AgentId](#) > & [requestedAgents](#) () const  
*Gets a reference to the vector of requested agents.*
- const std::vector< [AgentId](#) > & [cancellations](#) () const  
*Gets a reference to the vector of cancellations.*
- bool [remove](#) (const [AgentId](#) &id, bool removeAllInstances=true)  
*Removes the specified id from the lists of requested agents, including both requests and cancellations.*
- bool [removeRequest](#) (const [AgentId](#) &id, bool removeAllInstances=true)  
*Removes the specified id from the list of agent requests; does not affect the list of cancellations.*
- bool [removeCancellation](#) (const [AgentId](#) &id, bool removeAllInstances=true)  
*Removes the specified id from the list of agent request cancellations; does not affect the list of requests.*
- void [targets](#) (std::set< int > &targets)  
*Puts the targets of all the requests into the set.*
- void [targetsOfRequests](#) (std::set< int > &targets)  
*Puts the targets of all the requests into the set, including only the requests and not the cancellations.*
- void [targetsOfCancellations](#) (std::set< int > &targets)  
*Puts the targets of all the requests into the set, including only the requests and not the cancellations.*
- void [addRequest](#) (const [AgentId](#) &id)  
*Adds the specified agent to the collection agents being requested.*
- void [addCancellation](#) (const [AgentId](#) &id)  
*Adds the specified agent to the collection of agents for which a previous request is being cancelled.*
- int [requestCount](#) () const  
*Gets the number agents requested.*
- int [requestCountRequested](#) () const  
*Gets the number of agents requested, counting only the requests and not the cancellations.*
- int [requestCountCancellations](#) () const  
*Gets the number of agents requested, counting only the cancellations and not the requests.*
- bool [contains](#) (const [AgentId](#) &id)  
*Returns true if this [AgentRequest](#) contains a request for the specified id (either a request or a cancellation), otherwise false.*
- bool [containsInRequests](#) (const [AgentId](#) &id)  
*Returns true if the list of requests contains the specified id (the list of cancellations is ignored)*
- bool [containsInCancellations](#) (const [AgentId](#) &id)  
*Returns true if the list of cancellations contains the specified id (the list of requests is ignored)*
- int [sourceProcess](#) () const  
*Gets the source process of these requests, that is, the process making the request.*
- int [targetProcess](#) () const  
*If the requested agent ids are all on the same process then target process will identify that process.*

## Friends

- class **boost::serialization::access**
- class **Importer\_LIST**
- class **Importer\_SET**
- class **Importer\_MAP\_int**
- `std::ostream & operator<<` (`std::ostream &os`, `const AgentRequest &request`)

*Prints the specified [AgentRequest](#) to the specified ostream.*

### 4.9.1 Detailed Description

Encapsulates a request made by one process for agents in another.

Includes a list of requests and a list that represents cancellations of previous requests.

### 4.9.2 Constructor & Destructor Documentation

#### 4.9.2.1 `repast::AgentRequest::AgentRequest ( int sourceProcess )`

Creates an [AgentRequest](#) that comes from the specified process.

Parameters

<i>sourceProcess</i>	the rank of the process making the request
----------------------	--

#### 4.9.2.2 `repast::AgentRequest::AgentRequest ( int sourceProcess, int targetProcess )`

Creates an [AgentRequest](#) made from the source process to the target process.

This can be used when all the requested agents reside on the same process (i.e. the target process).

Parameters

<i>sourceProcess</i>	the rank of the source process
<i>targetProcess</i>	the rank of the target process

### 4.9.3 Member Function Documentation

#### 4.9.3.1 `void repast::AgentRequest::addAll ( const AgentRequest & req )`

Adds all the agent ids (both requests and cancellations) in *req* to this [AgentRequest](#).

Parameters

<i>req</i>	the <a href="#">AgentRequest</a> to add all the agent ids from
------------	--

#### 4.9.3.2 `void repast::AgentRequest::addAllCancellations ( const AgentRequest & req )`

Adds all the agent ids in *req* to this request, including only the ids that are cancellations and not those that are requests.

Parameters

<i>req</i>	the <a href="#">AgentRequest</a> to add all the agent ids from
------------	--

#### 4.9.3.3 void repast::AgentRequest::addAllRequests ( const AgentRequest & req )

Adds all the agent ids in req to this request, including only the ids that are requests and not those that are cancellations.

##### Parameters

<i>req</i>	the <a href="#">AgentRequest</a> to add all the agent ids from
------------	--

#### 4.9.3.4 void repast::AgentRequest::addCancellation ( const AgentId & id )

Adds the specified agent to the collection of agents for which a previous request is being cancelled.

##### Parameters

<i>id</i>	the <a href="#">AgentId</a> of the agent for which the request is being cancelled
-----------	---

#### 4.9.3.5 void repast::AgentRequest::addRequest ( const AgentId & id )

Adds the specified agent to the collection agents being requested.

##### Parameters

<i>id</i>	the requested agent
-----------	---------------------

#### 4.9.3.6 const std::vector<AgentId>& repast::AgentRequest::cancellations ( ) const [inline]

Gets a reference to the vector of cancellations.

##### Returns

a reference to the vector of AgentIds representing cancellations.

#### 4.9.3.7 bool repast::AgentRequest::contains ( const AgentId & id )

Returns true if this [AgentRequest](#) contains a request for the specified id (either a request or a cancellation), otherwise false.

##### Parameters

<i>id</i>	the id sought in the lists of requests and cancellations
-----------	--

##### Returns

true if either the list of requests or the list of cancellations contains the specified id

#### 4.9.3.8 bool repast::AgentRequest::containsInCancellations ( const AgentId & id )

Returns true if the list of cancellations contains the specified id (the list of requests is ignored)

## Parameters

<i>id</i>	the <a href="#">AgentId</a> sought
-----------	------------------------------------

## Returns

true if the specified [AgentId](#) is in the list of cancellations

## 4.9.3.9 bool repast::AgentRequest::containsInRequests ( const AgentId &amp; id )

Returns true if the list of requests contains the specified id (the list of cancellations is ignored)

## Parameters

<i>id</i>	the <a href="#">AgentId</a> sought
-----------	------------------------------------

## Returns

true if the specified [AgentId](#) is in the list of requests

## 4.9.3.10 bool repast::AgentRequest::remove ( const AgentId &amp; id, bool removeAllInstances = true )

Removes the specified id from the lists of requested agents, including both requests and cancellations.

## Parameters

<i>id</i>	the <a href="#">AgentId</a> to be removed
<i>removeAll-Instances</i>	if true (the default), all instances of the <a href="#">AgentId</a> are removed; if false, only the first instance found is removed

## Returns

true if the id was found (in either list) and removed, otherwise false.

## 4.9.3.11 bool repast::AgentRequest::removeCancellation ( const AgentId &amp; id, bool removeAllInstances = true )

Removes the specified id from the list of agent request cancellations; does not affect the list of requests.

## Parameters

<i>id</i>	the <a href="#">AgentId</a> to be removed
<i>removeAll-Instances</i>	if true (the default), all instances of the <a href="#">AgentId</a> are removed; if false, only the first instance found is removed

## Returns

true if the id was found in the list of cancellations and removed, otherwise false

## 4.9.3.12 bool repast::AgentRequest::removeRequest ( const AgentId &amp; id, bool removeAllInstances = true )

Removes the specified id from the list of agent requests; does not affect the list of cancellations.

## Parameters

<i>id</i>	the <a href="#">AgentId</a> to be removed
<i>removeAll-Instances</i>	if true (the default), all instances of the <a href="#">AgentId</a> are removed; if false, only the first instance found is removed

## Returns

true if the id was found in the list of requests and removed, otherwise false

#### 4.9.3.13 `int repast::AgentRequest::requestCount ( ) const [inline]`

Gets the number agents requested.

Includes both requests and cancellations; exactly equivalent to

[requestCountRequested\(\)](#) + [requestCountCancellations\(\)](#)

## Returns

the number agents requested.

#### 4.9.3.14 `int repast::AgentRequest::requestCountCancellations ( ) const [inline]`

Gets the number of agents requested, counting only the cancellations and not the requests.

## Returns

the number of agents requested (cancellations only)

#### 4.9.3.15 `int repast::AgentRequest::requestCountRequested ( ) const [inline]`

Gets the number of agents requested, counting only the requests and not the cancellations.

## Returns

the number of agents requested (requests only)

#### 4.9.3.16 `const std::vector<AgentId>& repast::AgentRequest::requestedAgents ( ) const [inline]`

Gets a reference to the vector of requested agents.

## Returns

a reference to the vector of requested agents.

#### 4.9.3.17 `int repast::AgentRequest::sourceProcess ( ) const [inline]`

Gets the source process of these requests, that is, the process making the request.

## Returns

the process making the request

4.9.3.18 `int repast::AgentRequest::targetProcess ( ) const [inline]`

If the requested agent ids are all on the same process then target process will identify that process.  
Otherwise this will return -1.

4.9.3.19 `void repast::AgentRequest::targets ( std::set< int > & targets )`

Puts the targets of all the requests into the set.  
Includes both the requests and the cancellations.

Parameters

<i>targets</i>	set into which targets will be placed
----------------	---------------------------------------

4.9.3.20 `void repast::AgentRequest::targetsOfCancellations ( std::set< int > & targets )`

Puts the targets of all the requests into the set, including only the requests and not the cancellations.

Parameters

<i>targets</i>	the set into which the targets will be placed
----------------	---

4.9.3.21 `void repast::AgentRequest::targetsOfRequests ( std::set< int > & targets )`

Puts the targets of all the requests into the set, including only the requests and not the cancellations.

Parameters

<i>targets</i>	the set into which the targets will be placed
----------------	---

The documentation for this class was generated from the following files:

- repast\_hpc/AgentRequest.h
- repast\_hpc/AgentRequest.cpp

## 4.10 repast::AgentStateFilter< T > Struct Template Reference

NON USER API.

```
#include <SharedContext.h>
```

### Public Member Functions

- **AgentStateFilter** (int rankInCommunicator)
- **AgentStateFilter** (bool localFlag, int rankInCommunicator)
- bool **operator()** (const boost::shared\_ptr< T > &ptr)

### Public Attributes

- int **rank**
- bool **local**

### 4.10.1 Detailed Description

```
template<typename T> struct repast::AgentStateFilter< T >
```

NON USER API.

The documentation for this struct was generated from the following file:

- repast\_hpc/SharedContext.h

## 4.11 repast::AgentStatus Class Reference

Encapsulates the status (moved or removed) of agent in order to synchronize that status across processes.

```
#include <AgentStatus.h>
```

### Public Types

- enum [Status](#) { **REMOVED**, **MOVED** }  
*Enum indicating the status of th agent.*

### Public Member Functions

- [AgentStatus](#) ()  
*No-arg constructor for serialization.*
- [AgentStatus](#) ([AgentId](#) id)  
*Creates an [AgentStatus](#) indicating the status for the specified agent.*
- [AgentStatus](#) ([AgentId](#) old, [AgentId](#) newId)  
*Creates an [AgentStatus](#) indicating the status for the specified agent and the new id of that agent as result from the change in status.*
- [Status](#) [getStatus](#) () const  
*Gets the status.*
- const [AgentId](#) & [getId](#) () const  
*Gets the id of the agent that this is the status for.*
- const [AgentId](#) & [getOldId](#) () const  
*Gets the old id of the agent that this is the status for, if this contains an old and updated [AgentId](#).*
- const [AgentId](#) & [getNewId](#) () const  
*Gets the new updated id of the agent that this is the status for, if this contains an old and updated [AgentId](#).*

### Friends

- class **boost::serialization::access**
- bool [operator<](#) (const [AgentStatus](#) &one, const [AgentStatus](#) &two)  
*Comparison operator that can be used in sorts, etc.*

### 4.11.1 Detailed Description

Encapsulates the status (moved or removed) of agent in order to synchronize that status across processes.



## 4.11.2 Constructor & Destructor Documentation

### 4.11.2.1 repast::AgentStatus::AgentStatus ( AgentId *id* )

Creates an [AgentStatus](#) indicating the status for the specified agent.

## Parameters

<i>id</i>	the id of the agent whose status this represents
-----------	--

4.11.2.2 `repast::AgentStatus::AgentStatus ( AgentId old, AgentId newId )`

Creates an [AgentStatus](#) indicating the status for the specified agent and the new id of that agent as result from the change in status.

When an agent moves between processes its current rank may change and thus the current rank part of its id will change.

## Parameters

<i>old</i>	the id of the agent whose status this represents
<i>newId</i>	the new id of the agent that results from its status change

## 4.11.3 Member Function Documentation

4.11.3.1 `const AgentId& repast::AgentStatus::getId ( ) const [inline]`

Gets the id of the agent that this is the status for.

## Returns

the id of the agent that this is the status for.

4.11.3.2 `const AgentId& repast::AgentStatus::getNewId ( ) const [inline]`

Gets the new updated id of the agent that this is the status for, if this contains an old and updated [AgentId](#).

## Returns

Gets the new id of the agent that this is the status for, if this contains an old and updated [AgentId](#).

4.11.3.3 `const AgentId& repast::AgentStatus::getOldId ( ) const [inline]`

Gets the old id of the agent that this is the status for, if this contains an old and updated [AgentId](#).

## Returns

Gets the old id of the agent that this is the status for, if this contains an old and updated [AgentId](#).

4.11.3.4 `Status repast::AgentStatus::getStatus ( ) const [inline]`

Gets the status.

## Returns

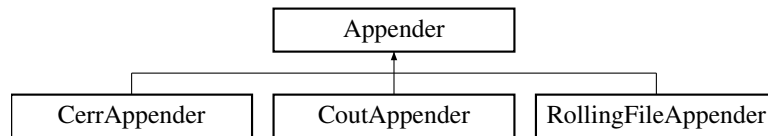
the status

The documentation for this class was generated from the following files:

- `repast_hpc/AgentStatus.h`
- `repast_hpc/AgentStatus.cpp`

## 4.12 Appender Class Reference

Inheritance diagram for Appender:



### Public Member Functions

- **Appender** (const std::string name)
- virtual void **write** (const std::string &line)=0
- virtual void **close** ()
- const std::string & **name** () const

### Protected Attributes

- const std::string **\_name**

The documentation for this class was generated from the following files:

- repast\_hpc/logger.h
- repast\_hpc/logger.cpp

## 4.13 AppenderBuilder Class Reference

### Public Member Functions

- **AppenderBuilder** (const std::string name)
- **Appender** \* **build** ()

### Public Attributes

- std::string **name**
- std::string **file\_name**
- long **max\_size**
- int **max\_idx**

The documentation for this class was generated from the following files:

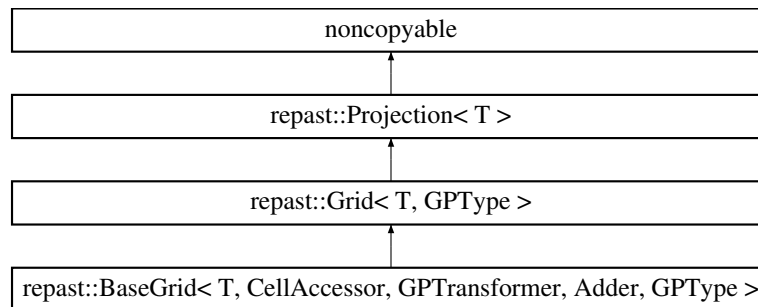
- repast\_hpc/logger.h
- repast\_hpc/logger.cpp

## 4.14 repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType > Class Template Reference

Base grid implementation, implementing elements common to both Grids and ContinuousSpaces.

```
#include <BaseGrid.h>
```

Inheritance diagram for repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >:



### Public Types

- typedef  
boost::transform\_iterator  
< [AgentFromGridPoint](#)< T,  
GPType >, LocationMapConstIter > [const\\_iterator](#)  
*A const iterator over shared\_ptr<T>.*

### Public Member Functions

- [BaseGrid](#) (std::string [name](#), [GridDimensions](#) [dimensions](#))  
*Creates a [BaseGrid](#) with the specified name and dimensions.*
- virtual bool [contains](#) (const [AgentId](#) &id)  
*Gets whether or not this grid contains the agent with the specified id.*
- virtual bool [getLocation](#) (const T \*agent, std::vector< GPType > &pt) const  
*Gets the location of this agent and puts it in the specified vector.*
- virtual bool [getLocation](#) (const [AgentId](#) &id, std::vector< GPType > &out) const  
*Gets the location of this agent and puts it in the specified vectors.*
- virtual T \* [getObjectAt](#) (const [Point](#)< GPType > &pt) const  
*Gets the first object found at the specified point, or NULL if there is no such object.*
- virtual void [getObjectsAt](#) (const [Point](#)< GPType > &pt, std::vector< T \* > &out) const  
*Gets all the objects found at the specified point.*
- virtual bool [moveTo](#) (const T \*agent, const std::vector< GPType > &newLocation)  
*Moves the specified agent to the specified location.*
- virtual bool [moveTo](#) (const T \*agent, const [Point](#)< GPType > &newLocation)  
*Moves the specified agent to the specified location.*
- virtual bool [moveTo](#) (const [AgentId](#) &id, const std::vector< GPType > &newLocation)  
*Moves the specified agent to the specified location.*
- virtual bool [moveTo](#) (const [AgentId](#) &id, const [Point](#)< GPType > &pt)  
*Moves the specified agent to the specified point.*
- virtual std::pair< bool, [Point](#)  
< GPType > > [moveByDisplacement](#) (const T \*agent, const std::vector< GPType > &displacement)  
*Moves the specified object from its current location by the specified amount.*

- virtual std::pair< bool, [Point](#)  
< GPType > > [moveByVector](#) (const T \*agent, double distance, const std::vector< double > &anglesInRadians)  
*doc inherited from [Grid](#)*
- virtual [const\\_iterator](#) [begin](#) () const  
*Gets an iterator over the agents in this [BaseGrid](#) starting with the first agent.*
- virtual [const\\_iterator](#) [end](#) () const  
*Gets the end of an iterator over the agents in this [BaseGrid](#).*
- virtual size\_t [size](#) () const  
*Gets the number of agents in this [BaseGrid](#).*
- virtual double [getDistance](#) (const [Point](#)< GPType > &pt1, const [Point](#)< GPType > &pt2) const  
*Gets the distance between the two grid points.*
- virtual double [getDistanceSq](#) (const [Point](#)< GPType > &pt1, const [Point](#)< GPType > &pt2) const  
*Gets the square of the distance between the two grid points.*
- virtual void [getDisplacement](#) (const [Point](#)< GPType > &pt1, const [Point](#)< GPType > &pt2, std::vector< GPType > &out) const  
*Gets vector difference between point 1 and point 2, putting the result in out.*
- virtual const [GridDimensions](#) [dimensions](#) () const  
*Gets the dimensions of this [Grid](#).*
- virtual void [translate](#) (const [Point](#)< GPType > &location, const [Point](#)< GPType > &displacement, std::vector< GPType > &out) const  
*Translates the specified location by the specified displacement put the result in out.*
- virtual void [transform](#) (const std::vector< GPType > &location, std::vector< GPType > &out) const  
*Transforms the specified location using the properties (e.g.*
- virtual bool [isPeriodic](#) () const  
*Gets whether or not this grid is periodic (i.e.*
- virtual [ProjectionInfoPacket](#) \* [getProjectionInfo](#) ([AgentId](#) id, bool secondaryInfo=false, std::set< [AgentId](#) > \*secondaryIds=0, int destProc=-1)
- virtual void [updateProjectionInfo](#) ([ProjectionInfoPacket](#) \*pip, [Context](#)< T > \*context)
- virtual void [getAgentsToPush](#) (std::set< [AgentId](#) > &agentsToTest, std::map< int, std::set< [AgentId](#) > > &agentsToPush)  
*Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.*

## Protected Types

- typedef AgentLocationMap::iterator **LocationMapIter**
- typedef AgentLocationMap::const\_iterator **LocationMapConstIter**

## Protected Member Functions

- virtual bool **addAgent** (boost::shared\_ptr< T > agent)
- virtual void **removeAgent** (T \*agent)
- LocationMapConstIter **locationsBegin** () const
- LocationMapConstIter **locationsEnd** () const
- T \* **get** (const [AgentId](#) &id)

## Protected Attributes

- GPTransformer **gpTransformer**
- Adder **adder**

### 4.14.1 Detailed Description

`template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>class repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >`

Base grid implementation, implementing elements common to both Grids and ContinuousSpaces.

Standard grid and space types that provide defaults for the various template parameters can be found in Space in Space.h

#### Template Parameters

<i>T</i>	the type of objects contained by this <a href="#">BaseGrid</a>
<i>CellAccessor</i>	implements the actual storage for the grid.
<i>GPTransformer</i>	transforms cell points according to the topology (e.g. periodic) of the <a href="#">BaseGrid</a> .
<i>Adder</i>	determines how objects are added to the grid from its associated context.
<i>GPType</i>	the coordinate type of the grid point locations. This must be an int or a double.

### 4.14.2 Constructor & Destructor Documentation

4.14.2.1 `template<typename T , typename CellAccessor , typename GPTransformer , typename Adder , typename GPType > repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::BaseGrid ( std::string name, GridDimensions dimensions )`

Creates a [BaseGrid](#) with the specified name and dimensions.

#### Parameters

<i>name</i>	the name of the <a href="#">BaseGrid</a>
<i>dimensions</i>	the dimensions of the <a href="#">BaseGrid</a>

### 4.14.3 Member Function Documentation

4.14.3.1 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType> virtual const_iterator repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::begin ( ) const [inline], [virtual]`

Gets an iterator over the agents in this [BaseGrid](#) starting with the first agent.

The iterator dereferences into `shared_ptr<T>`. The actual agent can be accessed by dereferencing the iter: `(*iter)->getId()` for example.

#### Returns

an iterator over the agents in this [BaseGrid](#) starting with the first agent.

4.14.3.2 `template<typename T , typename CellAccessor , typename GPTransformer , typename Adder , typename GPType > bool repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::contains ( const AgentId & id ) [virtual]`

Gets whether or not this grid contains the agent with the specified id.

#### Parameters

<i>id</i>	the id of the agent to check
-----------	------------------------------

**Returns**

true if the grid contains the agent, otherwise false.

Implements [repast::Grid< T, GPType >](#).

```
4.14.3.3  template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType> virtual
          const GridDimensions repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::dimensions ( )
          const [inline],[virtual]
```

Gets the dimensions of this [Grid](#).

**Returns**

the dimensions of this [Grid](#).

Implements [repast::Grid< T, GPType >](#).

Reimplemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), and [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#).

```
4.14.3.4  template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
          virtual const_iterator repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::end ( ) const
          [inline],[virtual]
```

Gets the end of an iterator over the agents in this [BaseGrid](#).

**Returns**

the end of an iterator over the agents in this [BaseGrid](#).

```
4.14.3.5  template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
          virtual void repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::getAgentsToPush ( std::set<
          AgentId > & agentsToTest, std::map< int, std::set< AgentId > > & agentsToPush ) [inline],
          [virtual]
```

Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.

Generally spaces must push agents that are in 'buffer zones' and graphs must push local agents that are vertices to master edges where the other vertex is non- local. The results are returned per-process in the agentsToPush map.

Implements [repast::Grid< T, GPType >](#).

Reimplemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#), and [repast::SharedDiscreteSpace< T, GPTransformer, Adder >](#).

```
4.14.3.6  template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
          void repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::getDisplacement ( const Point<
          GPType > & pt1, const Point< GPType > & pt2, std::vector< GPType > & out ) const [virtual]
```

Gets vector difference between point 1 and point 2, putting the result in out.

## Parameters

	<i>p1</i>	the first point
	<i>p2</i>	the second point
out	<i>the</i>	vector where the difference will be put

Implements [repast::Grid< T, GPType >](#).

```
4.14.3.7  template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
double repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::getDistance ( const Point<
GPType > & pt1, const Point< GPType > & pt2 ) const    [virtual]
```

Gets the distance between the two grid points.

## Parameters

	<i>p1</i>	the first point
	<i>p2</i>	the second point

## Returns

the distance between pt1 and pt2.

Implements [repast::Grid< T, GPType >](#).

```
4.14.3.8  template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
double repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::getDistanceSq ( const Point<
GPType > & pt1, const Point< GPType > & pt2 ) const    [virtual]
```

Gets the square of the distance between the two grid points.

## Parameters

	<i>p1</i>	the first point
	<i>p2</i>	the second point

## Returns

the square of the distance between pt1 and pt2.

Implements [repast::Grid< T, GPType >](#).

```
4.14.3.9  template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
bool repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::getLocation ( const T * agent,
std::vector< GPType > & out ) const    [virtual]
```

Gets the location of this agent and puts it in the specified vector.

The x coordinate will be the first value, the y the second and so on.

## Parameters

	<i>agent</i>	the agent whose location we want to get
out	<i>the</i>	vector where the agents location will be put

## Returns

true if the location was successfully found, otherwise false.

Implements [repast::Grid< T, GPType >](#).



4.14.3.10 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>  
bool repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::getLocation ( const AgentId & id,  
std::vector< GPType > & out ) const [virtual]`

Gets the location of this agent and puts it in the specified vectors.

The x coordinate will be the first value, the y the second and so on.

#### Parameters

	<i>id</i>	the id of the agent whose location we want to get
<i>out</i>	<i>out</i>	the agent's location will be put into this vector

#### Returns

true if the location was successfully found, otherwise false.

Implements [repast::Grid< T, GPType >](#).

4.14.3.11 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType> T  
* repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::getObjectAt ( const Point< GPType >  
& pt ) const [virtual]`

Gets the first object found at the specified point, or NULL if there is no such object.

#### Returns

the first object found at the specified point, or NULL if there is no such object.

Implements [repast::Grid< T, GPType >](#).

4.14.3.12 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>  
void repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::getObjectsAt ( const Point<  
GPType > & pt, std::vector< T* > & out ) const [virtual]`

Gets all the objects found at the specified point.

The found objects will be put into the out parameter.

#### Parameters

	<i>pt</i>	the point to get all the objects at
<i>out</i>	<i>out</i>	the vector into which the found objects will be put

Implements [repast::Grid< T, GPType >](#).

4.14.3.13 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>  
virtual bool repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::isPeriodic ( ) const  
[inline], [virtual]`

Gets whether or not this grid is periodic (i.e.

toroidal).

#### Returns

true if this [Grid](#) is periodic, otherwise false.

Implements [repast::Grid< T, GPType >](#).

4.14.3.14 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>  
std::pair< bool, Point< GPType > > repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType  
>::moveByDisplacement ( const T * agent, const std::vector< GPType > & displacement ) [virtual]`

Moves the specified object from its current location by the specified amount.

For example `moveByDisplacement(object, 3, -2, 1)` will move the object by 3 along the x-axis, -2 along the y and 1 along the z. The displacement argument can be less than the number of dimensions in the space in which case the remaining argument will be set to 0. For example, `moveByDisplacement(object, 3)` will move the object 3 along the x-axis and 0 along the y and z axes, assuming a 3D grid.

#### Parameters

<i>agent</i>	the object to move
<i>displacement</i>	the amount to move the object

#### Returns

a pair containing a bool that indicates whether the move was a success or not, and the point where the agent was moved to.

Implements `repast::Grid< T, GPType >`.

4.14.3.15 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>  
bool repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::moveTo ( const T * agent, const  
std::vector< GPType > & newLocation ) [virtual]`

Moves the specified agent to the specified location.

Returns true if the move was successful otherwise false. The agent must be already added to the context associated with this space, otherwise this throws an `out_of_range` exception if the new location out of bounds.

#### Parameters

<i>agent</i>	the agent to move
<i>newLocation</i>	the location to move to

#### Returns

true if the move was successful, otherwise false

4.14.3.16 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>  
bool repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::moveTo ( const T * agent, const  
Point< GPType > & newLocation ) [virtual]`

Moves the specified agent to the specified location.

Returns true if the move was successful otherwise false. The agent must be already added to the context associated with this space, otherwise this throws an `out_of_range` exception if the new location out of bounds.

#### Parameters

<i>agent</i>	the agent to move
<i>newLocation</i>	the location to move to

#### Returns

true if the move was successful, otherwise false

4.14.3.17 `template<typename T, typename CellAccessor , typename GPTransformer , typename Adder , typename GPType>  
bool repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::moveTo ( const AgentId & id, const  
std::vector< GPType > & newLocation ) [virtual]`

Moves the specified agent to the specified location.

Returns true if the move was successful otherwise false. The agent must be already added to the context associated with this space, otherwise this throws an `out_of_range` exception if the new location out of bounds.

Parameters

<i>id</i>	the id of the agent to move
<i>newLocation</i>	the location to move to

Returns

true if the move was successful, otherwise false

Reimplemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), and [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#).

4.14.3.18 `template<typename T, typename CellAccessor , typename GPTransformer , typename Adder , typename GPType>  
bool repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::moveTo ( const AgentId & id, const  
Point< GPType > & pt ) [virtual]`

Moves the specified agent to the specified point.

Parameters

<i>id</i>	the id of the agent to move
<i>pt</i>	where to move the agent to

Returns

true if the move was successful, otherwise false

Implements [repast::Grid< T, GPType >](#).

Reimplemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), and [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#).

4.14.3.19 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>  
virtual size_t repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::size ( ) const  
[inline], [virtual]`

Gets the number of agents in this [BaseGrid](#).

Returns

the number of agents in this [BaseGrid](#).

4.14.3.20 `template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>  
virtual void repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::transform ( const  
std::vector< GPType > & location, std::vector< GPType > & out ) const [inline], [virtual]`

Transforms the specified location using the properties (e.g. toroidal) of this space.

## Parameters

	<i>location</i>	the location to transform
out	<i>out</i>	the vector where the result of the transform will be put

Implements [repastr::Grid< T, GPType >](#).

```
4.14.3.21 template<typename T, typename CellAccessor, typename GPTransformer, typename Adder, typename GPType>
virtual void repastr::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >::translate ( const Point<
GPType > & location, const Point< GPType > & displacement, std::vector< GPType > & out ) const
[inline],[virtual]
```

Translates the specified location by the specified displacement put the result in out.

## Parameters

	<i>location</i>	the initial location
	<i>displacement</i>	the amount to translate the location by
out	<i>out</i>	the vector where the result of the translation is put

Implements [repastr::Grid< T, GPType >](#).

The documentation for this class was generated from the following file:

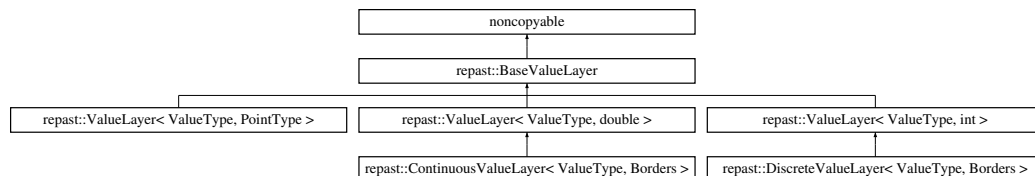
- repastr\_hpc/BaseGrid.h

## 4.15 repastr::BaseValueLayer Class Reference

Base implementation of a [ValueLayer](#).

```
#include <ValueLayer.h>
```

Inheritance diagram for repastr::BaseValueLayer:



### Public Member Functions

- [BaseValueLayer](#) (const std::string &name)  
Creates a [BaseValueLayer](#) with the specified name.
- std::string [name](#) () const  
Gets the value layer's name.

### Protected Attributes

- std::string [\\_name](#)

#### 4.15.1 Detailed Description

Base implementation of a [ValueLayer](#).

A [ValueLayer](#) stores values by location.

## 4.15.2 Member Function Documentation

### 4.15.2.1 `std::string repast::BaseValueLayer::name ( ) const` `[inline]`

Gets the value layer's name.

#### Returns

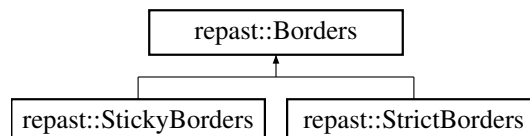
the name of the value layer.

The documentation for this class was generated from the following files:

- `repast_hpc/ValueLayer.h`
- `repast_hpc/ValueLayer.cpp`

## 4.16 repast::Borders Class Reference

Inheritance diagram for `repast::Borders`:



### Public Member Functions

- **Borders** ([GridDimensions](#) d)
- void **transform** (const std::vector< int > &in, std::vector< int > &out) const
- void **transform** (const std::vector< double > &in, std::vector< double > &out) const
- bool **isPeriodic** () const

### Protected Member Functions

- void **boundsCheck** (const std::vector< int > &pt) const
- void **boundsCheck** (const std::vector< double > &pt) const

### Protected Attributes

- const [GridDimensions](#) **\_dimensions**

The documentation for this class was generated from the following files:

- `repast_hpc/GridComponents.h`
- `repast_hpc/GridComponents.cpp`

## 4.17 repast::CartTopology Class Reference

### Public Member Functions

- **CartTopology** (std::vector< int > processesPerDim, std::vector< double > origin, std::vector< double > extents, bool spacelsPeriodic, boost::mpi::communicator \*world)

- void [getCoordinates](#) (int rank, std::vector< int > &coords)  
*Gets the coordinates in the MPI Cartesian Communicator for the specified rank.*
- [GridDimensions getDimensions](#) (int rank)  
*Gets the [GridDimensions](#) boundaries for the specified rank.*
- [GridDimensions getDimensions](#) (std::vector< int > &pCoordinates)  
*Gets the [GridDimensions](#) boundaries for the specified MPI coordinates.*
- void **createNeighbors** ([Neighbors](#) &nghs)

The documentation for this class was generated from the following files:

- repast\_hpc/SharedBaseGrid.h
- repast\_hpc/SharedBaseGrid.cpp

## 4.18 repast::CellContents< AgentContent, GPType > Class Template Reference

NON USER API.

```
#include <SharedBaseGrid.h>
```

### Public Member Functions

- template<class Archive >  
void **serialize** (Archive &ar, const unsigned int version)
- **CellContents** ([Point](#)< GPType > pt)

### Public Attributes

- [Point](#)< GPType > **\_pt**
- std::vector< AgentContent > **\_objs**

### Friends

- class **boost::serialization::access**

#### 4.18.1 Detailed Description

```
template<typename AgentContent, typename GPType>class repast::CellContents< AgentContent, GPType >
```

NON USER API.

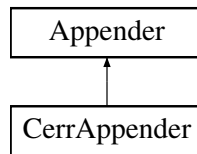
Encapsulates the contents of a grid / space location so that it can be sent between processes.

The documentation for this class was generated from the following file:

- repast\_hpc/SharedBaseGrid.h

## 4.19 CerrAppender Class Reference

Inheritance diagram for CerrAppender:



### Public Member Functions

- void **write** (const string &line)

### Additional Inherited Members

The documentation for this class was generated from the following file:

- repast\_hpc/logger.cpp

## 4.20 ConfigLexer Class Reference

### Public Member Functions

- **ConfigLexer** (const string &file\_name, boost::mpi::communicator \*comm=0, int maxConfigFileSize=MAX\_CONFIG\_FILE\_SIZE)
- TOKEN **next\_token** ()
- string **key** ()
- string **value** ()
- string **error** ()
- int **line** ()
- void **reset** ()

The documentation for this class was generated from the following file:

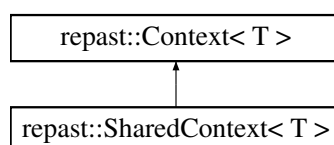
- repast\_hpc/logger.cpp

## 4.21 repast::Context< T > Class Template Reference

Collection of agents of type T with set semantics.

```
#include <Context.h>
```

Inheritance diagram for repast::Context< T >:



## Public Types

- typedef  
boost::transform\_iterator  
< [SecondElement](#)< T >, typename  
AgentMap::const\_iterator > **const\_iterator**
- typedef boost::filter\_iterator  
< [IsAgentType](#)< T >, typename  
[Context](#)< T >::const\_iterator > **const\_bytype\_iterator**

## Public Member Functions

- virtual [~Context](#) ()  
*Destroys this context and the projections it contains.*
- T \* [addAgent](#) (T \*agent)  
*Adds the agent to the context.*
- virtual void [addProjection](#) ([Projection](#)< T > \*projection)  
*Adds the specified projection to this context.*
- [Projection](#)< T > \* [getProjection](#) (const std::string &name)  
*Get the named [Projection](#).*
- void [removeAgent](#) (const [AgentId](#) id)  
*Removes the specified agent from this context.*
- void [removeAgent](#) (T \*agent)  
*Removes the specified agent from this context.*
- T \* [getAgent](#) (const [AgentId](#) &id)  
*Gets the specified agent.*
- void [getRandomAgents](#) (const int count, std::vector< T \* > &agents)  
*Gets at random the specified count of agents and returns them in the agents vector.*
- const\_iterator [begin](#) () const  
*Gets the start of iterator over the agents in this context.*
- const\_iterator [end](#) () const  
*Gets the end of an iterator over the agents in this context.*
- const\_bytype\_iterator [byTypeBegin](#) (int typeId) const  
*Gets the start of an iterator over agents in this context of the specified type.*
- const\_bytype\_iterator [byTypeEnd](#) (int typeId) const  
*Gets the end of an iterator over agents in this context of the specified type.*
- bool [contains](#) (const [AgentId](#) &id)  
*Returns true if the specified agent is in this context, otherwise false.*
- int [size](#) () const  
*Gets the size (number of agents) in this context.*
- void [addValueLayer](#) ([BaseValueLayer](#) \*valueLayer)  
*Adds a value layer to this context.*
- template<typename ValueType , typename Borders >  
[DiscreteValueLayer](#)< ValueType,  
[Borders](#) > \* [getDiscreteValueLayer](#) (const std::string &valueLayerName)  
*Gets the named discrete value layer from this [Context](#).*
- template<typename ValueType , typename Borders >  
[ContinuousValueLayer](#)  
< ValueType, [Borders](#) > \* [getContinuousValueLayer](#) (const std::string &valueLayerName)  
*Gets the named continuous value layer from this [Context](#).*



- template<typename filterStruct >  
boost::filter\_iterator  
< filterStruct, typename  
Context< T >::const\_iterator > [filteredBegin](#) (const filterStruct &fStruct)  
*Creates a filtered iterator over the set of agents in this context and returns it with a value equal to the beginning of the list.*
- template<typename filterStruct >  
boost::filter\_iterator  
< filterStruct, typename  
Context< T >::const\_iterator > [filteredEnd](#) (const filterStruct &fStruct)  
*Creates a filtered iterator over the set of agents in this context and returns it with a value equal to one step past end of the list.*
- template<typename filterStruct >  
boost::filter\_iterator  
< filterStruct, typename  
Context< T >  
::const\_bytype\_iterator > [byTypeFilteredBegin](#) (const int type, const filterStruct &fStruct)  
*Creates a filtered iterator over the set of agents in this context of the specified type (per their [AgentId](#) values), and returns it with a value equal to the beginning of the list.*
- template<typename filterStruct >  
boost::filter\_iterator  
< filterStruct, typename  
Context< T >  
::const\_bytype\_iterator > [byTypeFilteredEnd](#) (const int type, const filterStruct &fStruct)  
*Creates a filtered iterator over the set of agents in this context of the specified type (per their [AgentId](#) values), and returns it with a value equal to one past the end of the list.*
- void [selectAgents](#) (std::set< T \* > &selectedAgents, bool remove=false)  
*Gets a set of pointers to all agents in this context.*
- void [selectAgents](#) (std::vector< T \* > &selectedAgents, bool remove=false)  
*Gets a randomly ordered vector of pointers to all agents in this context.*
- void [selectAgents](#) (int count, std::set< T \* > &selectedAgents, bool remove=false)  
*Gets a set of pointers to a specified number of randomly selected agents.*
- void [selectAgents](#) (int count, std::vector< T \* > &selectedAgents, bool remove=false)  
*Gets a randomly ordered vector of pointers to a specified number of randomly selected agents.*
- void [selectAgents](#) (std::set< T \* > &selectedAgents, int type, bool remove=false, int popSize=-1)  
*Gets a set of pointers to all agents in this context of a specified type (per their [AgentId](#) values).*
- void [selectAgents](#) (std::vector< T \* > &selectedAgents, int type, bool remove=false, int popSize=-1)  
*Gets a randomly ordered vector of pointers to all agents in this context of a specified type (per their [AgentId](#) values).*
- void [selectAgents](#) (int count, std::set< T \* > &selectedAgents, int type, bool remove=false, int popSize=-1)  
*Gets a set of pointers to a specified number of randomly selected agents of a specified type (per their [AgentId](#) values).*
- void [selectAgents](#) (int count, std::vector< T \* > &selectedAgents, int type, bool remove=false, int popSize=-1)  
*Gets a randomly ordered vector of pointers to a specified number of randomly selected agents of a specified type (per their [AgentId](#) values).*
- template<typename filterStruct >  
void [selectAgents](#) (std::set< T \* > &selectedAgents, filterStruct &filter, bool remove=false, int popSize=-1)  
*Gets a set of pointers to all agents in this context matching a user-defined filter.*
- template<typename filterStruct >  
void [selectAgents](#) (std::vector< T \* > &selectedAgents, filterStruct &filter, bool remove=false, int popSize=-1)  
*Gets a randomly ordered vector of pointers to all agents in this context matching a user-defined filter.*
- template<typename filterStruct >  
void [selectAgents](#) (int count, std::set< T \* > &selectedAgents, filterStruct &filter, bool remove=false, int popSize=-1)  
*Gets a set of pointers to a specified number of randomly selected agents matching a user-defined filter.*

- `template<typename filterStruct >`  
`void selectAgents (int count, std::vector< T * > &selectedAgents, filterStruct &filter, bool remove=false, int popSize=-1)`  
*Gets a randomly ordered vector of pointers to a specified number of randomly selected agents matching a user-defined filter.*
- `template<typename filterStruct >`  
`void selectAgents (std::set< T * > &selectedAgents, int type, filterStruct &filter, bool remove=false, int popSize=-1)`  
*Gets a set of pointers to all agents in this context of a specified type (per their [AgentId](#) values) and matching a user-defined filter.*
- `template<typename filterStruct >`  
`void selectAgents (std::vector< T * > &selectedAgents, int type, filterStruct &filter, bool remove=false, int popSize=-1)`  
*Gets a randomly ordered vector of pointers to all agents in this context of a specified type (per their [AgentId](#) values) and matching a user-defined filter.*
- `template<typename filterStruct >`  
`void selectAgents (int count, std::set< T * > &selectedAgents, int type, filterStruct &filter, bool remove=false, int popSize=-1)`  
*Gets a set of pointers to a specified number of randomly selected agents of a specified type (per their [AgentId](#) values) and matching a user-defined filter.*
- `template<typename filterStruct >`  
`void selectAgents (int count, std::vector< T * > &selectedAgents, int type, filterStruct &filter, bool remove=false, int popSize=-1)`  
*Gets a randomly ordered vector of pointers to a specified number of randomly selected agents of a specified type (per their [AgentId](#) values) and matching a user-defined filter.*
- `void getProjectionInfo (AgentRequest req, std::map< std::string, std::vector< repast::ProjectionInfoPacket * > > &map, bool secondaryInfo=false, std::set< AgentId > *secondaryIds=0, int destProc=-1)`  
*Gets the projection information for all projections in this context, for all agents whose IDs are listed in the [AgentRequest](#).*
- `void setProjectionInfo (std::map< std::string, std::vector< repast::ProjectionInfoPacket * > > &projInfo)`  
*Sets the projection information as specified.*
- `void cleanProjectionInfo (std::set< AgentId > &agentsToKeep)`

## Protected Attributes

- `std::vector< Projection< T > * > projections`

### 4.21.1 Detailed Description

`template<typename T>class repast::Context< T >`

Collection of agents of type T with set semantics.

