

Linear Regression

Linear regression

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- The model is linear:

$$\hat{y} = w_0 + \sum_{k=1}^p x_k \cdot w_k = //\mathbf{x} = [1, x_1, x_2, \dots, x_p]// = \mathbf{x}^T \mathbf{w}$$

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we added an additional column of 1's to the design matrix to simplify the formulas

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- Least squares method (MSE minimization) provides a solution:

$$\hat{\mathbf{w}} = \arg \min_{\mathbf{w}} \|Y - \hat{Y}\|_2^2 = \arg \min_{\mathbf{w}} \|Y - X\mathbf{w}\|_2^2$$

Analytical solution

Denote quadratic loss function:

$$Q(\mathbf{w}) = (Y - X\mathbf{w})^T (Y - X\mathbf{w}) = \|Y - X\mathbf{w}\|_2^2 ,$$

where $X = [\mathbf{x}_1, \dots, \mathbf{x}_n]$, $\mathbf{x}_i \in \mathbb{R}^p$ $Y = [y_1, \dots, y_n]$, $y_i \in \mathbb{R}$.

To find optimal solution let's equal to zero the derivative of the equation above:

$$\begin{aligned}\nabla_{\mathbf{w}} Q(\mathbf{w}) &= \nabla_{\mathbf{w}} [Y^T Y - Y^T X \mathbf{w} - \mathbf{w}^T X^T Y + \mathbf{w}^T X^T X \mathbf{w}] = \\ &= 0 - X^T Y - X^T Y + (X^T X + X^T X) \mathbf{w} = 0\end{aligned}$$

$$\hat{\mathbf{w}} = (X^T X)^{-1} X^T Y$$

what if this matrix is singular?

Analytical solution

$$\hat{\mathbf{w}} = \boxed{(X^T X)^{-1}} X^T Y$$

what if this matrix is *singular*?

Unstable solution

In case of multicollinear features the matrix $X^T X$ is almost singular .

