Programming Documentation

2496V 2023-2024

Table of Contents

1	Introduction	3
2	Goals	3
3	PID	3
4	Chassis Movement	3
5	Motion Profiling	3
6	Programming Skills	3
7	Autonomous Routines	3

Introduction 1

Hello my name is Anthony Low.

$\mathbf{2}$ Goals

Vieta's Formulas:

r+s=-b/a and rs=c/a for all quadratics $ax^2+bx+c=0$ Proof:

- 1. Quadratics are also written in the from a(x-r)(x-s)=0 2. Expanding this form gives $ax^2-a(r+s)x+ars=0$
- 3. Like terms imply:

$$1. -a(r+s) = b$$

$$r + s = -b/a$$

 $2. \ ars = c$

$$rs = c/a$$

- PID 3
- Chassis Movement 4
- **Motion Profiling** 5
- **Programming Skills** 6
- **Autonomous Routines** 7