Object identity and equality is determined by their [AgentId](#).

Template Parameters

<i>the</i>	type objects contained by the <a href="#">Context</a> . The T must extends <a href="#">repast::Agent</a> .
------------	--

### 4.21.2 Member Function Documentation

#### 4.21.2.1 `template<typename T> T * repast::Context< T >::addAgent ( T * agent )`

Adds the agent to the context.

Performs a check to ensure that no agent with the same ID (presumably the 'same' agent) has previously been added. If a matching ID is found, the new agent is not added, and the address of the pre-existing agent is returned. If no match is found, the agent is added and the return value is the same as the value passed

## Parameters

<i>agent</i>	the agent to add
--------------	------------------

## Returns

the address of the agent in the context; will be the same as the address passed if the agent was successfully added, but if there was already an agent with the same ID the address returned will be that of the pre-existing agent, which is not replaced.

**4.21.2.2** `template<typename T> void repast::Context< T >::addProjection ( Projection< T > * projection )`  
`[virtual]`

Adds the specified projection to this context.

All the agents in this context will be added to the [Projection](#). Any agents subsequently added to this context will also be added to the [Projection](#).

## Parameters

<i>projection</i>	the projection to add
-------------------	-----------------------

Reimplemented in [repast::SharedContext< T >](#).

**4.21.2.3** `template<typename T> void repast::Context< T >::addValueLayer ( BaseValueLayer * valueLayer )`

Adds a value layer to this context.

## Parameters

<i>valueLayer</i>	the value layer to add
-------------------	------------------------

**4.21.2.4** `template<typename T> const_iterator repast::Context< T >::begin ( ) const` `[inline]`

Gets the start of iterator over the agents in this context.

The iterator dereferences into `shared_ptr<T>`. The actual agent can be accessed by dereferencing the iter: `(*iter)->getId()` for example.

## Returns

the start of iterator over the agents in this context.

**4.21.2.5** `template<typename T> const_bytype_iterator repast::Context< T >::byTypeBegin ( int typeid ) const`  
`[inline]`

Gets the start of an iterator over agents in this context of the specified type.

The type corresponds to the type component of an agent's [AgentId](#).

## Parameters

<i>typeid</i>	the type of the agent. Only Agents whose <code>agentId.agentType()</code> is equal to this <code>typeid</code> will be included in the iterator
---------------	---

## Returns

the start of an iterator over agents in this context of the specified type.

4.21.2.6 `template<typename T> const_bytype_iterator repast::Context< T >::byTypeEnd ( int typeld ) const`  
`[inline]`

Gets the end of an iterator over agents in this context of the specified type.

The type corresponds to the type component of an agent's [AgentId](#).

#### Parameters

<i>typeld</i>	the type of the agent. Only Agents whose agentId.agentType() is equal to this typeld will be included in the iterator
---------------	---

#### Returns

the end of an iterator over agents in this context of the specified type.

4.21.2.7 `template<typename T> template<typename filterStruct> boost::filter_iterator< filterStruct, typename Context< T >::const_bytype_iterator > repast::Context< T >::byTypeFilteredBegin ( const int type, const filterStruct & fStruct )`

Creates a filtered iterator over the set of agents in this context of the specified type (per their [AgentId](#) values), and returns it with a value equal to the beginning of the list.

The struct can be any user-defined structure that implements a unary operator (see [IsAgentType](#)) that can be passed and which will become a filter to sort across the agent list, e.g.:

```
struct filter { bool operator()(const boost::shared_ptr<T>& ptr){ return (ptr->getAgentValue() == targetValue;) } }
```

This should allow filtering of agents by type and on any attribute.

#### Parameters

<i>fStruct</i>	an instance of the struct to be used as the filter
<i>type</i>	the numeric type of agents to be included in the list

#### Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

#### Returns

an iterator positioned at the beginning of the list of agents meeting the filter's criteria

4.21.2.8 `template<typename T> template<typename filterStruct> boost::filter_iterator< filterStruct, typename Context< T >::const_bytype_iterator > repast::Context< T >::byTypeFilteredEnd ( const int type, const filterStruct & fStruct )`

Creates a filtered iterator over the set of agents in this context of the specified type (per their [AgentId](#) values), and returns it with a value equal to one past the end of the list.

The struct can be any user-defined structure that implements a unary operator (see [IsAgentType](#)) that can be passed and which will become a filter to sort across the agent list, e.g.:

```
struct filter { bool operator()(const boost::shared_ptr<T>& ptr){ return (ptr->getAgentValue() == targetValue;) } }
```

This should allow filtering of agents by type and on any attribute.

**Parameters**

<i>fStruct</i>	an instance of the struct to be used as the filter
<i>type</i>	the numeric type of agents to be included in the list

**Template Parameters**

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

**Returns**

an iterator positioned at one past the end of the list of agents meeting the filter's criteria

**4.21.2.9** `template<typename T> const_iterator repast::Context< T >::end ( ) const [inline]`

Gets the end of an iterator over the agents in this context.

The iterator dereferences into `shared_ptr<T>`. The actual agent can be accessed by dereferencing the iter: `(*iter)->getId()` for example.

**Returns**

the end of an iterator over the agents in this context

**4.21.2.10** `template<typename T> template<typename filterStruct> boost::filter_iterator< filterStruct, typename Context< T >::const_iterator> repast::Context< T >::filteredBegin ( const filterStruct & fStruct )`

Creates a filtered iterator over the set of agents in this context and returns it with a value equal to the beginning of the list.

The struct can be any user-defined structure that implements a unary operator (see [IsAgentType](#)) that can be passed and which will become a filter to sort across the agent list, e.g.:

```
struct filter { bool operator()(const boost::shared_ptr<T>& ptr){ return (ptr->getAgentValue() == targetValue;)} }
```

This should allow filtering of agents by any attribute.

**Parameters**

<i>fStruct</i>	an instance of the struct to be used as the filter
----------------	--

**Template Parameters**

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

**Returns**

an iterator positioned at the beginning of the list of agents meeting the filter's criteria

**4.21.2.11** `template<typename T> template<typename filterStruct> boost::filter_iterator< filterStruct, typename Context< T >::const_iterator> repast::Context< T >::filteredEnd ( const filterStruct & fStruct )`

Creates a filtered iterator over the set of agents in this context and returns it with a value equal to one step past end of the list.

The struct can be any user-defined structure that implements a unary operator (see [IsAgentType](#)) that can be passed and which will become a filter to sort across the agent list, e.g.:

```
struct filter { bool operator()(const boost::shared_ptr<T>& ptr){ return (ptr->getAgentValue() == targetValue;)} }
```

This should allow filtering of agents by any attribute.

## Parameters

<i>fStruct</i>	an instance of the struct to be used as the filter
----------------	--

## Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

## Returns

an iterator positioned at one past the end of the list of agents meeting the filter's criteria

4.21.2.12 `template<typename T> T * repast::Context< T >::getAgent ( const AgentId & id )`

Gets the specified agent.

## Parameters

<i>the</i>	id of the agent to get.
------------	-------------------------

4.21.2.13 `template<typename T> template<typename ValueType , typename Borders > ContinuousValueLayer< ValueType, Borders > * repast::Context< T >::getContinuousValueLayer ( const std::string & valueLayerName )`

Gets the named continuous value layer from this [Context](#).

The value layer must have been previously added.

## Parameters

<i>valueLayerName</i>	the name of the value layer to get
-----------------------	------------------------------------

## Template Parameters

<i>ValueType</i>	the numeric type contained by the value layer
<i>Borders</i>	the Border type of the value layer

## Returns

the named continuous value layer from this [Context](#).

4.21.2.14 `template<typename T> template<typename ValueType , typename Borders > DiscreteValueLayer< ValueType, Borders > * repast::Context< T >::getDiscreteValueLayer ( const std::string & valueLayerName )`

Gets the named discrete value layer from this [Context](#).

The value layer must have been previously added.

## Parameters

<i>valueLayerName</i>	the name of the value layer to get
-----------------------	------------------------------------

## Template Parameters

<i>ValueType</i>	the numeric type contained by the value layer
------------------	---

<a href="#">Borders</a>	the Border type of the value layer
-------------------------	------------------------------------

**Returns**

the named discrete value layer from this [Context](#).

4.21.2.15 `template<typename T> Projection< T> * repast::Context< T>::getProjection ( const std::string & name )`

Get the named [Projection](#).

**Parameters**

<i>the</i>	name of the projection to get
------------	-------------------------------

**Returns**

the named [Projection](#) or 0 if no such [Projection](#) is found.

4.21.2.16 `template<typename T> void repast::Context< T>::getProjectionInfo ( AgentRequest req, std::map< std::string, std::vector< repast::ProjectionInfoPacket *>> & map, bool secondaryInfo = false, std::set< AgentId> * secondaryIds = 0, int destProc = -1 )`

Gets the projection information for all projections in this context, for all agents whose IDs are listed in the [Agent-Request](#).

The general sense of this method can be easily understood: given a list of agents, get the projection information for all of those agents. But there are some subtleties that should be kept in mind.

"The projection information for an agent" is misleading. In fact, the projection information that is needed can vary depending on the context and on the kind of projection.

Generally speaking, spaces return only one kind projection information: coordinate locations for the agent specified. This is the simplest case.

The more complicated case is given by graphs. A graph projection can return different sets of information depending on how that information will have to be used. The basic issue is that a graph projection returns sets of edges, and edges must be connected to other agents; this means that a mechanism must be in place for ensuring that the projection info that arrives can be used, which means that for a given 'ego' agent, all 'alter' agents that are connected to it by edges must also be on the receiving process. (Note: Repast HPC 1.0 versions sent all of the alter agents' content along with the edge send; this version does not do this, partly to minimize the amount of information being packaged and sent but also because the alternative method used is integrated with the normal bookkeeping for sharing agent information across processes (AgentRequests).) In different circumstances, different assumptions can be made about what information will be available on the receiving process. Note that the coordinate information is generally referred to as 'Primary' information, while edge information is 'secondary'; in a third category ('secondary IDs') are the IDs of the alter agents, which can be packaged separately.

The impact of this is that this function is generally called in the following ways:

- 1) When requesting agents: in this case, a copy of the agent will be sent from one process to another. No secondary information will be sent at all. This is because it is assumed that if an agent participated in a graph on the receiving process, it would already be present on that process and would not be being requested.
- 2) When synchronizing [Projection](#) Information: in this case, some secondary information (edges) is needed: the edges that connect the specified ego agent with edges on the receiving process. No secondary IDs are needed, because the only edges being sent are those that connect to agents on the receiving process, which will be assumed to already be available on that process.
- 3) When synchronizing [Agent](#) Status (moving agents from process to process): in this case, the full collection of projection information is needed, including all of the edges in which the specified agent participates and all of the secondary IDs. (The secondary IDs of agents that are already on the receiving process can be omitted, at least theoretically.) This allows the full reconstruction of [Projection](#) Information on the receiving process.



## Parameters

<i>req</i>	List of IDs for agents whose information is requested
<i>map</i>	A map into which the projection information will be placed. Key values represent the names of the projections in this context.
<i>secondaryInfo</i>	true if the 'secondary' projection info must also be returned
<i>secondaryIds</i>	A set of IDs for agents who are referred to by the projection informaton being returned (may be null)
<i>destProc</i>	The Process that will be receiving this information (the information sent may be customized depending on the destination process). If not specified a larger set of information will be sent.

**4.21.2.17** `template<typename T> void repast::Context< T >::getRandomAgents ( const int count, std::vector< T * > & agents )`

Gets at random the specified count of agents and returns them in the agents vector.

## Parameters

	<i>count</i>	the number of agents to get
out	<i>agents</i>	a vector where the agents will be returned

**4.21.2.18** `template<typename T> void repast::Context< T >::removeAgent ( const AgentId id )`

Removes the specified agent from this context.

## Parameters

<i>id</i>	the id of the agent to remove
-----------	-------------------------------

**4.21.2.19** `template<typename T> void repast::Context< T >::selectAgents ( std::set< T * > & selectedAgents, bool remove = false )`

Gets a set of pointers to all agents in this context.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

## Parameters

out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)

**4.21.2.20** `template<typename T> void repast::Context< T >::selectAgents ( std::vector< T * > & selectedAgents, bool remove = false )`

Gets a randomly ordered vector of pointers to all agents in this context.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

## Parameters

out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
-----	-----------------------	---

	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
--	---------------	--

**4.21.2.21** `template<typename T> void repast::Context< T >::selectAgents ( int count, std::set< T * > & selectedAgents, bool remove = false )`

Gets a set of pointers to a specified number of randomly selected agents.

If the set passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

#### Parameters

	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)

**4.21.2.22** `template<typename T> void repast::Context< T >::selectAgents ( int count, std::vector< T * > & selectedAgents, bool remove = false )`

Gets a randomly ordered vector of pointers to a specified number of randomly selected agents.

If the vector passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

#### Parameters

	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)

**4.21.2.23** `template<typename T> void repast::Context< T >::selectAgents ( std::set< T * > & selectedAgents, int type, bool remove = false, int popSize = -1 )`

Gets a set of pointers to all agents in this context of a specified type (per their [AgentId](#) values).

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

#### Parameters

out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected

	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

**4.21.2.24** `template<typename T> void repast::Context< T >::selectAgents ( std::vector< T * > & selectedAgents, int type, bool remove = false, int popSize = -1 )`

Gets a randomly ordered vector of pointers to all agents in this context of a specified type (per their [AgentId](#) values).

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

#### Parameters

out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

**4.21.2.25** `template<typename T> void repast::Context< T >::selectAgents ( int count, std::set< T * > & selectedAgents, int type, bool remove = false, int popSize = -1 )`

Gets a set of pointers to a specified number of randomly selected agents of a specified type (per their [AgentId](#) values).

If the set passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

#### Parameters

	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

**4.21.2.26** `template<typename T> void repast::Context< T >::selectAgents ( int count, std::vector< T * > & selectedAgents, int type, bool remove = false, int popSize = -1 )`

Gets a randomly ordered vector of pointers to a specified number of randomly selected agents of a specified type (per their [AgentId](#) values).

If the vector passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

#### Parameters

	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

**4.21.2.27** `template<typename T> template<typename filterStruct> void repast::Context< T >::selectAgents ( std::set< T * > & selectedAgents, filterStruct & filter, bool remove = false, int popSize = -1 )`

Gets a set of pointers to all agents in this context matching a user-defined filter.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

that can possibly be selected, all possible agents will be selected

#### Parameters

out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

#### Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

**4.21.2.28** `template<typename T> template<typename filterStruct> void repast::Context< T >::selectAgents ( std::vector< T * > & selectedAgents, filterStruct & filter, bool remove = false, int popSize = -1 )`

Gets a randomly ordered vector of pointers to all agents in this context matching a user-defined filter.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

#### Parameters

out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
-----	-----------------------	---

	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

## Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

**4.21.2.29** `template<typename T> template<typename filterStruct> void repast::Context< T >::selectAgents ( int count, std::set< T * > & selectedAgents, filterStruct & filter, bool remove = false, int popSize = -1 )`

Gets a set of pointers to a specified number of randomly selected agents matching a user-defined filter.

If the set passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

## Parameters

	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

## Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

**4.21.2.30** `template<typename T> template<typename filterStruct> void repast::Context< T >::selectAgents ( int count, std::vector< T * > & selectedAgents, filterStruct & filter, bool remove = false, int popSize = -1 )`

Gets a randomly ordered vector of pointers to a specified number of randomly selected agents matching a user-defined filter.

If the vector passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

## Parameters

	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
--	--------------	---

out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

#### Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

**4.21.2.31** `template<typename T> template<typename filterStruct> void repast::Context< T>::selectAgents ( std::set< T*> & selectedAgents, int type, filterStruct & filter, bool remove = false, int popSize = -1 )`

Gets a set of pointers to all agents in this context of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

#### Parameters

out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

#### Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

**4.21.2.32** `template<typename T> template<typename filterStruct> void repast::Context< T>::selectAgents ( std::vector< T*> & selectedAgents, int type, filterStruct & filter, bool remove = false, int popSize = -1 )`

Gets a randomly ordered vector of pointers to all agents in this context of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

#### Parameters

out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)

	<i>popSize</i>	size of the population from which the sample will be drawn
--	----------------	--

## Template Parameters

	<i>filterStruct</i>	the type of the filter to be applied to the agents
--	---------------------	--

**4.21.2.33** `template<typename T> template<typename filterStruct> void repast::Context< T >::selectAgents ( int count, std::set< T * > & selectedAgents, int type, filterStruct & filter, bool remove = false, int popSize = -1 )`

Gets a set of pointers to a specified number of randomly selected agents of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

If the set passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

## Parameters

	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

## Template Parameters

	<i>filterStruct</i>	the type of the filter to be applied to the agents
--	---------------------	--

**4.21.2.34** `template<typename T> template<typename filterStruct> void repast::Context< T >::selectAgents ( int count, std::vector< T * > & selectedAgents, int type, filterStruct & filter, bool remove = false, int popSize = -1 )`

Gets a randomly ordered vector of pointers to a specified number of randomly selected agents of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

If the vector passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

## Parameters

	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
--	--------------	---

out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

#### Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

4.21.2.35 `template<typename T> void repast::Context< T >::setProjectionInfo ( std::map< std::string, std::vector< repast::ProjectionInfoPacket * > > & projInfo )`

Sets the projection information as specified.

#### Parameters

<i>projInfo</i>	map where keys represent projections in this context and the values represent collections of projection information content that will be used to specify the relationships among the agents.
-----------------	--

The documentation for this class was generated from the following file:

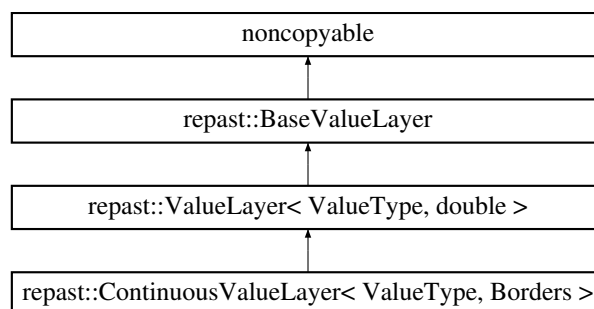
- repast\_hpc/Context.h

## 4.22 repast::ContinuousValueLayer< ValueType, Borders > Class Template Reference

Continuous value layer whose location coordinates are double.

```
#include <ValueLayer.h>
```

Inheritance diagram for repast::ContinuousValueLayer< ValueType, Borders >:



### Public Member Functions

- **ContinuousValueLayer** (const ContinuousValueLayer< ValueType, Borders > &other)
- ContinuousValueLayer & operator= (const ContinuousValueLayer< ValueType, Borders > &rhs)
- ContinuousValueLayer (const std::string &name, const GridDimensions &dimensions, const ValueType &defaultValue=ValueType())  
Creates a ContinuousValueLayer whose cells contain a default value of ValueType() with the specified dimensions.
- ValueType & get (const Point< double > &pt)  
Gets the value at the specified point.
- void set (const ValueType &value, const Point< double > &pt)  
Sets the value at the specified point.



### 4.22.1 Detailed Description

```
template<typename ValueType, typename Borders>class repast::ContinuousValueLayer< ValueType, Borders >
```

Continuous value layer whose location coordinates are double.

#### Template Parameters

<i>ValueType</i>	the type of what the value layer stores.
<i>Borders</i>	the type of borders (wrapped / periodic, strict). Border types can be found in <a href="#">GridComponents.h</a>

### 4.22.2 Constructor & Destructor Documentation

4.22.2.1 `template<typename ValueType , typename Borders > repast::ContinuousValueLayer< ValueType, Borders >::ContinuousValueLayer ( const std::string & name, const GridDimensions & dimensions, const ValueType & defaultValue = ValueType() )`

Creates a [ContinuousValueLayer](#) whose cells contain a default value of `ValueType()` with the specified dimensions.

#### Parameters

<i>name</i>	the name of the <a href="#">ContinuousValueLayer</a>
<i>dimension</i>	the dimensions of the <a href="#">ContinuousValueLayer</a>
<i>dense</i>	whether or not the <a href="#">ValueLayer</a> will be densely populated or not
<i>defaultValue</i>	the default value to return if no value has been set of a location. The default is the result of <code>ValueType()</code> .

### 4.22.3 Member Function Documentation

4.22.3.1 `template<typename ValueType , typename Borders > ValueType & repast::ContinuousValueLayer< ValueType, Borders >::get ( const Point< double > & pt ) [virtual]`

Gets the value at the specified point.

If no value has been set at the specified point then this returns the default value.

param *pt* the location to get the value of

#### Returns

the value at the specified point, or if no value has been set, then the default value.

Implements [repast::ValueLayer< ValueType, double >](#).

4.22.3.2 `template<typename ValueType , typename Borders > void repast::ContinuousValueLayer< ValueType, Borders >::set ( const ValueType & value, const Point< double > & pt ) [virtual]`

Sets the value at the specified point.

#### Parameters

<i>value</i>	the value
<i>pt</i>	the point where the value should be stored

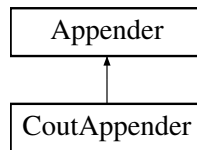
Implements [repast::ValueLayer< ValueType, double >](#).

The documentation for this class was generated from the following file:

- `repast_hpc/ValueLayer.h`

## 4.23 CoutAppender Class Reference

Inheritance diagram for CoutAppender:



### Public Member Functions

- void **write** (const string &line)

### Additional Inherited Members

The documentation for this class was generated from the following file:

- repast\_hpc/logger.cpp

## 4.24 repast::data\_type\_traits< T > Struct Template Reference

The documentation for this struct was generated from the following file:

- repast\_hpc/SVDataSource.h

## 4.25 repast::data\_type\_traits< double > Struct Template Reference

### Static Public Member Functions

- static SVDataSource::DataType **data\_type** ()

The documentation for this struct was generated from the following file:

- repast\_hpc/SVDataSource.h

## 4.26 repast::data\_type\_traits< int > Struct Template Reference

### Static Public Member Functions

- static SVDataSource::DataType **data\_type** ()

The documentation for this struct was generated from the following file:

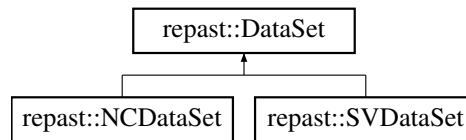
- repast\_hpc/SVDataSource.h

## 4.27 repast::DataSet Class Reference

Interface for recording and writing data.

```
#include <DataSet.h>
```

Inheritance diagram for repast::DataSet:



### Public Member Functions

- virtual void [record](#) ()=0  
*Records the data.*
- virtual void [write](#) ()=0  
*Writes the data.*
- virtual void [close](#) ()=0  
*Closes the dataset, after which it must be recreated to be used.*

#### 4.27.1 Detailed Description

Interface for recording and writing data.

The documentation for this class was generated from the following file:

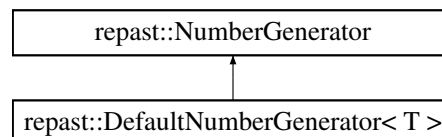
- repast\_hpc/DataSet.h

## 4.28 repast::DefaultNumberGenerator< T > Class Template Reference

Adapts the templated boost::variate\_generator to the [NumberGenerator](#) interface.

```
#include <Random.h>
```

Inheritance diagram for repast::DefaultNumberGenerator< T >:



### Public Member Functions

- **DefaultNumberGenerator** (T generator)
- double [next](#) ()  
*Gets the "next" number from this Number Generator.*

### 4.28.1 Detailed Description

```
template<typename T>class repast::DefaultNumberGenerator< T >
```

Adapts the templated boost::variate\_generator to the [NumberGenerator](#) interface.

The documentation for this class was generated from the following file:

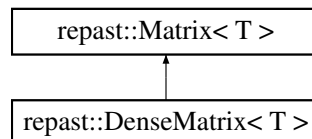
- repast\_hpc/Random.h

## 4.29 repast::DenseMatrix< T > Class Template Reference

A dense matrix implementation that stores each cell individually.

```
#include <matrix.h>
```

Inheritance diagram for repast::DenseMatrix< T >:



### Public Member Functions

- [DenseMatrix](#) (const [DenseMatrix](#)< T > &)  
*Creates a [DenseMatrix](#) as a copy of the specified [DenseMatrix](#).*
- [DenseMatrix](#)< T > & **operator=** (const [DenseMatrix](#)< T > &)
- [DenseMatrix](#) (const [Point](#)< int > &shape, const T &defValue=T())  
*Creates a [DenseMatrix](#) of the specified shape and default value.*
- T & [get](#) (const [Point](#)< int > &index)  
*Gets the value at the specified index.*
- void [set](#) (const T &value, const [Point](#)< int > &index)  
*Sets the value at the specified index.*

### Additional Inherited Members

#### 4.29.1 Detailed Description

```
template<typename T>class repast::DenseMatrix< T >
```

A dense matrix implementation that stores each cell individually.

The documentation for this class was generated from the following file:

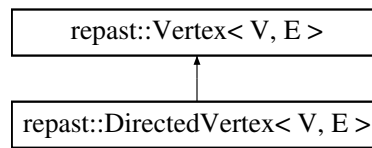
- repast\_hpc/matrix.h

## 4.30 repast::DirectedVertex< V, E > Class Template Reference

Used internally by repast graphs / networks to encapsulate the vertices of a directed graph.

```
#include <DirectedVertex.h>
```

Inheritance diagram for repast::DirectedVertex< V, E >:



## Public Member Functions

- [DirectedVertex](#) (boost::shared\_ptr< V > item)  
*Creates a [DirectedVertex](#) that will contain the specified item.*
- virtual boost::shared\_ptr< E > [removeEdge](#) ([Vertex](#)< V, E > \*other, [EdgeType](#) type)  
*Removes the edge of the specified type between this [Vertex](#) and the specified [Vertex](#).*
- virtual boost::shared\_ptr< E > [findEdge](#) ([Vertex](#)< V, E > \*other, [EdgeType](#) type)  
*Finds the edge of the specified type between this [Vertex](#) and the specified vertex.*
- virtual void [addEdge](#) ([Vertex](#)< V, E > \*other, boost::shared\_ptr< E > edge, [EdgeType](#) type)  
*Adds an edge of the specified type between this [Vertex](#) and the specified vertex.*
- virtual void [successors](#) (std::vector< V \* > &out)  
*Gets the successors of this [Vertex](#).*
- virtual void [predecessors](#) (std::vector< V \* > &out)  
*Gets the predecessors of this [Vertex](#).*
- virtual void [adjacent](#) (std::vector< V \* > &out)  
*Gets the Vertices adjacent to this [Vertex](#).*
- virtual void [edges](#) ([EdgeType](#) type, std::vector< boost::shared\_ptr< E > > &out)  
*Gets all the edges of the specified type in which this [Vertex](#) participates and return them in out.*
- int [inDegree](#) ()  
*Gets the in degree of this [Vertex](#).*
- int [outDegree](#) ()  
*Gets the out degree of this [Vertex](#).*

### 4.30.1 Detailed Description

```
template<typename V, typename E>class repast::DirectedVertex< V, E >
```

Used internally by repast graphs / networks to encapsulate the vertices of a directed graph.

#### Template Parameters

V	the type of object stored by in a <a href="#">Vertex</a> .
E	the EdgeType of the network.

### 4.30.2 Member Function Documentation

4.30.2.1 `template<typename V, typename E> void repast::DirectedVertex< V, E >::addEdge ( Vertex< V, E > * other, boost::shared_ptr< E > edge, EdgeType type ) [virtual]`

Adds an edge of the specified type between this [Vertex](#) and the specified vertex.

## Parameters

<i>edge</i>	the edge to add
<i>other</i>	the other end of the edge
<i>type</i>	the type of edge to add

Implements [repast::Vertex< V, E >](#).

4.30.2.2 `template<typename V , typename E > void repast::DirectedVertex< V, E >::adjacent ( std::vector< V * > & out ) [virtual]`

Gets the Vertices adjacent to this [Vertex](#).

## Parameters

<i>out</i>	<i>the</i>	vector where the adjacent vectors will be put
------------	------------	---

Implements [repast::Vertex< V, E >](#).

4.30.2.3 `template<typename V , typename E > void repast::DirectedVertex< V, E >::edges ( EdgeType type, std::vector< boost::shared_ptr< E > > & out ) [virtual]`

Gets all the edges of the specified type in which this [Vertex](#) participates and return them in out.

## Parameters

	<i>type</i>	the type of edges to get
<i>out</i>	<i>where</i>	the edges will be put.

Implements [repast::Vertex< V, E >](#).

4.30.2.4 `template<typename V , typename E > boost::shared_ptr< E > repast::DirectedVertex< V, E >::findEdge ( Vertex< V, E > * other, EdgeType type ) [virtual]`

Finds the edge of the specified type between this [Vertex](#) and the specified vertex.

## Parameters

<i>other</i>	the other end of the edge
<i>type</i>	the type of edge to remove

## Returns

the found edge, or 0.

Implements [repast::Vertex< V, E >](#).

4.30.2.5 `template<typename V , typename E > int repast::DirectedVertex< V, E >::inDegree ( ) [virtual]`

Gets the in degree of this [Vertex](#).

## Returns

the in degree of this [Vertex](#).

Implements [repast::Vertex< V, E >](#).

4.30.2.6 `template<typename V, typename E> int repast::DirectedVertex< V, E >::outDegree ( ) [virtual]`

Gets the out degree of this [Vertex](#).

#### Returns

the out degree of this [Vertex](#).

Implements [repast::Vertex< V, E >](#).

4.30.2.7 `template<typename V, typename E> void repast::DirectedVertex< V, E >::predecessors ( std::vector< V * > & out ) [virtual]`

Gets the predecessors of this [Vertex](#).

#### Parameters

out	the	vector where any predecessors will be put
-----	-----	---

Implements [repast::Vertex< V, E >](#).

4.30.2.8 `template<typename V, typename E> boost::shared_ptr< E > repast::DirectedVertex< V, E >::removeEdge ( Vertex< V, E > * other, EdgeType type ) [virtual]`

Removes the edge of the specified type between this [Vertex](#) and the specified [Vertex](#).

#### Parameters

other	the other end of the edge
type	the type of edge to remove

#### Returns

the removed edge if such an edge was found, otherwise 0.

Implements [repast::Vertex< V, E >](#).

4.30.2.9 `template<typename V, typename E> void repast::DirectedVertex< V, E >::successors ( std::vector< V * > & out ) [virtual]`

Gets the successors of this [Vertex](#).

#### Parameters

out	the	vector where any successors will be put
-----	-----	---

Implements [repast::Vertex< V, E >](#).

The documentation for this class was generated from the following file:

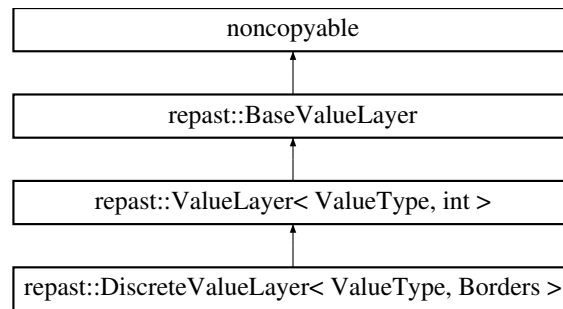
- repast\_hpc/DirectedVertex.h

## 4.31 repast::DiscreteValueLayer< ValueType, Borders > Class Template Reference

Creates [ValueLayer](#) whose location coordinates are ints.

```
#include <ValueLayer.h>
```

Inheritance diagram for repast::DiscreteValueLayer< ValueType, Borders >:



## Public Member Functions

- **DiscreteValueLayer** (const [DiscreteValueLayer](#)< [ValueType](#), [Borders](#) > &other)
- [DiscreteValueLayer](#) & **operator=** (const [DiscreteValueLayer](#)< [ValueType](#), [Borders](#) > &rhs)
- [DiscreteValueLayer](#) (const std::string &name, const [GridDimensions](#) &dimensions, bool dense, const [ValueType](#) &defaultValue=[ValueType](#)())  
*Creates a [DiscreteValueLayer](#) whose cells contain a default value of [ValueType](#)() with the specified dimensions.*
- [ValueType](#) & [get](#) (const [Point](#)< int > &pt)  
*Gets the value at the specified point.*
- void [set](#) (const [ValueType](#) &value, const [Point](#)< int > &pt)  
*Sets the value at the specified point.*

### 4.31.1 Detailed Description

template<typename [ValueType](#), typename [Borders](#)>class repast::DiscreteValueLayer< [ValueType](#), [Borders](#) >

Creates [ValueLayer](#) whose location coordinates are ints.

#### Template Parameters

<a href="#">ValueType</a>	the type of what the value layer stores.
<a href="#">Borders</a>	the type of borders (wrapped / periodic, strict). Border types can be found in <a href="#">GridComponents.h</a>

### 4.31.2 Constructor & Destructor Documentation

4.31.2.1 template<typename [ValueType](#) , typename [Borders](#) > repast::DiscreteValueLayer< [ValueType](#), [Borders](#) >::DiscreteValueLayer ( const std::string & name, const [GridDimensions](#) & dimensions, bool dense, const [ValueType](#) & defaultValue = [ValueType](#)() )

Creates a [DiscreteValueLayer](#) whose cells contain a default value of [ValueType](#)() with the specified dimensions.

#### Parameters

name	the name of the <a href="#">DiscreteValueLayer</a>
dimension	the dimensions of the <a href="#">DiscreteValueLayer</a>
dense	whether or not the <a href="#">ValueLayer</a> will be densely populated or not
defaultValue	the default value to return if no value has been set of a location. The default is the result of <a href="#">ValueType</a> () .

### 4.31.3 Member Function Documentation



4.31.3.1 `template<typename ValueType , typename Borders > ValueType & repast::DiscreteValueLayer< ValueType, Borders >::get ( const Point< int > & pt ) [virtual]`

Gets the value at the specified point.

If no value has been set at the specified point then this returns the default value.

param pt the location to get the value of

Returns

the value at the specified point, or if no value has been set, then the default value.

Implements [repast::ValueLayer< ValueType, int >](#).

4.31.3.2 `template<typename ValueType , typename Borders > void repast::DiscreteValueLayer< ValueType, Borders >::set ( const ValueType & value, const Point< int > & pt ) [virtual]`

Sets the value at the specified point.

Parameters

<i>value</i>	the value
<i>pt</i>	the point where the value should be stored

Implements [repast::ValueLayer< ValueType, int >](#).

The documentation for this class was generated from the following file:

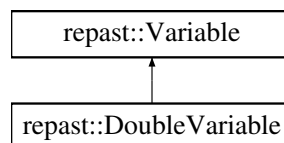
- repast\_hpc/ValueLayer.h

## 4.32 repast::DoubleVariable Class Reference

NON USER API.

```
#include <Variable.h>
```

Inheritance diagram for repast::DoubleVariable:



### Public Member Functions

- virtual void [write](#) (size\_t index, std::ostream &out)  
*Writes the data at the specified index to the specified ostream.*
- virtual void [insert](#) (double \*array, size\_t size)  
*Insertes all the doubles in the double array into the collection of data stored in this [Variable](#).*
- virtual void [insert](#) (int \*array, size\_t size)  
*Insertes all the ints in the int array into the collection of data stored in this [Variable](#).*
- virtual void [clear](#) ()  
*Clears this [Variable](#) of all the data stored in it.*

### 4.32.1 Detailed Description

NON USER API.

Used in [SVDDataSet](#) to manage double data.

### 4.32.2 Member Function Documentation

4.32.2.1 `void repast::DoubleVariable::insert ( double * array, size_t size )` `[virtual]`

Insertes all the doubles in the double array into the collection of data stored in this [Variable](#).

Parameters

<i>array</i>	the array to insert
<i>size</i>	the size of the array

Implements [repast::Variable](#).

4.32.2.2 `void repast::DoubleVariable::insert ( int * array, size_t size )` `[virtual]`

Insertes all the ints in the int array into the collection of data stored in this [Variable](#).

Parameters

<i>array</i>	the array to insert
<i>size</i>	the size of the array

Implements [repast::Variable](#).

4.32.2.3 `void repast::DoubleVariable::write ( size_t index, std::ofstream & out )` `[virtual]`

Writes the data at the specified index to the specified ofstream.

Parameters

<i>index</i>	the index of the data to write
<i>out</i>	the ofstream to write the data to

Implements [repast::Variable](#).

The documentation for this class was generated from the following files:

- `repast_hpc/Variable.h`
- `repast_hpc/Variable.cpp`

## 4.33 `repast::EdgeExporter< E >` Class Template Reference

NON USER API.

```
#include <SharedNetwork.h>
```

### Public Types

- `typedef std::map< int, std::vector< boost::shared_ptr< E >> * >::iterator` **EdgeMapIterator**

## Public Member Functions

- void **addAgentExportRequest** (int exportTo, const [AgentId](#) &id)
- void **edgeRemoved** (boost::shared\_ptr< E > edge, std::map< int, std::vector< std::pair< [AgentId](#), [AgentId](#) > > > &removeMap)  
*Whether or not this is exported the specified edge.*
- void **addEdge** (boost::shared\_ptr< E > edge)  
*Tests if the edge needs to be exported and if so adds it to the collection of edges to be exported.*
- void **gatherReceivers** (std::vector< int > &out)  
*Gathers the receivers into out.*
- void **gatherExporters** (std::vector< int > &out)  
*Gathers the procs that this will send export requests to into out.*
- void **sendExportRequests** (boost::mpi::communicator &comm, std::vector< boost::mpi::request > &requests)  
*Send the export requests.*
- std::map< int, std::vector< boost::shared\_ptr< E > > \* > & **getEdgesToExport** ()  
*Gets the edges to export.*
- std::map< int, std::vector< boost::shared\_ptr< E > > \* > & **getExportedEdges** ()  
*Gets the edges this process is exporting.*
- void **cleanUp** ()  
*Cleans up after exported edges have been sent and received.*

## Friends

- template<typename Vertex , typename Edge , typename AgentContent , typename EdgeContent , typename EdgeManager , typename AgentCreator >  
void **createComplementaryEdges** ([SharedNetwork](#)< [Vertex](#), Edge, EdgeContent, EdgeManager > \*net, [SharedContext](#)< [Vertex](#) > &context, EdgeManager &edgeManager, AgentCreator &creator)  
*Notifies other processes of any edges that have been created between nodes on this process and imported nodes.*

### 4.33.1 Detailed Description

template<typename E>class repast::EdgeExporter< E >

NON USER API.

Handles exporting edges created locally between one or more non-local agents. This also coordinates notification of which processes should be exporting to which in the case of edges where a node is foreign to the sending and receiving process.

All this is done internally in the [SharedNetwork](#).