It leads to unstable solution:

```
w_true  
array([ 2.68647887, -0.52184084, -1.12776533])  
  
w_star = np.linalg.inv(X.T.dot(X)).dot(X.T).dot(Y)  
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corresponding features are almost collinear

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the coefficients are huge and sum up to almost 0

Regularization

To make the matrix nonsingular, we can add a diagonal matrix:

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Actually, it's a solution for the following loss function:

$$Q(\mathbf{w}) = \|Y - X\mathbf{w}\|_2^2 + \lambda^2 \|\mathbf{w}\|_2^2$$

exercise: derive it by yourself

Gauss-Markov theorem

Gauss-Markov theorem

Suppose target values are expressed in following form:

$$Y = X\mathbf{w} + \boldsymbol{\varepsilon}, \text{ where } \boldsymbol{\varepsilon} = [\varepsilon_1, \dots, \varepsilon_N]$$

are random variables

Gauss–Markov assumptions:

- $\mathbb{E}(\varepsilon_i) = 0 \quad \forall i$
- $\text{Var}(\varepsilon_i) = \sigma^2 < \inf \quad \forall i$
- $\text{Cov}(\varepsilon_i, \varepsilon_j) = 0 \quad \forall i \neq j$

- $\mathbb{E}(\varepsilon_i) = 0 \quad \forall i$ Gauss-Markov theorem
- $\text{Var}(\varepsilon_i) = \sigma^2 < \inf \quad \forall i$
- $\text{Cov}(\varepsilon_i, \varepsilon_j) = 0 \quad \forall i \neq j$

$$\hat{\mathbf{w}} = (X^T X)^{-1} X^T Y$$

delivers **B**est **L**inear **U**nbiased **E**stimator

Loss functions in regression

$$MSE(\mathbf{y}, \hat{\mathbf{y}}) = \frac{1}{N} \|\mathbf{y} - \hat{\mathbf{y}}\|_2^2 = \frac{1}{N} \sum_i (y_i - \hat{y}_i)^2$$

$$MAE(\mathbf{y}, \hat{\mathbf{y}}) = \frac{1}{N} \|\mathbf{y} - \hat{\mathbf{y}}\|_1 = \frac{1}{N} \sum_i |y_i - \hat{y}_i|$$

Once more: loss functions:

$$MSE = \frac{1}{n} \|\mathbf{x}^T \mathbf{w} - \mathbf{y}\|_2^2$$

