

DASH: Motivation, API & Implementation

Hardware Evolution

- Parallelism due to clock rate wall
- Less memory and bandwidth per instruction

Software Parallelism

- Need for thread-safe data access
- Data and task parallelism

Software Challenges

- Missing thread-safe library support
- Trade-off between locking and copying

Modern Library

- Generic data access
- Multi-threaded task-parallel algorithms

Efficient Multi-Threaded
Data Access, Sharing and Synchronization

Simple Generic Data Storage Library
for any C++ type

Open Source
C++ Library

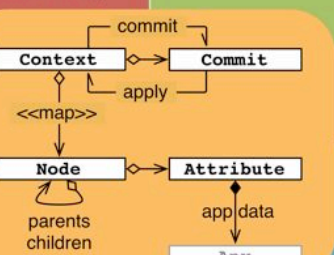
DASH

Context

Provides isolated view on stored data
Per-thread "distributed memory"

Commit

Set of changes emitted by and applied to context



Node

Has attributes, parent and child Nodes
Forms DAGs of application data

Attribute

Holds "any" application C++ object
Objects implement serialization

Implementation

Based On

- Atomic variables
- Lock-free algorithms
- boost::any for application data

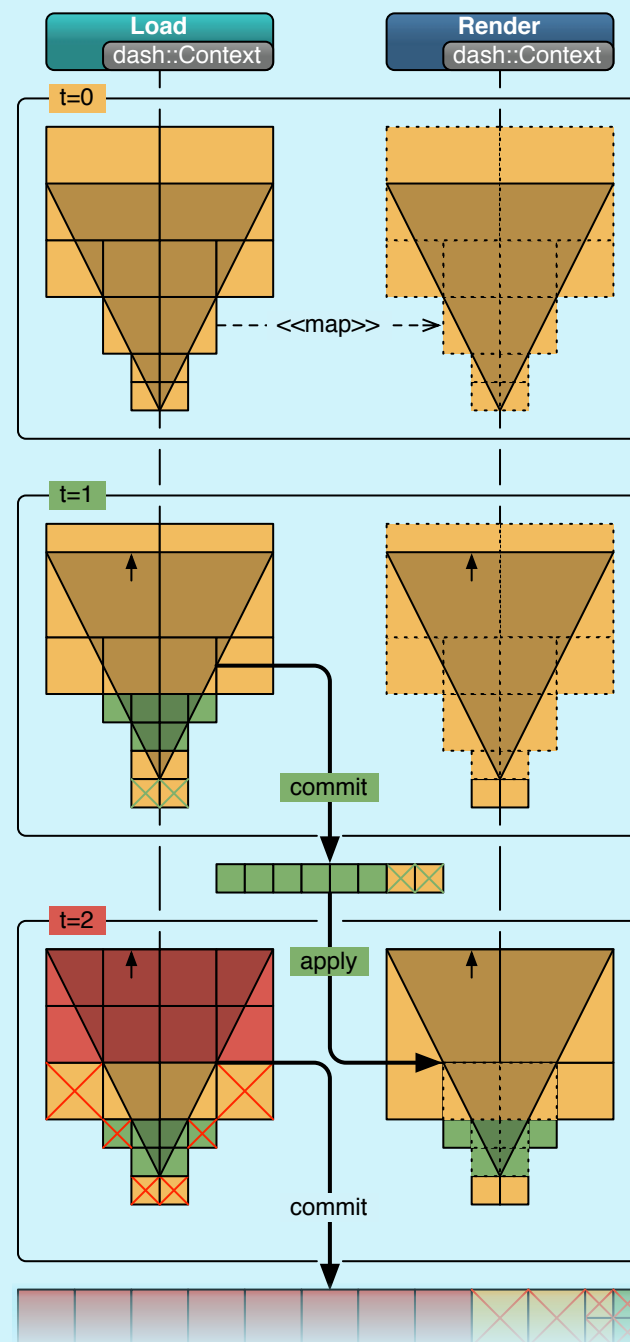
Guarantees

- Lock-free & wait-free concurrent read accesses
- Fast writes with no data contention
- No copies for data updates between contexts

Provides

- Memory efficiency: copy on write
- Fast data access and thread synchronization
- Extensibility to persistence and data distribution

Use Case: Asynchronous LOD Loading



Each thread has `dash::Context`

Both contexts initially share all data
`dash::Nodes` form graph

LOD data stored in `dash::Attributes`

Graph is mapped to both contexts

Data is copied on write (COW)

Load

Update data for new frustum

Updated nodes are copied

Unchanged nodes are shared

Commit bundles all changes

Render

Context provides unchanged view

Load

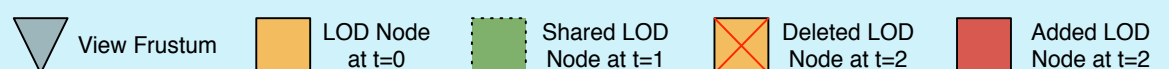
Create commit for next $t=2$

Render

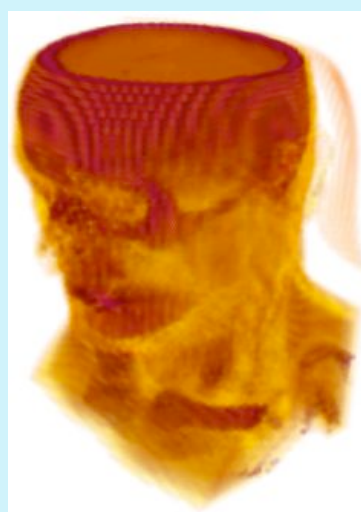
Apply commit from loader thread

Replaced nodes are unreferenced

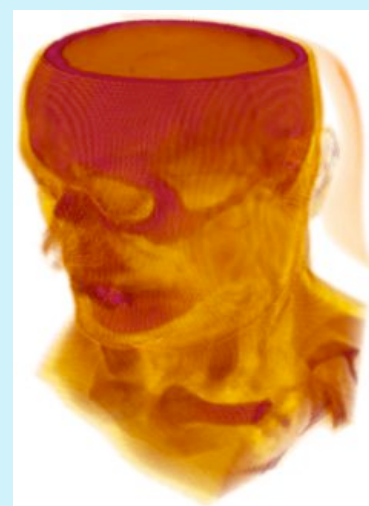
Context provides view at $t=1$



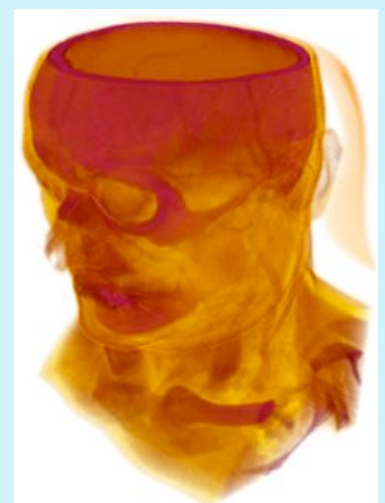
Real-time Volume Rendering for the Visible Male Dataset*



$t = 0$



$t = 1$



$t = 2$

bluebrain.epfl.ch

<https://github.com/BlueBrain/dash>