Support Vector Machines

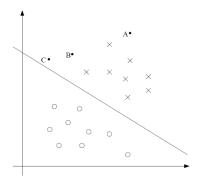
ML Instruction Team, Fall 2022

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Intuition: Margins

Separating Hyperplane



- Our confidence about the prediction of classes of A, B and C relies on their distance from decision boundary.
- We try to find the optimal hyperplane that separates the classes in the feature space.



Hyperplane

Hyperplane: A hyperplane in p dimensions is a flat affine subspace of dimension p-1:

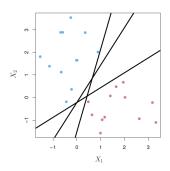
$$\beta_0+\beta_1X_1+\beta_2X_2+\ldots+\beta_pX_p=0$$

- The vector $\beta = (\beta_1, \beta_2, ..., \beta_p)$ is called the normal vector it points in a direction orthogonal to the surface of the defined hyperplane.
- If $f(X) = \beta_0 + \beta_1 X_1 + \beta_2 X_2 + \ldots + \beta_p X_p = \beta^T X + \beta_0$, then f(X) divides the p-dimensional feature space into two half-spaces (f(X) > 0 for one side and f(X) < 0 for the other side).
- So if we code $Y^{(i)} \in \{\pm 1\}$, then $\forall i$

$$Y^{(i)}f(X^{(i)})>0 \\$$



Maximal Margin Classifier



Maximal(Optimal) Separating Hyperplane: The separating hyperplane with the biggest margin between the classes.

$$\begin{aligned} \max_{\beta_0,\beta_1,...,\beta_p,\ M} & \\ \text{s.t.} \quad \sum_{j=1}^p \beta_j^2 = 1 \\ & y^{(i)}(\beta^T x^{(i)} + \beta_0) > M \quad \forall i \in \{1,2,...,N\} \end{aligned} \tag{1}$$

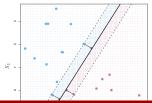
QP solvers.

- Eq.(1) can be rephrased as a convex quadratic problem and be solved efficiently using
- (Euclidean) distance between two hyperplanes

$$\mathcal{H}_1 = \{x|\beta^Tx + \beta_0 = 1\} \qquad \mathcal{H}_2 = \{x|\beta^Tx + \beta_0 = -1\}$$

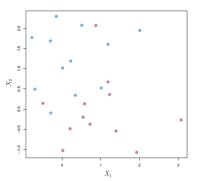
is **dist**($\mathcal{H}_1, \mathcal{H}_2$) = $2/||\beta||_2$

$$\begin{split} & \min_{\beta,\beta_0} & \frac{1}{2} ||\beta||_2^2 \\ \text{s.t.} & y^{(i)}(\beta^T x^{(i)} + \beta_0) \geq 1 \quad \forall i \in 1,2,...,N \end{split} \tag{2}$$



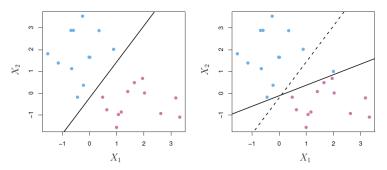
Non-linear Separable Data

In most cases however, the data are not linearly separable unless N < p.



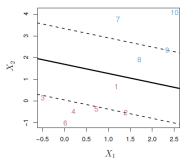
Noisy Data

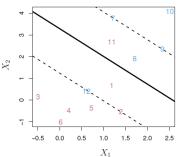
Sometimes the data are linearly separable, but noisy. This can lead to a poor solution for the maximal margin classifier. Also, hard-margin classifier is sensitive to outliers.



The *support vector classifier* maximizes a *soft* margin.

Allowing some samples to violate the margin, with slack variables, in a controlled manner.

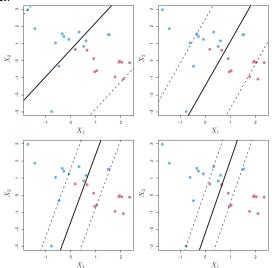




$$\begin{aligned} & \min_{\beta,\beta_0,\xi} & & \frac{1}{2} ||\beta||_2^2 + C \sum_{i=1}^N \xi_i \\ & \text{s.t.} & & y^{(i)}(\beta^T x^{(i)} + \beta_0) \geq 1 - \xi_i \\ & & & \xi_i \geq 0 \quad \forall i \in \{1,2,\dots,N\} \end{aligned} \tag{3}$$

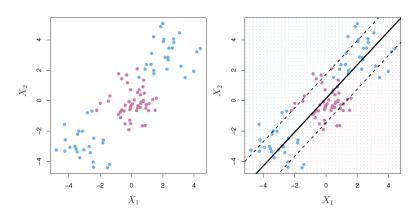
Effect of Regularization Parameter

C is a regularization parameter that controls the bias-variance trade-off of the support vector classifier.



The Need for Non-Linear Boundary

Linear boundary can fail in many cases, regardless of the value of C.



Final Notes

Thank You!

Any Question?