only works for Gauss-Markov theorem

$$MAE = \frac{1}{n} \|\mathbf{x}^T \mathbf{w} - \mathbf{y}\|_1$$

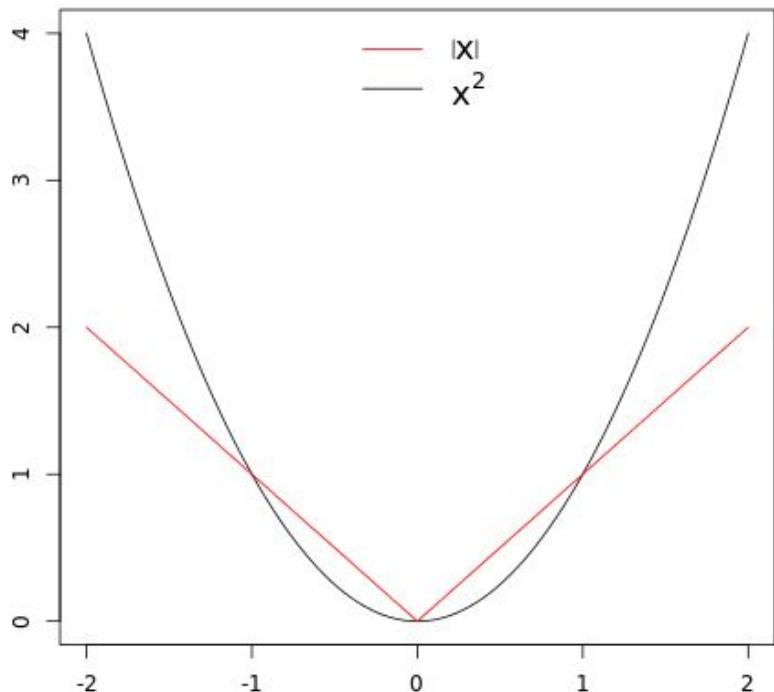
Regularization terms:

- $L_2 : \|\mathbf{w}\|_2^2$

- $L_1 : \|\mathbf{w}\|_1$

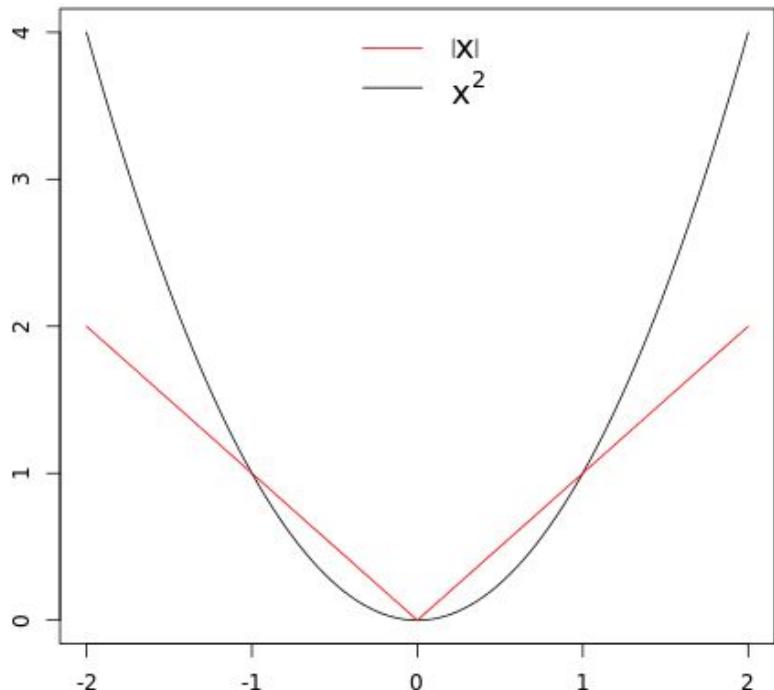
What's the difference?

- MSE (L_2)
 - delivers BLUE according to Gauss-Markov theorem
 - differentiable
 - sensitive to noise
- MAE (L_1)
 - non-differentiable
 - not a problem
 - much more prone to noise



What's the difference?

- L_2 regularization
 - constraints weights
 - delivers more stable solution
 - differentiable
- L_1 regularization
 - non-differentiable
 - not a problem
 - selects features



Loss functions in regression

Other functions to measure the quality in regression:

- R2 score
- MAPE
- SMAPE
- ...

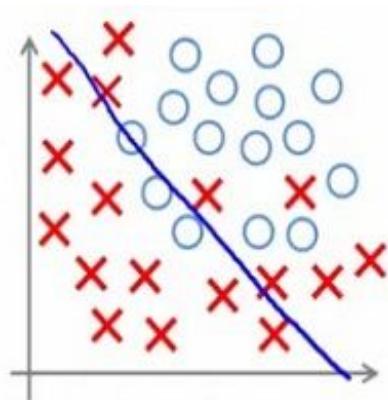
Model validation and evaluation