### 4.33.2 Member Function Documentation

4.33.2.1 template<typename E > void repast::EdgeExporter< E >::gatherReceivers ( std::vector< int > & out )

Gathers the receivers into out.

A receiver is a process this [EdgeExporter](#) should send an edge to.

4.33.2.2 `template<typename E> void repast::EdgeExporter< E >::sendExportRequests ( boost::mpi::communicator & comm, std::vector< boost::mpi::request > & requests )`

Send the export requests.

This does an isend and the resulting requests are placed in the specified vector.

### 4.33.3 Friends And Related Function Documentation

4.33.3.1 `template<typename E> template<typename Vertex , typename Edge , typename AgentContent , typename EdgeContent , typename EdgeManager , typename AgentCreator > void createComplementaryEdges ( SharedNetwork< Vertex, Edge, EdgeContent, EdgeManager > * net, SharedContext< Vertex > & context, EdgeManager & edgeManager, AgentCreator & creator ) [friend]`

Notifies other processes of any edges that have been created between nodes on this process and imported nodes.

The other process will then create the complimentary edge. For example, if P1 creates an edge between A and B where B resides on P2, then this method will notify P2 to create the incoming edge A->B on its copy of B. Any unknown agents will be added to the context. For example, if P2 didn't have a reference to A, then A will be added to P2's context.

#### Parameters

<i>net</i>	the network in which to create the complementary edges or from which to send complementary edges
<i>context</i>	the context that contains the agents in the process
<i>edgeManager</i>	creates edges from EdgeContent and creates EdgeContent from an edge and a context.
<i>creator</i>	creates agents from AgentContent.

#### Template Parameters

<i>Vertex</i>	the vertex (agent) type
<i>Edge</i>	the edge type
<i>AgentContent</i>	the serializable struct or class that describes the agent state. It must contain a <code>getId()</code> method that returns the <a href="#">AgentId</a> of the agent it describes.
<i>EdgeContent</i>	the serializable struct or class that describes edge state. At the very least EdgeContent must contain two public fields <code>sourceContent</code> and <code>targetContent</code> of type <a href="#">AgentContent</a> . These represent the source and target of the edge.
<i>EdgeManager</i>	create edges from EdgeContent and provides EdgeContent given a context and an edge of type Edge. It must implement <code>void provideEdgeContent(constEdge* edge, std::vector&lt;EdgeContent&gt;&amp; edgeContent)</code> and <code>Edge* createEdge(repast::Context&lt;Vertex&gt;&amp; context, EdgeContent&amp; edge);</code>
<i>AgentCreator</i>	creates agents from AgentContent, implementing the following method <code>Vertex* createAgent(constAgentContent&amp; content);</code>

The documentation for this class was generated from the following file:

- `repast_hpc/SharedNetwork.h`

## 4.34 repast::EventCompare Class Reference

NON USER API.

```
#include <Schedule.h>
```

### Public Member Functions

- `int operator()` (const [ScheduledEvent](#) \*one, const [ScheduledEvent](#) \*two)

### 4.34.1 Detailed Description

NON USER API.

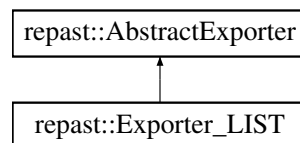
Compares ScheduledEvents based on their tick times.

The documentation for this class was generated from the following file:

- repast\_hpc/Schedule.h

## 4.35 repast::Exporter\_LIST Class Reference

Inheritance diagram for repast::Exporter\_LIST:



### Public Member Functions

- virtual void [registerIncomingRequests](#) (std::vector< [AgentRequest](#) > &requests)  
*Makes a record of the data receives (in the form of a vector of AgentRequests) so that the agents' data can be sent to the requesting processes.*
- **Exporter\_LIST** (StatusMap \*outgoingStatusMap, [AgentExporterData](#) \*outgoingAgentExporterInfo)
- virtual std::string [getReport](#) ()  
*Gets a printable report of the state of this object.*

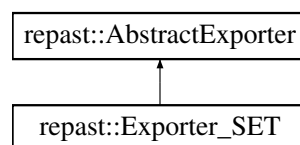
### Additional Inherited Members

The documentation for this class was generated from the following files:

- repast\_hpc/AgentImporterExporter.h
- repast\_hpc/AgentImporterExporter.cpp

## 4.36 repast::Exporter\_SET Class Reference

Inheritance diagram for repast::Exporter\_SET:



### Public Member Functions

- virtual void [registerIncomingRequests](#) (std::vector< [AgentRequest](#) > &requests)  
*Makes a record of the data receives (in the form of a vector of AgentRequests) so that the agents' data can be sent to the requesting processes.*

- **Exporter\_SET** (StatusMap \*outgoingStatusMap, [AgentExporterData](#) \*outgoingAgentExporterInfo)
- virtual std::string [getReport](#) ()

*Gets a printable report of the state of this object.*

### Additional Inherited Members

The documentation for this class was generated from the following files:

- repast\_hpc/AgentImporterExporter.h
- repast\_hpc/AgentImporterExporter.cpp

## 4.37 repast::ExportRequest Class Reference

NON USER API.

```
#include <SharedNetwork.h>
```

### Public Member Functions

- **ExportRequest** (int exportTo, [AgentId](#) id)
- [AgentId](#) **agent** () const
- int **exportTo** ()

### Friends

- class **boost::serialization::access**

### 4.37.1 Detailed Description

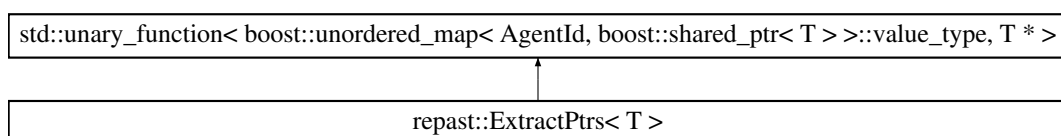
NON USER API.

The documentation for this class was generated from the following files:

- repast\_hpc/SharedNetwork.h
- repast\_hpc/SharedNetwork.cpp

## 4.38 repast::ExtractPtrs< T > Struct Template Reference

Inheritance diagram for repast::ExtractPtrs< T >:



## Public Member Functions

- `T * operator()` (typename boost::unordered\_map< [AgentId](#), boost::shared\_ptr< T > >::value\_type &val)

The documentation for this struct was generated from the following file:

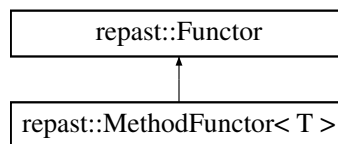
- repast\_hpc/MultipleOccupancy.h

## 4.39 repast::Functor Class Reference

[Functor](#) interface.

```
#include <Schedule.h>
```

Inheritance diagram for repast::Functor:



## Public Member Functions

- virtual void **operator**() ()=0

### 4.39.1 Detailed Description

[Functor](#) interface.

The documentation for this class was generated from the following files:

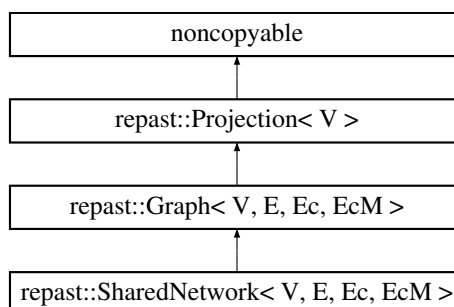
- repast\_hpc/Schedule.h
- repast\_hpc/Schedule.cpp

## 4.40 repast::Graph< V, E, Ec, EcM > Class Template Reference

[Graph](#) / Network implementation where agents are vertices in the graph.

```
#include <Graph.h>
```

Inheritance diagram for repast::Graph< V, E, Ec, EcM >:



## Public Types

- typedef  
boost::transform\_iterator  
< [NodeGetter](#)< V, E >, typename  
VertexMap::const\_iterator > [vertex\\_iterator](#)  
*An iterator over the agents that are the vertices in this [Graph](#).*

## Public Member Functions

- [Graph](#) (std::string [name](#), bool directed, EcM \*edgeContentMgr)  
*Creates a [Graph](#) with the specified name.*
- [Graph](#) (const [Graph](#)< V, E, Ec, EcM > &graph)  
*Copy constructor for the graph.*
- [Graph](#) & **operator=** (const [Graph](#) &graph)
- virtual boost::shared\_ptr< E > [addEdge](#) (V \*source, V \*target)  
*Adds an edge between source and target to this [Graph](#).*
- virtual boost::shared\_ptr< E > [addEdge](#) (V \*source, V \*target, double weight)  
*Adds an edge with the specified weight between source and target to this [Graph](#).*
- virtual boost::shared\_ptr< E > [findEdge](#) (V \*source, V \*target)  
*Gets the edge between the source and target or 0 if no such edge is found.*
- virtual void [successors](#) (V \*vertex, std::vector< V \* > &out)  
*Gets the successors of the specified vertex and puts them in out.*
- virtual void [predecessors](#) (V \*vertex, std::vector< V \* > &out)  
*Gets the predecessors of the specified vertex and puts them in out.*
- virtual void [adjacent](#) (V \*vertex, std::vector< V \* > &out)  
*Gets all the agent adjacent to the specified vertex.*
- virtual void [removeEdge](#) (V \*source, V \*target)  
*Removes the edge between source and target from this [Graph](#).*
- virtual void [removeEdge](#) (const [AgentId](#) &source, const [AgentId](#) &target)  
*Removes the edge between source and target from this [Graph](#).*
- virtual int [inDegree](#) (V \*vertex)  
*Gets the in-degree of the specified vertex.*
- virtual int [outDegree](#) (V \*vertex)  
*Gets the out-degree of the specified vertex.*
- int [edgeCount](#) () const  
*Gets the number of edges in this [Graph](#).*
- int [vertexCount](#) () const  
*Gets the number of vertices in this [Graph](#).*
- [vertex\\_iterator](#) [verticesBegin](#) ()  
*Gets the start of an iterator over all the vertices in this graph.*
- [vertex\\_iterator](#) [verticesEnd](#) ()  
*Gets the end of an iterator over all the vertices in this graph.*
- void **showEdges** ()
- virtual bool **isMaster** (E \*e)=0
- virtual bool [keepsAgentsOnSyncProj](#) ()  
*Should return true if the [Projection](#) implemented can 'keep' some (non-local) agents during a projection information synchronization operation.*
- virtual bool [sendsSecondaryAgentsOnStatusExchange](#) ()  
*Should return true if the [Projection](#) implemented will send secondary agents during a status exchange.*
- virtual void [getInfoExchangePartners](#) (std::set< int > &psToSendTo, std::set< int > &psToReceiveFrom)



*Gets the set of processes with which this [Projection](#) exchanges projection info.*

- virtual void [getAgentStatusExchangePartners](#) (std::set< int > &psToSendTo, std::set< int > &psToReceiveFrom)

*Gets the set of processes with which this [Projection](#) exchanges agent status info- that is, the set of processes from which agents can move to this one or to which they can move when moving from this one.*

- virtual void [getProjectionInfo](#) (std::vector< [AgentId](#) > &agents, std::vector< [ProjectionInfoPacket](#) \* > &packets, bool secondaryInfo=false, std::set< [AgentId](#) > \*secondaryIds=0, int destProc=-1)

*Convenience wrapper that gets all of the projection information for the agents specified (calls implementation in child class that gets only the information for one agent).*

- virtual [ProjectionInfoPacket](#) \* [getProjectionInfo](#) ([AgentId](#) id, bool secondaryInfo=false, std::set< [AgentId](#) > \*secondaryIds=0, int destProc=-1)
- virtual void [updateProjectionInfo](#) ([ProjectionInfoPacket](#) \*pip, [Context](#)< V > \*context)
- virtual void [getRequiredAgents](#) (std::set< [AgentId](#) > &agentsToTest, std::set< [AgentId](#) > &agentsRequired, RADIUS radius=[Projection](#)< V >::PRIMARY)
- virtual void [getAgentsToPush](#) (std::set< [AgentId](#) > &agentsToTest, std::map< int, std::set< [AgentId](#) > > &agentsToPush)

*Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.*

- virtual void [cleanProjectionInfo](#) (std::set< [AgentId](#) > &agentsToKeep)
- void [clearConflictedEdges](#) ()
- void [getConflictedEdges](#) (std::set< boost::shared\_ptr< E > > &conflictedEdges)

## Public Attributes

- std::set< int > [ranksToSendProjInfoTo](#)
- std::set< int > [ranksToReceiveProjInfoFrom](#)
- std::set< int > [ranksToSendAgentStatusInfoTo](#)
- std::set< int > [ranksToReceiveAgentStatusInfoFrom](#)
- bool [keepsAgents](#)
- bool [sendsSecondaryAgents](#)

## Protected Types

- typedef boost::unordered\_map< [AgentId](#), [Vertex](#)< V, E > \*, [HashId](#) > [VertexMap](#)
- typedef [VertexMap](#)::iterator [VertexMapIterator](#)
- typedef [Projection](#)< V >::RADIUS [RADIUS](#)

## Protected Member Functions

- void [cleanUp](#) ()
- void [init](#) (const [Graph](#) &graph)
- virtual bool [addAgent](#) (boost::shared\_ptr< V > agent)
- virtual void [removeAgent](#) (V \*agent)
- virtual void [doAddEdge](#) (boost::shared\_ptr< E > edge, bool allowOverwrite=true)

## Protected Attributes

- int [edgeCount\\_](#)
- bool [isDirected](#)
- [VertexMap](#) [vertices](#)
- EcM \* [edgeContentManager](#)

#### 4.40.1 Detailed Description

```
template<typename V, typename E, typename Ec, typename EcM>class repast::Graph< V, E, Ec, EcM >
```

[Graph](#) / Network implementation where agents are vertices in the graph.

## Template Parameters

<i>V</i>	the type agents in the graph. This type should extend <a href="#">repast::Agent</a>
<i>E</i>	the edge type of the graph. This type should extend <a href="#">repast::RepastEdge</a> .
<i>Ec</i>	class of serializable Edge Content
<i>EcM</i>	Class that is capable of transforming an Edge into Edge Content and vice versa

## 4.40.2 Constructor &amp; Destructor Documentation

4.40.2.1 `template<typename V, typename E, typename Ec, typename EcM> repast::Graph< V, E, Ec, EcM >::Graph ( std::string name, bool directed, EcM * edgeContentMgr ) [inline]`

Creates a [Graph](#) with the specified name.

## Parameters

<i>name</i>	the name of the graph
<i>directed</i>	whether or not the created <a href="#">Graph</a> is directed

## 4.40.3 Member Function Documentation

4.40.3.1 `template<typename V, typename E, typename Ec, typename EcM> boost::shared_ptr< E > repast::Graph< V, E, Ec, EcM >::addEdge ( V * source, V * target ) [virtual]`

Adds an edge between source and target to this [Graph](#).

## Parameters

<i>source</i>	the source of the edge
<i>target</i>	the target of the edge

## Returns

the added edge.

4.40.3.2 `template<typename V, typename E, typename Ec, typename EcM> boost::shared_ptr< E > repast::Graph< V, E, Ec, EcM >::addEdge ( V * source, V * target, double weight ) [virtual]`

Adds an edge with the specified weight between source and target to this [Graph](#).

## Parameters

<i>source</i>	the source of the edge
<i>target</i>	the target of the edge
<i>weight</i>	the weight of the edge

## Returns

the added edge.

4.40.3.3 `template<typename V, typename E, typename Ec, typename EcM> void repast::Graph< V, E, Ec, EcM >::adjacent ( V * vertex, std::vector< V * > & out ) [virtual]`

Gets all the agent adjacent to the specified vertex.

## Parameters

	<i>vertex</i>	the vertex whose adjacent agents we want to get
out	<i>the</i>	vector where the results will be put

4.40.3.4 `template<typename V, typename E, typename Ec, typename EcM> int repast::Graph< V, E, Ec, EcM >::edgeCount ( ) const [inline]`

Gets the number of edges in this [Graph](#).

## Returns

the number of edges in this [Graph](#).

4.40.3.5 `template<typename V, typename E, typename Ec, typename EcM> boost::shared_ptr< E > repast::Graph< V, E, Ec, EcM >::findEdge ( V * source, V * target ) [virtual]`

Gets the edge between the source and target or 0 if no such edge is found.

## Parameters

<i>source</i>	the source of the edge to find
<i>target</i>	the target of the edge to find

## Returns

the found edge or 0.

4.40.3.6 `template<typename V, typename E, typename Ec, typename EcM> void repast::Graph< V, E, Ec, EcM >::getAgentStatusExchangePartners ( std::set< int > & psToSendTo, std::set< int > & psToReceiveFrom ) [virtual]`

Gets the set of processes with which this [Projection](#) exchanges agent status info- that is, the set of processes from which agents can move to this one or to which they can move when moving from this one.

In the most general case this will be all other processors. However, simulations where agents move in spaces will usually exchange agents only with a small subset of 'neighbor' processes, which is knowable in advance and constant. To accommodate the general case, the algorithm for exchanging information must poll all other processes to see which are sending to this one; if this is known in advance, this additional (expensive) step can be skipped.

Implements [repast::Projection< V >](#).

4.40.3.7 `template<typename V, typename E, typename Ec, typename EcM> void repast::Graph< V, E, Ec, EcM >::getAgentsToPush ( std::set< AgentId > & agentsToTest, std::map< int, std::set< AgentId > > & agentsToPush ) [virtual]`

Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.

Generally spaces must push agents that are in 'buffer zones' and graphs must push local agents that are vertices to master edges where the other vertex is non- local. The results are returned per-process in the agentsToPush map.

Implements [repast::Projection< V >](#).

4.40.3.8 `template<typename V, typename E, typename Ec, typename EcM> void repast::Graph< V, E, Ec, EcM >::getInfoExchangePartners ( std::set< int > & psToSendTo, std::set< int > & psToReceiveFrom ) [virtual]`

Gets the set of processes with which this [Projection](#) exchanges projection info.

In the most general case this will be all other processors; this is the case for graphs, where agent connections can be arbitrary. However, spaces usually exchange information only with a small subset of 'neighbor' processes, which is knowable in advance and constant. To accommodate the general case, the algorithm for exchanging information must poll all other processes to see which are sending to this one; if this is known in advance, this additional (expensive) step can be skipped.

Implements [repast::Projection< V >](#).

**4.40.3.9** `template<typename V, typename E, typename Ec, typename EcM> int repast::Graph< V, E, Ec, EcM >::inDegree ( V * vertex ) [virtual]`

Gets the in-degree of the specified vertex.

#### Returns

the in-degree of the specified vertex.

**4.40.3.10** `template<typename V, typename E, typename Ec, typename EcM> virtual bool repast::Graph< V, E, Ec, EcM >::keepsAgentsOnSyncProj( ) [inline],[virtual]`

Should return true if the [Projection](#) implemented can 'keep' some (non-local) agents during a projection information synchronization operation.

Generally spaces will allow all non-local agents to be deleted, but graphs keep the non-local agents that participate in Master edges.

It is possible to override these. A graph projection can be created that does not permit non-local agents to be 'kept'. This would be an extremely unusual use case, but it is possible.

Note that these are used for optimization. If no projection in a given context keeps any agents, several steps in the synchronization algorithm can be omitted. Of course, omitting these steps when a projection actually retains agents can caused undefined problems.

#### Returns

true if this projection will keep non-local agents during a projection information synchronziation event, false if it will not.

Implements [repast::Projection< V >](#).

**4.40.3.11** `template<typename V, typename E, typename Ec, typename EcM> int repast::Graph< V, E, Ec, EcM >::outDegree ( V * vertex ) [virtual]`

Gets the out-degree of the specified vertex.

#### Returns

the out-degree of the specified vertex.

**4.40.3.12** `template<typename V, typename E, typename Ec, typename EcM> void repast::Graph< V, E, Ec, EcM >::predecessors ( V * vertex, std::vector< V * > & out ) [virtual]`

Gets the predecessors of the specified vertex and puts them in out.

## Parameters

	<i>vertex</i>	the vertex whose predecessors we want to get
out	<i>where</i>	the predecessors will be returned

4.40.3.13 `template<typename V , typename E , typename Ec , typename EcM > void repast::Graph< V, E, Ec, EcM >::removeEdge ( V * source, V * target ) [virtual]`

Removes the edge between source and target from this [Graph](#).

## Parameters

<i>source</i>	the source of the edge
<i>target</i>	the target of the edge

Reimplemented in [repast::SharedNetwork< V, E, Ec, EcM >](#).

4.40.3.14 `template<typename V , typename E , typename Ec , typename EcM > void repast::Graph< V, E, Ec, EcM >::removeEdge ( const AgentId & source, const AgentId & target ) [virtual]`

Removes the edge between source and target from this [Graph](#).

## Parameters

<i>source</i>	the id of the vertex that is the source of the edge
<i>target</i>	the id of the vertex that is the target of the edge

4.40.3.15 `template<typename V, typename E, typename Ec, typename EcM> virtual bool repast::Graph< V, E, Ec, EcM >::sendsSecondaryAgentsOnStatusExchange ( ) [inline], [virtual]`

Should return true if the [Projection](#) implemented will send secondary agents during a status exchange.

Generally spaces do not and graphs do.

If no secondary agents will be sent, portions of the algorithm can be omitted for optimization.

## Returns

true if the [Projection](#) returns secondary agents, false if not

Implements [repast::Projection< V >](#).

4.40.3.16 `template<typename V , typename E , typename Ec , typename EcM > void repast::Graph< V, E, Ec, EcM >::successors ( V * vertex, std::vector< V * > & out ) [virtual]`

Gets the successors of the specified vertex and puts them in out.

## Parameters

	<i>vertex</i>	the vertex whose successors we want to get
out	<i>where</i>	the successors will be returned

4.40.3.17 `template<typename V, typename E, typename Ec, typename EcM> int repast::Graph< V, E, Ec, EcM >::vertexCount ( ) const [inline]`

Gets the number of vertices in this [Graph](#).

**Returns**

the number of vertices in this [Graph](#).

4.40.3.18 `template<typename V, typename E, typename Ec, typename EcM> vertex_iterator repast::Graph< V, E, Ec, EcM>::verticesBegin ( ) [inline]`

Gets the start of an iterator over all the vertices in this graph.

The iterator dereferences to a pointer to agents of type V.

**Returns**

the start of an iterator over all the vertices in this graph.

4.40.3.19 `template<typename V, typename E, typename Ec, typename EcM> vertex_iterator repast::Graph< V, E, Ec, EcM>::verticesEnd ( ) [inline]`

Gets the end of an iterator over all the vertices in this graph.

The iterator dereferences to a pointer to agents of type V.

**Returns**

the end of an iterator over all the vertices in this graph.

The documentation for this class was generated from the following file:

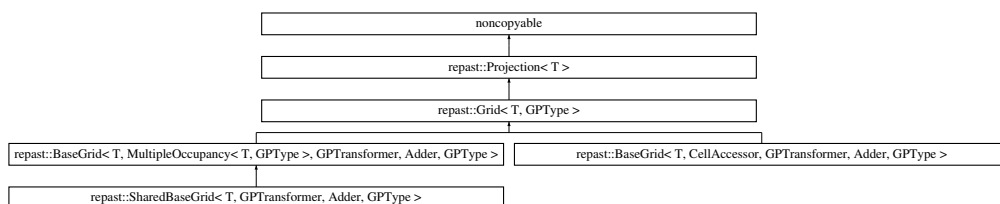
- `repast_hpc/Graph.h`

## 4.41 repast::Grid< T, GPTYPE > Class Template Reference

Abstract interface for Grids and ContinuousSpaces.

```
#include <Grid.h>
```

Inheritance diagram for `repast::Grid< T, GPTYPE >`:

**Public Member Functions**

- [Grid](#) (std::string *name*)  
*Creates a [Grid](#) with the specified name.*
- virtual bool [contains](#) (const [AgentId](#) &id)=0  
*Gets whether or not this grid contains the agent with the specified id.*
- virtual bool [moveTo](#) (const [AgentId](#) &id, const [Point](#)< GPTYPE > &pt)=0  
*Moves the specified agent to the specified point.*

- virtual std::pair< bool, [Point](#)  
< GType > > [moveByVector](#) (const T \*agent, double distance, const std::vector< double > &anglesInRadians)=0  
*Moves the specified object the specified distance from its current position along the specified angle.*
- virtual std::pair< bool, [Point](#)  
< GType > > [moveByDisplacement](#) (const T \*agent, const std::vector< GType > &displacement)=0  
*Moves the specified object from its current location by the specified amount.*
- virtual const [GridDimensions](#) [dimensions](#) () const =0  
*Gets the dimensions of this [Grid](#).*
- virtual T \* [getObjectAt](#) (const [Point](#)< GType > &pt) const =0  
*Gets the first object found at the specified point, or NULL if there is no such object.*
- virtual void [getObjectsAt](#) (const [Point](#)< GType > &pt, std::vector< T \* > &out) const =0  
*Gets all the objects found at the specified point.*
- virtual bool [getLocation](#) (const T \*agent, std::vector< GType > &out) const =0  
*Gets the location of this agent and puts it in the specified vector.*
- virtual bool [getLocation](#) (const [AgentId](#) &id, std::vector< GType > &out) const =0  
*Gets the location of this agent and puts it in the specified vectors.*
- virtual void [getDisplacement](#) (const [Point](#)< GType > &pt1, const [Point](#)< GType > &pt2, std::vector< GType > &out) const =0  
*Gets vector difference between point 1 and point 2, putting the result in out.*
- virtual double [getDistance](#) (const [Point](#)< GType > &pt1, const [Point](#)< GType > &pt2) const =0  
*Gets the distance between the two grid points.*
- virtual double [getDistanceSq](#) (const [Point](#)< GType > &pt1, const [Point](#)< GType > &pt2) const =0  
*Gets the square of the distance between the two grid points.*
- virtual void [translate](#) (const [Point](#)< GType > &location, const [Point](#)< GType > &displacement, std::vector< GType > &out) const =0  
*Translates the specified location by the specified displacement put the result in out.*
- virtual void [transform](#) (const std::vector< GType > &location, std::vector< GType > &out) const =0  
*Transforms the specified location using the properties (e.g.*
- virtual bool [isPeriodic](#) () const =0  
*Gets whether or not this grid is periodic (i.e.*
- virtual [ProjectionInfoPacket](#) \* [getProjectionInfo](#) ([AgentId](#) id, bool secondaryInfo=false, std::set< [AgentId](#) > \*secondaryIds=0, int destProc=-1)=0
- virtual void [updateProjectionInfo](#) ([ProjectionInfoPacket](#) \*pip, [Context](#)< T > \*context)=0
- virtual void [getRequiredAgents](#) (std::set< [AgentId](#) > &agentsToTest, std::set< [AgentId](#) > &agentsRequired, [RADIUS](#) radius=[Projection](#)< T >::PRIMARY)  
*Given a set of agents to test, gets the subset that must be kept in order to fulfill the projection's 'contract' to the specified radius.*
- virtual void [getAgentsToPush](#) (std::set< [AgentId](#) > &agentsToTest, std::map< int, std::set< [AgentId](#) > > &agentsToPush)=0  
*Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.*
- virtual bool [keepsAgentsOnSyncProj](#) ()  
*Should return true if the [Projection](#) implemented can 'keep' some (non-local) agents during a projection information synchronization operation.*
- virtual bool [sendsSecondaryAgentsOnStatusExchange](#) ()  
*Should return true if the [Projection](#) implemented will send secondary agents during a status exchange.*
- virtual void [getInfoExchangePartners](#) (std::set< int > &psToSendTo, std::set< int > &psToReceiveFrom)=0  
*Gets the set of processes with which this [Projection](#) exchanges projection info.*
- virtual void [getAgentStatusExchangePartners](#) (std::set< int > &psToSendTo, std::set< int > &psToReceiveFrom)=0  
*Gets the set of processes with which this [Projection](#) exchanges agent status info- that is, the set of processes from which agents can move to this one or to which they can move when moving from this one.*
- virtual void [cleanProjectionInfo](#) (std::set< [AgentId](#) > &agentsToKeep)



## Additional Inherited Members

### 4.41.1 Detailed Description

`template<typename T, typename GPType>class repast::Grid< T, GPType >`

Abstract interface for Grids and ContinuousSpaces.

#### Template Parameters

<i>T</i>	the type of objects this <a href="#">Grid</a> contains
<i>GPType</i>	the coordinate type of the grid point locations. This must be an int or a double.

### 4.41.2 Constructor & Destructor Documentation

4.41.2.1 `template<typename T, typename GPType> repast::Grid< T, GPType >::Grid ( std::string name ) [inline]`

Creates a [Grid](#) with the specified name.

#### Parameters

<i>name</i>	the name of the <a href="#">Grid</a> . This should be unique among Projections.
-------------	---

### 4.41.3 Member Function Documentation

4.41.3.1 `template<typename T, typename GPType> virtual bool repast::Grid< T, GPType >::contains ( const AgentId & id ) [pure virtual]`

Gets whether or not this grid contains the agent with the specified id.

#### Parameters

<i>id</i>	the id of the agent to check
-----------	------------------------------

#### Returns

true if the grid contains the agent, otherwise false.

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

4.41.3.2 `template<typename T, typename GPType> virtual const GridDimensions repast::Grid< T, GPType >::dimensions ( ) const [pure virtual]`

Gets the dimensions of this [Grid](#).

#### Returns

the dimensions of this [Grid](#).

Implemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

4.41.3.3 `template<typename T, typename GPTYPE> virtual void repast::Grid< T, GPTYPE >::getAgentStatus-ExchangePartners ( std::set< int > & psToSendTo, std::set< int > & psToReceiveFrom ) [pure virtual]`

Gets the set of processes with which this [Projection](#) exchanges agent status info- that is, the set of processes from which agents can move to this one or to which they can move when moving from this one.

In the most general case this will be all other processors. However, simulations where agents move in spaces will usually exchange agents only with a small subset of 'neighbor' processes, which is knowable in advance and constant. To accommodate the general case, the algorithm for exchanging information must poll all other processes to see which are sending to this one; if this is known in advance, this additional (expensive) step can be skipped.

Implements [repast::Projection< T >](#).

Implemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPTYPE >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), and [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#).

4.41.3.4 `template<typename T, typename GPTYPE> virtual void repast::Grid< T, GPTYPE >::getAgentsToPush ( std::set< AgentId > & agentsToTest, std::map< int, std::set< AgentId > > & agentsToPush ) [pure virtual]`

Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.

Generally spaces must push agents that are in 'buffer zones' and graphs must push local agents that are vertices to master edges where the other vertex is non- local. The results are returned per-process in the agentsToPush map.

Implements [repast::Projection< T >](#).

Implemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPTYPE >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPTYPE >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPTYPE >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#), and [repast::SharedDiscreteSpace< T, GPTransformer, Adder >](#).

4.41.3.5 `template<typename T, typename GPTYPE> virtual void repast::Grid< T, GPTYPE >::getDisplacement ( const Point< GPTYPE > & pt1, const Point< GPTYPE > & pt2, std::vector< GPTYPE > & out ) const [pure virtual]`

Gets vector difference between point 1 and point 2, putting the result in out.

Parameters

	<i>p1</i>	the first point
	<i>p2</i>	the second point
out	<i>the</i>	vector where the difference will be put

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPTYPE >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPTYPE >, GPTransformer, Adder, GPTYPE >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

4.41.3.6 `template<typename T, typename GPTYPE> virtual double repast::Grid< T, GPTYPE >::getDistance ( const Point< GPTYPE > & pt1, const Point< GPTYPE > & pt2 ) const [pure virtual]`

Gets the distance between the two grid points.

## Parameters

<i>p1</i>	the first point
<i>p2</i>	the second point

## Returns

the distance between `pt1` and `pt2`.

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

**4.41.3.7** `template<typename T, typename GPType> virtual double repast::Grid< T, GPType >::getDistanceSq ( const Point< GPType > & pt1, const Point< GPType > & pt2 ) const` [pure virtual]

Gets the square of the distance between the two grid points.

## Parameters

<i>p1</i>	the first point
<i>p2</i>	the second point

## Returns

the square of the distance between `pt1` and `pt2`.

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

**4.41.3.8** `template<typename T, typename GPType> virtual void repast::Grid< T, GPType >::getInfoExchangePartners ( std::set< int > & psToSendTo, std::set< int > & psToReceiveFrom )` [pure virtual]

Gets the set of processes with which this [Projection](#) exchanges projection info.

In the most general case this will be all other processors; this is the case for graphs, where agent connections can be arbitrary. However, spaces usually exchange information only with a small subset of 'neighbor' processes, which is knowable in advance and constant. To accommodate the general case, the algorithm for exchanging information must poll all other processes to see which are sending to this one; if this is known in advance, this additional (expensive) step can be skipped.

Implements [repast::Projection< T >](#).

Implemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), and [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#).

**4.41.3.9** `template<typename T, typename GPType> virtual bool repast::Grid< T, GPType >::getLocation ( const T * agent, std::vector< GPType > & out ) const` [pure virtual]

Gets the location of this agent and puts it in the specified vector.

The x coordinate will be the first value, the y the second and so on.

**Parameters**

	<i>agent</i>	the agent whose location we want to get
out	<i>the</i>	vector where the agents location will be put

**Returns**

true if the location was successfully found, otherwise false.

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

**4.41.3.10** `template<typename T, typename GPType> virtual bool repast::Grid< T, GPType >::getLocation ( const AgentId & id, std::vector< GPType > & out ) const [pure virtual]`

Gets the location of this agent and puts it in the specified vectors.

The x coordinate will be the first value, the y the second and so on.

**Parameters**

	<i>id</i>	the id of the agent whose location we want to get
out	<i>out</i>	the agent's location will be put into this vector

**Returns**

true if the location was successfully found, otherwise false.

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

**4.41.3.11** `template<typename T, typename GPType> virtual T* repast::Grid< T, GPType >::getObjectAt ( const Point< GPType > & pt ) const [pure virtual]`

Gets the first object found at the specified point, or NULL if there is no such object.

**Returns**

the first object found at the specified point, or NULL if there is no such object.

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

**4.41.3.12** `template<typename T, typename GPType> virtual void repast::Grid< T, GPType >::getObjectsAt ( const Point< GPType > & pt, std::vector< T* > & out ) const [pure virtual]`

Gets all the objects found at the specified point.

The found objects will be put into the out parameter.

## Parameters

	<i>pt</i>	the point to get all the objects at
out	<i>out</i>	the vector into which the found objects will be put

Implemented in `repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >`, `repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >`, `repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >`, and `repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >`.

**4.41.3.13** `template<typename T, typename GPType> virtual void repast::Grid< T, GPType >::getRequiredAgents ( std::set< AgentId > & agentsToTest, std::set< AgentId > & agentsRequired, RADIUS radius = Projection< T >::PRIMARY ) [inline],[virtual]`

Given a set of agents to test, gets the subset that must be kept in order to fulfill the projection's 'contract' to the specified radius.

Generally spaces do not require any agents, but graphs do- generally the non-local ends to master copies of edges.

Implements `repast::Projection< T >`.

**4.41.3.14** `template<typename T, typename GPType> virtual bool repast::Grid< T, GPType >::isPeriodic ( ) const [pure virtual]`

Gets whether or not this grid is periodic (i.e. toroidal).

## Returns

true if this `Grid` is periodic, otherwise false.

Implemented in `repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >`, `repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >`, `repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >`, and `repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >`.

**4.41.3.15** `template<typename T, typename GPType> virtual bool repast::Grid< T, GPType >::keepsAgentsOnSyncProj ( ) [inline],[virtual]`

Should return true if the `Projection` implemented can 'keep' some (non-local) agents during a projection information synchronization operation.

Generally spaces will allow all non-local agents to be deleted, but graphs keep the non-local agents that participate in Master edges.

It is possible to override these. A graph projection can be created that does not permit non-local agents to be 'kept'. This would be an extremely unusual use case, but it is possible.

Note that these are used for optimization. If no projection in a given context keeps any agents, several steps in the synchronization algorithm can be omitted. Of course, omitting these steps when a projection actually retains agents can caused undefined problems.

## Returns

true if this projection will keep non-local agents during a projection information synchronziation event, false if it will not.

Implements `repast::Projection< T >`.

```
4.41.3.16  template<typename T, typename GPTYPE> virtual std::pair<bool, Point<GPTYPE> > repast::Grid< T,
           GPTYPE >::moveByDisplacement ( const T * agent, const std::vector< GPTYPE > & displacement )  [pure
           virtual]
```

Moves the specified object from its current location by the specified amount.

For example `moveByDisplacement(object, 3, -2, 1)` will move the object by 3 along the x-axis, -2 along the y and 1 along the z. The displacement argument can be less than the number of dimensions in the space in which case the remaining argument will be set to 0. For example, `moveByDisplacement(object, 3)` will move the object 3 along the x-axis and 0 along the y and z axes, assuming a 3D grid.

#### Parameters

<i>agent</i>	the object to move
<i>displacement</i>	the amount to move the object

#### Returns

a pair containing a bool that indicates whether the move was a success or not, and the point where the agent was moved to.

Implemented in `repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPTYPE >`, `repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >`, `repast::BaseGrid< T, MultipleOccupancy< T, GPTYPE >, GPTransformer, Adder, GPTYPE >`, and `repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >`.

```
4.41.3.17  template<typename T, typename GPTYPE> virtual std::pair<bool, Point<GPTYPE> > repast::Grid< T, GPTYPE
           >::moveByVector ( const T * agent, double distance, const std::vector< double > & anglesInRadians )  [pure
           virtual]
```

Moves the specified object the specified distance from its current position along the specified angle.

For example, `moveByVector(object, 1, Grid.NORTH)` will move the object 1 unit "north" up the y-axis, assuming a 2D grid. Similarly, `grid.moveByVector(object, 2, 0, Math.toRadians(90), 0)` will rotate 90 degrees around the y-axis, thus moving the object 2 units along the z-axis.

**Note that the radians / degrees are incremented in a anti-clockwise fashion, such that 0 degrees is "east", 90 degrees is "north", 180 is "west" and 270 is "south."**

#### Parameters

<i>agent</i>	the object to move
<i>distance</i>	the distance to move
<i>anglesInRadians</i>	the angle to move along in radians.

#### Returns

**a pair containing a bool that indicates whether the move was a success or not, and the point where the agent was moved to.**

Implemented in `repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPTYPE >`, `repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >`, `repast::BaseGrid< T, MultipleOccupancy< T, GPTYPE >, GPTransformer, Adder, GPTYPE >`, and `repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >`.

```
4.41.3.18  template<typename T, typename GPTYPE> virtual bool repast::Grid< T, GPTYPE >::moveTo ( const AgentId &
           id, const Point< GPTYPE > & pt )  [pure virtual]
```

Moves the specified agent to the specified point.

## Parameters

<i>id</i>	the id of the agent to move
<i>pt</i>	where to move the agent to

## Returns

true if the move was successful, otherwise false

Implemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

**4.41.3.19** `template<typename T, typename GPType> virtual bool repast::Grid< T, GPType >::sendsSecondaryAgentsOnStatusExchange ( ) [inline], [virtual]`

Should return true if the [Projection](#) implemented will send secondary agents during a status exchange.

Generally spaces do not and graphs do.

If no secondary agents will be sent, portions of the algorithm can be omitted for optimization.

## Returns

true if the [Projection](#) returns secondary agents, false if not

Implements [repast::Projection< T >](#).

**4.41.3.20** `template<typename T, typename GPType> virtual void repast::Grid< T, GPType >::transform ( const std::vector< GPType > & location, std::vector< GPType > & out ) const [pure virtual]`

Transforms the specified location using the properties (e.g.

toroidal) of this space.

## Parameters

	<i>location</i>	the location to transform
<i>out</i>	<i>out</i>	the vector where the result of the transform will be put

Implemented in [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), and [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

**4.41.3.21** `template<typename T, typename GPType> virtual void repast::Grid< T, GPType >::translate ( const Point< GPType > & location, const Point< GPType > & displacement, std::vector< GPType > & out ) const [pure virtual]`

Translates the specified location by the specified displacement put the result in out.

## Parameters

	<i>location</i>	the initial location
--	-----------------	----------------------

	<i>displacement</i>	the amount to translate the location by
out	<i>out</i>	the vector where the result of the translation is put

Implemented in [repastr::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repastr::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repastr::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), and [repastr::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#).

The documentation for this class was generated from the following file:

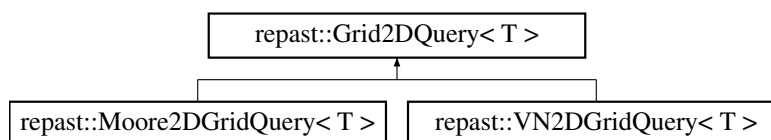
- [repastr\\_hpc/Grid.h](#)

## 4.42 repastr::Grid2DQuery< T > Class Template Reference

Base class for neighborhood queries on discrete Grids.

```
#include <Grid2DQuery.h>
```

Inheritance diagram for repastr::Grid2DQuery< T >:



### Public Member Functions

- [Grid2DQuery](#) (const [Grid](#)< T, int > \*grid)  
*Creates [Grid2DQuery](#) that will query the specified [Grid](#).*
- virtual void [query](#) (const [Point](#)< int > &center, int range, bool includeCenter, std::vector< T \* > &out) const =0  
*Queries the [Grid](#) for the neighbors surrounding the center point within a specified range.*

### Protected Attributes

- const [Grid](#)< T, int > \* **\_grid**
- int **minMax** [2][2]

#### 4.42.1 Detailed Description

```
template<typename T>class repastr::Grid2DQuery< T >
```

Base class for neighborhood queries on discrete Grids.

