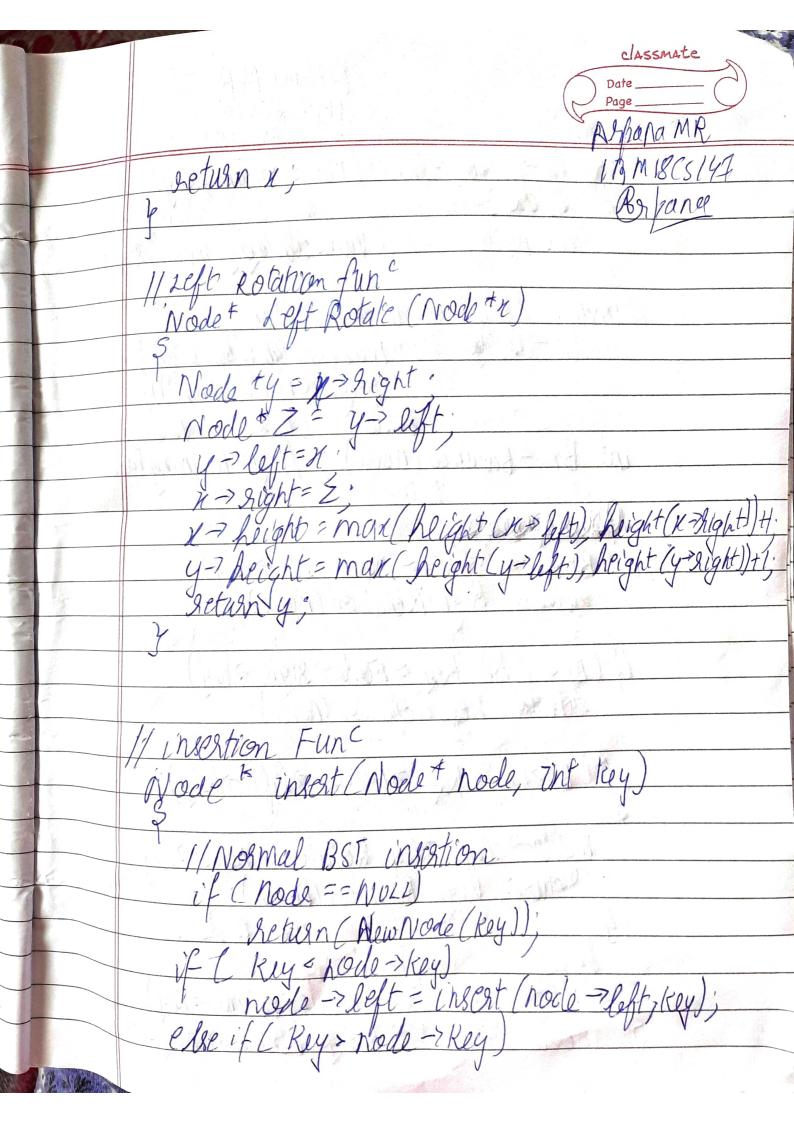
ROGRAM-04 WAP to perform inscrtion & de 1/ Node declaration ass Node Node left, hight; I function to assign new node No to the second Node \* NewNode Cint Key Node + node = new Node(); node -> key = key; node -> left = NULL; node -> high = NULL; herentdneedl -> height=1; //initially rode is not added to true getur (node)

classmate height ( Node \*N Sturn N- height to calculate Balance Factor Right Rotation fun y-> height = man heig



classmate Ahana MR Dote Page 1BMIS(SIN) che Node - night = intert (node - night, key); Retain node; I if value already present, exp it // Update Aright of ancestor node; node -> height = | t max(height (node-left), height (node-> right)); int BF = Bulance (node); // get balancing Farkor if (BF>1 2 A Kely < noclo-left->key)
seturn Right Rotation (node); if (BF<-1 DA Key > node-> sight-> key) Seturn Left Rotation (node); if (BF>1 D& Key > node > lift > key) Return Right Rotation (node); if (BF<-1 1 to Key< node= night-zkey)

5 node - Right = Right Rolation (node-night);

13 MING 1997 return Left Rotation (node); letur node; // Finding mintrallee of a tree & returning the node Node \* min Node (Nodo\* Node) Node + Cur = node; 11 find minimum node while (call - left 1=NULL) cush = curr - left; setur cush; 11 Ocletion Fun C Node\* delete (Node + hoest, int key) 1/Normal BST deletion if (ROST == NULL) seturn soot; 17 (Key < 900t -> Key)
800t -> lift = Resolution delete (root -> lift key)

A Alara MR 1BM18(S147 classmate clse if (key>root-> kog)

Ande-> hight = delete (node-> hight, keg); Vode \*temp = pode>left ? node>left: node>right; (temp==NDLL) temp= prode; st. 11 one thild \* node = \*temps else (1 swo children Node \* temp = min Node (hode > right); hode - right - delite (rode - right temp > 124)

classmate SharaMR BM18(5147 Corpane if (hode == NULL) Leturn nodo; node = height = 1 + max (height (node - left),
hught (node - hight)); un+ palana=Balana(nod); if (halance > (AA Balance (Mode) > left) > =0) Return Right Rolation (node); f C balance > 122 Balano (node >left < 0 \$) rode -> feft = Left Rotation (rode - left);

Letwn Right Rotation (rode); halance C-1 At Balance (node-slight) <=0 Return Left Rotation (node);

F (balance <-1 As Balance (node > hight)>0)

F Avde -> hight = Right Rotation (node - sign)

Ty Leturn LeptRolavion (node)