

```
def __init__(self, vertices):
```

```
# No. of vertices
```

```
self.V = vertices
```

```
# default dictionary to store graph
```

```
self.graph = defaultdict(list)
```

```
# function to add an edge to graph
```

```
def addEdge(self, u, v):
```

```
self.graph[u].append(v)
```

```
# function to perform a Depth-Limited search
```

```
# from given source 'src'
```

```
def DLS(self, src, target, maxDepth):
```

```
if src == target: return True
```

```
# if reached the maximum depth, stop recurring
```

```
if maxDepth <= 0: return False
```

```
# recur for all the vertices adjacent to the vertex
```

```
for i in self.graph[src]:
```

```
if (self.DLS(i, target, maxDepth - 1)):
```

```
return True
```

```
return False
```

```
# 100fs to search if target is reachable from v
```

```
# it issues recursive DLS()
```

```
def 100fs(self, src, target, maxDepth):
```

```
# repeatedly depth-limit search till the # maximum depth
```

```
for i in range(maxDepth):
```

```
if (self.DLS(src, target, i)):
```

```
return True
```

```
return False
```