#### Template Parameters

<i>T</i>	the type of object in the <a href="#">Grid</a> .
----------	--

#### 4.42.2 Member Function Documentation

4.42.2.1 `template<typename T> virtual void repastr::Grid2DQuery< T >::query ( const Point< int > &center, int range, bool includeCenter, std::vector< T * > &out ) const` [pure virtual]

Queries the [Grid](#) for the neighbors surrounding the center point within a specified range.



What constitutes the neighborhood is determined by subclass implementors.

## Parameters

	<i>center</i>	the center of the neighborhood
	<i>range</i>	the range of the neighborhood out from the center
	<i>includeCenter</i>	whether or not to include any agents at the center
out	<i>the</i>	neighboring agents will be returned in this vector

Implemented in [repast::Moore2DGridQuery< T >](#), and [repast::VN2DGridQuery< T >](#).

The documentation for this class was generated from the following file:

- [repast\\_hpc/Grid2DQuery.h](#)

## 4.43 repast::GridBufferSyncher< T, GPType > Class Template Reference

NON USER API.

```
#include <SharedBaseGrid.h>
```

### Public Member Functions

- **GridBufferSyncher** (boost::mpi::communicator \*world)
- std::vector< [CellContents](#)< T, GPType > > \* **received** (size\_t index)
- int **nghRank** (size\_t index)
- size\_t **vecsSize** ()
- void **send** (int rank, std::vector< [CellContents](#)< T, GPType > > &contents, int tag)  
*Sends the contents to the rank.*
- void **receive** ([Neighbor](#) \*ngh, int tag)
- void **wait** ()

### 4.43.1 Detailed Description

```
template<typename T, typename GPType>class repast::GridBufferSyncher< T, GPType >
```

NON USER API.

Helper class that provides support for synchronizing a grid / space buffer.

The documentation for this class was generated from the following file:

- [repast\\_hpc/SharedBaseGrid.h](#)

## 4.44 repast::GridDimensions Class Reference

### Public Member Functions

- **GridDimensions** ([Point](#)< double > extent)
- **GridDimensions** ([Point](#)< double > [origin](#), [Point](#)< double > extent)  
*Creates a [GridDimensions](#) with the specified origin and extent.*
- bool **contains** (const [Point](#)< int > &pt) const
- bool **contains** (const std::vector< int > &pt) const
- bool **contains** (const [Point](#)< double > &pt) const
- bool **contains** (const std::vector< double > &pt) const

- const [Point](#)< double > & [origin](#) () const  
*Gets the origin.*
- const [Point](#)< double > & [extents](#) () const  
*Gets the extents along each dimension.*
- const double & [origin](#) (int index) const
- const double & [extents](#) (int index) const
- size\_t [dimensionCount](#) () const

## Friends

- bool [operator==](#) (const [GridDimensions](#) &one, const [GridDimensions](#) &two)
- std::ostream & [operator<<](#) (std::ostream &os, const [GridDimensions](#) &dimensions)

The documentation for this class was generated from the following files:

- repast\_hpc/GridDimensions.h
- repast\_hpc/GridDimensions.cpp

## 4.45 repast::GridMovePacket< PtType > Struct Template Reference

Encapsulates a info about an agent moving off the grid: the rank it moved to, its grid location, and the agent id.

```
#include <GridMovePackets.h>
```

## Public Member Functions

- **GridMovePacket** (const [Point](#)< PtType > &pt, const [AgentId](#) &id, int rank)
- template<class Archive >  
void **serialize** (Archive &ar, const unsigned int version)

## Public Attributes

- [Point](#)< PtType > [\\_pt](#)
- [AgentId](#) [\\_id](#)
- int [\\_rank](#)

### 4.45.1 Detailed Description

```
template<typename PtType>struct repast::GridMovePacket< PtType >
```

Encapsulates a info about an agent moving off the grid: the rank it moved to, its grid location, and the agent id.

The documentation for this struct was generated from the following file:

- repast\_hpc/GridMovePackets.h

## 4.46 repast::GridMovePackets< PtType > Class Template Reference

## Public Member Functions

- void **addPacket** (const [GridMovePacket](#)< PtType > &packet)

- void **clear** ()
- void **removePacketFor** (const [AgentId](#) &id)  
*Removes any GridMovePacket-s associated with the specified agent id.*
- void **send** (std::vector< boost::mpi::request > &requests, boost::mpi::communicator world)
- void **receivers** (std::vector< int > &receivers)

The documentation for this class was generated from the following file:

- repast\_hpc/GridMovePackets.h

## 4.47 repast::GridPointHolder< T, GPType > Struct Template Reference

Encapsulates a grid point and what is held in it.

```
#include <BaseGrid.h>
```

### Public Attributes

- bool **inGrid**
- [Point](#)< GPType > **point**
- boost::shared\_ptr< T > **ptr**

### 4.47.1 Detailed Description

```
template<typename T, typename GPType>struct repast::GridPointHolder< T, GPType >
```

Encapsulates a grid point and what is held in it.

The documentation for this struct was generated from the following file:

- repast\_hpc/BaseGrid.h

## 4.48 repast::HashGridPoint< T > Struct Template Reference

### Public Member Functions

- std::size\_t **operator()** (const [Point](#)< T > &pt) const

The documentation for this struct was generated from the following file:

- repast\_hpc/Point.h

## 4.49 repast::HashId Struct Reference

**operator()** implementation that returns the hashcode of an [AgentId](#).

```
#include <AgentId.h>
```

### Public Member Functions

- std::size\_t **operator()** (const [AgentId](#) &id) const

#### 4.49.1 Detailed Description

operator() implementation that returns the hashcode of an [AgentId](#).

The documentation for this struct was generated from the following file:

- repast\_hpc/AgentId.h

### 4.50 repast::HashVertex< V, E > Struct Template Reference

Hashes a [Vertex](#) using the hashcode of the [AgentId](#) that the vertex contains.

```
#include <Vertex.h>
```

#### Public Member Functions

- `std::size_t operator() (Vertex< V, E > *vertex) const`

#### 4.50.1 Detailed Description

```
template<typename V, typename E>struct repast::HashVertex< V, E >
```

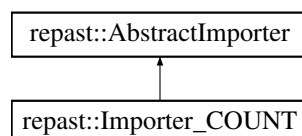
Hashes a [Vertex](#) using the hashcode of the [AgentId](#) that the vertex contains.

The documentation for this struct was generated from the following file:

- repast\_hpc/Vertex.h

### 4.51 repast::Importer\_COUNT Class Reference

Inheritance diagram for repast::Importer\_COUNT:



#### Public Member Functions

- virtual void [registerOutgoingRequests](#) ([AgentRequest](#) &req)  
*Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.*
- virtual void [importedAgentsRemoved](#) (const [AgentId](#) &id)  
*Notifies this importer that the agent that it (presumably) has been importing has been removed from the simulation on its home process, and the information for that agent will no longer be sent.*
- virtual void [importedAgentsMoved](#) (const [AgentId](#) &id, int newProcess)  
*Notifies this importer that the agent that it (presumably) has been importing from another process has been moved; its information will now be received from its new home process (unless the agent was moved to this process)*
- virtual std::string [getReport](#) ()  
*Get a printable indication of the data in this object.*
- virtual void [getSetOfAgentsBeingImported](#) (std::set< [AgentId](#) > &set)

## Additional Inherited Members

### 4.51.1 Member Function Documentation

#### 4.51.1.1 void Importer\_COUNT::registerOutgoingRequests ( AgentRequest & req ) [virtual]

Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.

The record must at a minimum indicate which other processes are sending agent information, but may include other information, such as how many times a particular agent has been requested.

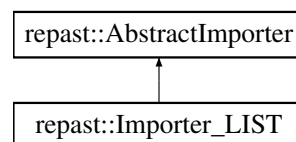
Implements [repast::AbstractImporter](#).

The documentation for this class was generated from the following files:

- repast\_hpc/AgentImporterExporter.h
- repast\_hpc/AgentImporterExporter.cpp

## 4.52 repast::Importer\_LIST Class Reference

Inheritance diagram for repast::Importer\_LIST:



## Public Member Functions

- virtual void [registerOutgoingRequests](#) (AgentRequest &req)  
*Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.*
- virtual void [importedAgentsRemoved](#) (const AgentId &id)  
*Notifies this importer that the agent that it (presumably) has been importing has been removed from the simulation on its home process, and the information for that agent will no longer be sent.*
- virtual void [importedAgentsMoved](#) (const AgentId &id, int newProcess)  
*Notifies this importer that the agent that it (presumably) has been importing from another process has been moved; its information will now be received from its new home process (unless the agent was moved to this process)*
- virtual std::string [getReport](#) ()  
*Get a printable indication of the data in this object.*
- virtual void [getSetOfAgentsBeingImported](#) (std::set< AgentId > &set)
- virtual void [clear](#) ()

## Additional Inherited Members

### 4.52.1 Member Function Documentation

#### 4.52.1.1 void Importer\_LIST::registerOutgoingRequests ( AgentRequest & req ) [virtual]

Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.

The record must at a minimum indicate which other processes are sending agent information, but may include other information, such as how many times a particular agent has been requested.

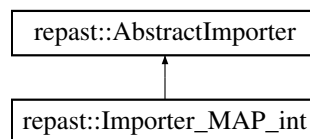
Implements [repast::AbstractImporter](#).

The documentation for this class was generated from the following files:

- repast\_hpc/AgentImporterExporter.h
- repast\_hpc/AgentImporterExporter.cpp

## 4.53 repast::Importer\_MAP\_int Class Reference

Inheritance diagram for repast::Importer\_MAP\_int:



### Public Member Functions

- virtual void [registerOutgoingRequests](#) ([AgentRequest](#) &req)  
*Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.*
- virtual void [importedAgentsRemoved](#) (const [AgentId](#) &id)  
*Notifies this importer that the agent that it (presumably) has been importing has been removed from the simulation on its home process, and the information for that agent will no longer be sent.*
- virtual void [importedAgentsMoved](#) (const [AgentId](#) &id, int newProcess)  
*Notifies this importer that the agent that it (presumably) has been importing from another process has been moved; its information will now be received from its new home process (unless the agent was moved to this process)*
- virtual std::string [getReport](#) ()  
*Get a printable indication of the data in this object.*
- virtual void [getSetOfAgentsBeingImported](#) (std::set< [AgentId](#) > &set)
- virtual void [clear](#) ()

### Additional Inherited Members

#### 4.53.1 Member Function Documentation

##### 4.53.1.1 void Importer\_MAP\_int::registerOutgoingRequests ( [AgentRequest](#) & req ) [virtual]

Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.

The record must at a minimum indicate which other processes are sending agent information, but may include other information, such as how many times a particular agent has been requested.

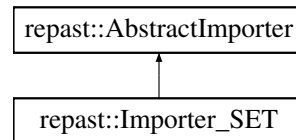
Implements [repast::AbstractImporter](#).

The documentation for this class was generated from the following files:

- repast\_hpc/AgentImporterExporter.h
- repast\_hpc/AgentImporterExporter.cpp

## 4.54 repast::Importer\_SET Class Reference

Inheritance diagram for repast::Importer\_SET:



### Public Member Functions

- virtual void [registerOutgoingRequests](#) ([AgentRequest](#) &req)  
*Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.*
- virtual void [importedAgentsRemoved](#) (const [AgentId](#) &id)  
*Notifies this importer that the agent that it (presumably) has been importing has been removed from the simulation on its home process, and the information for that agent will no longer be sent.*
- virtual void [importedAgentsMoved](#) (const [AgentId](#) &id, int newProcess)  
*Notifies this importer that the agent that it (presumably) has been importing from another process has been moved; its information will now be received from its new home process (unless the agent was moved to this process)*
- virtual std::string [getReport](#) ()  
*Get a printable indication of the data in this object.*
- virtual void [getSetOfAgentsBeingImported](#) (std::set< [AgentId](#) > &set)
- virtual void [clear](#) ()

### Additional Inherited Members

#### 4.54.1 Member Function Documentation

4.54.1.1 void [Importer\\_SET::registerOutgoingRequests](#) ( [AgentRequest](#) & req ) [virtual]

Given an agent request (including requests for agents on multiple other processes), makes a record of the agents that are being requested by this process and will therefore be received from other processes.

The record must at a minimum indicate which other processes are sending agent information, but may include other information, such as how many times a particular agent has been requested.

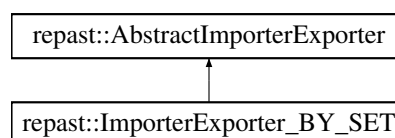
Implements [repast::AbstractImporter](#).

The documentation for this class was generated from the following files:

- repast\_hpc/AgentImporterExporter.h
- repast\_hpc/AgentImporterExporter.cpp

## 4.55 repast::ImporterExporter\_BY\_SET Class Reference

Inheritance diagram for repast::ImporterExporter\_BY\_SET:





## Public Member Functions

- virtual const std::set< int > & **getExportingProcesses** ()
- const std::set< int > & **getExportingProcesses** (std::string setName)
- virtual void **registerOutgoingRequests** ([AgentRequest](#) &request)
- void **registerOutgoingRequests** ([AgentRequest](#) &request, std::string setName, AGENT\_IMPORTER\_EXPORTER\_TYPE setType=DEFAULT\_ENUM\_SYMBOL)
- virtual void **importedAgentsRemoved** (const [AgentId](#) &id)
- virtual void **importedAgentsMoved** (const [AgentId](#) &id, int newProcess)
- virtual void **importedAgentsNowLocal** (const [AgentId](#) &id)
- virtual const  
AbstractExporter::StatusMap \* **getOutgoingStatusChanges** ()
- virtual const std::set< int > & **getProcessesExportedTo** ()
- const std::set< int > & **getProcessesExportedTo** (std::string setName)
- virtual void **registerIncomingRequests** (std::vector< [AgentRequest](#) > &requests)
- void **registerIncomingRequests** (std::vector< [AgentRequest](#) > &requests, std::string setName)
- virtual void **agentRemoved** (const [AgentId](#) &id)
- virtual void **agentMoved** (const [AgentId](#) &id, int newProcess)
- virtual void **incorporateAgentExporterInfo** (std::map< int, [AgentRequest](#) \* > info)
- void **incorporateAgentExporterInfo** (std::map< std::string, std::map< int, [AgentRequest](#) \* > \* > info)
- virtual void **clearStatusMap** ()
- virtual AgentExporterInfo \* **getAgentExportInfo** (int destProc)
- virtual void **clearAgentExportInfo** ()
- virtual const std::map< int,  
[AgentRequest](#) > & **getAgentsToExport** ()
- const std::map< int,  
[AgentRequest](#) > & **getAgentsToExport** (std::string setName)
- virtual std::string **version** ()  
  
*Returns the version of this [AbstractImporterExporter](#).*
- void **dropSet** (std::string setName)
- virtual std::string **getReport** ()  
  
*Gets a printable report of the state of this object.*
- virtual void **getSetOfAgentsBeingImported** (std::set< [AgentId](#) > &set)
- void **getSetOfAgentsBeingImported** (std::set< [AgentId](#) > &set, std::string excludeSet)
- virtual void **clear** ()
- void **clear** (std::string setName)
- virtual void **clearExporter** ()
- void **clearExporter** (std::string setName)
- void **clearExportToSpecificProc** (int rank)

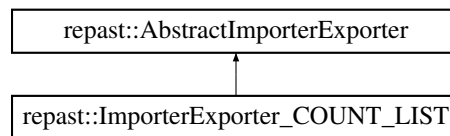
## Additional Inherited Members

The documentation for this class was generated from the following files:

- repast\_hpc/AgentImporterExporter.h
- repast\_hpc/AgentImporterExporter.cpp

## 4.56 repast::ImporterExporter\_COUNT\_LIST Class Reference

Inheritance diagram for repast::ImporterExporter\_COUNT\_LIST:



### Public Member Functions

- **ImporterExporter\_COUNT\_LIST** (AbstractExporter::StatusMap \*outgoingStatusMap, [AgentExporterData](#) \*outgoingAgentExporterInfo)
- virtual std::string [version](#) ()  
*Returns the version of this [AbstractImporterExporter](#).*

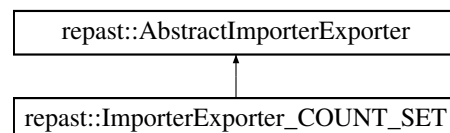
### Additional Inherited Members

The documentation for this class was generated from the following files:

- repast\_hpc/AgentImporterExporter.h
- repast\_hpc/AgentImporterExporter.cpp

## 4.57 repast::ImporterExporter\_COUNT\_SET Class Reference

Inheritance diagram for repast::ImporterExporter\_COUNT\_SET:



### Public Member Functions

- **ImporterExporter\_COUNT\_SET** (AbstractExporter::StatusMap \*outgoingStatusMap, [AgentExporterData](#) \*outgoingAgentExporterInfo)
- virtual std::string [version](#) ()  
*Returns the version of this [AbstractImporterExporter](#).*

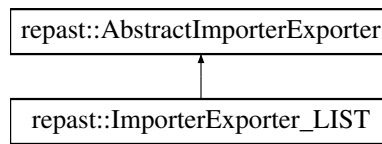
### Additional Inherited Members

The documentation for this class was generated from the following files:

- repast\_hpc/AgentImporterExporter.h
- repast\_hpc/AgentImporterExporter.cpp

## 4.58 repast::ImporterExporter\_LIST Class Reference

Inheritance diagram for repast::ImporterExporter\_LIST:



### Public Member Functions

- **ImporterExporter\_LIST** (AbstractExporter::StatusMap \*outgoingStatusMap, [AgentExporterData](#) \*outgoing-AgentExporterInfo)
- virtual std::string [version](#) ()  
*Returns the version of this [AbstractImporterExporter](#).*

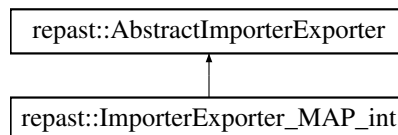
### Additional Inherited Members

The documentation for this class was generated from the following files:

- repast\_hpc/AgentImporterExporter.h
- repast\_hpc/AgentImporterExporter.cpp

## 4.59 repast::ImporterExporter\_MAP\_int Class Reference

Inheritance diagram for repast::ImporterExporter\_MAP\_int:



### Public Member Functions

- **ImporterExporter\_MAP\_int** (AbstractExporter::StatusMap \*outgoingStatusMap, [AgentExporterData](#) \*outgoingAgentExporterInfo)
- virtual std::string [version](#) ()  
*Returns the version of this [AbstractImporterExporter](#).*

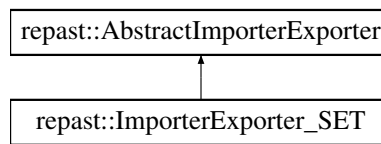
### Additional Inherited Members

The documentation for this class was generated from the following files:

- repast\_hpc/AgentImporterExporter.h
- repast\_hpc/AgentImporterExporter.cpp

## 4.60 repast::ImporterExporter\_SET Class Reference

Inheritance diagram for repast::ImporterExporter\_SET:



### Public Member Functions

- **ImporterExporter\_SET** (AbstractExporter::StatusMap \*outgoingStatusMap, [AgentExporterData](#) \*outgoing-AgentExporterInfo)
- virtual std::string [version](#) ()  
*Returns the version of this [AbstractImporterExporter](#).*

### Additional Inherited Members

The documentation for this class was generated from the following files:

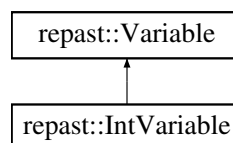
- repast\_hpc/AgentImporterExporter.h
- repast\_hpc/AgentImporterExporter.cpp

## 4.61 repast::IntVariable Class Reference

NON USER API.

```
#include <Variable.h>
```

Inheritance diagram for repast::IntVariable:



### Public Member Functions

- virtual void [write](#) (size\_t index, std::ofstream &out)  
*Writes the data at the specified index to the specified ofstream.*
- virtual void [insert](#) (double \*array, size\_t size)  
*Insertes all the doubles in the double array into the collection of data stored in this [Variable](#).*
- virtual void [insert](#) (int \*array, size\_t size)  
*Insertes all the ints in the int array into the collection of data stored in this [Variable](#).*
- virtual void [clear](#) ()  
*Clears this [Variable](#) of all the data stored in it.*

### 4.61.1 Detailed Description

NON USER API.

Used in [SVDDataSet](#) to manage integer data.

### 4.61.2 Member Function Documentation

#### 4.61.2.1 void repast::IntVariable::insert ( double \* *array*, size\_t *size* ) [virtual]

Insertes all the doubles in the double array into the collection of data stored in this [Variable](#).

Parameters

<i>array</i>	the array to insert
<i>size</i>	the size of the array

Implements [repast::Variable](#).

#### 4.61.2.2 void repast::IntVariable::insert ( int \* *array*, size\_t *size* ) [virtual]

Insertes all the ints in the int array into the collection of data stored in this [Variable](#).

Parameters

<i>array</i>	the array to insert
<i>size</i>	the size of the array

Implements [repast::Variable](#).

#### 4.61.2.3 void repast::IntVariable::write ( size\_t *index*, std::ofstream & *out* ) [virtual]

Writes the data at the specified index to the specified ofstream.

Parameters

<i>index</i>	the index of the data to write
<i>out</i>	the ofstream to write the data to

Implements [repast::Variable](#).

The documentation for this class was generated from the following files:

- repast\_hpc/Variable.h
- repast\_hpc/Variable.cpp

## 4.62 repast::IsAgentType< T > Struct Template Reference

Struct that allows filtering by [Agent](#) Type.

```
#include <AgentId.h>
```

### Public Member Functions

- **IsAgentType** (int typeId)
- bool **operator()** (const boost::shared\_ptr< T > &ptr)
- bool **operator()** (const T \*agent)

## Public Attributes

- `int _typeid`

### 4.62.1 Detailed Description

```
template<typename T>struct repast::IsAgentType< T >
```

Struct that allows filtering by [Agent](#) Type.

The documentation for this struct was generated from the following file:

- `repast_hpc/AgentId.h`

## 4.63 `repast::IsLocalAgent< T >` Struct Template Reference

NON USER API.

```
#include <SharedContext.h>
```

## Public Member Functions

- **`IsLocalAgent`** (int rankInCommunicator)
- **`operator()`** (const boost::shared\_ptr< T > &ptr)

## Public Attributes

- `int rank`

### 4.63.1 Detailed Description

```
template<typename T>struct repast::IsLocalAgent< T >
```

NON USER API.

The documentation for this struct was generated from the following file:

- `repast_hpc/SharedContext.h`

## 4.64 `repast::IsNotType< T >` Struct Template Reference

Struct that allows filtering by `!(Agent` Type)

```
#include <AgentId.h>
```

## Public Member Functions

- **`IsNotType`** (int typeid)
- **`operator()`** (const boost::shared\_ptr< T > &ptr)
- **`operator()`** (const T \*agent)

## Public Attributes

- `int _typeid`

### 4.64.1 Detailed Description

```
template<typename T>struct repast::IsNotType< T >
```

Struct that allows filtering by !(Agent Type)

The documentation for this struct was generated from the following file:

- `repast_hpc/AgentId.h`

## 4.65 repast::ItemReceipt< E > Class Template Reference

NON USER API.

```
#include <SharedNetwork.h>
```

## Public Member Functions

- **ItemReceipt** (int source)

## Public Attributes

- `std::vector< E > items`
- `int source_`

### 4.65.1 Detailed Description

```
template<typename E>class repast::ItemReceipt< E >
```

NON USER API.

Receipt for edges

The documentation for this class was generated from the following file:

- `repast_hpc/SharedNetwork.h`

## 4.66 repast::KEBuilder< V, E, Ec, EcM > Class Template Reference

Builds KE type networks.

```
#include <NetworkBuilder.h>
```

## Public Member Functions

- `void build (repast::Properties &props, repast::Graph< V, E, Ec, EcM > *graph)`  
*Builds the network.*

### 4.66.1 Detailed Description

```
template<typename V, typename E, typename Ec, typename EcM>class repast::KEBuilder< V, E, Ec, EcM >
```

Buils KE type networks.

See Klemm and Eguiluz, "Growing scale-free network with small world behavior" in Phys. Rev. E 65.

### 4.66.2 Member Function Documentation

```
4.66.2.1 template<typename V , typename E , typename Ec , typename EcM > void repast::KEBuilder< V, E, Ec, EcM
>::build ( repast::Properties & props, repast::Graph< V, E, Ec, EcM > * graph )
```

Buils the network.

The graph should contains the vertices the build the network with and props should contain the M values.

Parameters

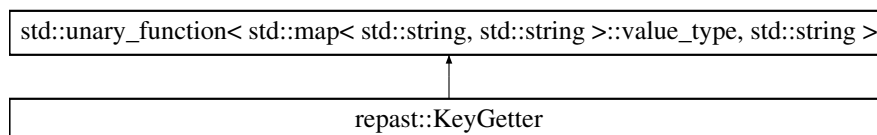
<i>props</i>	a <a href="#">Properties</a> containing a property "ke.model.m" that specifies the M value.
<i>graph</i>	the graph to build the network

The documentation for this class was generated from the following file:

- repast\_hpc/NetworkBuilder.h

## 4.67 repast::KeyGetter Struct Reference

Inheritance diagram for repast::KeyGetter:



### Public Member Functions

- `std::string operator() (const std::map< std::string, std::string >::value_type &value) const`

The documentation for this struct was generated from the following files:

- repast\_hpc/Properties.h
- repast\_hpc/Properties.cpp

## 4.68 Log4CL Class Reference

### Public Member Functions

- [Logger](#) & `get_logger` (std::string logger\_name)
- void `close` ()



### Static Public Member Functions

- static [Log4CL](#) \* **instance** ()
- static void **configure** (int, const std::string &, boost::mpi::communicator \*comm=0, int maxConfigFileSize=MAX\_CONFIG\_FILE\_SIZE)
- static void **configure** (int)

### Protected Member Functions

- **Log4CL** (int)

### Friends

- class **Log4CLConfigurator**

The documentation for this class was generated from the following files:

- repast\_hpc/logger.h
- repast\_hpc/logger.cpp

## 4.69 Log4CLConfigurator Class Reference

### Public Member Functions

- [Log4CL](#) \* **configure** (const std::string &config\_file, int proc\_id, boost::mpi::communicator \*comm=0, int maxConfigFileSize=MAX\_CONFIG\_FILE\_SIZE)

The documentation for this class was generated from the following files:

- repast\_hpc/logger.h
- repast\_hpc/logger.cpp

## 4.70 Logger Class Reference

### Public Member Functions

- **Logger** (const std::string, LOG\_LEVEL, int proc\_id)
- void **log** (LOG\_LEVEL, const std::string msg)
- void **close** ()
- void **add\_appender** ([Appender](#) \*appender)

The documentation for this class was generated from the following files:

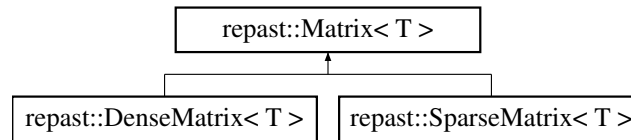
- repast\_hpc/logger.h
- repast\_hpc/logger.cpp

## 4.71 repast::Matrix< T > Class Template Reference

Base class for matrix implementations.

```
#include <matrix.h>
```

Inheritance diagram for repast::Matrix< T >:



### Public Member Functions

- **Matrix** (const **Point**< int > &size, const T &defaultValue=T())  
*Creates a matrix of the specified size and with the specified default value.*
- virtual T & **get** (const **Point**< int > &index)=0  
*Gets the value at the specified index.*
- virtual void **set** (const T &value, const **Point**< int > &index)=0  
*Sets the value at the specified index.*
- T & **operator[]** (const **Point**< int > &index)
- const T & **operator[]** (const **Point**< int > &index) const
- const T & **defaultValue** () const  
*Gets the default value of any unset matrix cell.*
- const **Point**< int > **shape** () const  
*Gets the shape (i.e.*

### Protected Member Functions

- int **calcIndex** (const **Point**< int > &index)
- void **boundsCheck** (const **Point**< int > &index)
- void **create** ()

### Protected Attributes

- int \* **stride**
- T **defValue**
- **Point**< int > **\_size**
- int **dCount**

#### 4.71.1 Detailed Description

```
template<typename T>class repast::Matrix< T >
```

Base class for matrix implementations.

## 4.71.2 Constructor & Destructor Documentation

4.71.2.1 `template<typename T> repast::Matrix< T >::Matrix ( const Point< int > & size, const T & defaultValue = T () ) [explicit]`

Creates a matrix of the specified size and with the specified default value.

## Parameters

<i>size</i>	the size of the matrix in each dimension
-------------	--

### 4.71.3 Member Function Documentation

4.71.3.1 `template<typename T> const Point<int> repast::Matrix< T >::shape ( ) const` `[inline]`

Gets the shape (i.e.

the length of each dimensions) of the matrix.

The documentation for this class was generated from the following file:

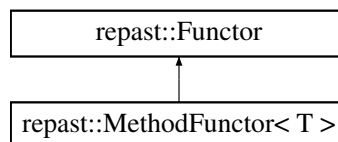
- `repast_hpc/matrix.h`

## 4.72 `repast::MethodFunctor< T >` Class Template Reference

Adapts a no-arg method call on an object instance to a [Functor](#) interface.

```
#include <Schedule.h>
```

Inheritance diagram for `repast::MethodFunctor< T >`:



### Public Member Functions

- **MethodFunctor** (`T *_obj`, `void(T::*_fptr)()`)
- void **operator()** ()

### 4.72.1 Detailed Description

```
template<typename T> class repast::MethodFunctor< T >
```

Adapts a no-arg method call on an object instance to a [Functor](#) interface.

This is used by the [Schedule](#) code to schedule method calls on objects.

#### Template Parameters

<i>T</i>	the object type on which the call will be made.
----------	---

The documentation for this class was generated from the following file:

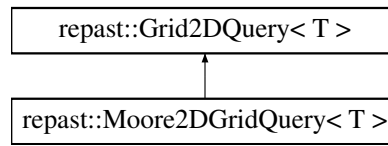
- `repast_hpc/Schedule.h`

## 4.73 `repast::Moore2DGridQuery< T >` Class Template Reference

Neighborhood query that gathers neighbors in a Moore (N, S, E, W, NE, etc.) neighborhood.

```
#include <Moore2DGridQuery.h>
```

Inheritance diagram for repast::Moore2DGridQuery< T >:



## Public Member Functions

- [Moore2DGridQuery](#) (const [Grid](#)< T, int > \*grid)  
Creates [Moore2DGridQuery](#) that will query the specified [Grid](#).
- virtual void [query](#) (const [Point](#)< int > &center, int range, bool includeCenter, std::vector< T \* > &out) const  
Queries the [Grid](#) for the Moore neighbors surrounding the center point within a specified range.

## Additional Inherited Members

### 4.73.1 Detailed Description

```
template<typename T>class repast::Moore2DGridQuery< T >
```

Neighborhood query that gathers neighbors in a Moore (N, S, E, W, NE, etc.) neighborhood.

Template Parameters

<i>T</i>	the type of agents in the <a href="#">Grid</a>
----------	--

### 4.73.2 Member Function Documentation

4.73.2.1 `template<typename T> void repast::Moore2DGridQuery< T >::query ( const Point< int > &center, int range, bool includeCenter, std::vector< T * > &out ) const` [virtual]

Queries the [Grid](#) for the Moore neighbors surrounding the center point within a specified range.

Parameters

	<i>center</i>	the center of the neighborhood
	<i>range</i>	the range of the neighborhood out from the center
	<i>includeCenter</i>	whether or not to include any agents at the center
<i>out</i>	<i>the</i>	neighboring agents will be returned in this vector

Implements [repast::Grid2DQuery< T >](#).

The documentation for this class was generated from the following file:

- repast\_hpc/Moore2DGridQuery.h

## 4.74 repast::MultipleOccupancy< T, GPType > Class Template Reference

Multiple Occupancy cell accessor for accessing the occupants of locations in a [Grid](#).

```
#include <MultipleOccupancy.h>
```

## Public Member Functions

- `T * get (const Point< GPTYPE > &location) const`  
*Gets the first object found at the specified location.*
- `void getAll (const Point< GPTYPE > &location, std::vector< T * > &out) const`  
*Gets all the items found at the specified location.*
- `bool put (boost::shared_ptr< T > &agent, const Point< GPTYPE > &location)`  
*Puts the specified item at the specified location.*
- `void remove (boost::shared_ptr< T > &agent, const Point< GPTYPE > &location)`  
*Removes the specified item from the specified location.*

### 4.74.1 Detailed Description

`template<typename T, typename GPTYPE>class repast::MultipleOccupancy< T, GPTYPE >`

Multiple Occupancy cell accessor for accessing the occupants of locations in a [Grid](#).

Each locations can have multiple occupants.

#### Parameters

<i>T</i>	the type of object in the <a href="#">Grid</a>
<i>GPTYPE</i>	the coordinate type of the grid point locations. This must be an int or a double.

### 4.74.2 Member Function Documentation

4.74.2.1 `template<typename T, typename GPTYPE> T * repast::MultipleOccupancy< T, GPTYPE >::get ( const Point< GPTYPE > & location ) const`

Gets the first object found at the specified location.

#### Parameters

<i>location</i>	the location to get the object at
-----------------	-----------------------------------

#### Returns

the first object found at the specified location or 0 if there are no objects at the specified location.

4.74.2.2 `template<typename T, typename GPTYPE> void repast::MultipleOccupancy< T, GPTYPE >::getAll ( const Point< GPTYPE > & location, std::vector< T * > & out ) const`

Gets all the items found at the specified location.

#### Parameters

	<i>location</i>	the location to get the items at
<i>out</i>	<i>the</i>	found items will be returned in this vector

4.74.2.3 `template<typename T, typename GPTYPE> bool repast::MultipleOccupancy< T, GPTYPE >::put ( boost::shared_ptr< T > & agent, const Point< GPTYPE > & location )`

Puts the specified item at the specified location.

## Parameters

<i>agent</i>	the item to put
<i>location</i>	the location to put the item at

4.74.2.4 `template<typename T, typename GType> void repast::MultipleOccupancy< T, GType >::remove ( boost::shared_ptr< T > & agent, const Point< GType > & location )`

Removes the specified item from the specified location.

## Parameters

<i>agent</i>	the item to remove
<i>location</i>	the location to remove the item from

The documentation for this class was generated from the following file:

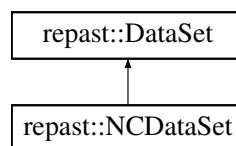
- repast\_hpc/MultipleOccupancy.h

## 4.75 repast::NCDataSet Class Reference

Provides data recording and writing into a single file in NetCDF format.

```
#include <NCDataSet.h>
```

Inheritance diagram for repast::NCDataSet:



### Public Member Functions

- void [record](#) ()  
*Records the data.*
- void [write](#) ()  
*Writes the data.*
- void [close](#) ()  
*Closes the dataset, after which it must be recreated to be used.*

### Friends

- class **NCDataSetBuilder**

### 4.75.1 Detailed Description

Provides data recording and writing into a single file in NetCDF format.

A [NCDataSet](#) uses rank 0 to write to a single file from multiple pan-process data sources. A [NCDataSet](#) should be built using a [NCDataSetBuilder](#).

The documentation for this class was generated from the following files:

- repast\_hpc/NCDataSet.h
- repast\_hpc/NCDataSet.cpp

## 4.76 repast::NCDataSetBuilder Class Reference

Used to build NCDataSets to record data in NetCDF format.

```
#include <NCDataSetBuilder.h>
```

### Public Member Functions

- [NCDataSetBuilder](#) (std::string file, const [Schedule](#) &schedule)  
*Creates an [NCDataSetBuilder](#) that will write to the specified file and get its tick counts from the specified schedule.*
- [NCDataSetBuilder](#) & addDataSource ([NCDataSource](#) \*source)  
*Adds a [NCDataSource](#) to this [NCDataSetBuilder](#).*
- [NCDataSet](#) \* createDataSet ()  
*Creates the [NCDataSet](#) defined by this [NCDataSetBuilder](#).*

### 4.76.1 Detailed Description

Used to build NCDataSets to record data in NetCDF format.

Steps for use are:

1. Create a [NCDataSetBuilder](#).
2. Add NCDataSources to the builder using the createNCDataSource functions. Each DataSource defines a variable and where the data for that variable will be retrieved. Recording data on the [NCDataSet](#) produced by the builder will record this data for each variable.
3. Call createDataSet to create the [NCDataSet](#).
4. [Schedule](#) calls to record and write on the [NCDataSet](#).

### 4.76.2 Constructor & Destructor Documentation

#### 4.76.2.1 repast::NCDataSetBuilder::NCDataSetBuilder ( std::string file, const Schedule & schedule )

Creates an [NCDataSetBuilder](#) that will write to the specified file and get its tick counts from the specified schedule.

Parameters

<i>file</i>	the name of the file to write to. Only rank 0 will actually write to this file.
<i>schedule</i>	the schedule to get tick counts from

### 4.76.3 Member Function Documentation

#### 4.76.3.1 NCDataSetBuilder & repast::NCDataSetBuilder::addDataSource ( NCDataSource \* source )

Adds a [NCDataSource](#) to this [NCDataSetBuilder](#).

The added [NCDataSource](#) defines a variable and where the data for that variable will be retrieved. Recording data on the [NCDataSet](#) produced by this builder will record this data for each variable.



## 4.76.3.2 NCDataSet \* repast::NCDataSetBuilder::createDataSet ( )

Creates the [NCDataSet](#) defined by this [NCDataSetBuilder](#).

The caller is responsible for properly deleting the returned pointer.

## Returns

the created [NCDataSet](#).

The documentation for this class was generated from the following files:

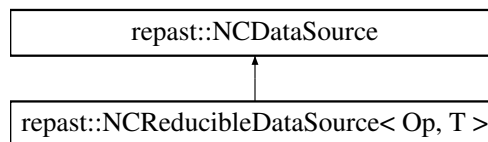
- repast\_hpc/NCDataSetBuilder.h
- repast\_hpc/NCDataSetBuilder.cpp

## 4.77 repast::NCDataSource Class Reference

Data source used internally by NCDataSets.

```
#include <NCDataSource.h>
```

Inheritance diagram for repast::NCDataSource:



## Public Member Functions

- **NCDataSource** (std::string name)
- virtual void **record** ()=0
- virtual void **write** (NcVar \*var)=0
- virtual NcType **ncType** ()=0
- const std::string **name** () const

## Protected Attributes

- std::string **\_name**

## 4.77.1 Detailed Description

Data source used internally by NCDataSets.

The documentation for this class was generated from the following file:

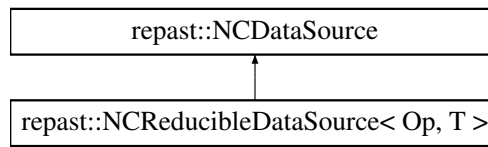
- repast\_hpc/NCDataSource.h

## 4.78 repast::NCReducibleDataSource&lt; Op, T &gt; Class Template Reference

Source of data and a reduction operation.

```
#include <NCReducibleDataSource.h>
```

Inheritance diagram for `repast::NCReducibleDataSource< Op, T >`:



## Public Member Functions

- **NCReducibleDataSource** (std::string name, [TDataSource< T > \\*dataSource](#), Op op)
- virtual NcType **ncType** ()
- virtual void **record** ()
- virtual void **write** (NcVar \*var)

## Protected Attributes

- Op **op\_**
- std::vector< T > **data**
- [TDataSource< T > \\* dataSource\\_](#)
- int **rank**
- int **start**

### 4.78.1 Detailed Description

```
template<typename Op, typename T>class repast::NCReducibleDataSource< Op, T >
```

Source of data and a reduction operation.

Used internally by a [NCDataSet](#) to store the data sources. their associated ops etc.

The documentation for this class was generated from the following file:

- `repast_hpc/NCReducibleDataSource.h`

### 4.79 repast::NcTypeTrait< T > Struct Template Reference

The documentation for this struct was generated from the following file:

- `repast_hpc/NCDataSource.h`

### 4.80 repast::NcTypeTrait< double > Struct Template Reference

#### Static Public Attributes

- static const NcType **type** = ncDouble

The documentation for this struct was generated from the following file:

- `repast_hpc/NCDataSource.h`

## 4.81 repast::NcTypeTrait< int > Struct Template Reference

### Static Public Attributes

- static const NcType **type** = ncInt

The documentation for this struct was generated from the following file:

- repast\_hpc/NCDataSource.h

## 4.82 repast::Neighbor Class Reference

NON USER API.

```
#include <SharedBaseGrid.h>
```

### Public Member Functions

- **Neighbor** (int rank, [GridDimensions](#) bounds)
- int **rank** () const
- [GridDimensions](#) **bounds** () const

### 4.82.1 Detailed Description

NON USER API.

A grid topology process neighbor.

