# **Decision Tree**

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### **Motivation**

- PCA identifies one or more orthogonal directions that capture the greatest amount of variance in a feature matrix  $X \in \mathbb{R}^{m \times n}$ .
- Assuming zero-mean feature matrix  $X \in \mathbb{R}^{m \times n}$ , the variance of the samples' projections onto aunit vector v is given by:

In light of this consideration, we define the first desired vector  $v_1$  as the solution to the constrained optimization problem:

$$\max_{\|v\|_2=1} v^t X^t X v$$

We convert this constrained optimization problem into an unconstrained one by writing down its Lagrangian:

$$\mathcal{L}(v) := v^t X^t X v - \lambda (v^t v - 1)$$

### First PC

First-order necessary conditions for optimal value imply that:

$$0 = \nabla \mathcal{L}(v_1) = 2X^t X v_1 - 2\lambda v_1$$

- Since  $X^t X v_1 = \lambda v_1$ ,  $v_1$  is an eigenvector of  $X^t X$  with eigenvalue  $\lambda$ .
- Since we constrain  $||v_1||_2^2 = v_1^t v_1 = 1$ , the value of the objective is precisely:

$$v_1^t X^t X v_1 = v_1^t (\lambda v_1) = \lambda v_1^t v_1 = \lambda$$

The optimal value is  $\lambda = \lambda_{\max}(X^t X)$ , which is achieved when  $v_1$  is a unit eigenvector of  $X^tX$  corresponding to its largest eigenvalue.



# More PCs?

- How to find more direction with the desired property?
  - ▶ Ideally, the subsequent directions found should also be directions of high variance
  - ▶ They should be orthogonal to the existing ones in order to minimize redundancy.
- We define the k-th loading vector  $v_k$  as the solution to the constrained optimization problem:

$$\max_{v} v^{t} X^{t} X v \quad \text{subject to} \quad v^{t} v = 1, v^{t} v_{i} = 0, \quad i = 1, \dots, k-1$$

- Claim:  $v_k$  is a unit eigenvector of  $X^tX$  corresponding to its k-th largest eigenvalue.
- The unit vector that defines the k-th axis is called the k-th principal component (PC).

### Evaluation of PCs

Assuming the singular value decomposition of feature matrix X as follows:

$$X = U\Sigma V^T = [u_1, u_2, \cdots, u_r][ \begin{matrix} \sigma_1 & & 0 & & v_1^T \\ & \sigma_2 & & & v_2^T \\ & & \ddots & & \end{bmatrix}[ \begin{matrix} v_1^T \\ v_2^T \\ \vdots \\ v_r^T \end{matrix}]$$

The first k PCs are  $W_k = [v_1, v_2, \cdots, v_k]$ .

- **Explained Variance Ratio** explains the proportion of the dataset's variance that lies along the axis of each PC.
- PCA can also be viewed as the projection of the sample points to the subspace with the minimum perpendicular distance.

## Other Derivation?

#### Definition

For a matrix X, operator 2-norm is defined as

$$||X||_2 = \sup \frac{||Xv||_2}{||v||_2} = \max(s_i)$$

and Frobenius norm as

$$||X||_F = \sqrt{\sum_{ij} X_{ij}^2} = \sqrt{\operatorname{tr}(X^t X)} = \sqrt{\sum \sigma_i^2}$$

where  $\sigma_i$  are singular values of X, i.e. diagonal elements of  $\Sigma$  in the singular value decomposition  $X = U\Sigma V^t$ 

## Other Derivation?

- PCA is given by the same singular value decomposition when the data are centered.
- lacksquare  $U\Sigma$  are principal components, and V are principal axes, i.e. eigenvectors of the covariance matrix.
- The reconstruction of X with only the k principal components corresponding to the k largest singular values is given by  $X_k = U_k \Sigma_k V_k^{\top}$ .
- The Eckart-Young theorem says that  $X_k$  is the matrix minimizing the norm of the reconstruction error ||X A|| among all matrices A of rank k.
- This is true for both, Frobenius norm and the operator 2-norm



Thank You!

Any Question?