Supervised learning problem statement

Let's denote:

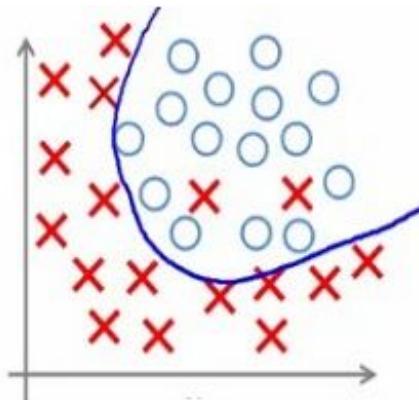
- Training set $\mathcal{L} = \{\mathbf{x}_i, y_i\}_{i=1}^n$, where
 - $(\mathbf{x} \in \mathbb{R}^p, y \in \mathbb{R})$ for regression
 - $\mathbf{x}_i \in \mathbb{R}^p, y_i \in \{+1, -1\}$ for binary classification
- Model $f(\mathbf{x})$ predicts some value for every object
- Loss function $Q(\mathbf{x}, y, f)$ that should be minimized

Overfitting vs. underfitting

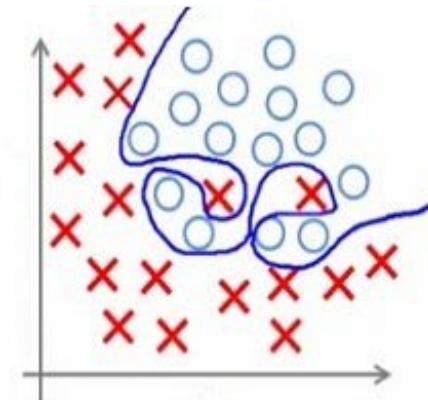


Under-fitting

(too simple to
explain the
variance)



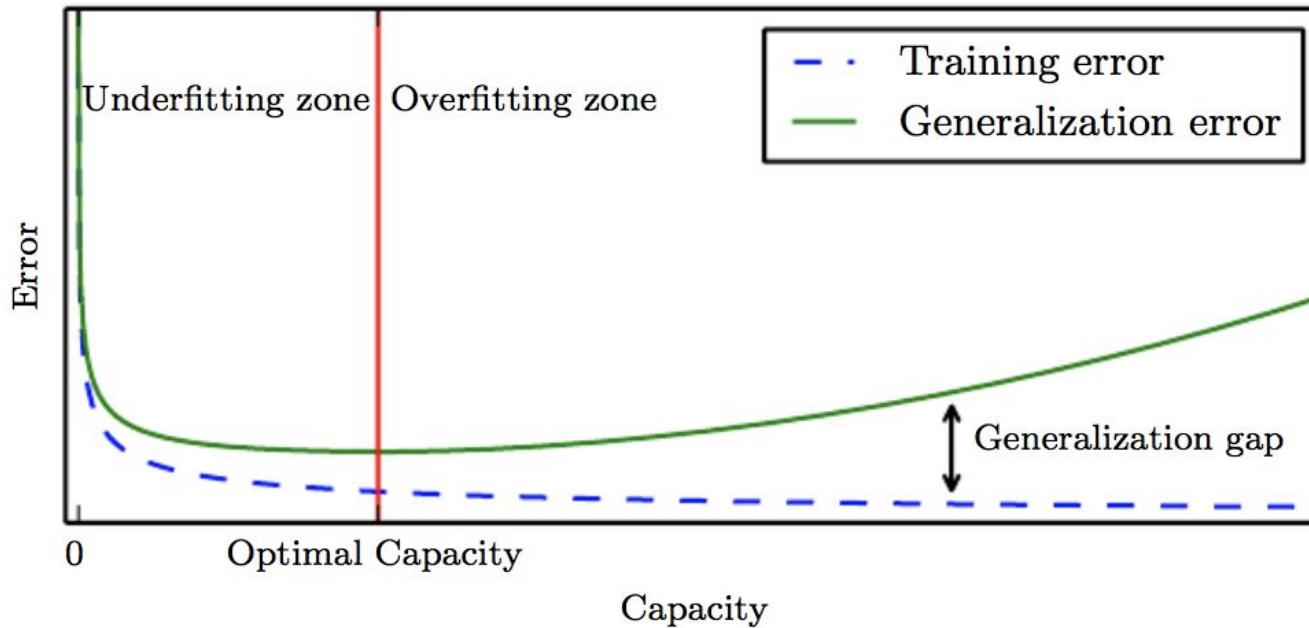
Appropriate-fitting



Over-fitting

(forcefitting -- too
good to be true)

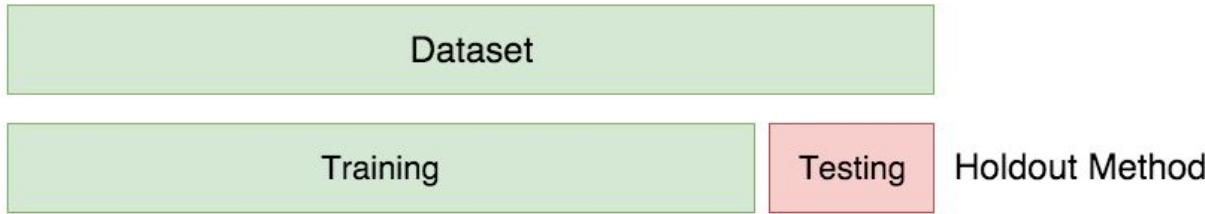
Overfitting vs. underfitting



Overfitting vs. underfitting

- We can control overfitting / underfitting by altering model's capacity (ability to fit a wide variety of functions):