The documentation for this class was generated from the following files:

- repast\_hpc/SharedBaseGrid.h
- repast\_hpc/SharedBaseGrid.cpp

## 4.83 repast::Neighbors Class Reference

NON USER API.

```
#include <SharedBaseGrid.h>
```

### Public Types

- enum [Location](#) {  
  **E, W, N, S,**  
  **NE, NW, SE, SW** }

*Describes the relative location of grid topology process neighbors.*

### Public Member Functions

- void [addNeighbor](#) ([Neighbor](#) \*ngh, [Neighbors::Location](#) location)  
*Adds a neighbor at the specified location.*
- [Neighbor](#) \* [neighbor](#) ([Neighbors::Location](#) location) const  
*Gets the neighbor at the specified location.*

- **Neighbor** \* **findNeighbor** (const std::vector< int > &pt)  
*Finds the neighbor that contains the specified point.*
- **Neighbor** \* **findNeighbor** (const std::vector< double > &pt)  
*Finds the neighbor that contains the specified point.*
- void **getNeighborRanks** (std::set< int > &ranks)

### Static Public Attributes

- static const int **LOCATION\_SIZE** = 8

### Friends

- std::ostream & **operator**<< (std::ostream &os, const **Neighbors** &nghs)

## 4.83.1 Detailed Description

NON USER API.

Provides look up grid topology process neighbors given a point in the pan process grid.

## 4.83.2 Member Function Documentation

### 4.83.2.1 **Neighbor** \* **repast::Neighbors::findNeighbor** ( const std::vector< int > & *pt* )

Finds the neighbor that contains the specified point.

#### Returns

the found neighbor

### 4.83.2.2 **Neighbor** \* **repast::Neighbors::findNeighbor** ( const std::vector< double > & *pt* )

Finds the neighbor that contains the specified point.

#### Returns

the found neighbor

### 4.83.2.3 **Neighbor** \* **repast::Neighbors::neighbor** ( **Neighbors::Location** *location* ) const

Gets the neighbor at the specified location.

#### Parameters

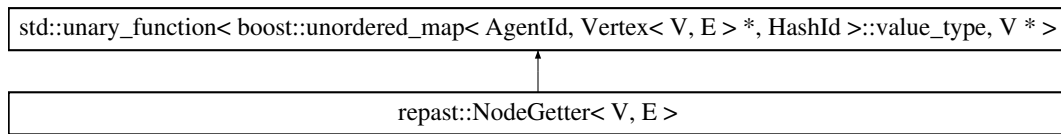
<i>location</i>	the location of the neighbor.
-----------------	-------------------------------

The documentation for this class was generated from the following files:

- repast\_hpc/SharedBaseGrid.h
- repast\_hpc/SharedBaseGrid.cpp

## 4.84 repast::NodeGetter< V, E > Struct Template Reference

Inheritance diagram for repast::NodeGetter< V, E >:



### Public Member Functions

- `V * operator()` (const typename boost::unordered\_map< [AgentId](#), [Vertex< V, E > \\*](#), [HashId](#) >::value\_type &value) const

The documentation for this struct was generated from the following file:

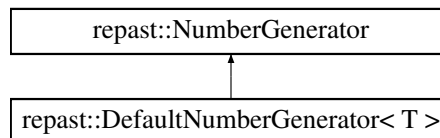
- `repast_hpc/Vertex.h`

## 4.85 repast::NumberGenerator Class Reference

Number generator interface.

```
#include <Random.h>
```

Inheritance diagram for repast::NumberGenerator:



### Public Member Functions

- virtual double [next](#) ()=0  
*Gets the "next" number from this Number Generator.*

### 4.85.1 Detailed Description

Number generator interface.

The documentation for this class was generated from the following file:

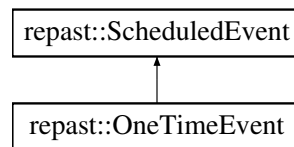
- `repast_hpc/Random.h`

## 4.86 repast::OneTimeEvent Class Reference

NON USER API.

```
#include <Schedule.h>
```

Inheritance diagram for repast::OneTimeEvent:



## Public Member Functions

- **OneTimeEvent** (double, [RepastEvent](#) \*)
- virtual bool [reschedule](#) (std::priority\_queue< [ScheduledEvent](#) \*, std::vector< [ScheduledEvent](#) \* >, [EventCompare](#) > &)

*Always returns false, as it does not reschedule itself.*

## Additional Inherited Members

### 4.86.1 Detailed Description

NON USER API.

[ScheduledEvent](#) that will only execute only once.

The documentation for this class was generated from the following files:

- repast\_hpc/Schedule.h
- repast\_hpc/Schedule.cpp

## 4.87 repast::Point< T > Class Template Reference

A N-dimensional [Point](#) representation.

```
#include <Point.h>
```

## Public Types

- typedef std::vector< T > ::const\_iterator **const\_iterator**

## Public Member Functions

- [Point](#) (T x)  
*Creates a one dimensional point with the specified value.*
- [Point](#) (T x, T y)  
*Creates a two dimensional point with the specified values.*
- [Point](#) (T x, T y, T z)  
*Creates a three dimensional point with the specified values.*
- [Point](#) (std::vector< T > coordinates)  
*Creates a multi-dimensional point with the specified values.*
- T [getX](#) () const  
*Gets the x coordinate of the point.*
- T [getY](#) () const  
*Gets the y coordinate of the point.*

- T `getZ` () const  
*Gets the z coordinate of the point.*
- T `getCoordinate` (int coordIndex) const  
*Gets the coordinate of the point in the specified dimension.*
- void `add` (const `Point`< T > &pt)  
*Adds the specified GridPoint to this GridPoint.*
- size\_t `dimensionCount` () const  
*Gets the number of dimensions of this point.*
- const T & `operator[]` (size\_t index) const  
*Gets the coordinate value at the specified index.*
- T & `operator[]` (size\_t index)  
*Gets the coordinate value at the specified index.*
- const std::vector< T > & `coords` () const  
*Gets the coordinates of this point as a vector.*
- const\_iterator `begin` () const  
*Gets the start of an iterator over the coordinates of this point.*
- const\_iterator `end` () const  
*Gets the end of an iterator over the coordinates of this point.*
- void `copy` (std::vector< T > &out) const  
*Copies the point into the specified vector.*

## Friends

- struct `HashGridPoint`< T >
- class `boost::serialization::access`
- bool `operator==` (const `Point`< T > &one, const `Point`< T > &two)
- std::ostream & `operator<<` (std::ostream &os, const `Point`< T > &pt)

## 4.87.1 Detailed Description

template<typename T>class repast::Point< T >

A N-dimensional `Point` representation.

N dimensional point for addressing matrix locations.

### Parameters

<code>T</code>	a numeric type. In repast and relogo these are limited to int and double.
----------------	---

## 4.87.2 Constructor & Destructor Documentation

4.87.2.1 template<typename T> repast::Point< T >::Point ( T x ) `[explicit]`

Creates a one dimensional point with the specified value.

### Parameters

<code>x</code>	the x coordinate of the point
----------------	-------------------------------

4.87.2.2 template<typename T> repast::Point< T >::Point ( T x, T y )

Creates a two dimensional point with the specified values.

## Parameters

<i>x</i>	the x coordinate of the point
<i>y</i>	the y coordinate of the point

4.87.2.3 `template<typename T> repast::Point< T >::Point ( T x, T y, T z )`

Creates a three dimensional point with the specified values.

## Parameters

<i>x</i>	the x coordinate of the point
<i>y</i>	the y coordinate of the point
<i>z</i>	the z coordinate of the point

4.87.2.4 `template<typename T> repast::Point< T >::Point ( std::vector< T > coordinates )`

Creates a multi-dimensional point with the specified values.

## Parameters

<i>coordinates</i>	the coordinate values of the point. The first element will be x, the second y and so on.
--------------------	--

## 4.87.3 Member Function Documentation

4.87.3.1 `template<typename T> void repast::Point< T >::add ( const Point< T > & pt )`

Adds the specified GridPoint to this GridPoint.

This GridPoint contains the result.

## Exceptions

<i>invalid_argument</i>	exception if the pt doesn't have the same number of dimensions as this GridPoint.
-------------------------	---

4.87.3.2 `template<typename T> const_iterator repast::Point< T >::begin ( ) const [inline]`

Gets the start of an iterator over the coordinates of this point.

## Returns

the start of an iterator over the coordinates of this point.

4.87.3.3 `template<typename T> const std::vector<T>& repast::Point< T >::coords ( ) const [inline]`

Gets the coordinates of this point as a vector.

## Returns

a vector containing the coordinates of this point.

4.87.3.4 `template<typename T> void repast::Point< T >::copy ( std::vector< T > & out ) const`

Copies the point into the specified vector.

Assumes the array is the same length as this GridPoint.



## Parameters

<i>out</i>	<i>the</i>	vector to copy the point coordinates into
------------	------------	---

**4.87.3.5** `template<typename T> size_t repast::Point< T >::dimensionCount ( ) const` `[inline]`

Gets the number of dimensions of this point.

## Returns

the number of dimensions of this point.

**4.87.3.6** `template<typename T> const_iterator repast::Point< T >::end ( ) const` `[inline]`

Gets the end of an iterator over the coordinates of this point.

## Returns

the end of an iterator over the coordinates of this point.

**4.87.3.7** `template<typename T> T repast::Point< T >::getCoordinate ( int coordIndex ) const`

Gets the coordinate of the point in the specified dimension.

## Parameters

<i>coordIndex</i>	the dimension of the point to get the coordinate for. X is the first, y is the second and so on.
-------------------	--

## Returns

the coordinate of the point in the specified dimension.

## Exceptions

<i>an</i>	out_of_range exception if this GridPoint has doesn't have the specified dimension.
-----------	--

**4.87.3.8** `template<typename T> T repast::Point< T >::getX ( ) const`

Gets the x coordinate of the point.

## Returns

the x coordinate of the point.

**4.87.3.9** `template<typename T> T repast::Point< T >::getY ( ) const`

Gets the y coordinate of the point.

## Returns

the y coordinate of the point.

## Exceptions

<i>an</i>	out_of_range exception if this GridPoint has less than 2 dimensions.
-----------	--

4.87.3.10 `template<typename T> T repast::Point< T >::getZ ( ) const`

Gets the z coordinate of the point.

## Returns

the z coordinate of the point.

## Exceptions

<i>an</i>	out_of_range exception if this GridPoint has less than 3 dimensions.
-----------	--

4.87.3.11 `template<typename T> const T& repast::Point< T >::operator[] ( size_t index ) const` `[inline]`

Gets the coordinate value at the specified index.

## Parameters

<i>index</i>	the dimension of the point to get the coordinate for. X is the first, y is the second and so on.
--------------	--

## Returns

the coordinate of the point in the specified dimension.

4.87.3.12 `template<typename T> T& repast::Point< T >::operator[] ( size_t index )` `[inline]`

Gets the coordinate value at the specified index.

## Parameters

<i>index</i>	the dimension of the point to get the coordinate for. X is the first, y is the second and so on.
--------------	--

## Returns

the coordinate of the point in the specified dimension.

The documentation for this class was generated from the following file:

- repast\_hpc/Point.h

## 4.88 repast::Problem Class Reference

### Public Member Functions

- **Problem** (int i, double lb, double ub)
- bool **contains** (double val)
- int **index** () const

The documentation for this class was generated from the following files:

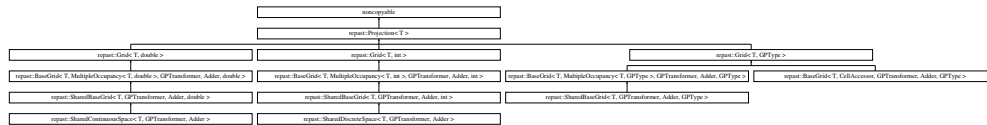
- repast\_hpc/NetworkBuilder.h
- repast\_hpc/NetworkBuilder.cpp

## 4.89 repast::Projection< T > Class Template Reference

Abstract base class for Projections.

```
#include <Projection.h>
```

Inheritance diagram for repast::Projection< T >:



### Public Types

- enum **RADIUS** { **PRIMARY**, **SECONDARY** }

### Public Member Functions

- [Projection](#) (std::string [name](#))  
*Creates a projection with specified name.*
- const std::string [name](#) () const  
*Gets the name of this projection.*
- void [addFilterVal](#) (int type)  
*Adds an entry to the list of agent types that can be added to this projection.*
- void [removeFilterVal](#) (int type)  
*Removes an entry from the list of agent types that can be added to this projection.*
- void [clearFilter](#) ()  
*Clears the list of agent types that can be added to this projection; the result is that the filter is empty, and any agent can be added.*
- bool [agentCanBeAdded](#) (boost::shared\_ptr< T > agent)  
*Returns true if the agent can be added to the projection, which will be the case if the filter list is empty or if the agent's type is in the filter list.*
- virtual bool [keepsAgentsOnSyncProj](#) ()=0  
*Should return true if the [Projection](#) implemented can 'keep' some (non-local) agents during a projection information synchronization operation.*
- virtual bool [sendsSecondaryAgentsOnStatusExchange](#) ()=0  
*Should return true if the [Projection](#) implemented will send secondary agents during a status exchange.*
- virtual void [getInfoExchangePartners](#) (std::set< int > &psToSendTo, std::set< int > &psToReceiveFrom)=0  
*Gets the set of processes with which this [Projection](#) exchanges projection info.*
- virtual void [getAgentStatusExchangePartners](#) (std::set< int > &psToSendTo, std::set< int > &psToReceiveFrom)=0  
*Gets the set of processes with which this [Projection](#) exchanges agent status info- that is, the set of processes from which agents can move to this one or to which they can move when moving from this one.*
- virtual void [getRequiredAgents](#) (std::set< [AgentId](#) > &agentsToTest, std::set< [AgentId](#) > &agentsRequired, RADIUS radius=PRIMARY)=0  
*Given a set of agents to test, gets the subset that must be kept in order to fulfill the projection's 'contract' to the specified radius.*
- virtual void [getAgentsToPush](#) (std::set< [AgentId](#) > &agentsToTest, std::map< int, std::set< [AgentId](#) > > &agentsToPush)=0  
*Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.*
- virtual void [getProjectionInfo](#) (std::vector< [AgentId](#) > &agents, std::vector< [ProjectionInfoPacket](#) \* > &packets, bool secondaryInfo=false, std::set< [AgentId](#) > \*secondaryIds=0, int destProc=-1)

*Convenience wrapper that gets all of the projection information for the agents specified (calls implementation in child class that gets only the information for one agent).*

- void **updateProjectionInfo** (std::vector< [ProjectionInfoPacket](#) \* > &pips, [Context](#)< T > \*context)

*Updates the projection information for the agents in this projection according to the information contained in the vector of information packets passed.*

- virtual void **cleanProjectionInfo** (std::set< [AgentId](#) > &agentsToKeep)=0
- virtual void **balance** ()

### Protected Member Functions

- virtual bool **addAgent** (boost::shared\_ptr< T > agent)=0
- virtual void **removeAgent** (T \*agent)=0
- virtual [ProjectionInfoPacket](#) \* **getProjectionInfo** ([AgentId](#) id, bool secondaryInfo=false, std::set< [AgentId](#) > \*secondaryIds=0, int destProc=-1)=0
- virtual void **updateProjectionInfo** ([ProjectionInfoPacket](#) \*pip, [Context](#)< T > \*context)=0

### Protected Attributes

- std::string **name\_**
- std::set< int > **filter**

### Friends

- class **Context**< T >

## 4.89.1 Detailed Description

template<typename T>class repast::Projection< T >

Abstract base class for Projections.

## 4.89.2 Constructor & Destructor Documentation

4.89.2.1 template<typename T> repast::Projection< T >::Projection ( std::string *name* ) [inline]

Creates a projection with specified name.

#### Parameters

<i>name</i>	the name of the projection. This must be unique across projections
-------------	--

## 4.89.3 Member Function Documentation

4.89.3.1 template<typename T> void repast::Projection< T >::addFilterVal ( int *type* ) [inline]

Adds an entry to the list of agent types that can be added to this projection.

Note: no indication if type is already listed

#### Parameters

<i>type</i>	type to be added
-------------	------------------

4.89.3.2 `template<typename T> bool repast::Projection< T >::agentCanBeAdded ( boost::shared_ptr< T > agent )`  
`[inline]`

Returns true if the agent can be added to the projection, which will be the case if the filter list is empty or if the agent's type is in the filter list.

Parameters

<i>agent</i>	pointer to the agent to be tested
--------------	-----------------------------------

4.89.3.3 `template<typename T> virtual void repast::Projection< T >::getAgentStatusExchangePartners ( std::set< int > & psToSendTo, std::set< int > & psToReceiveFrom )` `[pure virtual]`

Gets the set of processes with which this [Projection](#) exchanges agent status info- that is, the set of processes from which agents can move to this one or to which they can move when moving from this one.

In the most general case this will be all other processors. However, simulations where agents move in spaces will usually exchange agents only with a small subset of 'neighbor' processes, which is knowable in advance and constant. To accommodate the general case, the algorithm for exchanging information must poll all other processes to see which are sending to this one; if this is known in advance, this additional (expensive) step can be skipped.

Implemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#), [repast::Graph< V, E, Ec, EcM >](#), [repast::Grid< T, GPType >](#), [repast::Grid< T, double >](#), and [repast::Grid< T, int >](#).

4.89.3.4 `template<typename T> virtual void repast::Projection< T >::getAgentsToPush ( std::set< AgentId > & agentsToTest, std::map< int, std::set< AgentId > > & agentsToPush )` `[pure virtual]`

Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.

Generally spaces must push agents that are in 'buffer zones' and graphs must push local agents that are vertices to master edges where the other vertex is non- local. The results are returned per-process in the agentsToPush map.

Implemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, CellAccessor, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, double >, GPTransformer, Adder, double >](#), [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#), [repast::BaseGrid< T, MultipleOccupancy< T, int >, GPTransformer, Adder, int >](#), [repast::Graph< V, E, Ec, EcM >](#), [repast::Grid< T, GPType >](#), [repast::Grid< T, double >](#), [repast::Grid< T, int >](#), and [repast::SharedDiscreteSpace< T, GPTransformer, Adder >](#).

4.89.3.5 `template<typename T> virtual void repast::Projection< T >::getInfoExchangePartners ( std::set< int > & psToSendTo, std::set< int > & psToReceiveFrom )` `[pure virtual]`

Gets the set of processes with which this [Projection](#) exchanges projection info.

In the most general case this will be all other processors; this is the case for graphs, where agent connections can be arbitrary. However, spaces usually exchange information only with a small subset of 'neighbor' processes, which is knowable in advance and constant. To accommodate the general case, the algorithm for exchanging information must poll all other processes to see which are sending to this one; if this is known in advance, this additional (expensive) step can be skipped.

Implemented in [repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#), [repast::SharedBaseGrid< T, GPTransformer, Adder, double >](#), [repast::Graph< V, E, Ec, EcM >](#), [repast::Grid< T, GPType >](#), [repast::Grid< T, double >](#), and [repast::Grid< T, int >](#).

**4.89.3.6** `template<typename T> virtual void repast::Projection< T >::getRequiredAgents ( std::set< AgentId > & agentsToTest, std::set< AgentId > & agentsRequired, RADIUS radius = PRIMARY ) [pure virtual]`

Given a set of agents to test, gets the subset that must be kept in order to fulfill the projection's 'contract' to the specified radius.

Generally spaces do not require any agents, but graphs do- generally the non-local ends to master copies of edges.

Implemented in [repast::Grid< T, GType >](#), [repast::Grid< T, double >](#), and [repast::Grid< T, int >](#).

**4.89.3.7** `template<typename T> virtual bool repast::Projection< T >::keepsAgentsOnSyncProj ( ) [pure virtual]`

Should return true if the [Projection](#) implemented can 'keep' some (non-local) agents during a projection information synchronization operation.

Generally spaces will allow all non-local agents to be deleted, but graphs keep the non-local agents that participate in Master edges.

It is possible to override these. A graph projection can be created that does not permit non-local agents to be 'kept'. This would be an extremely unusual use case, but it is possible.

Note that these are used for optimization. If no projection in a given context keeps any agents, several steps in the synchronization algorithm can be omitted. Of course, omitting these steps when a projection actually retains agents can caused undefined problems.

#### Returns

true if this projection will keep non-local agents during a projection information synchronziation event, false if it will not.

Implemented in [repast::Graph< V, E, Ec, EcM >](#), [repast::Grid< T, GType >](#), [repast::Grid< T, double >](#), and [repast::Grid< T, int >](#).

**4.89.3.8** `template<typename T> void repast::Projection< T >::removeFilterVal ( int type ) [inline]`

Removes an entry from the list of agent types that can be added to this projection.

Note: no indication if type is not listed

#### Parameters

<i>type</i>	entry to be removed
-------------	---------------------

**4.89.3.9** `template<typename T> virtual bool repast::Projection< T >::sendsSecondaryAgentsOnStatusExchange ( ) [pure virtual]`

Should return true if the [Projection](#) implemented will send secondary agents during a status exchange.

Generally spaces do not and graphs do.

If no secondary agents will be sent, portions of the algorithm can be omitted for optimization.

#### Returns

true if the [Projection](#) returns secondary agents, false if not

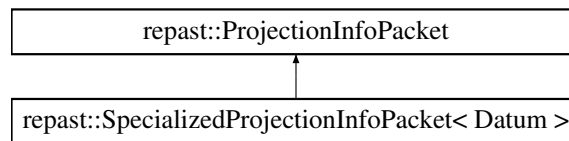
Implemented in [repast::Graph< V, E, Ec, EcM >](#), [repast::Grid< T, GType >](#), [repast::Grid< T, double >](#), and [repast::Grid< T, int >](#).

The documentation for this class was generated from the following file:

- [repast\\_hpc/Projection.h](#)

## 4.90 repast::ProjectionInfoPacket Class Reference

Inheritance diagram for repast::ProjectionInfoPacket:



### Public Member Functions

- **ProjectionInfoPacket** ([AgentId](#) agentId)
- template<class Archive >  
void **serialize** (Archive &ar, const unsigned int version)
- virtual bool **isEmpty** ()

### Public Attributes

- [AgentId](#) **id**

### Friends

- class **boost::serialization::access**

The documentation for this class was generated from the following file:

- repast\_hpc/Projection.h

## 4.91 repast::Properties Class Reference

Map type object that contains key, value string properties.

```
#include <Properties.h>
```

### Public Types

- typedef  
boost::transform\_iterator  
< [KeyGetter](#), std::map  
< std::string, std::string >  
::const\_iterator > **key\_iterator**

### Public Member Functions

- [Properties](#) ()  
*Creates an empty [Properties](#).*
- [Properties](#) (const std::string &file, boost::mpi::communicator \*comm=0, int maxPropFileSize=MAX\_PROP\_ - FILE\_SIZE)  
*Creates a new [Properties](#) using the properties defined in the specified file.*

- [Properties](#) (const std::string &file, int argc, char \*\*argv, boost::mpi::communicator \*comm=0, int maxPropFileSize=MAX\_PROP\_FILE\_SIZE)  
*Creates a new [Properties](#) using the properties defined in the specified file and any properties specified in Key=Val format in the argument array.*
- [Properties](#) (int argc, char \*\*argv)  
*Creates a new [Properties](#) using the properties specified in Key=Val format in the argument.*
- void [putProperty](#) (const std::string &key, std::string value)  
*Puts a property into this [Properties](#) with the specified key and value.*
- void [putProperty](#) (const std::string &key, long double value)  
*Puts a property into this [Properties](#) with the specified key and value.*
- std::string [getProperty](#) (const std::string &key) const  
*Gets the property with the specified key.*
- bool [contains](#) (const std::string &key) const  
*Gets whether or not this [Properties](#) contains the specified key.*
- key\_iterator [keys\\_begin](#) () const  
*Gets the start of an iterator over this [Properties](#)' keys.*
- key\_iterator [keys\\_end](#) () const  
*Gets the end of an iterator over this [Properties](#)' keys.*
- void [readFile](#) (const std::string &file, boost::mpi::communicator \*comm=0, int maxPropFileSize=MAX\_PROP\_FILE\_SIZE)  
*Adds any properties defined in the specified file.*
- void [processCommandLineArguments](#) (int argc, char \*\*argv)  
*Processes a char\*\* array of the given size; any component that has an equals sign is entered as a property value, overriding any previous entry read from the properties file.*
- int [size](#) () const  
*Gets the number of properties in this [Properties](#).*
- void [log](#) (std::string logName, std::vector< std::string > \*keysToWrite=0)  
*Writes the contents of the properties file to the specified repast log (at 'INFO' log level)*
- void [writeToSVFile](#) (std::string fileName, std::string separator=",")  
*Writes the contents of the properties file to the specified separated-value file.*
- void [writeToSVFile](#) (std::string fileName, std::vector< std::string > &keysToWrite, std::string separator=",")  
*Writes the contents of the properties file to the specified separated-value file.*

#### 4.91.1 Detailed Description

Map type object that contains key, value string properties.

A [Properties](#) instance can be constructed from a file. Each line is a property with the key and value separated by =. For example,

```
some.property = 3
```

```
another.property = hello
```

#### 4.91.2 Constructor & Destructor Documentation

##### 4.91.2.1 `repast::Properties::Properties ( const std::string & file, boost::mpi::communicator * comm = 0, int maxPropFileSize = MAX_PROP_FILE_SIZE )`

Creates a new [Properties](#) using the properties defined in the specified file.

Each line is a property with the key and value separated by =. For example,

```
some.property = 3
```

```
another.property = hello
```



## Parameters

<i>file</i>	the properties file path
<i>comm</i>	pointer to a communicator; if null (the default), all processes read the properties file separately. If a communicator is provided, rank 0 reads the file and broadcasts it to all other ranks.
<i>maxPropFileSize</i>	optional parameter; if the properties file is larger than the default MAX_PROP_FILE_SIZE, the new size can be passed here.

**4.91.2.2** `repast::Properties::Properties ( const std::string & file, int argc, char ** argv, boost::mpi::communicator * comm = 0, int maxPropFileSize = MAX_PROP_FILE_SIZE )`

Creates a new [Properties](#) using the properties defined in the specified file and any properties specified in Key=Val format in the argument array.

[Properties](#) in the argument array will supersede any in the properties file.

Each line in the properties file is a property with the key and value separated by =. For example,

some.property = 3

another.property = hello

## Parameters

<i>file</i>	the properties file path
<i>argc</i>	count of the elements in the argv array
<i>array</i>	of char* that may include Key=Value pairs. Elements with no '=' are ignored.
<i>comm</i>	pointer to a communicator; if null (the default), all processes read the properties file separately. If a communicator is provided, rank 0 reads the file and broadcasts it to all other ranks.
<i>maxPropFileSize</i>	optional parameter; if the properties file is larger than the default MAX_PROP_FILE_SIZE, the new size can be passed here.

**4.91.2.3** `repast::Properties::Properties ( int argc, char ** argv )`

Creates a new [Properties](#) using the properties specified in Key=Val format in the argument.

## Parameters

<i>argc</i>	count of the elements in the argv array
<i>array</i>	of char* that may include Key=Value pairs. Elements with no '=' are ignored.

### 4.91.3 Member Function Documentation

**4.91.3.1** `bool repast::Properties::contains ( const std::string & key ) const`

Gets whether or not this [Properties](#) contains the specified key.

## Parameters

<i>key</i>	the property key
------------	------------------

**4.91.3.2** `string repast::Properties::getProperty ( const std::string & key ) const`

Gets the property with the specified key.

## Parameters

<i>key</i>	the property key
------------	------------------

## Returns

the value for that key, or an empty string if the property is not found.

4.91.3.3 `key_iterator repast::Properties::keys_begin ( ) const [inline]`

Gets the start of an iterator over this [Properties](#)' keys.

## Returns

the start of an iterator over this [Properties](#)' keys.

4.91.3.4 `key_iterator repast::Properties::keys_end ( ) const [inline]`

Gets the end of an iterator over this [Properties](#)' keys.

## Returns

the end of an iterator over this [Properties](#)' keys.

4.91.3.5 `void repast::Properties::log ( std::string logName, std::vector< std::string > * keysToWrite = 0 ) [inline]`

Writes the contents of the properties file to the specified repast log (at 'INFO' log level)

## Parameters

<i>logName</i>	name of the log to use
<i>keysToWrite</i>	optional; if included, writes only the keys included in the vector and their values, in the order they appear in the vector. Will write blank values for any key name in the vector that is not in the properties file. If not included, all properties and their values are written, in map order.

4.91.3.6 `void repast::Properties::processCommandLineArguments ( int argc, char ** argv )`

Processes a char\*\* array of the given size; any component that has an equals sign is entered as a property value, overriding any previous entry read from the properties file.

## Parameters

<i>argc</i>	the number of entries in the array
<i>argv</i>	the array of char values to be mapped

4.91.3.7 `void repast::Properties::putProperty ( const std::string & key, std::string value )`

Puts a property into this [Properties](#) with the specified key and value.

## Parameters

---

<i>key</i>	the property key
<i>value</i>	the property value

#### 4.91.3.8 void repast::Properties::putProperty ( const std::string & *key*, long double *value* )

Puts a property into this [Properties](#) with the specified key and value.

Note that even though the second argument can be passed as a numeric value, it is stored as a string

##### Parameters

<i>key</i>	the property key
<i>value</i>	the property value

#### 4.91.3.9 void repast::Properties::readFile ( const std::string & *file*, boost::mpi::communicator \* *comm* = 0, int *maxPropFileSize* = MAX\_PROP\_FILE\_SIZE )

Adds any properties defined in the specified file.

Each line is a property with the key and value separated by =. For example,

some.property = 3

another.property = hello

##### Parameters

<i>file</i>	the properties file path
<i>comm</i>	pointer to a communicator; if null (the default), all processes read the properties file separately. If a communicator is provided, rank 0 reads the file and broadcasts it to all other ranks.

#### 4.91.3.10 int repast::Properties::size ( ) const [inline]

Gets the number of properties in this [Properties](#).

##### Returns

the number of properties in this [Properties](#).

#### 4.91.3.11 void repast::Properties::writeToSVFile ( std::string *fileName*, std::string *separator* = " , " )

Writes the contents of the properties file to the specified separated-value file.

If the file does not exist it is created and a header line is written with the key values.

##### Parameters

<i>fileName</i>	name
-----------------	------

#### 4.91.3.12 void repast::Properties::writeToSVFile ( std::string *fileName*, std::vector< std::string > & *keysToWrite*, std::string *separator* = " , " )

Writes the contents of the properties file to the specified separated-value file.

If the file does not exist it is created and a header line is written with the key values.

## Parameters

<i>fileName</i>	name
-----------------	------

The documentation for this class was generated from the following files:

- repast\_hpc/Properties.h
- repast\_hpc/Properties.cpp

## 4.92 repast::Random Class Reference

Methods for working with random distributions, draws etc.

```
#include <Random.h>
```

### Public Member Functions

- void [putGenerator](#) (const std::string &id, [NumberGenerator](#) \*generator)  
*Puts the named generator into this [Random](#).*
- [NumberGenerator](#) \* [getGenerator](#) (const std::string &id)  
*Gets the named generator or 0 if the name is not found.*
- boost::mt19937 & [engine](#) ()  
*Gets the random number engine from which the distributions are created.*
- boost::uint32\_t [seed](#) ()  
*Gets the current seed.*
- double [nextDouble](#) ()  
*Gets the next double in the range [0, 1).*
- [DoubleUniformGenerator](#) [createUniDoubleGenerator](#) (double from, double to)  
*Creates a generator that produces doubles in the range [from, to).*
- [IntUniformGenerator](#) [createUniIntGenerator](#) (int from, int to)  
*Creates a generator that produces ints in the range [from, to].*
- [TriangleGenerator](#) [createTriangleGenerator](#) (double lowerBound, double mostLikely, double upperBound)  
*Creates a triangle generator with the specified properties.*
- [CauchyGenerator](#) [createCauchyGenerator](#) (double median, double sigma)  
*pdf:  $p(x) = \sigma / (\pi * (\sigma^2 + (x - \text{median})^2))$*
- [ExponentialGenerator](#) [createExponentialGenerator](#) (double lambda)  
*pdf:  $p(x) = \lambda * \exp(-\lambda * x)$*
- [NormalGenerator](#) [createNormalGenerator](#) (double mean, double sigma)  
*Creates a normal generator.*
- [LogNormalGenerator](#) [createLogNormalGenerator](#) (double mean, double sigma)  
*Produces random numbers with  $p(x) = 1/(x * \text{normal\_sigma} * \sqrt{2*\pi}) * \exp(-(\log(x) - \text{normal\_mean})^2 / (2*\text{normal\_sigma}^2))$  for  $x > 0$ , where  $\text{normal\_mean} = \log(\text{mean}^2 / \sqrt{\text{sigma}^2 + \text{mean}^2})$  and  $\text{normal\_sigma} = \sqrt{\log(1 + \text{sigma}^2 / \text{mean}^2)}$*

### Static Public Member Functions

- static void [initialize](#) (boost::uint32\_t [seed](#))  
*Initialize the [Random](#) singleton with the specified seed.*
- static [Random](#) \* [instance](#) ()  
*Gets the singleton instance of this [Random](#).*

## Protected Member Functions

- **Random** (boost::uint32\_t [seed](#))

### 4.92.1 Detailed Description

Methods for working with random distributions, draws etc.

### 4.92.2 Member Function Documentation

#### 4.92.2.1 CauchyGenerator repast::Random::createCauchyGenerator ( double *median*, double *sigma* )

pdf:  $p(x) = \sigma / (\pi * (\sigma^2 + (x - \text{median})^2))$

Parameters

<i>median</i>	
<i>sigma</i>	

Returns

a Cauchy generator.

#### 4.92.2.2 ExponentialGenerator repast::Random::createExponentialGenerator ( double *lambda* )

pdf:  $p(x) = \lambda * \exp(-\lambda * x)$

Parameters

<i>lambda</i>	must be > 0
---------------	-------------

Returns

an exponential generator.

#### 4.92.2.3 NormalGenerator repast::Random::createNormalGenerator ( double *mean*, double *sigma* )

Creates a normal generator.

pdf:  $p(x) = 1/\sqrt{2*\pi*\sigma} * \exp(-(x - \text{mean})^2 / (2*\sigma^2))$

#### 4.92.2.4 TriangleGenerator repast::Random::createTriangleGenerator ( double *lowerBound*, double *mostLikely*, double *upperBound* )

Creates a triangle generator with the specified properties.

A TriangleGenerator produces a floating point value  $x$  where  $\text{lowerBound} \leq x \leq \text{upperBound}$  and *mostLikely* is the most probable value for  $x$ .

Parameters

<i>lowerBound</i>	the lower bound of the values produced by the generator
-------------------	---

<i>mostLikely</i>	the most likely value produced by the generator
<i>upperBound</i>	the upper bound of the values produced by the generator

**Returns**

a triangle generator.

**4.92.2.5 DoubleUniformGenerator** `repast::Random::createUniDoubleGenerator ( double from, double to )`

Creates a generator that produces doubles in the range [from, to).

inclusive of from, exclusive of to.

**Parameters**

<i>from</i>	the range start (inclusive)
<i>to</i>	the range end (exclusive)

**Returns**

a generator that produces doubles in the range [from, to).

**4.92.2.6 IntUniformGenerator** `repast::Random::createUniIntGenerator ( int from, int to )`

Creates a generator that produces ints in the range [from, to].

**Parameters**

<i>from</i>	the range start (inclusive)
<i>to</i>	the range end (inclusive)

**Returns**

a generator that produces ints in the range [from, to].

**4.92.2.7 boost::mt19937& repast::Random::engine ( )** `[inline]`

Gets the random number engine from which the distributions are created.

**Returns**

he random number engine from which the distributions are created.

**4.92.2.8 NumberGenerator \*** `repast::Random::getGenerator ( const std::string & id )`

Gets the named generator or 0 if the name is not found.

**Parameters**

<i>id</i>	the name of the generator to get
-----------	----------------------------------

**4.92.2.9 void** `repast::Random::initialize ( boost::uint32_t seed )` `[static]`

Initialize the [Random](#) singleton with the specified seed.

## Parameters

<i>the</i>	seed to initialize the random number generator with.
------------	--

4.92.2.10 `double repast::Random::nextDouble ( )`

Gets the next double in the range [0, 1).

## Returns

the next double in the range [0, 1).

4.92.2.11 `void repast::Random::putGenerator ( const std::string & id, NumberGenerator * generator )`

Puts the named generator into this [Random](#).

Added generators will be deleted by [Random](#) when it is destroyed.

## Parameters

<i>the</i>	id of the generator
<i>generator</i>	the generator to add

4.92.2.12 `boost::uint32_t repast::Random::seed ( ) [inline]`

Gets the current seed.

## Returns

the current seed.

The documentation for this class was generated from the following files:

- `repast_hpc/Random.h`
- `repast_hpc/Random.cpp`

4.93 `repast::RandomAccess< I >` Class Template Reference

Given an iterator and a number of elements, creates a data structure that allows efficient access to those elements.

```
#include <Random.h>
```

## Public Member Functions

- [RandomAccess](#) (*I* beginning, int size)  
*Constructs a [RandomAccess](#) instance for this iterator.*
- *I* [get](#) (int index)  
*Gets the element at the specified index.*

### 4.93.1 Detailed Description

`template<typename I> class repast::RandomAccess< I >`

Given an iterator and a number of elements, creates a data structure that allows efficient access to those elements.

Is only valid as long as the iterator is valid.

The basic implementation creates a vector of ordered pairs linking an integer and an iterator pointing to an element in the original iteration set. To find the *n*th element, the algorithm searches backwards through the list of 'landmarks', finds the highest landmark lower than *n*, chooses the iterator associated with that landmark, and steps forward until *n* is reached, adding new landmarks if appropriate. So given landmarks:

0 - pointer to element 0 100 - pointer to element 100 200 - pointer to element 200

if the request for element 438 is given, the algorithm will search backward and find landmark 200; it will then step forward, adding landmarks for 300 and 400, until element 438 is reached and returned.

Assuming that requests are evenly distributed, optimum interval for landmarks is the square root of the size of the list, and performance for the algorithm will be in  $\log(\text{size})$  time.

Note that other implementations are possible- for example, checking if enough memory would allow a completely indexed list. A long-term possibility is allowing the user to specify (for example, specify that the algorithm with lowest memory cost be used even though memory is initially available, perhaps because other routines will be filling that memory while this object is in use).

### 4.93.2 Constructor & Destructor Documentation

4.93.2.1 `template<typename I > repast::RandomAccess< I >::RandomAccess ( I beginning, int size )`  
`[inline]`

Constructs a [RandomAccess](#) instance for this iterator.

Parameters

<i>beginning</i>	
<i>size</i>	

### 4.93.3 Member Function Documentation

4.93.3.1 `template<typename I > I repast::RandomAccess< I >::get ( int index )` `[inline]`

Gets the element at the specified index.

Parameters

<i>index</i>	
--------------	--

The documentation for this class was generated from the following file:

- `repast_hpc/Random.h`

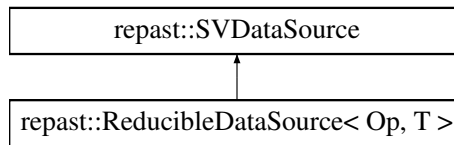
## 4.94 repast::ReducibleDataSource< Op, T > Class Template Reference

Source of data and a reduction operation.

`#include <ReducibleDataSource.h>`

Inheritance diagram for `repast::ReducibleDataSource< Op, T >`:





### Public Member Functions

- **ReducibleDataSource** (std::string name, [TDataSource](#)< T > \*dataSource, Op op)
- virtual void **record** ()
- virtual void **write** ([Variable](#) \*var)
- virtual [SVDataSource::DataType](#) **type** () const

### Protected Attributes

- Op **\_op**
- std::vector< T > **data**
- [TDataSource](#)< T > \* **\_dataSource**
- int **rank**

#### 4.94.1 Detailed Description

template<typename Op, typename T>class repast::ReducibleDataSource< Op, T >

Source of data and a reduction operation.

Used internally by a [SVDataSet](#) to store the data sources. their associated ops etc.

The documentation for this class was generated from the following file:

- repast\_hpc/ReducibleDataSource.h

## 4.95 repast::RepastEdge< V > Class Template Reference

Default graph / network edge implementation.

```
#include <Edge.h>
```

### Public Types

- enum **MASTER\_NODE** { **DEFAULT**, **SOURCE**, **TARGET** }

### Public Member Functions

- [RepastEdge](#) (V \*source, V \*target, MASTER\_NODE useTargetAsMaster=DEFAULT)  
*Creates a [RepastEdge](#) with the specified source and target and a default weight of 1.*
- [RepastEdge](#) (V \*source, V \*target, double weight, MASTER\_NODE useTargetAsMaster=DEFAULT)  
*Creates a [RepastEdge](#) with the specified source, target, and weight.*
- [RepastEdge](#) (boost::shared\_ptr< V > source, boost::shared\_ptr< V > target, MASTER\_NODE useTargetAsMaster=DEFAULT)  
*Creates a [RepastEdge](#) with the specified source and target and a default weight of 1.*

- [RepastEdge](#) (boost::shared\_ptr< V > [source](#), boost::shared\_ptr< V > [target](#), double [weight](#), MASTER\_NODE useTargetAsMaster=DEFAULT)  
Creates a [RepastEdge](#) with the specified source, target, and weight.
- [RepastEdge](#) (const [RepastEdge](#) &edge)  
Copy constructor that creates a [RepastEdge](#) from another [RepastEdge](#).
- V \* [source](#) () const  
Gets the source of this [RepastEdge](#).
- V \* [target](#) () const  
Gets the target of this [RepastEdge](#).
- void **target** (V \*target)
- void **source** (V \*source)
- double [weight](#) () const  
Gets the weight of this [RepastEdge](#).
- void **weight** (double wt)
- bool **usesTargetAsMaster** ()
- void **markConflicted** ()
- void **clearConflicted** ()
- bool **isConflicted** ()

#### 4.95.1 Detailed Description

```
template<typename V>class repast::RepastEdge< V >
```

Default graph / network edge implementation.

