

Take The L - Reinforcement Learning

Artificial Intelligence

Bachelors in Informatics and Computer Engineering

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Group 37_2.1C

Project Specification

The objective of this project is to implement a simplified version of the game Exactly One Mazes that we had developed in the previous project delivery, and create an agent that can figure out how to win the game

The objective of the game is to have the player cross from the bottom-left to the top right square, without crossing the same L shape more than one time



The Player can move in any direction, as long as the square he is in does not belong to an already visited L shape

Tools and Algorithms to be used

The assignment will make use of the following **tools**:

- **OpenAI Gym** - A framework that acts as a playground for testing agents, using controlled environments;
- **Numpy** - A library for processing data in arrays;
- **Matplotlib** and **Seaborn** - Data visualization libraries to draw plots and charts;
- **Jupyter Notebooks** - Interactive computing and development.

To teach the agent, the following **algorithms** will be employed:

- **Monte Carlo**;
- **Q-Learning** - State-action-reward-state;
- **SARSA** - State-action-reward-state-action.

Already Implemented Features

As of the first checkpoint, we have set up a simplified version of an OpenAI Gym environment where the agent will be trained.

This includes the definition of the **action space**, the **observation space**, and a simple **reward function**.

```
Loading the environment
```

```
-----  
| 0 | 0 | 0 | 0 |  
-----
```

```
| 0 | 0 | 0 | 0 |  
-----
```

```
| 0 | 0 | 0 | 0 |  
-----
```

```
| * | 0 | 0 | 0 |  
-----
```

```
Environemnt loaded succesffully  
action size: 4, state size: 16
```

There is also a stub for the agent to be developed.

Currently, the environment is being rendered on the command line only.

References

Game References

[Exactly One Mazes](#)

Algorithms References

[Q-Learning in Python](#)

[SARSA Learning](#)

[Monte Carlo Learning](#)

Tools Used

[OpenAI Gym Environments](#)

[Numpy Docs](#)

[Jupyter Docs](#)