- select appropriate hypothesis space
- learning algorithm's effective capacity may be less than the representational capacity of the model family

Evaluating the quality

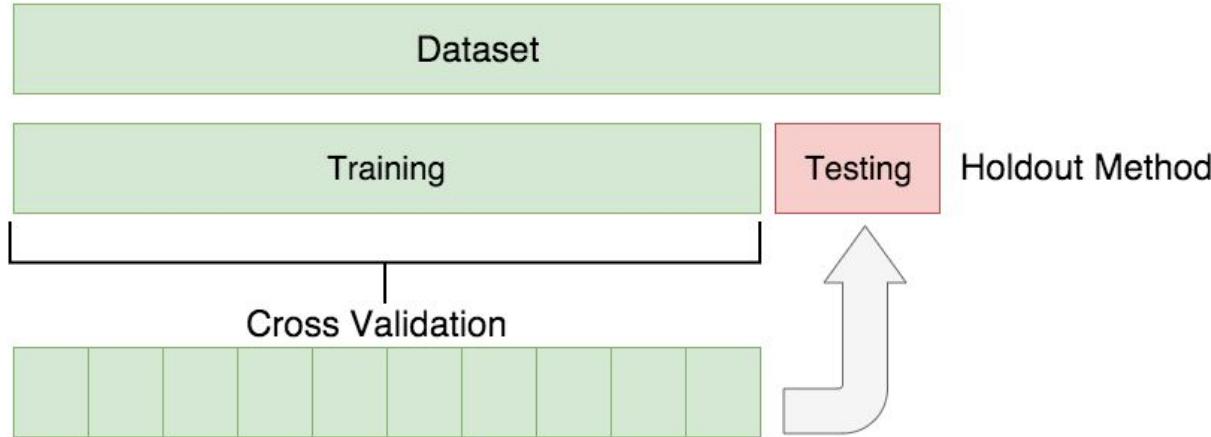


Evaluating the quality

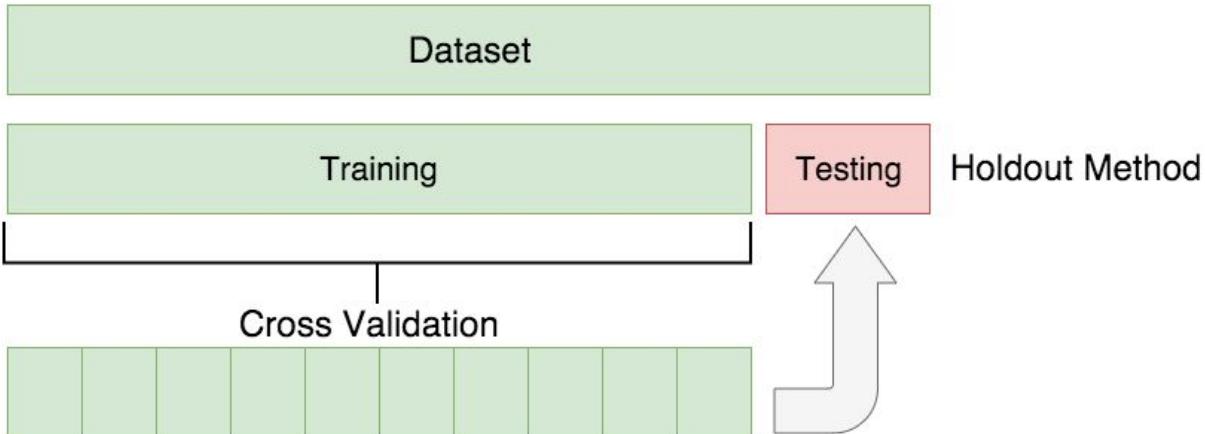


Is it good enough?

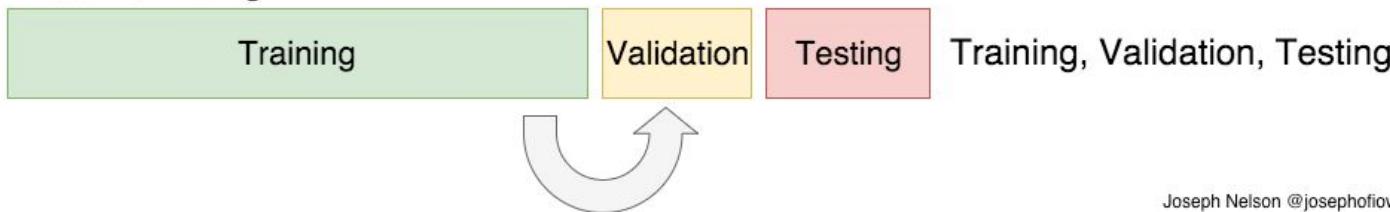
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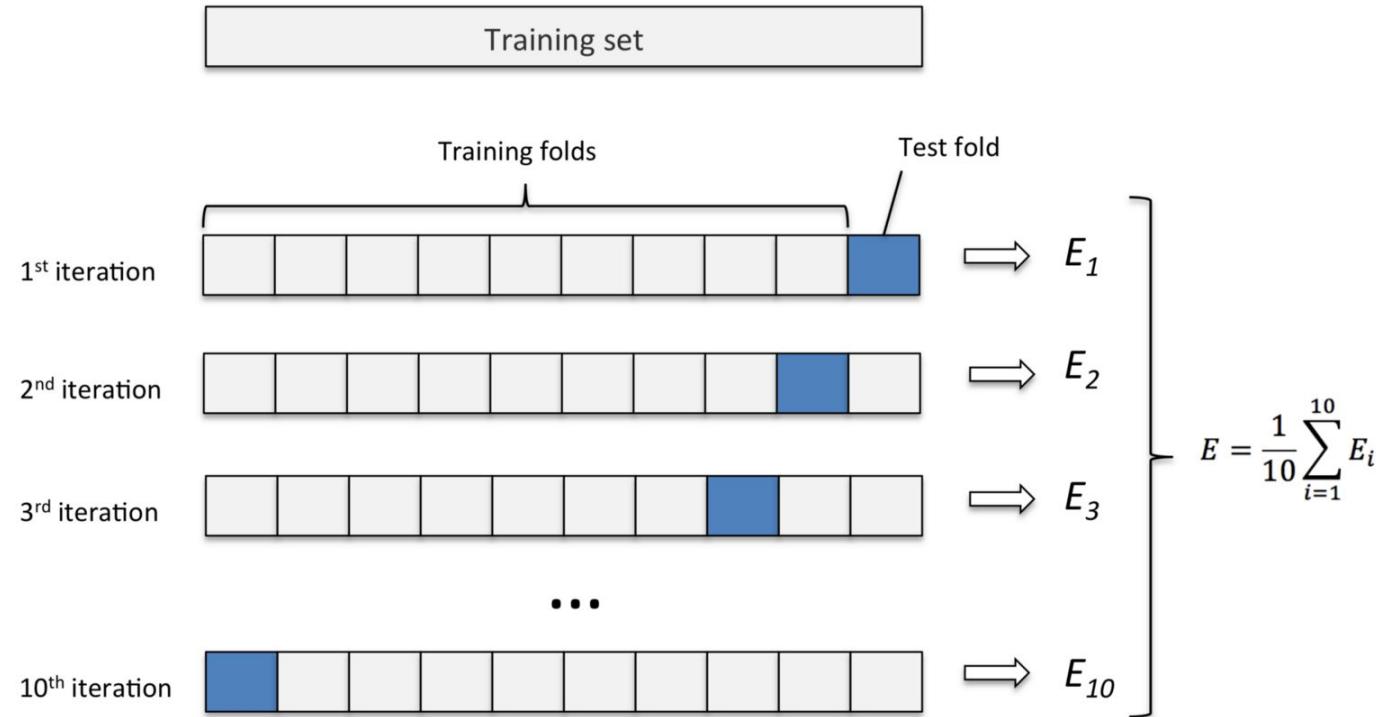
Data Permitting:



Joseph Nelson @josephofiowa

Image credit: Joseph Nelson [@josephofiowa](https://twitter.com/josephofiowa)

Cross-validation



- Linear models are simple yet quite effective models
- Regularization incorporates some prior assumptions/additional constraints
- Trust your validation

Backup

Linear models

$$Y = X_1 + X_2 + X_3$$


Dependent Variable

Independent Variable

Outcome Variable

Predictor Variable

Response Variable

Explanatory Variable