Template Parameters

V	agent type that is the source and target of the edge
---	--

#### 4.95.2 Constructor & Destructor Documentation

4.95.2.1 `template<typename V > repast::RepastEdge< V >::RepastEdge ( V * source, V * target, MASTER_NODE useTargetAsMaster = DEFAULT )`

Creates a [RepastEdge](#) with the specified source and target and a default weight of 1.

Parameters

<i>source</i>	the edge source
<i>target</i>	the edge target

4.95.2.2 `template<typename V > repast::RepastEdge< V >::RepastEdge ( V * source, V * target, double weight, MASTER_NODE useTargetAsMaster = DEFAULT )`

Creates a [RepastEdge](#) with the specified source, target, and weight.

Parameters

<i>source</i>	the edge source
<i>target</i>	the edge target
<i>weight</i>	the edge weight

4.95.2.3 `template<typename V> repast::RepastEdge< V >::RepastEdge ( boost::shared_ptr< V > source,  
boost::shared_ptr< V > target, MASTER_NODE useTargetAsMaster = DEFAULT )`

Creates a [RepastEdge](#) with the specified source and target and a default weight of 1.

## Parameters

<i>source</i>	the edge source
<i>target</i>	the edge target

4.95.2.4 `template<typename V> repast::RepastEdge< V>::RepastEdge ( boost::shared_ptr< V> source, boost::shared_ptr< V> target, double weight, MASTER_NODE useTargetAsMaster = DEFAULT )`

Creates a [RepastEdge](#) with the specified source, target, and weight.

## Parameters

<i>source</i>	the edge source
<i>target</i>	the edge target
<i>weight</i>	the edge weight

## 4.95.3 Member Function Documentation

4.95.3.1 `template<typename V> V* repast::RepastEdge< V>::source ( ) const [inline]`

Gets the source of this [RepastEdge](#).

## Returns

the source of this [RepastEdge](#).

4.95.3.2 `template<typename V> V* repast::RepastEdge< V>::target ( ) const [inline]`

Gets the target of this [RepastEdge](#).

## Returns

the target of this [RepastEdge](#).

4.95.3.3 `template<typename V> double repast::RepastEdge< V>::weight ( ) const [inline]`

Gets the weight of this [RepastEdge](#).

## Returns

the weight of this [RepastEdge](#).

The documentation for this class was generated from the following file:

- `repast_hpc/Edge.h`

4.96 `repast::RepastEdgeContent< V>` Struct Template Reference

Serializable; also, does not include agent content, only agent IDs.

```
#include <Edge.h>
```

## Public Member Functions

- template<class Archive >  
void **serialize** (Archive &ar, const unsigned int version)
- **RepastEdgeContent** ([RepastEdge](#)< V > \*edge)

## Public Attributes

- [AgentId](#) **source**
- [AgentId](#) **target**
- double **weight**
- bool **usesTargetAsMaster**

## Friends

- class **boost::serialization::access**

### 4.96.1 Detailed Description

template<typename V>struct repast::RepastEdgeContent< V >

Serializable; also, does not include agent content, only agent IDs.

#### Template Parameters

<a href="#">V</a>	type for vertices; must provide AgentID
-------------------	---

The documentation for this struct was generated from the following file:

- repast\_hpc/Edge.h

## 4.97 repast::RepastEdgeContentManager< V > Class Template Reference

Class for creating RepastEdges from [RepastEdgeContent](#), and vice versa.

```
#include <Edge.h>
```

## Public Member Functions

- [RepastEdge](#)< V > \* **createEdge** ([RepastEdgeContent](#)< V > &content, [Context](#)< V > \*context)
- [RepastEdgeContent](#)< V > \* **provideEdgeContent** ([RepastEdge](#)< V > \*edge)

### 4.97.1 Detailed Description

template<typename V>class repast::RepastEdgeContentManager< V >

Class for creating RepastEdges from [RepastEdgeContent](#), and vice versa.

#### Template Parameters

<a href="#">V</a>	type for vertices; must provide AgentID
-------------------	---

The documentation for this class was generated from the following file:

- repast\_hpc/Edge.h

## 4.98 repast::RepastEvent Class Reference

NON USER API.

```
#include <Schedule.h>
```

### Public Attributes

- double **tick**
- boost::shared\_ptr< [Functor](#) > **func\_ptr**

### 4.98.1 Detailed Description

NON USER API.

The documentation for this class was generated from the following files:

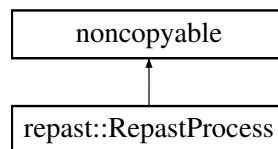
- repast\_hpc/Schedule.h
- repast\_hpc/Schedule.cpp

## 4.99 repast::RepastProcess Class Reference

Encapsulates the process in which repast is running and manages interprocess communication etc.

```
#include <RepastProcess.h>
```

Inheritance diagram for repast::RepastProcess:



### Public Types

- enum **EXCHANGE\_PATTERN** { **POLL**, **USE\_CURRENT**, **USE\_LAST\_OR\_POLL**, **USE\_LAST\_OR\_USE\_CURRENT** }

### Public Member Functions

- void [agentRemoved](#) (const [AgentId](#) &id)  
*NON USER API.*
- void [moveAgent](#) (const [AgentId](#) &id, int process)  
*NON USER API.*
- void [addExportedAgent](#) (int importingProcess, [AgentId](#) id)  
*NON USER API.*
- void [addImportedAgent](#) ([AgentId](#) id)  
*NON USER API.*
- int [rank](#) () const  
*Gets the rank of this process.*
- int [worldSize](#) () const

*Gets the number of processes in the world.*

- void **done** ()

*Notifies this [RepastProcess](#) that simulation has completed.*

- [ScheduleRunner](#) & **getScheduleRunner** ()

*Gets the [ScheduleRunner](#) used by this [RepastProcess](#).*

- boost::mpi::communicator \* **getCommunicator** ()
- void **dropImporterExporterSet** (std::string setName)
- std::string **ImporterExporterVersion** ()
- std::string **ImporterExporterReport** ()
- template<typename T, typename Content, typename Provider, typename Updater, typename AgentCreator >  
void **requestAgents** ([SharedContext](#)< T > &context, [AgentRequest](#) &request, Provider &provider, Updater &updater, AgentCreator &creator, std::string setName=DEFAULT\_AGENT\_REQUEST\_SET, AGENT\_IMPORTER\_EXPORTER\_TYPE setType=DEFAULT\_ENUM\_SYMBOL)

*Request agents from other processes.*

- template<typename Content, typename Provider, typename Updater >  
void **synchronizeAgentStates** (Provider &provider, Updater &updater, std::string setName=REQUEST\_AGENTS\_ALL)

*Synchronizes the state values of shared agents.*

- template<typename T, typename Content, typename Provider, typename Updater, typename AgentCreator >  
void **synchronizeProjectionInfo** ([SharedContext](#)< T > &context, Provider &provider, Updater &updater, AgentCreator &creator, EXCHANGE\_PATTERN exchangePattern=POLL, bool declareNoAgentsKeptOnAnyProcess=false)

*Synchronizes the [Projection](#) information for shared projections.*

- template<typename T, typename Content, typename Provider, typename AgentCreator, typename Updater >  
void **synchronizeAgentStatus** ([SharedContext](#)< T > &context, Provider &provider, Updater &updater, AgentCreator &creator, EXCHANGE\_PATTERN exchangePattern=POLL)

*Synchronizes the status (moved or died) of all agents across processes.*

## Static Public Member Functions

- static [RepastProcess](#) \* **init** (std::string propsfile, boost::mpi::communicator \*comm=0, int maxConfigFileSize=MAX\_CONFIG\_FILE\_SIZE)

*Initialize this [RepastProcess](#).*

- static [RepastProcess](#) \* **instance** ()

*Gets this [RepastProcess](#).*

- static boost::mpi::communicator \* **communicator** ()

## Protected Member Functions

- **RepastProcess** (boost::mpi::communicator \*comm=0)
- void **saveProjInfoSRProcs** (std::vector< int > &sends, std::vector< int > &recvs)
- void **saveAgentStatusInfoSRProcs** (std::vector< int > &sends, std::vector< int > &recvs)

### 4.99.1 Detailed Description

Encapsulates the process in which repast is running and manages interprocess communication etc.

This is singleton to insure that there is one per actual process.

## 4.99.2 Member Function Documentation

### 4.99.2.1 void repast::RepastProcess::addExportedAgent ( int *importingProcess*, AgentId *id* )

NON USER API.

Notifies this [RepastProcess](#) that it is exporting the specified agent to the specified process. This sort of notification is done automatically when requesting agents, but agents may get added in other ways.

### 4.99.2.2 void repast::RepastProcess::addImportedAgent ( AgentId *id* )

NON USER API.

Notifies this [RepastProcess](#) that it is importing the specified agent. This sort of notification is normally done automatically when requesting agents, but imports can occur in other ways.

### 4.99.2.3 void repast::RepastProcess::agentRemoved ( const AgentId & *id* )

NON USER API.

Notifies this [RepastProcess](#) that the specified agent has been removed (e.g. the agent "died").

### 4.99.2.4 void repast::RepastProcess::done ( )

Notifies this [RepastProcess](#) that simulation has completed.

This should be called when the simulation has completed.

### 4.99.2.5 ScheduleRunner& repast::RepastProcess::getScheduleRunner ( ) [inline]

Gets the [ScheduleRunner](#) used by this [RepastProcess](#).

Returns

the [ScheduleRunner](#) used by this [RepastProcess](#).

### 4.99.2.6 RepastProcess \* repast::RepastProcess::init ( std::string *propsfile*, boost::mpi::communicator \* *comm* = 0, int *maxConfigFileSize* = MAX\_CONFIG\_FILE\_SIZE ) [static]

Initialize this [RepastProcess](#).

This must be called before the [RepastProcess](#) is used. If a configuration properties file is specified this properties file will be used to configure logging.

Parameters

<i>propsfile</i>	a configuration properties file. This can be an empty string.
------------------	---

### 4.99.2.7 RepastProcess \* repast::RepastProcess::instance ( ) [static]

Gets this [RepastProcess](#).

Returns

this [RepastProcess](#) instance.



4.99.2.8 void repast::RepastProcess::moveAgent ( const AgentId & *id*, int *process* )

NON USER API.

Notifies this [RepastProcess](#) that the specified agent should be moved from this process to the specified process.

Parameters

<i>id</i>	the id of the agent to be moved
<i>process</i>	the process to move the agent to

4.99.2.9 int repast::RepastProcess::rank ( ) const [inline]

Gets the rank of this process.

Returns

the rank of this process.

4.99.2.10 template<typename T , typename Content , typename Provider , typename Updater , typename AgentCreator > void repast::RepastProcess::requestAgents ( SharedContext< T > & *context*, AgentRequest & *request*, Provider & *provider*, Updater & *updater*, AgentCreator & *creator*, std::string *setName* = DEFAULT\_AGENT\_REQUEST\_SET, AGENT\_IMPORTER\_EXPORTER\_TYPE *setType* = DEFAULT\_ENUM\_SYMBOL )

Request agents from other processes.

Requests agents from one process to others.

Copies of the requested agents' Content are retrieved from their respective processes, created using the Agent-Creator and added to the specified context.

Parameters

<i>context</i>	the context to which the requested agents will be added
<i>request</i>	the <a href="#">AgentRequest</a> containing the ids of the requested agents
<i>provider</i>	provides Content for a given an <a href="#">AgentRequest</a>
<i>creator</i>	creates agents of type T given Content.

Template Parameters

<i>T</i>	the type of the agents in the context
<i>Content</i>	the serializable struct or class that describes the state of agents
<i>Provider</i>	given an <a href="#">AgentRequest</a> , a Provider provides the Content for the requested agents, implementing void provideContent(const <a href="#">AgentRequest</a> &, std::vector< Content>&)
<i>AgentCreator</i>	a class that can create agents from Content, implementing T* createAgent(Content&).

4.99.2.11 template<typename Content , typename Provider , typename Updater > void repast::RepastProcess::synchronize-AgentStates ( Provider & *provider*, Updater & *updater*, std::string *setName* = REQUEST\_AGENTS\_ALL )

Synchronizes the state values of shared agents.

Does not change the [Projection](#) information for those agents.

4.99.2.12 `template<typename T , typename Content , typename Provider , typename AgentCreator , typename Updater > void  
repast::RepastProcess::synchronizeAgentStatus ( SharedContext< T > & context, Provider & provider, Updater  
& updater, AgentCreator & creator, EXCHANGE_PATTERN exchangePattern = POLL )`

Synchronizes the status (moved or died) of all agents across processes.

## Parameters

<i>context</i>	the <a href="#">SharedContext</a> that contains the agents on this proceses
<i>provider</i>	the class that provides agents given an <a href="#">AgentRequest</a>
<i>creator</i>	creates agents of type T given Content.

## Template Parameters

<i>T</i>	the type of agents in the context
<i>Content</i>	the serializable struct or class that describes an agents state.
<i>Provider</i>	a class that provides Content, when given an <a href="#">AgentRequest</a> , implementing void provideContent(const repast::AgentRequest&, std::vector<Content>& out)
<i>AgentCreator</i>	a class that can create agents from Content, implementing T* createAgent(-Content&).

The documentation for this class was generated from the following files:

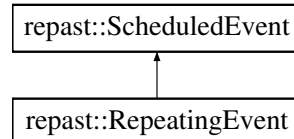
- repast\_hpc/RepastProcess.h
- repast\_hpc/RepastProcess.cpp

## 4.100 repast::RepeatingEvent Class Reference

NON USER API.

```
#include <Schedule.h>
```

Inheritance diagram for repast::RepeatingEvent:



### Public Member Functions

- **RepeatingEvent** (double start, double \_interval, [RepastEvent](#) \*)
- virtual bool [reschedule](#) (std::priority\_queue< [ScheduledEvent](#) \*, std::vector< [ScheduledEvent](#) \* >, [Event-Compare](#) > &)

*Returns true if this event is rescheduled on the specified queue, otherwise false.*

### Additional Inherited Members

#### 4.100.1 Detailed Description

NON USER API.

[ScheduledEvent](#) that executes repeatedly. This will reschedule itself repeatedly at the appropriate interval.

The documentation for this class was generated from the following files:

- repast\_hpc/Schedule.h
- repast\_hpc/Schedule.cpp

## 4.101 repast::Request\_Packet< Content > Class Template Reference

### Public Member Functions

- **Request\_Packet** (std::vector< Content > \*agentContent, std::map< std::string, std::vector< [ProjectionInfoPacket](#) \* > > \*projectionInfo)
- template<class Archive >  
void **serialize** (Archive &ar, const unsigned int version)

### Public Attributes

- std::vector< Content > \* **agentContentPtr**
- std::map< std::string, std::vector< [ProjectionInfoPacket](#) \* > > \* **projectionInfoPtr**

### Friends

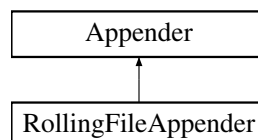
- class **boost::serialization::access**

The documentation for this class was generated from the following file:

- repast\_hpc/RepastProcess.h

## 4.102 RollingFileAppender Class Reference

Inheritance diagram for RollingFileAppender:



### Public Member Functions

- **RollingFileAppender** (const string name, const string file\_name, int max\_backup, int max\_size)
- virtual void **write** (const string &log\_line)
- virtual void **close** ()

### Additional Inherited Members

The documentation for this class was generated from the following file:

- repast\_hpc/logger.cpp

## 4.103 repast::Schedule Class Reference

NON USER API.

```
#include <Schedule.h>
```

## Public Types

- typedef boost::shared\_ptr  
< Functor > FunctorPtr  
*Typedef of for the functors that get scheduled.*

## Public Member Functions

- ScheduledEvent \* schedule\_event (double at, FunctorPtr functor)  
*Schedule the specified functor to execute once at the specified tick.*
- ScheduledEvent \* schedule\_event (double start, double interval, FunctorPtr func)  
*Schedules the specified functor to execute start at start, and at the specified interval thereafter.*
- void execute ()
- double getCurrentTick () const  
*Gets the current simulation tick.*
- double getNextTick () const  
*Gets the next tick at which the next events will be executed.*

### 4.103.1 Detailed Description

NON USER API.

The simulation schedule queue. This wraps priority queue to schedule repast ScheduledEvents.

### 4.103.2 Member Function Documentation

#### 4.103.2.1 double repast::Schedule::getCurrentTick ( ) const [inline]

Gets the current simulation tick.

##### Returns

the current simulation tick.

#### 4.103.2.2 double repast::Schedule::getNextTick ( ) const [inline]

Gets the next tick at which the next events will be executed.

##### Returns

the next tick at which the next events will be executed.

#### 4.103.2.3 ScheduledEvent \* repast::Schedule::schedule\_event ( double at, FunctorPtr functor )

*Schedule* the specified functor to execute once at the specified tick.

##### Parameters

<i>at</i>	the tick to execute at
<i>functor</i>	the functor to schedule

##### Returns

the event that has been scheduled

4.103.2.4 **ScheduledEvent** \* `repast::Schedule::schedule_event ( double start, double interval, FunctorPtr func )`

Schedules the specified functor to execute start at start, and at the specified interval thereafter.

## Parameters

<i>start</i>	
<i>interval</i>	
<i>func</i>	

## Returns

the event that has been scheduled

The documentation for this class was generated from the following files:

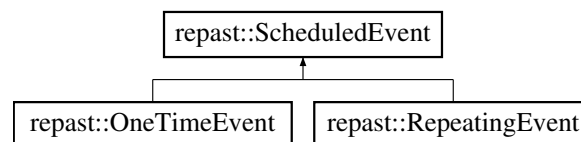
- repast\_hpc/Schedule.h
- repast\_hpc/Schedule.cpp

## 4.104 repast::ScheduledEvent Class Reference

NON USER API.

```
#include <Schedule.h>
```

Inheritance diagram for repast::ScheduledEvent:



### Public Member Functions

- **ScheduledEvent** (double, [RepastEvent](#) \*)
- virtual bool [reschedule](#) (std::priority\_queue< [ScheduledEvent](#) \*, std::vector< [ScheduledEvent](#) \* >, [EventCompare](#) > &)=0  
*Returns true if this event is rescheduled on the specified queue, otherwise false.*
- [RepastEvent](#) \* [get\\_event](#) ()  
*Gets the [RepastEvent](#) that this ScheduleEvent wraps.*

### Protected Attributes

- [RepastEvent](#) \* **event**
- double **start**

### Friends

- class **EventCompare**

#### 4.104.1 Detailed Description

NON USER API.

The actual object that is scheduled the priority queue for execution.

The documentation for this class was generated from the following files:

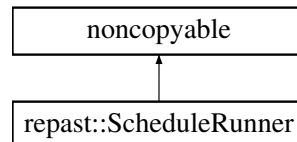
- `repast_hpc/Schedule.h`
- `repast_hpc/Schedule.cpp`

## 4.105 repast::ScheduleRunner Class Reference

Runs the [Schedule](#) by popping events off of the [Schedule](#) and executing them.

```
#include <Schedule.h>
```

Inheritance diagram for `repast::ScheduleRunner`:



### Public Member Functions

- **ScheduleRunner** (`boost::mpi::communicator *world`)
- `ScheduledEvent * scheduleEvent` (`double at`, `Schedule::FunctorPtr func`)  
*Schedules the [Functor](#) to execute at the specified tick.*
- `ScheduledEvent * scheduleEvent` (`double start`, `double interval`, `Schedule::FunctorPtr func`)  
*Schedules the [Functor](#) to execute at the specified start tick and every interval thereafter.*
- `void scheduleEndEvent` (`Schedule::FunctorPtr func`)  
*Schedules the specified functor to execute when the simulation ends.*
- `void scheduleStop` (`double at`)  
*Schedules the simulation to stop at the specified tick.*
- `void run` ()  
*Starts and runs the simulation schedule.*
- `double currentTick` ()  
*Gets the current tick.*
- `void stop` ()  
*Stops the simulation.*
- `const Schedule & schedule` ()  
*Gets the schedule executed by this simulation runner.*

### 4.105.1 Detailed Description

Runs the [Schedule](#) by popping events off of the [Schedule](#) and executing them.

Also provides methods for scheduling events. Simulation events should be scheduled for execution using this class which is accessible via `RepastProcess::instance()->getScheduleRunner()`

### 4.105.2 Member Function Documentation

#### 4.105.2.1 `double repast::ScheduleRunner::currentTick ( )` `[inline]`

Gets the current tick.

Returns

the current tick



4.105.2.2 `const Schedule& repast::ScheduleRunner::schedule ( ) [inline]`

Gets the schedule executed by this simulation runner.

## Returns

the schedule used by this simulation runner.

4.105.2.3 `void repast::ScheduleRunner::scheduleEndEvent ( Schedule::FunctorPtr func )`

Schedules the specified functor to execute when the simulation ends.

## Parameters

<i>func</i>	the functor to execute when the simulation ends
-------------	---

4.105.2.4 `ScheduledEvent * repast::ScheduleRunner::scheduleEvent ( double at, Schedule::FunctorPtr func )`

Schedules the [Functor](#) to execute at the specified tick.

## Parameters

<i>at</i>	the time to execute at
<i>func</i>	the functor to execute

## Returns

the event that was scheduled for the func

4.105.2.5 `ScheduledEvent * repast::ScheduleRunner::scheduleEvent ( double start, double interval, Schedule::FunctorPtr func )`

Schedules the [Functor](#) to execute at the specified start tick and every interval thereafter.

## Parameters

<i>start</i>	the time to start at
<i>interval</i>	the interval to execute at
<i>func</i>	the functor to execute

## Returns

the event that was scheduled for the func

4.105.2.6 `void repast::ScheduleRunner::scheduleStop ( double at )`

Schedules the simulation to stop at the specified tick.

## Parameters

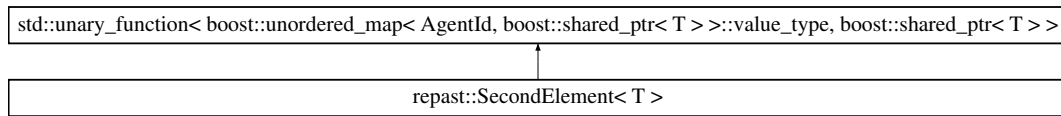
<i>at</i>	the tick at which the simulation should stop
-----------	--

The documentation for this class was generated from the following files:

- repast\_hpc/Schedule.h
- repast\_hpc/Schedule.cpp

## 4.106 `repast::SecondElement< T >` Struct Template Reference

Inheritance diagram for `repast::SecondElement< T >`:



### Public Member Functions

- `boost::shared_ptr< T > operator()` (const typename `boost::unordered_map< AgentId, boost::shared_ptr< T > >::value_type` &value) const

The documentation for this struct was generated from the following file:

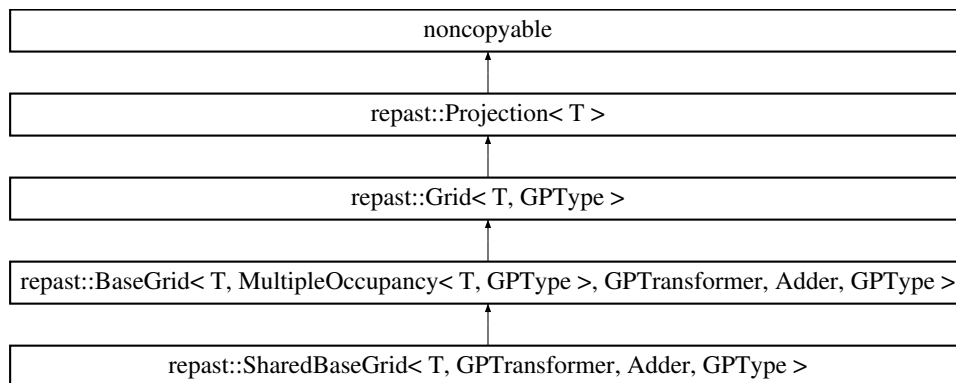
- `repast_hpc/Context.h`

## 4.107 `repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >` Class Template Reference

[Grid](#) / Space implementation specialized for the distributed context.

```
#include <SharedBaseGrid.h>
```

Inheritance diagram for `repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >`:



### Public Member Functions

- void **balance** ()
- [SharedBaseGrid](#) (std::string [name](#), [GridDimensions](#) gridDims, std::vector< int > processDims, int buffer, boost::mpi::communicator \*world)  
*Creates a SharedGrid with the specified name.*
- [GridDimensions bounds](#) () const  
*Gets the local bounds of this SharedGrid.*
- virtual const [GridDimensions dimensions](#) () const  
*Gets the local bounds of this SharedGrid.*
- void [synchMove](#) ()  
*Synchronizes the movement of agents off on one grid and onto another.*

- void **initSynchBuffer** ([SharedContext](#)< T > &context)  
*Initializes the synch buffer operation.*
- virtual bool **moveTo** (const [AgentId](#) &id, const std::vector< GPType > &newLocation)  
*Moves the specified agent to the specified location.*
- virtual bool **moveTo** (const [AgentId](#) &id, const [Point](#)< GPType > &pt)  
*Moves the specified agent to the specified point.*
- virtual void **removeAgent** (T \*agent)
- virtual void **getRequiredAgents** (std::set< [AgentId](#) > &agentsToTest, std::set< [AgentId](#) > &agentsRequired)
- virtual void **getAgentsToPush** (std::set< [AgentId](#) > &agentsToTest, std::map< int, std::set< [AgentId](#) > > &agentsToPush)  
*Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.*
- virtual void **getInfoExchangePartners** (std::set< int > &psToSendTo, std::set< int > &psToReceiveFrom)  
*Gets the set of processes with which this [Projection](#) exchanges projection info.*
- virtual void **getAgentStatusExchangePartners** (std::set< int > &psToSendTo, std::set< int > &psToReceiveFrom)  
*Gets the set of processes with which this [Projection](#) exchanges agent status info- that is, the set of processes from which agents can move to this one or to which they can move when moving from this one.*
- virtual void **updateProjectionInfo** ([ProjectionInfoPacket](#) \*pip, [Context](#)< T > \*context)

## Protected Types

- typedef [repast::BaseGrid](#)< T, [MultipleOccupancy](#)< T, GPType > , GPTransformer, Adder, GPType > **GridBaseType**

## Protected Member Functions

- [GridDimensions](#) **createSendBufferBounds** ([Neighbors::Location](#) location)
- virtual void **synchMoveTo** (const [AgentId](#) &id, const [Point](#)< GPType > &pt)=0
- void **getMovingAgentInfo** (std::map< int, std::vector< [AgentId](#) > > agentsToMove, [GridMovePackets](#)< GPType > outgoing)
- bool **locationIsInBuffer** ([Point](#)< GPType > pt)
- bool **agentIsInBuffer** ([AgentId](#) id)

## Protected Attributes

- int **\_buffer**
- [GridDimensions](#) **localBounds**
- [Neighbors](#) **nghs**
- std::vector< [AgentId](#) > **buffered**
- int **rank**
- boost::mpi::communicator \* **comm**

### 4.107.1 Detailed Description

template<typename T, typename GPTransformer, typename Adder, typename GPType>class repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >

[Grid](#) / Space implementation specialized for the distributed context.

Each [SharedBaseGrid](#) of the same name running on different processes is part of a pan process grid. This class manages this local part of the grid and its communication with its process neighbors. Users can specify a buffer

size that determines how much of the neighboring grids are visible in this grid. For example, if this grid originates at 0x0 and ends at 3x3, a buffer of 1 would make the locations (4,0), (4,1) (4,2) ... (4,4) and (0,4), (1,4)... (4,4) visible in this grid. The [SharedBaseGrid](#) takes many template parameters. Default variations of these that define typical grids and spaces are given in SharedGrids in SharedSpace.h

#### Template Parameters

<i>T</i>	the type of objects contained by this <a href="#">BaseGrid</a>
<i>GPTransformer</i>	transforms cell points according to the topology (e.g. periodic) of the <a href="#">BaseGrid</a> .
<i>Adder</i>	determines how objects are added to the grid from its associated context.
<i>GPType</i>	the coordinate type of the grid point locations. This must be an int or a double.

## 4.107.2 Constructor & Destructor Documentation

4.107.2.1 `template<typename T , typename GPTransformer , typename Adder , typename GPType >  
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::SharedBaseGrid ( std::string name,  
GridDimensions gridDims, std::vector< int > processDims, int buffer, boost::mpi::communicator * world )`

Creates a SharedGrid with the specified name.

#### Parameters

<i>name</i>	the name of this <a href="#">SharedBaseGrid</a>
<i>gridDims</i>	the dimensions of the entire pan-process grid
<i>processDims</i>	the number of processes in each dimension. This must divide evenly into gridDims.
<i>buffer</i>	the size of the buffer between this part of the pan-process grid and its neighbors.

## 4.107.3 Member Function Documentation

4.107.3.1 `template<typename T, typename GPTransformer, typename Adder, typename GPType> GridDimensions  
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::bounds ( ) const [inline]`

Gets the local bounds of this SharedGrid.

The local bounds are the dimensions of the section of the pan-process grid represented by this SharedGrid.

#### Returns

the local bounds of this SharedGrid.

4.107.3.2 `template<typename T, typename GPTransformer, typename Adder, typename GPType> virtual const  
GridDimensions repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::dimensions ( ) const  
[inline], [virtual]`

Gets the local bounds of this SharedGrid.

The local bounds are the dimensions of the section of the pan-process grid represented by this SharedGrid.

#### Returns

the local bounds of this SharedGrid.

Reimplemented from [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#).

```
4.107.3.3  template<typename T, typename GPTransformer, typename Adder, typename GPType> virtual void
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::getAgentStatusExchangePartners ( std::set<
int > & psToSendTo, std::set< int > & psToReceiveFrom )  [inline], [virtual]
```

Gets the set of processes with which this [Projection](#) exchanges agent status info- that is, the set of processes from which agents can move to this one or to which they can move when moving from this one.

In the most general case this will be all other processors. However, simulations where agents move in spaces will usually exchange agents only with a small subset of 'neighbor' processes, which is knowable in advance and constant. To accommodate the general case, the algorithm for exchanging information must poll all other processes to see which are sending to this one; if this is known in advance, this additional (expensive) step can be skipped.

Implements [repast::Grid< T, GPType >](#).

```
4.107.3.4  template<typename T , typename GPTransformer , typename Adder , typename GPType > void
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::getAgentsToPush ( std::set< AgentId > &
agentsToTest, std::map< int, std::set< AgentId > > & agentsToPush )  [virtual]
```

Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.

Generally spaces must push agents that are in 'buffer zones' and graphs must push local agents that are vertices to master edges where the other vertex is non- local. The results are returned per-process in the agentsToPush map.

Reimplemented from [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#).

Reimplemented in [repast::SharedDiscreteSpace< T, GPTransformer, Adder >](#).

```
4.107.3.5  template<typename T, typename GPTransformer, typename Adder, typename GPType> virtual void
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::getInfoExchangePartners ( std::set< int > &
psToSendTo, std::set< int > & psToReceiveFrom )  [inline], [virtual]
```

Gets the set of processes with which this [Projection](#) exchanges projection info.

In the most general case this will be all other processors; this is the case for graphs, where agent connections can be arbitrary. However, spaces usually exchange information only with a small subset of 'neighbor' processes, which is knowable in advance and constant. To accommodate the general case, the algorithm for exchanging information must poll all other processes to see which are sending to this one; if this is known in advance, this additional (expensive) step can be skipped.

Implements [repast::Grid< T, GPType >](#).

```
4.107.3.6  template<typename T, typename GPTransformer , typename Adder , typename GPType > void
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::initSynchBuffer ( SharedContext< T > &
context )
```

Initializes the synch buffer operation.

This should be called before synchronizing the buffers themselves.

#### Parameters

<i>the</i>	<a href="#">SharedContext</a> that contains this SharedGrid projection.
------------	---

```
4.107.3.7  template<typename T , typename GPTransformer , typename Adder , typename GPType> bool
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::moveTo ( const AgentId & id, const
std::vector< GPType > & newLocation )  [virtual]
```

Moves the specified agent to the specified location.

Returns true if the move was successful otherwise false. The agent must be already added to the context associated with this space, otherwise this throws an `out_of_range` exception if the new location out of bounds.

## Parameters

<i>id</i>	the id of the agent to move
<i>newLocation</i>	the location to move to

## Returns

true if the move was successful, otherwise false

Reimplemented from [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#).

```
4.107.3.8 template<typename T , typename GPTransformer , typename Adder , typename GPType> bool
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::moveTo ( const AgentId & id, const Point<
GPType > & pt ) [virtual]
```

Moves the specified agent to the specified point.

## Parameters

<i>id</i>	the id of the agent to move
<i>pt</i>	where to move the agent to

## Returns

true if the move was successful, otherwise false

Reimplemented from [repast::BaseGrid< T, MultipleOccupancy< T, GPType >, GPTransformer, Adder, GPType >](#).

```
4.107.3.9 template<typename T , typename GPTransformer , typename Adder , typename GPType > void
repast::SharedBaseGrid< T, GPTransformer, Adder, GPType >::synchMove ( )
```

Synchronizes the movement of agents off on one grid and onto another.

If there is any chance that an agent has moved off the local dimensions of this SharedGrid and into those managed by another then this must be called.

The documentation for this class was generated from the following file:

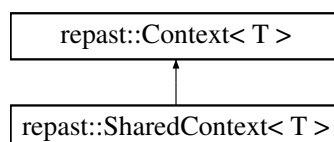
- repast\_hpc/SharedBaseGrid.h

## 4.108 repast::SharedContext< T > Class Template Reference

[Context](#) implementation specialized for the parallel distributed simulation.

```
#include <SharedContext.h>
```

Inheritance diagram for repast::SharedContext< T >:



## Public Types

- enum **filterLocalFlag** { **LOCAL** = 1, **NON\_LOCAL** = 0 }

- typedef boost::filter\_iterator  
< [IsLocalAgent](#)< T >, typename  
[Context](#)< T >::const\_iterator > **const\_local\_iterator**
- typedef boost::filter\_iterator  
< [AgentStateFilter](#)< T >  
, typename [Context](#)< T >  
::const\_iterator > **const\_state\_aware\_iterator**
- typedef boost::filter\_iterator  
< [AgentStateFilter](#)< T >  
, typename [Context](#)< T >  
::const\_bytype\_iterator > **const\_state\_aware\_bytype\_iterator**
- typedef [Projection](#)< T >::RADIUS **RADIUS**

## Public Member Functions

- **SharedContext** (boost::mpi::communicator \*comm)
- const\_local\_iterator [localBegin](#) () const  
*Gets the start of iterator over the local agents in this context.*
- const\_local\_iterator [localEnd](#) () const  
*Gets the end of an iterator over the local agents in this context.*
- void [removeAgent](#) (const [AgentId](#) id)  
*Removes the specified agent from this context.*
- void [removeAgent](#) (T \*agent)  
*Removes the specified agent from this context.*
- void [importedAgentRemoved](#) (const [AgentId](#) &id)  
*Notifies this context that the specified non-local agent has been removed and this context should then delete that agent from itself.*
- void [incrementProjRefCount](#) (const [AgentId](#) &id)  
*Increments the projection reference count for the specified agent.*
- void [decrementProjRefCount](#) (const [AgentId](#) &id)  
*Decrements the projection reference count for the specified agent.*
- const\_state\_aware\_iterator [begin](#) (filterLocalFlag local)  
*Gets the start of an iterator that will iterate over only local or non-local agents.*
- const\_state\_aware\_iterator [end](#) (filterLocalFlag local)  
*Gets the end of an iterator that will iterate over only local or non-local agents.*
- const\_state\_aware\_bytype\_iterator [byTypeBegin](#) (filterLocalFlag local, int type)  
*Gets the start of an iterator that will iterate over only local or non-local agents of a certain type (per their [AgentId](#) value)*
- const\_state\_aware\_bytype\_iterator [byTypeEnd](#) (filterLocalFlag local, int type)  
*Gets the end of an iterator that will iterate over only local or non-local agents of a certain type (per their [AgentId](#) value)*
- template<typename filterStruct >  
boost::filter\_iterator  
< filterStruct, typename  
[SharedContext](#)< T >  
::const\_state\_aware\_iterator > [filteredBegin](#) (filterLocalFlag local, filterStruct &fStruct)  
*Gets the start of an iterator that will iterate over only local or non-local agents meeting the criteria of the user-defined struct (see [IsLocalAgent](#) for an example)*
- template<typename filterStruct >  
boost::filter\_iterator  
< filterStruct, typename  
[SharedContext](#)< T >  
::const\_state\_aware\_iterator > [filteredEnd](#) (filterLocalFlag local, filterStruct &fStruct)  
*Gets the end of an iterator that will iterate over only local or non-local agents meeting the criteria of the user-defined struct (see [IsLocalAgent](#) for an example)*



- `template<typename filterStruct >`  
`boost::filter_iterator`  
`< filterStruct, typename`  
`SharedContext< T >`  
`::const_state_aware_bytype_iterator > byTypeFilteredBegin` (`filterLocalFlag local, int type, filterStruct &fStruct`)  
*Gets the start of an iterator that will iterate over only local or non-local agents of the specified type and meeting the criteria of the user-defined struct (see [IsLocalAgent](#) for an example)*
- `template<typename filterStruct >`  
`boost::filter_iterator`  
`< filterStruct, typename`  
`SharedContext< T >`  
`::const_state_aware_bytype_iterator > byTypeFilteredEnd` (`filterLocalFlag local, int type, filterStruct &fStruct`)  
*Gets the end of an iterator that will iterate over only local or non-local agents of the specified type and meeting the criteria of the user-defined struct (see [IsLocalAgent](#) for an example)*
- `void selectAgents` (`filterLocalFlag localOrNonLocalOnly, std::set< T * > &selectedAgents, bool remove=false, int popSize=-1`)  
*Gets a set of pointers to all local or non-local agents in this context.*
- `void selectAgents` (`filterLocalFlag localOrNonLocalOnly, std::vector< T * > &selectedAgents, bool remove=false, int popSize=-1`)  
*Gets a randomly ordered vector of pointers to all local or non-local agents in this context.*
- `void selectAgents` (`filterLocalFlag localOrNonLocalOnly, int count, std::set< T * > &selectedAgents, bool remove=false, int popSize=-1`)  
*Gets a set of pointers to a specified number of randomly selected local or non-local agents.*
- `void selectAgents` (`filterLocalFlag localOrNonLocalOnly, int count, std::vector< T * > &selectedAgents, bool remove=false, int popSize=-1`)  
*Gets a randomly ordered vector of pointers to a specified number of randomly selected local or non-local agents.*
- `void selectAgents` (`filterLocalFlag localOrNonLocalOnly, std::set< T * > &selectedAgents, int type, bool remove=false, int popSize=-1`)  
*Gets a set of pointers to all local or non-local agents in this context of a specified type (per their [AgentId](#) values).*
- `void selectAgents` (`filterLocalFlag localOrNonLocalOnly, std::vector< T * > &selectedAgents, int type, bool remove=false, int popSize=-1`)  
*Gets a randomly ordered vector of pointers to all local or non-local agents in this context of a specified type (per their [AgentId](#) values).*
- `void selectAgents` (`filterLocalFlag localOrNonLocalOnly, int count, std::set< T * > &selectedAgents, int type, bool remove=false, int popSize=-1`)  
*Gets a set of pointers to a specified number of randomly selected local or non-local agents of a specified type (per their [AgentId](#) values).*
- `void selectAgents` (`filterLocalFlag localOrNonLocalOnly, int count, std::vector< T * > &selectedAgents, int type, bool remove=false, int popSize=-1`)  
*Gets a randomly ordered vector of pointers to a specified number of randomly selected local or non-local agents of a specified type (per their [AgentId](#) values).*
- `template<typename filterStruct >`  
`void selectAgents` (`filterLocalFlag localOrNonLocalOnly, std::set< T * > &selectedAgents, filterStruct &filter, bool remove=false, int popSize=-1`)  
*Gets a set of pointers to all local or non-local agents in this context matching a user-defined filter.*
- `template<typename filterStruct >`  
`void selectAgents` (`filterLocalFlag localOrNonLocalOnly, std::vector< T * > &selectedAgents, filterStruct &filter, bool remove=false, int popSize=-1`)  
*Gets a randomly ordered vector of pointers to all local or non-local agents in this context matching a user-defined filter.*
- `template<typename filterStruct >`  
`void selectAgents` (`filterLocalFlag localOrNonLocalOnly, int count, std::set< T * > &selectedAgents, filterStruct &filter, bool remove=false, int popSize=-1`)

*Gets a set of pointers to a specified number of randomly selected local or non-local agents matching a user-defined filter.*

- template<typename filterStruct >  
void [selectAgents](#) (filterLocalFlag localOrNonLocalOnly, int count, std::vector< T \* > &selectedAgents, filterStruct &filter, bool remove=false, int popSize=-1)

*Gets a randomly ordered vector of pointers to a specified number of randomly selected local or non-local agents matching a user-defined filter.*

- template<typename filterStruct >  
void [selectAgents](#) (filterLocalFlag localOrNonLocalOnly, std::set< T \* > &selectedAgents, int type, filterStruct &filter, bool remove=false, int popSize=-1)

*Gets a set of pointers to all local or non-local agents in this context of a specified type (per their [AgentId](#) values) and matching a user-defined filter.*

- template<typename filterStruct >  
void [selectAgents](#) (filterLocalFlag localOrNonLocalOnly, std::vector< T \* > &selectedAgents, int type, filterStruct &filter, bool remove=false, int popSize=-1)

*Gets a randomly ordered vector of pointers to all local or non-local agents in this context of a specified type (per their [AgentId](#) values) and matching a user-defined filter.*

- template<typename filterStruct >  
void [selectAgents](#) (filterLocalFlag localOrNonLocalOnly, int count, std::set< T \* > &selectedAgents, int type, filterStruct &filter, bool remove=false, int popSize=-1)

*Gets a set of pointers to a specified number of randomly selected local or non-local agents of a specified type (per their [AgentId](#) values) and matching a user-defined filter.*

- template<typename filterStruct >  
void [selectAgents](#) (filterLocalFlag localOrNonLocalOnly, int count, std::vector< T \* > &selectedAgents, int type, filterStruct &filter, bool remove=false, int popSize=-1)

*Gets a randomly ordered vector of pointers to a specified number of randomly selected local or non-local agents of a specified type (per their [AgentId](#) values) and matching a user-defined filter.*

- bool [keepsAgentsOnSyncProj](#) ()

*Returns true if any of the projections in this context will try to 'keep' non-local agents during a synchronize projection operation.*

- bool **sendsSecondaryDataOnStatusExchange** ()
- void **getProjInfoExchangePartners** (std::set< int > &sends, std::set< int > &recvs)
- void **getAgentStatusInfoExchangePartners** (std::set< int > &sends, std::set< int > &recvs)
- void **getRequiredAgents** (std::set< [AgentId](#) > &agentsToTest, std::set< [AgentId](#) > &agentsToKeep, RADIUS radius=[Projection](#)< T >::PRIMARY)

*Given a set of agents to test, returns the set of those agents that must be kept in order to keep required projection information.*

- void **getNonlocalAgentsToDrop** (std::set< [AgentId](#) > &agentsToKeep, std::set< [AgentId](#) > &agentsToDrop, RADIUS radius=[Projection](#)< T >::PRIMARY)

*Given an initial set of agents that must be kept a priori, add any agents that must be kept due to projection requirements, and return the set of all non-local agents that can be dropped.*

- void **getAgentsToPushToOtherProcesses** (std::map< int, std::set< [AgentId](#) > > &agentsToPush)
- virtual void **addProjection** ([Projection](#)< T > \*projection)

*Adds the specified projection to this context.*

## Public Attributes

- [IsLocalAgent](#)< T > **localPredicate**
- [AgentStateFilter](#)< T > **LOCAL\_FILTER**
- [AgentStateFilter](#)< T > **NON\_LOCAL\_FILTER**
- std::vector< std::string > **getAgentsToPushProjOrder**

## Additional Inherited Members

### 4.108.1 Detailed Description

template<typename T>class repast::SharedContext< T >

[Context](#) implementation specialized for the parallel distributed simulation.

A [SharedContext](#) contains both local, that is, agents whose behavior is run on the [SharedContext](#)'s process and foreign agents, that is, copies of agents whose behavior is run on some other process.

#### Parameters

<i>T</i>	the type of agents in the context.
----------	------------------------------------

### 4.108.2 Member Function Documentation

4.108.2.1 template<typename T > void repast::SharedContext< T >::addProjection ( [Projection](#)< T > \* *projection* )  
[virtual]

Adds the specified projection to this context.

All the agents in this context will be added to the [Projection](#). Any agents subsequently added to this context will also be added to the [Projection](#).

#### Parameters

<i>projection</i>	the projection to add
-------------------	-----------------------

Reimplemented from [repast::Context< T >](#).

4.108.2.2 template<typename T > boost::filter\_iterator< [AgentStateFilter](#)< T >, typename [Context](#)< T >::const\_iterator > repast::SharedContext< T >::begin ( [filterLocalFlag](#) *local* )

Gets the start of an iterator that will iterate over only local or non-local agents.

#### Parameters

<i>local</i>	flag indicating whether local or non-local agents are to be included
--------------	--

4.108.2.3 template<typename T > boost::filter\_iterator< [AgentStateFilter](#)< T >, typename [Context](#)< T >::const\_bytype\_iterator > repast::SharedContext< T >::byTypeBegin ( [filterLocalFlag](#) *local*, int *type* )

Gets the start of an iterator that will iterate over only local or non-local agents of a certain type (per their [AgentId](#) value)

#### Parameters

<i>local</i>	flag indicating whether local or non-local agents are to be included
<i>type</i>	type to included

4.108.2.4 template<typename T > boost::filter\_iterator< [AgentStateFilter](#)< T >, typename [Context](#)< T >::const\_bytype\_iterator > repast::SharedContext< T >::byTypeEnd ( [filterLocalFlag](#) *local*, int *type* )

Gets the end of an iterator that will iterate over only local or non-local agents of a certain type (per their [AgentId](#) value)

## Parameters

<i>local</i>	flag indicating whether local or non-local agents are to be included
<i>type</i>	type to included

4.108.2.5 `template<typename T> template<typename filterStruct> boost::filter_iterator< filterStruct, typename SharedContext< T>::const_state_aware_bytype_iterator> repast::SharedContext< T>::byTypeFilteredBegin ( filterLocalFlag local, int type, filterStruct & fStruct )`

Gets the start of an iterator that will iterate over only local or non-local agents of the specified type and meeting the criteria of the user-defined struct (see [IsLocalAgent](#) for an example)

## Parameters

<i>local</i>	flag indicating whether local or non-local agents are to be included
<i>type</i>	type to be included
<i>filter</i>	struct with unary operator (boost::shared_ptr<T>) that returns true or false; used to selectively include agents.

## Template Parameters

<i>filterStruct</i>	the class of the filter to be used
---------------------	------------------------------------

4.108.2.6 `template<typename T> template<typename filterStruct> boost::filter_iterator< filterStruct, typename SharedContext< T>::const_state_aware_bytype_iterator> repast::SharedContext< T>::byTypeFilteredEnd ( filterLocalFlag local, int type, filterStruct & fStruct )`

Gets the end of an iterator that will iterate over only local or non-local agents of the specified type and meeting the criteria of the user-defined struct (see [IsLocalAgent](#) for an example)

## Parameters

<i>local</i>	flag indicating whether local or non-local agents are to be included
<i>type</i>	type to be included
<i>filter</i>	struct with unary operator (boost::shared_ptr<T>) that returns true or false; used to selectively include agents.

## Template Parameters

<i>filterStruct</i>	the class of the filter to be used
---------------------	------------------------------------

4.108.2.7 `template<typename T> void repast::SharedContext< T>::decrementProjRefCount ( const AgentId & id )`

Decrements the projection reference count for the specified agent.

## Parameters

<i>id</i>	the id of the agent
-----------	---------------------

4.108.2.8 `template<typename T> boost::filter_iterator< AgentStateFilter< T>, typename Context< T>::const_iterator> repast::SharedContext< T>::end ( filterLocalFlag local )`

Gets the end of an iterator that will iterate over only local or non-local agents.

## Parameters

<i>local</i>	flag indicating whether local or non-local agents are to be included
--------------	--

4.108.2.9 `template<typename T > template<typename filterStruct > boost::filter_iterator< filterStruct, typename SharedContext< T >::const_state_aware_iterator > repast::SharedContext< T >::filteredBegin ( filterLocalFlag local, filterStruct & fStruct )`

Gets the start of an iterator that will iterate over only local or non-local agents meeting the criteria of the user-defined struct (see [IsLocalAgent](#) for an example)

## Parameters

<i>local</i>	flag indicating whether local or non-local agents are to be included
<i>filter</i>	struct with unary operator (boost::shared_ptr<T>) that returns true or false; used to selectively include agents.

## Template Parameters

<i>filterStruct</i>	the class of the filter to be used
---------------------	------------------------------------

4.108.2.10 `template<typename T > template<typename filterStruct > boost::filter_iterator< filterStruct, typename SharedContext< T >::const_state_aware_iterator > repast::SharedContext< T >::filteredEnd ( filterLocalFlag local, filterStruct & fStruct )`

Gets the end of an iterator that will iterate over only local or non-local agents meeting the criteria of the user-defined struct (see [IsLocalAgent](#) for an example)

## Parameters

<i>local</i>	flag indicating whether local or non-local agents are to be included
<i>filter</i>	struct with unary operator (boost::shared_ptr<T>) that returns true or false; used to selectively include agents.

## Template Parameters

<i>filterStruct</i>	the class of the filter to be used
---------------------	------------------------------------

4.108.2.11 `template<typename T > void repast::SharedContext< T >::importedAgentRemoved ( const AgentId & id )`

Notifies this context that the specified non-local agent has been removed and this context should then delete that agent from itself.

## Parameters

<i>id</i>	the id of the agent that was removed
-----------	--------------------------------------

4.108.2.12 `template<typename T > void repast::SharedContext< T >::incrementProjRefCount ( const AgentId & id )`

Increments the projection reference count for the specified agent.

## Parameters

<i>id</i>	the id of the agent
-----------	---------------------

**4.108.2.13** `template<typename T > bool repast::SharedContext< T >::keepsAgentsOnSyncProj ( )`

Returns true if any of the projections in this context will try to 'keep' non-local agents during a synchronize projection operation.

(Generally graphs keep local agents that are part of master copies of links, but spaces do not keep any local agents.)

**4.108.2.14** `template<typename T > boost::filter_iterator< IsLocalAgent< T >, typename Context< T >::const_iterator > repast::SharedContext< T >::localBegin ( ) const`

Gets the start of iterator over the local agents in this context.

The iterator dereferences into `shared_ptr<T>`. The actual agent can be accessed by dereferencing the iter: `(*iter)->getId()` for example.

#### Returns

the start of iterator over the local agents in this context.

**4.108.2.15** `template<typename T > boost::filter_iterator< IsLocalAgent< T >, typename Context< T >::const_iterator > repast::SharedContext< T >::localEnd ( ) const`

Gets the end of an iterator over the local agents in this context.

The iterator dereferences into `shared_ptr<T>`. The actual agent can be accessed by dereferenceing the iter: `(*iter)->getId()` for example.

**4.108.2.16** `template<typename T > void repast::SharedContext< T >::removeAgent ( const AgentId id )`

Removes the specified agent from this context.

If the agent is non-local, this checks to make sure that it is not referenced by any projection before its removed.

#### Parameters

<i>id</i>	the id of the agent to remove
-----------	-------------------------------

**4.108.2.17** `template<typename T > void repast::SharedContext< T >::removeAgent ( T * agent )`

Removes the specified agent from this context.

If the agent is non-local, this checks to make sure that it is not referenced by any projection before its removed.

#### Parameters

<i>agent</i>	the agent to remove
--------------	---------------------

**4.108.2.18** `template<typename T > void repast::SharedContext< T >::selectAgents ( filterLocalFlag localOrNonLocalOnly, std::set< T * > & selectedAgents, bool remove = false, int popSize = -1 )`

Gets a set of pointers to all local or non-local agents in this context.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

## Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

**4.108.2.19** `template<typename T > void repast::SharedContext< T >::selectAgents ( filterLocalFlag localOrNonLocalOnly, std::vector< T * > & selectedAgents, bool remove = false, int popSize = -1 )`

Gets a randomly ordered vector of pointers to all local or non-local agents in this context.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

## Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

**4.108.2.20** `template<typename T > void repast::SharedContext< T >::selectAgents ( filterLocalFlag localOrNonLocalOnly, int count, std::set< T * > & selectedAgents, bool remove = false, int popSize = -1 )`

Gets a set of pointers to a specified number of randomly selected local or non-local agents.

If the set passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

## Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

**4.108.2.21** `template<typename T > void repast::SharedContext< T >::selectAgents ( filterLocalFlag  
localOrNonLocalOnly, int count, std::vector< T * > & selectedAgents, bool remove = false, int popSize = -1 )`

Gets a randomly ordered vector of pointers to a specified number of randomly selected local or non-local agents.

If the vector passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

#### Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

**4.108.2.22** `template<typename T > void repast::SharedContext< T >::selectAgents ( filterLocalFlag  
localOrNonLocalOnly, std::set< T * > & selectedAgents, int type, bool remove = false, int popSize = -1 )`

Gets a set of pointers to all local or non-local agents in this context of a specified type (per their [AgentId](#) values).

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

#### Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

**4.108.2.23** `template<typename T > void repast::SharedContext< T >::selectAgents ( filterLocalFlag  
localOrNonLocalOnly, std::vector< T * > & selectedAgents, int type, bool remove = false, int popSize = -1 )`

Gets a randomly ordered vector of pointers to all local or non-local agents in this context of a specified type (per their [AgentId](#) values).

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.



## Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

4.108.2.24 `template<typename T > void repast::SharedContext< T >::selectAgents ( filterLocalFlag localOrNonLocalOnly, int count, std::set< T * > & selectedAgents, int type, bool remove = false, int popSize = -1 )`

Gets a set of pointers to a specified number of randomly selected local or non-local agents of a specified type (per their [AgentId](#) values).

If the set passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

## Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

4.108.2.25 `template<typename T > void repast::SharedContext< T >::selectAgents ( filterLocalFlag localOrNonLocalOnly, int count, std::vector< T * > & selectedAgents, int type, bool remove = false, int popSize = -1 )`

Gets a randomly ordered vector of pointers to a specified number of randomly selected local or non-local agents of a specified type (per their [AgentId](#) values).

If the vector passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

## Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

4.108.2.26 `template<typename T > template<typename filterStruct > void repast::SharedContext< T >::selectAgents ( filterLocalFlag localOrNonLocalOnly, std::set< T * > & selectedAgents, filterStruct & filter, bool remove = false, int popSize = -1 )`

Gets a set of pointers to all local or non-local agents in this context matching a user-defined filter.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

#### Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

#### Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

4.108.2.27 `template<typename T > template<typename filterStruct > void repast::SharedContext< T >::selectAgents ( filterLocalFlag localOrNonLocalOnly, std::vector< T * > & selectedAgents, filterStruct & filter, bool remove = false, int popSize = -1 )`

Gets a randomly ordered vector of pointers to all local or non-local agents in this context matching a user-defined filter.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

#### Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
--	-----------------------------	---

out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

## Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

**4.108.2.28** `template<typename T > template<typename filterStruct > void repast::SharedContext< T >::selectAgents ( filterLocalFlag localOrNonLocalOnly, int count, std::set< T * > & selectedAgents, filterStruct & filter, bool remove = false, int popSize = -1 )`

Gets a set of pointers to a specified number of randomly selected local or non-local agents matching a user-defined filter.

If the set passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

## Parameters

	<i>localOrNonLocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

## Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

**4.108.2.29** `template<typename T > template<typename filterStruct > void repast::SharedContext< T >::selectAgents ( filterLocalFlag localOrNonLocalOnly, int count, std::vector< T * > & selectedAgents, filterStruct & filter, bool remove = false, int popSize = -1 )`

Gets a randomly ordered vector of pointers to a specified number of randomly selected local or non-local agents matching a user-defined filter.

If the vector passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

## Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

## Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

4.108.2.30 `template<typename T > template<typename filterStruct > void repast::SharedContext< T >::selectAgents ( filterLocalFlag localOrNonLocalOnly, std::set< T * > & selectedAgents, int type, filterStruct & filter, bool remove = false, int popSize = -1 )`

Gets a set of pointers to all local or non-local agents in this context of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

## Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

## Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

4.108.2.31 `template<typename T > template<typename filterStruct > void repast::SharedContext< T >::selectAgents ( filterLocalFlag localOrNonLocalOnly, std::vector< T * > & selectedAgents, int type, filterStruct & filter, bool remove = false, int popSize = -1 )`

Gets a randomly ordered vector of pointers to all local or non-local agents in this context of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

## Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

## Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

4.108.2.32 `template<typename T > template<typename filterStruct > void repast::SharedContext< T >::selectAgents ( filterLocalFlag localOrNonLocalOnly, int count, std::set< T * > & selectedAgents, int type, filterStruct & filter, bool remove = false, int popSize = -1 )`

Gets a set of pointers to a specified number of randomly selected local or non-local agents of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

If the set passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original set will be removed before the method returns.

The popSize parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

## Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a set into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

## Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

4.108.2.33 `template<typename T > template<typename filterStruct > void repast::SharedContext< T >::selectAgents ( filterLocalFlag localOrNonLocalOnly, int count, std::vector< T * > & selectedAgents, int type, filterStruct & filter, bool remove = false, int popSize = -1 )`

Gets a randomly ordered vector of pointers to a specified number of randomly selected local or non-local agents of a specified type (per their [AgentId](#) values) and matching a user-defined filter.

If the vector passed contains any elements when this method is called, the agents pointed to by those elements will be omitted from the selection.

If the 'remove' parameter is set to true, any elements in the original vector will be removed before the method returns.

The `popSize` parameter is used when the method is repeatedly called on a population whose size is known. Calls to this method typically begin by determining the size of the (valid) population to be sampled; if this is known, it can be provided here, improving performance.

#### Parameters

	<i>localOrNon-LocalOnly</i>	flag that indicates that the agents selected will be drawn only from agents either local or non-local to this process
	<i>count</i>	the number of agents to be selected. If this exceeds the number that can possibly be selected, all possible agents will be selected
out	<i>selectedAgents</i>	a vector into which the pointers to the agents will be placed
	<i>type</i>	numeric type of agent to be selected
	<i>filter</i>	user-defined filter specifying any criteria agents to be selected must meet
	<i>remove</i>	if true, remove any elements originally in the set before the set is returned (default is false)
	<i>popSize</i>	size of the population from which the sample will be drawn

#### Template Parameters

<i>filterStruct</i>	the type of the filter to be applied to the agents
---------------------	--

The documentation for this class was generated from the following file:

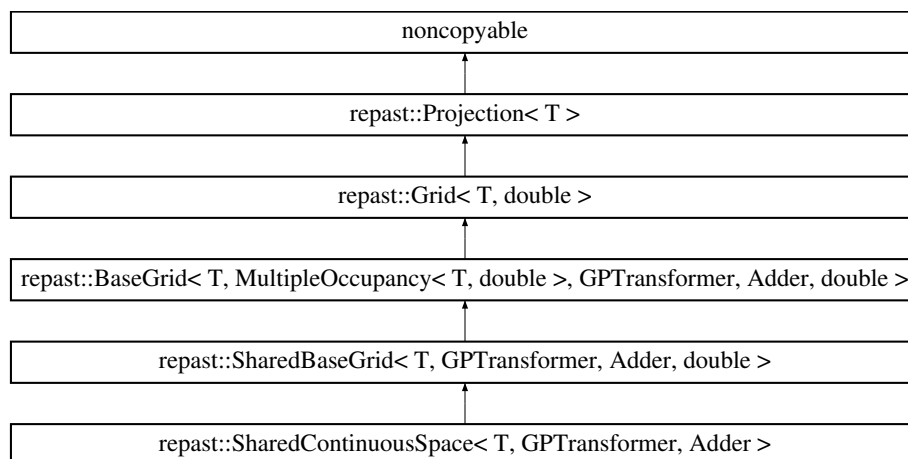
- `repat_hpc/SharedContext.h`

## 4.109 `repat::SharedContinuousSpace< T, GPTransformer, Adder >` Class Template Reference

Continuous space [SharedBaseGrid](#) implementation.

```
#include <SharedContinuousSpace.h>
```

Inheritance diagram for `repat::SharedContinuousSpace< T, GPTransformer, Adder >`:



#### Public Member Functions

- **SharedContinuousSpace** (`std::string` `name`, `GridDimensions` `gridDims`, `std::vector< int >` `processDims`, `int` `buffer`, `boost::mpi::communicator *` `world`)
- `template<typename AgentContent, typename Provider, typename AgentsCreator >`  
`void` `synchBuffer` (`SharedContext< T >` `&context`, `Provider` `&provider`, `AgentsCreator` `&creator`)  
*Synchronize the buffer area of this SharedGrid with its neighbors.*

- `template<typename AgentContent , typename ContentProvider , typename ContentReceiver >`  
`void synchBuffer (SharedContext< T > &context, ContentProvider &provider, ContentReceiver &receiver)`

## Protected Member Functions

- virtual `void synchMoveTo` (const [AgentId](#) &id, const [Point](#)< double > &pt)

### 4.109.1 Detailed Description

`template<typename T, typename GPTransformer, typename Adder>class repast::SharedContinuousSpace< T, GPTransformer, Adder >`

Continuous space [SharedBaseGrid](#) implementation.

This primarily adds the buffer synchronization appropriate for this type. Default templated typical SharedContinuousSpaces are defined in SharedGrids.

#### See Also

[SharedBaseGrid](#) for more details.

#### Template Parameters

<i>T</i>	the type of objects contained by this <a href="#">BaseGrid</a>
<i>GPTransformer</i>	transforms cell points according to the topology (e.g. periodic) of the <a href="#">BaseGrid</a> .
<i>Adder</i>	determines how objects are added to the grid from its associated context.

### 4.109.2 Member Function Documentation

4.109.2.1 `template<typename T , typename GPTransformer , typename Adder > template<typename AgentContent , typename Provider , typename AgentsCreator > void repast::SharedContinuousSpace< T, GPTransformer, Adder >::synchBuffer ( SharedContext< T > & context, Provider & provider, AgentsCreator & creator )`

Synchronize the buffer area of this SharedGrid with its neighbors.

This will copy the buffer area from the neighbors into this SharedGrid. This should be called immediately after `initSynchBuffer`.

#### Parameters

<i>context</i>	the <a href="#">SharedContext</a> that contains the agents in this SharedGrid.
<i>provider</i>	a class that provides AgentContent for the agents being buffered in neighboring grids.
<i>creator</i>	a class that creates a agents of type T when given AgentContent.

#### Template Parameters

<i>T</i>	the type of agent in this SharedGrid
<i>AgentContent</i>	the serializable struct or class that describes the state of agents.
<i>Provider</i>	a class that provides AgentContent for aagents, implementing <code>void provideContent(T* agent, std::vector&lt;AgentContent&gt;&amp; out)</code>
<i>AgentsCreator</i>	a class that creates agents given AgentContent, implementing <code>void createAgents(std::vector&lt;AgentContent&gt;&amp; contents, std::vector&lt;T*&gt;&amp; out)</code> . Creating agents from the vector of content and placing them in out.

The documentation for this class was generated from the following file:

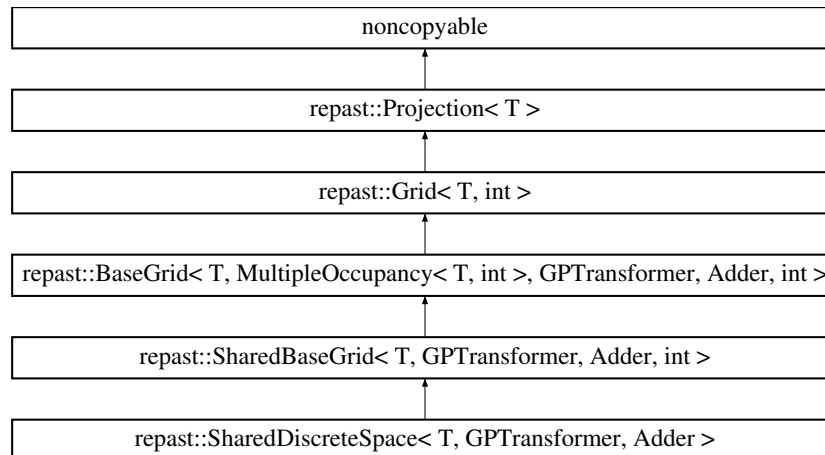
- `repast_hpc/SharedContinuousSpace.h`

## 4.110 `repast::SharedDiscreteSpace< T, GPTransformer, Adder >` Class Template Reference

Discrete matrix-like [SharedBaseGrid](#) implementation.

```
#include <SharedDiscreteSpace.h>
```

Inheritance diagram for `repast::SharedDiscreteSpace< T, GPTransformer, Adder >`:



### Public Member Functions

- **SharedDiscreteSpace** (std::string [name](#), [GridDimensions](#) gridDims, std::vector< int > processDims, int buffer, boost::mpi::communicator \*world)
- template<typename AgentContent, typename Provider, typename AgentsCreator >  
void [synchBuffer](#) ([SharedContext](#)< T > &context, Provider &provider, AgentsCreator &creator)  
*Synchronize the buffer area of this [SharedDiscreteSpace](#) with its neighbors.*
- virtual void [getAgentsToPush](#) (std::set< [AgentId](#) > &agentsToTest, std::map< int, std::set< [AgentId](#) > > &agentsToPush)  
*Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.*
- template<typename AgentContent, typename ContentProvider, typename ContentReceiver >  
void **synchBuffer** ([SharedContext](#)< T > &context, ContentProvider &provider, ContentReceiver &receiver)

### Protected Member Functions

- virtual void **synchMoveTo** (const [AgentId](#) &id, const [Point](#)< int > &pt)

#### 4.110.1 Detailed Description

```
template<typename T, typename GPTransformer, typename Adder>class repast::SharedDiscreteSpace< T, GPTransformer, Adder >
```

Discrete matrix-like [SharedBaseGrid](#) implementation.

This primarily adds the buffer synchronization appropriate for this type. Default templated typical SharedGrid types are defined in SharedGrids.

See Also

[SharedBaseGrid](#) for more details.



## Template Parameters

<i>T</i>	the type of objects contained by this <a href="#">BaseGrid</a>
<i>GPTransformer</i>	transforms cell points according to the topology (e.g. periodic) of the <a href="#">BaseGrid</a> .
<i>Adder</i>	determines how objects are added to the grid from its associated context.

## 4.110.2 Member Function Documentation

4.110.2.1 `template<typename T, typename GPTransformer, typename Adder> void repast::SharedDiscreteSpace< T, GPTransformer, Adder >::getAgentsToPush ( std::set< AgentId > & agentsToTest, std::map< int, std::set< AgentId >> & agentsToPush ) [virtual]`

Given a set of agents, gets the agents that this projection implementation must 'push' to other processes.

Generally spaces must push agents that are in 'buffer zones' and graphs must push local agents that are vertices to master edges where the other vertex is non- local. The results are returned per-process in the agentsToPush map.

Reimplemented from [repast::SharedBaseGrid< T, GPTransformer, Adder, int >](#).

4.110.2.2 `template<typename T, typename GPTransformer, typename Adder> template<typename AgentContent, typename Provider, typename AgentsCreator> void repast::SharedDiscreteSpace< T, GPTransformer, Adder >::synchBuffer ( SharedContext< T > & context, Provider & provider, AgentsCreator & creator )`

Synchronize the buffer area of this [SharedDiscreteSpace](#) with its neighbors.

This will copy the buffer area from the neighbors into this [SharedDiscreteSpace](#). This should be called immediately after `initSynchBuffer`.

## Parameters

<i>context</i>	the <a href="#">SharedContext</a> that contains the agents in this <a href="#">SharedDiscreteSpace</a> .
<i>provider</i>	a class that provides AgentContent for the agents being buffered in neighboring grids.
<i>creator</i>	a class that creates a agents of type T when given AgentContent.

## Template Parameters

<i>T</i>	the type of agent in this <a href="#">SharedDiscreteSpace</a>
<i>AgentContent</i>	the serializable struct or class that describes the state of agents.
<i>Provider</i>	a class that provides AgentContent for aagents, implementing void provideContent(T* agent, std::vector<AgentContent>& out)
<i>AgentsCreator</i>	a class that creates agents given AgentContent, implementing void createAgents(std::vector<AgentContent>& contents, std::vector<T*>& out). Creating agents from the vector of content and placing them in out.

The documentation for this class was generated from the following file:

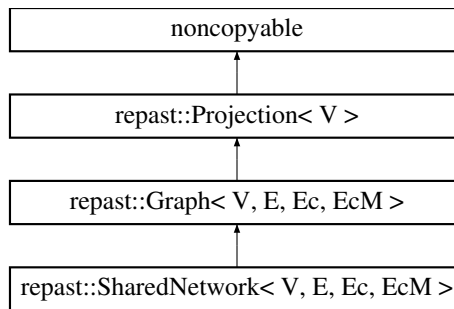
- `repast_hpc/SharedDiscreteSpace.h`

## 4.111 repast::SharedNetwork&lt; V, E, Ec, EcM &gt; Class Template Reference

Network implementation that can be shared across processes.

```
#include <SharedNetwork.h>
```

Inheritance diagram for `repast::SharedNetwork< V, E, Ec, EcM >`:



## Public Member Functions

- **SharedNetwork** (std::string [name](#), bool directed, EcM \*edgeContentMgr)  
*Creates a [SharedNetwork](#) with the specified name and whether or not the network is directed.*
- void **addSender** (int rank)  
*NON USER API.*
- void **removeSender** (int rank)  
*NON USER API Decrements the count of edges that are sent from rank to this network.*
- void **removeEdge** (V \*source, V \*target)  
*Removes the edge between source and target from this [Graph](#).*
- void **addEdge** (boost::shared\_ptr< E > edge)  
*Add an edge to this [SharedNetwork](#).*
- void **synchRemovedEdges** ()  
*Synchronizes any removed edges that are have been copied across processes.*
- virtual bool **isMaster** (E \*e)  
*Returns true if this is a master link; will be a master link if its master node is local.*

## Protected Member Functions

- virtual bool **addAgent** (boost::shared\_ptr< V > agent)
- virtual void **removeAgent** (V \*agent)
- virtual void **doAddEdge** (boost::shared\_ptr< E > edge)

## Friends

- template<typename Vertex , typename Edge , typename AgentContent , typename EdgeContent , typename EdgeManager , typename AgentCreator >  
void **createComplementaryEdges** ([SharedNetwork](#)< [Vertex](#), Edge, EdgeContent, EdgeManager > \*net, [SharedContext](#)< [Vertex](#) > &context, EdgeManager &edgeManager, AgentCreator &creator)  
*Notifies other processes of any edges that have been created between nodes on this process and imported nodes.*
- template<typename Vertex , typename Edge , typename EdgeContent , typename EdgeManager >  
void **synchEdges** ([SharedNetwork](#)< [Vertex](#), Edge, EdgeContent, EdgeManager > \*, EdgeManager &)  
*Synchronizes any edges that have been created as complementary edges.*

## Additional Inherited Members

### 4.111.1 Detailed Description

template<typename V, typename E, typename Ec, typename EcM>class repast::SharedNetwork< V, E, Ec, EcM >

Network implementation that can be shared across processes.

Networks are shared across processes by creating edges between local and non-local agents on a process. The createComplementaryEdges function will create complementary edges across processes in those cases. For example, if an edge is created between A1 and B2 on process 1 where B2 is copy of B1 on process 2, then creating complementary edges will create a copy of that edge on process 2, importing A1 into process 2 if necessary.

#### Template Parameters

<i>V</i>	the agent (vertex) type
<i>E</i>	the edge type. The edge type must be contain a constructor that takes a source and target of type V and extends <a href="#">RepastEdge</a> . <a href="#">RepastEdge</a> can also be used.

### 4.111.2 Constructor & Destructor Documentation

4.111.2.1 `template<typename V , typename E , typename Ec , typename EcM > repast::SharedNetwork< V, E, Ec, EcM >::SharedNetwork ( std::string name, bool directed, EcM * edgeContentMgr )`

Creates a [SharedNetwork](#) with the specified name and whether or not the network is directed.

#### Parameters

<i>the</i>	network name
<i>directed</i>	if true the network will be directed, otherwise not.

### 4.111.3 Member Function Documentation

4.111.3.1 `template<typename V , typename E , typename Ec , typename EcM > void repast::SharedNetwork< V, E, Ec, EcM >::addEdge ( boost::shared_ptr< E > edge )`

Add an edge to this [SharedNetwork](#).

#### Parameters

<i>edge</i>	the edge to add
-------------	-----------------

4.111.3.2 `template<typename V , typename E , typename Ec , typename EcM > void repast::SharedNetwork< V, E, Ec, EcM >::addSender ( int rank )`

NON USER API.

Increments the count of edges that are sent from rank to this network.

4.111.3.3 `template<typename V, typename E, typename Ec, typename EcM> virtual bool repast::SharedNetwork< V, E, Ec, EcM >::isMaster ( E * e ) [inline], [virtual]`

Returns true if this is a master link; will be a master link if its master node is local.

The master node is usually the edge 'source', but if the usesTargetAsMaster flag is set to true then the 'target' is the master node.

Implements [repast::Graph< V, E, Ec, EcM >](#).

4.111.3.4 `template<typename V , typename E , typename Ec , typename EcM > void repast::SharedNetwork< V, E, Ec, EcM >::removeEdge ( V * source, V * target ) [virtual]`

Removes the edge between source and target from this [Graph](#).

## Parameters

<i>source</i>	the source of the edge
<i>target</i>	the target of the edge

Reimplemented from [repast::Graph< V, E, Ec, EcM >](#).

## 4.111.4 Friends And Related Function Documentation

4.111.4.1 `template<typename V, typename E, typename Ec, typename EcM> template<typename Vertex , typename Edge , typename AgentContent , typename EdgeContent , typename EdgeManager , typename AgentCreator > void createComplementaryEdges ( SharedNetwork< Vertex, Edge, EdgeContent, EdgeManager > * net, SharedContext< Vertex > & context, EdgeManager & edgeManager, AgentCreator & creator ) [friend]`

Notifies other processes of any edges that have been created between nodes on this process and imported nodes.

The other process will then create the complimentary edge. For example, if P1 creates an edge between A and B where B resides on P2, then this method will notify P2 to create the incoming edge A->B on its copy of B. Any unknown agents will be added to the context. For example, if P2 didn't have a reference to A, then A will be added to P2's context.

## Parameters

<i>net</i>	the network in which to create the complementary edges or from which to send complementary edges
<i>context</i>	the context that contains the agents in the process
<i>edgeManager</i>	creates edges from EdgeContent and creates EdgeContent from an edge and a context.
<i>creator</i>	creates agents from AgentContent.

## Template Parameters

<a href="#">Vertex</a>	the vertex (agent) type
<i>Edge</i>	the edge type
<i>AgentContent</i>	the serializable struct or class that describes the agent state. It must contain a <code>getId()</code> method that returns the <a href="#">AgentId</a> of the agent it describes.
<i>EdgeContent</i>	the serializable struct or class that describes edge state. At the very least EdgeContent must contain two public fields <code>sourceContent</code> and <code>targetContent</code> of type <code>AgentContent</code> . These represent the source and target of the edge.
<i>EdgeManager</i>	create edges from EdgeContent and provides EdgeContent given a context and an edge of type Edge. It must implement <code>void provideEdgeContent(constEdge* edge, std::vector&lt;EdgeContent&gt;&amp; edgeContent)</code> and <code>Edge* createEdge(repast::Context&lt;Vertex&gt;&amp; context, EdgeContent&amp; edge);</code>
<i>AgentCreator</i>	creates agents from AgentContent, implementing the following method <code>Vertex* createAgent(constAgentContent&amp; content);</code>

4.111.4.2 `template<typename V, typename E, typename Ec, typename EcM> template<typename Vertex , typename Edge , typename EdgeContent , typename EdgeManager > void synchEdges ( SharedNetwork< Vertex, Edge, EdgeContent, EdgeManager > * net, EdgeManager & edgeManager ) [friend]`

Synchronizes any edges that have been created as complementary edges.

This only necessary if the edges have been deleted or their state has been changed in some way.

## Parameters

<i>net</i>	the network in which to create the complementary edges or from which to send complementary edges
<i>edgeManager</i>	updates edges from EdgeContent and creates EdgeContent from an edge and a context.

## Template Parameters

<a href="#">Vertex</a>	the vertex (agent) type
<a href="#">Edge</a>	the edge type
<a href="#">EdgeContent</a>	the serializable struct or class that describes edge state.
<a href="#">EdgeManager</a>	updates edges from EdgeContent and provides EdgeContent given a context and an edge of type Edge. It must implement void provideEdgeContent(const Edge* edge, std::vector<EdgeContent>& edgeContent) and void receiveEdgeContent(const EdgeContent& content);

The documentation for this class was generated from the following file:

- repast\_hpc/SharedNetwork.h

## 4.112 repast::SharedSpaces< T > Struct Template Reference

### Public Types

- typedef [SharedDiscreteSpace](#)< T, [WrapAroundBorders](#), [SimpleAdder](#)< T > > [SharedWrappedDiscreteSpace](#)  
*Discrete grid space with periodic (toroidal) borders.*
- typedef [SharedDiscreteSpace](#)< T, [StrictBorders](#), [SimpleAdder](#)< T > > [SharedStrictDiscreteSpace](#)  
*Discrete grid space with strict borders.*
- typedef [SharedContinuousSpace](#)< T, [WrapAroundBorders](#), [SimpleAdder](#)< T > > [SharedWrappedContinuousSpace](#)  
*Continuous space with periodic (toroidal) borders.*
- typedef [SharedContinuousSpace](#)< T, [StrictBorders](#), [SimpleAdder](#)< T > > [SharedStrictContinuousSpace](#)  
*Continuous space with strict borders.*

### 4.112.1 Member Typedef Documentation

4.112.1.1 `template<typename T> typedef SharedContinuousSpace<T, StrictBorders, SimpleAdder<T>> repast::SharedSpaces< T >::SharedStrictContinuousSpace`

Continuous space with strict borders.

Any added agents are not given a location, but are in "grid limbo" until moved via a grid move call.

4.112.1.2 `template<typename T> typedef SharedDiscreteSpace<T, StrictBorders, SimpleAdder<T>> repast::SharedSpaces< T >::SharedStrictDiscreteSpace`

Discrete grid space with strict borders.

Any added agents are not given a location, but are in "grid limbo" until moved via a grid move call.

4.112.1.3 `template<typename T> typedef SharedContinuousSpace<T, WrapAroundBorders, SimpleAdder<T>> repast::SharedSpaces< T >::SharedWrappedContinuousSpace`

Continuous space with periodic (toroidal) borders.

Any added agents are not given a location, but are in "grid limbo" until moved via a grid move call.

4.112.1.4 `template<typename T > typedef SharedDiscreteSpace<T, WrapAroundBorders, SimpleAdder<T> > repast::SharedSpaces< T >::SharedWrappedDiscreteSpace`

Discrete grid space with periodic (toroidal) borders.

Any added agents are not given a location, but are in "grid limbo" until moved via a grid move call.

The documentation for this struct was generated from the following file:

- `repast_hpc/SharedSpaces.h`

## 4.113 `repast::SimpleAdder< T >` Class Template Reference

### Public Member Functions

- `template<typename GridType > void init (GridDimensions dimensions, GridType *grid)`
- `bool add (boost::shared_ptr< T > agent)`

The documentation for this class was generated from the following file:

- `repast_hpc/GridComponents.h`

## 4.114 `repast::SingleOccupancy< T, GPType >` Class Template Reference

Single Occupancy cell accessor for accessing the occupants of locations in a [Grid](#).

```
#include <SingleOccupancy.h>
```

### Public Member Functions

- `T * get (const Point< GPType > &location) const`  
*Gets the object found at the specified location.*
- `void getAll (const Point< GPType > &location, std::vector< T * > &out) const`  
*Gets the item found at the specified location.*
- `bool put (boost::shared_ptr< T > &agent, const Point< GPType > &location)`  
*Puts the specified item at the specified location.*
- `void remove (boost::shared_ptr< T > &agent, const Point< GPType > &location)`  
*Removes the specified item from the specified location.*

### 4.114.1 Detailed Description

```
template<typename T, typename GPType>class repast::SingleOccupancy< T, GPType >
```

Single Occupancy cell accessor for accessing the occupants of locations in a [Grid](#).

Each locations can have only a single occupant.

#### Parameters

<i>T</i>	the type of object in the <a href="#">Grid</a>
<i>GPType</i>	the coordinate type of the grid point locations. This must be an int or a double.

#### 4.114.2 Member Function Documentation

4.114.2.1 `template<typename T , typename GPType > T * repast::SingleOccupancy< T, GPType >::get ( const Point< GPType > & location ) const`

Gets the object found at the specified location.

## Parameters

<i>location</i>	the location to get the object at
-----------------	-----------------------------------

## Returns

the first object found at the specified location or 0 if there are no objects at the specified location.

4.114.2.2 `template<typename T , typename GType > void repast::SingleOccupancy< T, GType >::getAll ( const Point< GType > & location, std::vector< T * > & out ) const`

Gets the item found at the specified location.

## Parameters

	<i>location</i>	the location to get the item at
out	<i>the</i>	found item will be returned in this vector

4.114.2.3 `template<typename T , typename GType > bool repast::SingleOccupancy< T, GType >::put ( boost::shared_ptr< T > & agent, const Point< GType > & location )`

Puts the specified item at the specified location.

## Parameters

<i>agent</i>	the item to put
<i>location</i>	the location to put the item at

4.114.2.4 `template<typename T , typename GType > void repast::SingleOccupancy< T, GType >::remove ( boost::shared_ptr< T > & agent, const Point< GType > & location )`

Removes the specified item from the specified location.

## Parameters

<i>agent</i>	the item to remove
<i>location</i>	the location to remove the item from

The documentation for this class was generated from the following file:

- repast\_hpc/SingleOccupancy.h

## 4.115 repast::Spaces< T > Struct Template Reference

## Public Types

- typedef [BaseGrid](#)< T, [SingleOccupancy](#)< T, int > , [StrictBorders](#), [SimpleAdder](#)< T >, int > **SingleStrictDiscreteSpace**
- typedef [BaseGrid](#)< T, [SingleOccupancy](#)< T, int > , [WrapAroundBorders](#), [SimpleAdder](#)< T >, int > **SingleWrappedDiscreteSpace**



- typedef [BaseGrid](#)< T, [MultipleOccupancy](#)< T, int >, [StrictBorders](#), [SimpleAdder](#)< T >, int > **MultipleStrictDiscreteSpace**
- typedef [BaseGrid](#)< T, [MultipleOccupancy](#)< T, int >, [WrapAroundBorders](#), [SimpleAdder](#)< T >, int > **MultipleWrappedDiscreteSpace**
- typedef [BaseGrid](#)< T, [SingleOccupancy](#)< T, double >, [StrictBorders](#), [SimpleAdder](#)< T >, double > **SingleStrictContinuousSpace**
- typedef [BaseGrid](#)< T, [SingleOccupancy](#)< T, double >, [WrapAroundBorders](#), [SimpleAdder](#)< T >, double > **SingleWrappedContinuousSpace**
- typedef [BaseGrid](#)< T, [MultipleOccupancy](#)< T, double >, [StrictBorders](#), [SimpleAdder](#)< T >, double > **MultipleStrictContinuousSpace**
- typedef [BaseGrid](#)< T, [MultipleOccupancy](#)< T, double >, [WrapAroundBorders](#), [SimpleAdder](#)< T >, double > **MultipleWrappedContinuousSpace**

The documentation for this struct was generated from the following file:

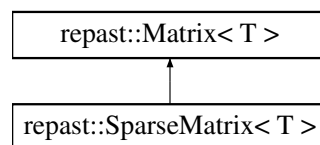
- repast\_hpc/Spaces.h

## 4.116 repast::SparseMatrix< T > Class Template Reference

A sparse matrix implementation that stores values in a map.

```
#include <matrix.h>
```

Inheritance diagram for repast::SparseMatrix< T >:



### Public Member Functions

- **SparseMatrix** (const [SparseMatrix](#)< T > &)
- [SparseMatrix](#)< T > & **operator=** (const [SparseMatrix](#)< T > &)
- [SparseMatrix](#) (const [Point](#)< int > &size, const T &defValue=T())  
Creates a [DenseMatrix](#) of the specified shape and default value.
- T & [get](#) (const [Point](#)< int > &index)  
Gets the value at the specified index.
- void [set](#) (const T &value, const [Point](#)< int > &index)  
Sets the value at the specified index.

## Additional Inherited Members

### 4.116.1 Detailed Description

```
template<typename T>class repast::SparseMatrix< T >
```

A sparse matrix implementation that stores values in a map.

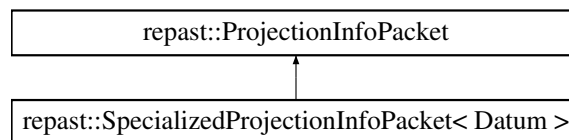
This should be used when the majority of the matrix cells contain the default value.

The documentation for this class was generated from the following file:

- repast\_hpc/matrix.h

### 4.117 repast::SpecializedProjectionInfoPacket< Datum > Class Template Reference

Inheritance diagram for repast::SpecializedProjectionInfoPacket< Datum >:



## Public Member Functions

- **SpecializedProjectionInfoPacket** ([AgentId](#) agentId)
- **SpecializedProjectionInfoPacket** ([AgentId](#) agentId, std::vector< Datum > projectionData)
- **SpecializedProjectionInfoPacket** ([AgentId](#) agentId, std::set< Datum > projectionData)
- template<class Archive >  
void **serialize** (Archive &ar, const unsigned int version)
- virtual bool **isEmpty** ()

## Public Attributes

- std::vector< Datum > **data**

## Friends

- class **boost::serialization::access**

The documentation for this class was generated from the following file:

- repast\_hpc/Projection.h

### 4.118 SRManager Class Reference

Coordinates send and receive between processes by notifying processes to expect a send from X other processes.

```
#include <SRManager.h>
```

## Public Member Functions

- [SRManager](#) (boost::mpi::communicator \*comm)  
Creates an [SRManager](#) that uses the specified communicator.
- [SRManager](#) (boost::mpi::communicator \*comm, int \*toSend, int \*toRecv)  
Creates an [SRManager](#) that uses the specified communicator, using the user-specified arrays instead of its internal arrays.
- void [mark](#) (int pos)  
Marks the position in the array as 'true' (sets to one).
- void [setVal](#) (int pos, int val)  
Sets the value at the given index in the array.
- void [clear](#) ()  
Clears the send and receive arrays (sets all values to 0).
- void [retrieveSources](#) ()  
Performs the actual send operation, populating the receive array with values from the other processes' send arrays.
- void [retrieveSources](#) (std::vector< int > &sources)  
Performs the send operation and populates the vector passed with values representing all elements in the array that have non-zero values after the receive.
- void [retrieveSources](#) (const std::vector< int > &targets, std::vector< int > &sources, int tag=0)  
Populates the send array based on the values listed in the 'targets' vector (which should be a list of process IDs to which this processer will send information) then performs the send operation, then populates the vector passed with values representing all elements in the receive array that have non-zero values after the receive.

### 4.118.1 Detailed Description

Coordinates send and receive between processes by notifying processes to expect a send from X other processes.

### 4.118.2 Constructor & Destructor Documentation

#### 4.118.2.1 SRManager::SRManager ( boost::mpi::communicator \* comm )

Creates an [SRManager](#) that uses the specified communicator.

Parameters

<i>comm</i>	the communicator to use
-------------	-------------------------

#### 4.118.2.2 SRManager::SRManager ( boost::mpi::communicator \* comm, int \* toSend, int \* toRecv )

Creates an [SRManager](#) that uses the specified communicator, using the user-specified arrays instead of its internal arrays.

The ability to use external arrays is a convenience for conditions in which it is useful to maintain the array of values for other purposes but exchange them using the [SRManager](#).

Parameters

<i>comm</i>	the communicator to use
<i>toSend</i>	the array to be used as the send array
<i>toRecv</i>	the array to be used as the receive array If the pointer passed for the receive array is null, an internal array will be used. This is to provide for situations in which the user wishes to maintain the send array but not the receive array.

### 4.118.3 Member Function Documentation

#### 4.118.3.1 void SRManager::mark ( int *pos* )

Marks the position in the array as 'true' (sets to one).

## Parameters

<i>pos</i>	the position in the array to be set, AKA the processor to which information will be sent.
------------	---

4.118.3.2 void SRManager::retrieveSources ( std::vector< int > & *sources* )

Performs the send operation and populates the vector passed with values representing all elements in the array that have non-zero values after the receive.

## Parameters

<i>sources</i>	vector that will have a list of all processes that sent non-zero values to this one
----------------	---

4.118.3.3 void SRManager::retrieveSources ( const std::vector< int > & *targets*, std::vector< int > & *sources*, int *tag* = 0 )

Populates the send array based on the values listed in the 'targets' vector (which should be a list of process IDs to which this processor will send information) then performs the send operation, then populates the vector passed with values representing all elements in the receive array that have non-zero values after the receive.

## Parameters

<i>targets</i>	vector of integers representing process to which this one intends to send information
<i>sources</i>	vector that will be populated with list of integers representing processes that will send this process information optional parameter, now obsolete (included for backward compatibility with boost-based <a href="#">SRManager</a> prior to 2.0 release.

4.118.3.4 void SRManager::setVal ( int *pos*, int *val* )

Sets the value at the given index in the array.

Note: Does not perform error checking; user should ensure that index value is valid.

## Parameters

<i>pos</i>	index value for position in array to be set
<i>val</i>	value to which the array element should be set

The documentation for this class was generated from the following files:

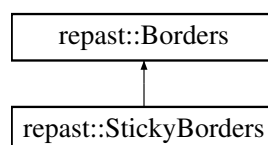
- repast\_hpc/SRManager.h
- repast\_hpc/SRManager.cpp

## 4.119 repast::StickyBorders Class Reference

Implements sticky border semantics: translates out side of the border are clamped to the border coordinates.

```
#include <GridComponents.h>
```

Inheritance diagram for repast::StickyBorders:



## Public Member Functions

- **StickyBorders** ([GridDimensions](#) d)
- void **translate** (const std::vector< double > &oldPos, std::vector< double > &newPos, const std::vector< double > &displacement) const
- void **translate** (const std::vector< int > &oldPos, std::vector< int > &newPos, const std::vector< int > &displacement) const

## Additional Inherited Members

### 4.119.1 Detailed Description

Implements sticky border semantics: translates out side of the border are clamped to the border coordinates.

Tranforms outside the border throw an exception.

The documentation for this class was generated from the following files:

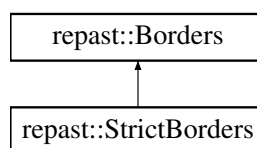
- repast\_hpc/GridComponents.h
- repast\_hpc/GridComponents.cpp

## 4.120 repast::StrictBorders Class Reference

Implements strict grid border semantics: anything outside the dimensions is out of bounds.

```
#include <GridComponents.h>
```

Inheritance diagram for repast::StrictBorders:



## Public Member Functions

- **StrictBorders** ([GridDimensions](#) d)
- void **translate** (const std::vector< double > &oldPos, std::vector< double > &newPos, const std::vector< double > &displacement) const
- void **translate** (const std::vector< int > &oldPos, std::vector< int > &newPos, const std::vector< int > &displacement) const

## Additional Inherited Members

### 4.120.1 Detailed Description

Implements strict grid border semantics: anything outside the dimensions is out of bounds.

The documentation for this class was generated from the following files:

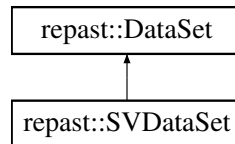
- repast\_hpc/GridComponents.h
- repast\_hpc/GridComponents.cpp

## 4.121 repast::SVDataSet Class Reference

Encapsualtes data recording to a single plain text file, separating the recorded values using a specified separator value.

```
#include <SVDataSet.h>
```

Inheritance diagram for repast::SVDataSet:



### Public Member Functions

- void [record](#) ()  
*Records data from any added data sources.*
- void [write](#) ()  
*Writes any recorded data to a file.*
- void [close](#) ()  
*Closes the data set.*

### Friends

- class **SVDataSetBuilder**

#### 4.121.1 Detailed Description

Encapsualtes data recording to a single plain text file, separating the recorded values using a specified separator value.

An [SVDataSet](#) uses rank 0 to write to a single file from multiple pan-process data sources. A [SVDataSet](#) should be built using a [SVDataSetBuilder](#).

The documentation for this class was generated from the following files:

- repast\_hpc/SVDataSet.h
- repast\_hpc/SVDataSet.cpp

## 4.122 repast::SVDataSetBuilder Class Reference

Used to build SVDataSets to record data in plain text tabular format.

```
#include <SVDataSetBuilder.h>
```

### Public Member Functions

- [SVDataSetBuilder](#) (const std::string &file, const std::string &separator, const [Schedule](#) &schedule)  
*Creates a [SVDataSetBuilder](#) that will create a [SVDataSet](#) that will write to the specified file and use the specified string as a data value separator.*
- [SVDataSetBuilder](#) & [addDataSource](#) ([SVDataSource](#) \*source)

Adds a DataSource to the DataSet produced by this builder.

- [SVDataset](#) \* createDataSet ( )

Creates the DataSource defined by this builder.

#### 4.122.1 Detailed Description

Used to build SVDatasets to record data in plain text tabular format.

Steps for use are:

1. Create a [SVDatasetBuilder](#).
2. Add SVDatasources to the builder using the createSVDatasource functions. Each data source defines a column in the output and where the data for that column will be retrieved. Recording data on the [SVDataset](#) produced by the builder will record this data for each column.
3. Call createDataSet to create the [SVDataset](#).
4. [Schedule](#) calls to record and write on the [SVDataset](#).

#### 4.122.2 Constructor & Destructor Documentation

##### 4.122.2.1 `repast::SVDatasetBuilder::SVDatasetBuilder ( const std::string & file, const std::string & separator, const Schedule & schedule )`

Creates a [SVDatasetBuilder](#) that will create a [SVDataset](#) that will write to the specified file and use the specified string as a data value separator.

Tick info will be gathered from the specified schedule.

Parameters

<i>file</i>	the file path where the data will be recorded to
<i>separator</i>	a string used to separate the data values (e.g. a ",").

#### 4.122.3 Member Function Documentation

##### 4.122.3.1 `SVDatasetBuilder & repast::SVDatasetBuilder::addDataSource ( SVDatasource * source )`

Adds a DataSource to the DataSet produced by this builder.

The createDataSource functions can be used to create Data Sources. Each data source defines a column in the output and where the data for that column will be retrieved. Recording data on the [SVDataset](#) produced by the builder will record this data for each column.

Parameters

<i>source</i>	the data source to add
---------------	------------------------

##### 4.122.3.2 `SVDataset * repast::SVDatasetBuilder::createDataSet ( )`

Creates the DataSource defined by this builder.

This can only be called once. The caller is responsible for properly deleting the returned pointer.

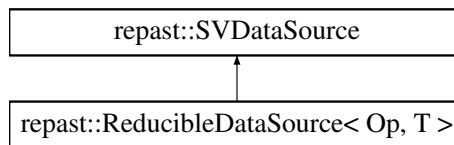
The documentation for this class was generated from the following files:

- `repast_hpc/SVDatasetBuilder.h`
- `repast_hpc/SVDatasetBuilder.cpp`



## 4.123 repast::SVDataSource Class Reference

Inheritance diagram for repast::SVDataSource:



### Public Types

- enum **DataType** { **INT**, **DOUBLE** }

### Public Member Functions

- **SVDataSource** (const std::string &name)
- virtual void **record** ()=0
- virtual void **write** (Variable \*var)=0
- virtual DataType **type** () const =0
- const std::string **name** () const

### Protected Attributes

- std::string **\_name**

The documentation for this class was generated from the following file:

- repast\_hpc/SVDataSource.h

## 4.124 repast::SyncStatus\_Packet< Content > Class Template Reference

### Public Member Functions

- **SyncStatus\_Packet** (std::vector< Content > \*agentContent, std::map< std::string, std::vector< ProjectionInfoPacket \* > > \*projectionInfo, std::set< AgentId > \*secondaryIds, AgentExporterInfo \*exporterInfo)
- **SyncStatus\_Packet** \* **deleteExporterInfo** ()  
*This is a very odd construction; it arises because the Packet must delete the exporter info on the process to which it has been sent, but it cannot delete the exporter info on the process from which it was sent.*
- template<class Archive >  
void **serialize** (Archive &ar, const unsigned int version)

### Public Attributes

- std::vector< Content > \* **agentContentPtr**
- std::map< std::string, std::vector< ProjectionInfoPacket \* > > \* **projectionInfoPtr**
- std::set< AgentId > \* **secondaryIdsPtr**
- AgentExporterInfo \* **exporterInfoPtr**

## Friends

- class **boost::serialization::access**

### 4.124.1 Member Function Documentation

4.124.1.1 `template<typename Content> SyncStatus_Packet* repast::SyncStatus_Packet< Content >::deleteExporterInfo ( ) [inline]`

This is a very odd construction; it arises because the Packet *must* delete the exporter info on the process to which it has been sent, but it *cannot* delete the exporter info on the process from which it was sent.

The solution is to call this function manually on the receiving process, but not call it on the sending proc. The pointer returned allows the abbreviation:

```
delete instance.deleteExporterInfo();
```

The documentation for this class was generated from the following file:

- repast\_hpc/RepastProcess.h

## 4.125 repast::TDataSource< T > Class Template Reference

Interface for class that act as datasoures for DataSets.

```
#include <TDataSource.h>
```

### Public Member Functions

- virtual T [getData](#) ()=0  
*Gets the data.*

### 4.125.1 Detailed Description

```
template<typename T>class repast::TDataSource< T >
```

Interface for class that act as datasoures for DataSets.

Template Parameters

<i>T</i>	the type of the data
----------	----------------------

### 4.125.2 Member Function Documentation

4.125.2.1 `template<typename T> virtual T repast::TDataSource< T >::getData ( ) [pure virtual]`

Gets the data.

Returns

the current data.

The documentation for this class was generated from the following file:

- repast\_hpc/TDataSource.h

## 4.126 repast::Timer Class Reference

Simple timing class.

```
#include <Utilities.h>
```

### Public Member Functions

- void [start](#) ()  
*Starts the timer.*
- long double [stop](#) ()  
*Stops the timer and returns the number of milliseconds elapsed since calling [start\(\)](#).*

#### 4.126.1 Detailed Description

Simple timing class.

Calling [start\(\)](#) starts the timer, calling [stop](#) returns the milliseconds since calling start.

#### 4.126.2 Member Function Documentation

##### 4.126.2.1 long double repast::Timer::stop ( )

Stops the timer and returns the number of milliseconds elapsed since calling [start\(\)](#).

Returns

the number of milliseconds elapsed since calling [start\(\)](#).

The documentation for this class was generated from the following files:

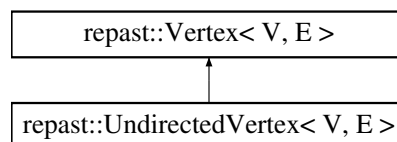
- repast\_hpc/Utilities.h
- repast\_hpc/Utilities.cpp

## 4.127 repast::UndirectedVertex< V, E > Class Template Reference

NON USER API.

```
#include <UndirectedVertex.h>
```

Inheritance diagram for repast::UndirectedVertex< V, E >:



### Public Member Functions

- **UndirectedVertex** (boost::shared\_ptr< V > [item](#))
- virtual boost::shared\_ptr< E > [removeEdge](#) ([Vertex](#)< V, E > \*other, [EdgeType](#) type)  
*Removes the edge of the specified type between this [Vertex](#) and the specified [Vertex](#).*

- virtual `boost::shared_ptr< E > findEdge (Vertex< V, E > *other, EdgeType type)`  
*Finds the edge of the specified type between this [Vertex](#) and the specified vertex.*
- virtual void `addEdge (Vertex< V, E > *other, boost::shared_ptr< E > edge, EdgeType type)`  
*Adds an edge of the specified type between this [Vertex](#) and the specified vertex.*
- virtual void `successors (std::vector< V * > &out)`  
*Gets the successors of this [Vertex](#).*
- virtual void `predecessors (std::vector< V * > &out)`  
*Gets the predecessors of this [Vertex](#).*
- virtual void `adjacent (std::vector< V * > &out)`  
*Gets the Vertices adjacent to this [Vertex](#).*
- virtual void `edges (EdgeType type, std::vector< boost::shared_ptr< E > > &out)`  
*Gets all the edges of the specified type in which this [Vertex](#) participates and return them in out.*
- int `inDegree ()`  
*Gets the in degree of this [Vertex](#).*
- int `outDegree ()`  
*Gets the out degree of this [Vertex](#).*

#### 4.127.1 Detailed Description

`template<typename V, typename E>class repast::UndirectedVertex< V, E >`

NON USER API.

A vertex in an undirected network.

Template Parameters

<code>V</code>	the vertex type
<code>E</code>	the edge type. The edge type must be or extend <a href="#">RepastEdge</a> .

#### 4.127.2 Member Function Documentation

4.127.2.1 `template<typename V , typename E > void repast::UndirectedVertex< V, E >::addEdge ( Vertex< V, E > * other, boost::shared_ptr< E > edge, EdgeType type ) [virtual]`

Adds an edge of the specified type between this [Vertex](#) and the specified vertex.

Parameters

<code>edge</code>	the edge to add
<code>other</code>	the other end of the edge
<code>type</code>	the type of edge to add

Implements [repast::Vertex< V, E >](#).

4.127.2.2 `template<typename V , typename E > void repast::UndirectedVertex< V, E >::adjacent ( std::vector< V * > & out ) [virtual]`

Gets the Vertices adjacent to this [Vertex](#).

Parameters

<code>out</code>	<i>the</i>	vector where the adjacent vectors will be put
------------------	------------	---

Implements [repast::Vertex< V, E >](#).

4.127.2.3 `template<typename V , typename E > void repast::UndirectedVertex< V, E >::edges ( EdgeType type, std::vector< boost::shared_ptr< E > > & out ) [virtual]`

Gets all the edges of the specified type in which this [Vertex](#) participates and return them in out.

## Parameters

	<i>type</i>	the type of edges to get
out	<i>where</i>	the edges will be put.

Implements [repast::Vertex< V, E >](#).

4.127.2.4 `template<typename V , typename E > boost::shared_ptr< E > repast::UndirectedVertex< V, E >::findEdge ( Vertex< V, E > * other, EdgeType type ) [virtual]`

Finds the edge of the specified type between this [Vertex](#) and the specified vertex.

## Parameters

<i>other</i>	the other end of the edge
<i>type</i>	the type of edge to remove

## Returns

the found edge, or 0.

Implements [repast::Vertex< V, E >](#).

4.127.2.5 `template<typename V , typename E > int repast::UndirectedVertex< V, E >::inDegree ( ) [virtual]`

Gets the in degree of this [Vertex](#).

## Returns

the in degree of this [Vertex](#).

Implements [repast::Vertex< V, E >](#).

4.127.2.6 `template<typename V , typename E > int repast::UndirectedVertex< V, E >::outDegree ( ) [virtual]`

Gets the out degree of this [Vertex](#).

## Returns

the out degree of this [Vertex](#).

Implements [repast::Vertex< V, E >](#).

4.127.2.7 `template<typename V , typename E > void repast::UndirectedVertex< V, E >::predecessors ( std::vector< V * > & out ) [virtual]`

Gets the predecessors of this [Vertex](#).

## Parameters

out	<i>the</i>	vector where any predecessors will be put
-----	------------	---

Implements [repast::Vertex< V, E >](#).

4.127.2.8 `template<typename V , typename E > boost::shared_ptr< E > repast::UndirectedVertex< V, E >::removeEdge ( Vertex< V, E > * other, EdgeType type ) [virtual]`

Removes the edge of the specified type between this [Vertex](#) and the specified [Vertex](#).

## Parameters

<i>other</i>	the other end of the edge
<i>type</i>	the type of edge to remove

## Returns

the removed edge if such an edge was found, otherwise 0.

Implements [repast::Vertex< V, E >](#).

4.127.2.9 `template<typename V, typename E> void repast::UndirectedVertex< V, E >::successors ( std::vector< V * > & out ) [virtual]`

Gets the successors of this [Vertex](#).

## Parameters

<i>out</i>	<i>the</i>	vector where any successors will be put
------------	------------	---

Implements [repast::Vertex< V, E >](#).

The documentation for this class was generated from the following file:

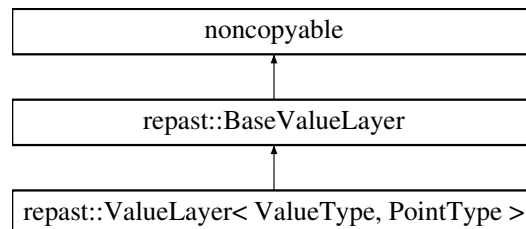
- repast\_hpc/UndirectedVertex.h

## 4.128 repast::ValueLayer< ValueType, PointType > Class Template Reference

A collection that stores values at point locations.

```
#include <ValueLayer.h>
```

Inheritance diagram for repast::ValueLayer< ValueType, PointType >:



### Public Member Functions

- **ValueLayer** (const std::string &name, const [GridDimensions](#) &dimensions)
- virtual ValueType & [get](#) (const [Point](#)< PointType > &pt)=0  
*Gets the value at the specified point.*
- virtual void [set](#) (const ValueType &value, const [Point](#)< PointType > &pt)=0  
*Sets the value at the specified point.*
- ValueType & [operator\[\]](#) (const [Point](#)< PointType > &pt)  
*Gets the value at the specified point.*
- const ValueType & [operator\[\]](#) (const [Point](#)< PointType > &pt) const  
*Gets the value at the specified point.*
- const [GridDimensions](#) dimensions () const  
*Gets the dimensions of this ValueLayer.*
- const [Point](#)< int > [shape](#) () const  
*Gets the extents of this ValueLayer.*

## Protected Member Functions

- void [translate](#) (std::vector< [PointType](#) > &pt)  
*Translates pt by dimensions origin.*

## Protected Attributes

- [GridDimensions](#) \_dimensions

### 4.128.1 Detailed Description

template<typename [ValueType](#), typename [PointType](#)>class [repast::ValueLayer](#)< [ValueType](#), [PointType](#) >

A collection that stores values at point locations.

Template Parameters

<i>ValueType</i>	the type stored by the value layer.
<i>the</i>	coordinate type (int or double) of the point locations.

### 4.128.2 Member Function Documentation

4.128.2.1 template<typename [ValueType](#), typename [PointType](#)> const [GridDimensions](#) [repast::ValueLayer](#)< [ValueType](#), [PointType](#) >::dimensions ( ) const [inline]

Gets the dimensions of this [ValueLayer](#).

Returns

the dimensions of this [ValueLayer](#).

4.128.2.2 template<typename [ValueType](#), typename [PointType](#)> virtual [ValueType](#)& [repast::ValueLayer](#)< [ValueType](#), [PointType](#) >::get ( const [Point](#)< [PointType](#) > & *pt* ) [pure virtual]

Gets the value at the specified point.

If no value has been set at the specified point then this returns some default value. Subclasses will determine the default value.

param pt the location to get the value of

Returns

the value at the specified point, or if no value has been set, then some default value.

Implemented in [repast::ContinuousValueLayer](#)< [ValueType](#), [Borders](#) >, and [repast::DiscreteValueLayer](#)< [ValueType](#), [Borders](#) >.

4.128.2.3 template<typename [ValueType](#) , typename [PointType](#)> [ValueType](#) & [repast::ValueLayer](#)< [ValueType](#), [PointType](#) >::operator[] ( const [Point](#)< [PointType](#) > & *pt* )

Gets the value at the specified point.

If no value has been set at the specified point then this returns some default value. Subclasses will determine the default value.

param pt the location to get the value of



## Returns

the value at the specified point, or if no value has been set, then some default value.

4.128.2.4 `template<typename ValueType , typename PointType> const ValueType & repast::ValueLayer< ValueType, PointType >::operator[] ( const Point< PointType > & pt ) const`

Gets the value at the specified point.

If no value has been set at the specified point then this returns some default value. Subclasses will determine the default value.

param `pt` the location to get the value of

## Returns

the value at the specified point, or if no value has been set, then some default value.

4.128.2.5 `template<typename ValueType, typename PointType> virtual void repast::ValueLayer< ValueType, PointType >::set ( const ValueType & value, const Point< PointType > & pt ) [pure virtual]`

Sets the value at the specified point.

## Parameters

<i>value</i>	the value
<i>pt</i>	the point where the value should be stored

Implemented in [repast::ContinuousValueLayer< ValueType, Borders >](#), and [repast::DiscreteValueLayer< ValueType, Borders >](#).

4.128.2.6 `template<typename ValueType, typename PointType> const Point<int> repast::ValueLayer< ValueType, PointType >::shape ( ) const [inline]`

Gets the extents of this [ValueLayer](#).

## Returns

the extents of this [ValueLayer](#).

The documentation for this class was generated from the following file:

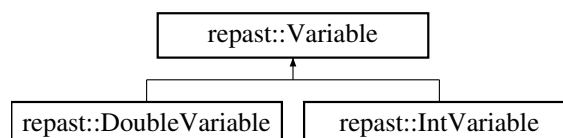
- `repast_hpc/ValueLayer.h`

## 4.129 `repast::Variable` Class Reference

NON USER API.

```
#include <Variable.h>
```

Inheritance diagram for `repast::Variable`:



## Public Member Functions

- virtual void [write](#) (size\_t index, std::ofstream &out)=0  
*Writes the data at the specified index to the specified ofstream.*
- virtual void [insert](#) (double \*array, size\_t size)=0  
*Insertes all the doubles in the double array into the collection of data stored in this [Variable](#).*
- virtual void [insert](#) (int \*array, size\_t size)=0  
*Insertes all the ints in the int array into the collection of data stored in this [Variable](#).*
- virtual void [clear](#) ()=0  
*Clears this [Variable](#) of all the data stored in it.*

### 4.129.1 Detailed Description

NON USER API.

Used in [SVDDataSet](#) to manage and store the data.

### 4.129.2 Member Function Documentation

#### 4.129.2.1 virtual void repast::Variable::insert ( double \* array, size\_t size ) [pure virtual]

Insertes all the doubles in the double array into the collection of data stored in this [Variable](#).

Parameters

<i>array</i>	the array to insert
<i>size</i>	the size of the array

Implemented in [repast::DoubleVariable](#), and [repast::IntVariable](#).

#### 4.129.2.2 virtual void repast::Variable::insert ( int \* array, size\_t size ) [pure virtual]

Insertes all the ints in the int array into the collection of data stored in this [Variable](#).

Parameters

<i>array</i>	the array to insert
<i>size</i>	the size of the array

Implemented in [repast::DoubleVariable](#), and [repast::IntVariable](#).

#### 4.129.2.3 virtual void repast::Variable::write ( size\_t index, std::ofstream & out ) [pure virtual]

Writes the data at the specified index to the specified ofstream.

Parameters

<i>index</i>	the index of the data to write
<i>out</i>	the ofstream to write the data to

Implemented in [repast::DoubleVariable](#), and [repast::IntVariable](#).

The documentation for this class was generated from the following file:

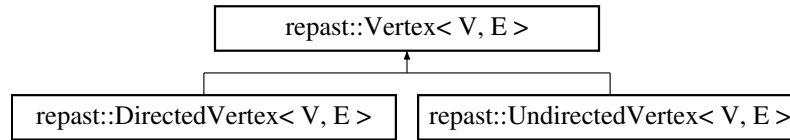
- [repast\\_hpc/Variable.h](#)

## 4.130 repast::Vertex< V, E > Class Template Reference

Used internally by repast graphs / networks to encapsulate Vertices.

```
#include <Vertex.h>
```

Inheritance diagram for repast::Vertex< V, E >:



### Public Types

- enum [EdgeType](#) { **INCOMING**, **OUTGOING** }  
*Enum that identifies whether an edge is incoming or outgoing.*
- typedef boost::unordered\_map  
  < [Vertex](#)< V, E >  
  \*, boost::shared\_ptr< E >  
  , [HashVertex](#)< V, E > > [AdjListMap](#)  
*Typedef for the adjacency list map that contains the other Vertices that this [Vertex](#) links to.*
- typedef AdjListMap::iterator **AdjListMapIterator**

### Public Member Functions

- [Vertex](#) (boost::shared\_ptr< V > [item](#))  
*Creates a [Vertex](#) that contains the specified item.*
- virtual boost::shared\_ptr< E > [removeEdge](#) ([Vertex](#) \*other, [EdgeType](#) type)=0  
*Removes the edge of the specified type between this [Vertex](#) and the specified [Vertex](#).*
- virtual boost::shared\_ptr< E > [findEdge](#) ([Vertex](#) \*other, [EdgeType](#) type)=0  
*Finds the edge of the specified type between this [Vertex](#) and the specified vertex.*
- virtual void [addEdge](#) ([Vertex](#)< V, E > \*other, boost::shared\_ptr< E > edge, [EdgeType](#) type)=0  
*Adds an edge of the specified type between this [Vertex](#) and the specified vertex.*
- virtual void [successors](#) (std::vector< V \* > &out)=0  
*Gets the successors of this [Vertex](#).*
- virtual void [predecessors](#) (std::vector< V \* > &out)=0  
*Gets the predecessors of this [Vertex](#).*
- virtual void [adjacent](#) (std::vector< V \* > &out)=0  
*Gets the Vertices adjacent to this [Vertex](#).*
- virtual void [edges](#) ([EdgeType](#) type, std::vector< boost::shared\_ptr< E > > &out)=0  
*Gets all the edges of the specified type in which this [Vertex](#) participates and return them in out.*
- virtual int [inDegree](#) ()=0  
*Gets the in degree of this [Vertex](#).*
- virtual int [outDegree](#) ()=0  
*Gets the out degree of this [Vertex](#).*
- boost::shared\_ptr< V > [item](#) () const  
*Gets the item that this [Vertex](#) contains.*

## Protected Member Functions

- `boost::shared_ptr< E > removeEdge (Vertex< V, E > *other, AdjListMap *adjMap)`
- `void getItems (AdjListMap *adjMap, std::vector< V * > &out)`
- `void edges (AdjListMap *adjMap, std::vector< boost::shared_ptr< E > > &out)`

## Protected Attributes

- `boost::shared_ptr< V > ptr`

## Friends

- `struct NodeGetter< V, E >`

### 4.130.1 Detailed Description

`template<typename V, typename E>class repast::Vertex< V, E >`

Used internally by repast graphs / networks to encapsulate Vertices.

#### Template Parameters

<i>V</i>	the type of object stored by in a <a href="#">Vertex</a> .
<i>E</i>	the edge type of the network.

### 4.130.2 Constructor & Destructor Documentation

4.130.2.1 `template<typename V, typename E > repast::Vertex< V, E >::Vertex ( boost::shared_ptr< V > item )`

Creates a [Vertex](#) that contains the specified item.

#### Parameters

<i>item</i>	the item the <a href="#">Vertex</a> should contain
-------------	--

### 4.130.3 Member Function Documentation

4.130.3.1 `template<typename V, typename E> virtual void repast::Vertex< V, E >::addEdge ( Vertex< V, E > * other, boost::shared_ptr< E > edge, EdgeType type ) [pure virtual]`

Adds an edge of the specified type between this [Vertex](#) and the specified vertex.

#### Parameters

<i>edge</i>	the edge to add
<i>other</i>	the other end of the edge
<i>type</i>	the type of edge to add

Implemented in `repast::DirectedVertex< V, E >`, and `repast::UndirectedVertex< V, E >`.

4.130.3.2 `template<typename V, typename E> virtual void repast::Vertex< V, E >::adjacent ( std::vector< V * > & out ) [pure virtual]`

Gets the Vertices adjacent to this [Vertex](#).

## Parameters

out	the	vector where the adjacent vectors will be put
-----	-----	---

Implemented in [repast::DirectedVertex< V, E >](#), and [repast::UndirectedVertex< V, E >](#).

**4.130.3.3** `template<typename V, typename E> virtual void repast::Vertex< V, E >::edges ( EdgeType type, std::vector< boost::shared_ptr< E > > & out ) [pure virtual]`

Gets all the edges of the specified type in which this [Vertex](#) participates and return them in out.

## Parameters

	type	the type of edges to get
out	where	the edges will be put.

Implemented in [repast::DirectedVertex< V, E >](#), and [repast::UndirectedVertex< V, E >](#).

**4.130.3.4** `template<typename V, typename E> virtual boost::shared_ptr<E> repast::Vertex< V, E >::findEdge ( Vertex< V, E > * other, EdgeType type ) [pure virtual]`

Finds the edge of the specified type between this [Vertex](#) and the specified vertex.

## Parameters

	other	the other end of the edge
	type	the type of edge to remove

## Returns

the found edge, or 0.

Implemented in [repast::DirectedVertex< V, E >](#), and [repast::UndirectedVertex< V, E >](#).

**4.130.3.5** `template<typename V, typename E> virtual int repast::Vertex< V, E >::inDegree ( ) [pure virtual]`

Gets the in degree of this [Vertex](#).

## Returns

the in degree of this [Vertex](#).

Implemented in [repast::DirectedVertex< V, E >](#), and [repast::UndirectedVertex< V, E >](#).

**4.130.3.6** `template<typename V, typename E> boost::shared_ptr<V> repast::Vertex< V, E >::item ( ) const [inline]`

Gets the item that this [Vertex](#) contains.

## Returns

the item.

**4.130.3.7** `template<typename V, typename E> virtual int repast::Vertex< V, E >::outDegree ( ) [pure virtual]`

Gets the out degree of this [Vertex](#).

**Returns**

the out degree of this [Vertex](#).

Implemented in [repast::DirectedVertex< V, E >](#), and [repast::UndirectedVertex< V, E >](#).

**4.130.3.8** `template<typename V, typename E> virtual void repast::Vertex< V, E >::predecessors ( std::vector< V * > & out ) [pure virtual]`

Gets the predecessors of this [Vertex](#).

**Parameters**

<i>out</i>	<i>the</i>	vector where any predecessors will be put
------------	------------	---

Implemented in [repast::DirectedVertex< V, E >](#), and [repast::UndirectedVertex< V, E >](#).

**4.130.3.9** `template<typename V, typename E> virtual boost::shared_ptr<E> repast::Vertex< V, E >::removeEdge ( Vertex< V, E > * other, EdgeType type ) [pure virtual]`

Removes the edge of the specified type between this [Vertex](#) and the specified [Vertex](#).

**Parameters**

<i>other</i>	the other end of the edge
<i>type</i>	the type of edge to remove

**Returns**

the removed edge if such an edge was found, otherwise 0.

Implemented in [repast::DirectedVertex< V, E >](#), and [repast::UndirectedVertex< V, E >](#).

**4.130.3.10** `template<typename V, typename E> virtual void repast::Vertex< V, E >::successors ( std::vector< V * > & out ) [pure virtual]`

Gets the successors of this [Vertex](#).

**Parameters**

<i>out</i>	<i>the</i>	vector where any successors will be put
------------	------------	---

Implemented in [repast::DirectedVertex< V, E >](#), and [repast::UndirectedVertex< V, E >](#).

The documentation for this class was generated from the following file:

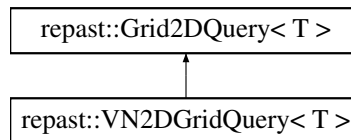
- [repast\\_hpc/Vertex.h](#)

## 4.131 [repast::VN2DGridQuery< T >](#) Class Template Reference

Neighborhood query that gathers neighbors in a Von Neumann (N, S, E, W) neighborhood.

```
#include <VN2DGridQuery.h>
```

Inheritance diagram for [repast::VN2DGridQuery< T >](#):



## Public Member Functions

- **VN2DGridQuery** (const [Grid](#)< T, int > \*grid)
- virtual void [query](#) (const [Point](#)< int > &center, int range, bool includeCenter, std::vector< T \* > &out) const  
*Queries the [Grid](#) for the Von Neumann neighbors surrounding the center point within a specified range.*

## Additional Inherited Members

### 4.131.1 Detailed Description

template<typename T>class repast::VN2DGridQuery< T >

Neighborhood query that gathers neighbors in a Von Neumann (N, S, E, W) neighborhood.

Template Parameters

<i>T</i>	the type of agents in the <a href="#">Grid</a>
----------	--

### 4.131.2 Member Function Documentation

4.131.2.1 template<typename T> void repast::VN2DGridQuery< T >::query ( const [Point](#)< int > &center, int range, bool includeCenter, std::vector< T \* > &out ) const [virtual]

Queries the [Grid](#) for the Von Neumann neighbors surrounding the center point within a specified range.

Parameters

	<i>center</i>	the center of the neighborhood
	<i>range</i>	the range of the neighborhood out from the center
	<i>includeCenter</i>	whether or not to include any agents at the center
<i>out</i>	<i>the</i>	neighboring agents will be returned in this vector

Implements [repast::Grid2DQuery< T >](#).

The documentation for this class was generated from the following file:

- repast\_hpc/VN2DGridQuery.h

## 4.132 repast::WrapAroundBorders Class Reference

Implements periodic wrap around style border semantics.

```
#include <GridComponents.h>
```

## Public Member Functions

- **WrapAroundBorders** ([GridDimensions](#) dimensions)
- void **transform** (const std::vector< int > &in, std::vector< int > &out) const

- void **transform** (const std::vector< double > &in, std::vector< double > &out) const
- void **translate** (const std::vector< double > &oldPos, std::vector< double > &newPos, const std::vector< double > &displacement) const
- void **translate** (const std::vector< int > &oldPos, std::vector< int > &newPos, const std::vector< int > &displacement) const
- void **init** (const [GridDimensions](#) &dimensions)
- bool **isPeriodic** () const

#### 4.132.1 Detailed Description

Implements periodic wrap around style border semantics.

Points that are outside the borders are wrapped until the point is inside the borders.

The documentation for this class was generated from the following files:

- repast\_hpc/GridComponents.h
- repast\_hpc/GridComponents.cpp