

Simulation Flow Diagrams

Class Architecture

This document describes the class structure of the simulation system.

Method Naming Conventions

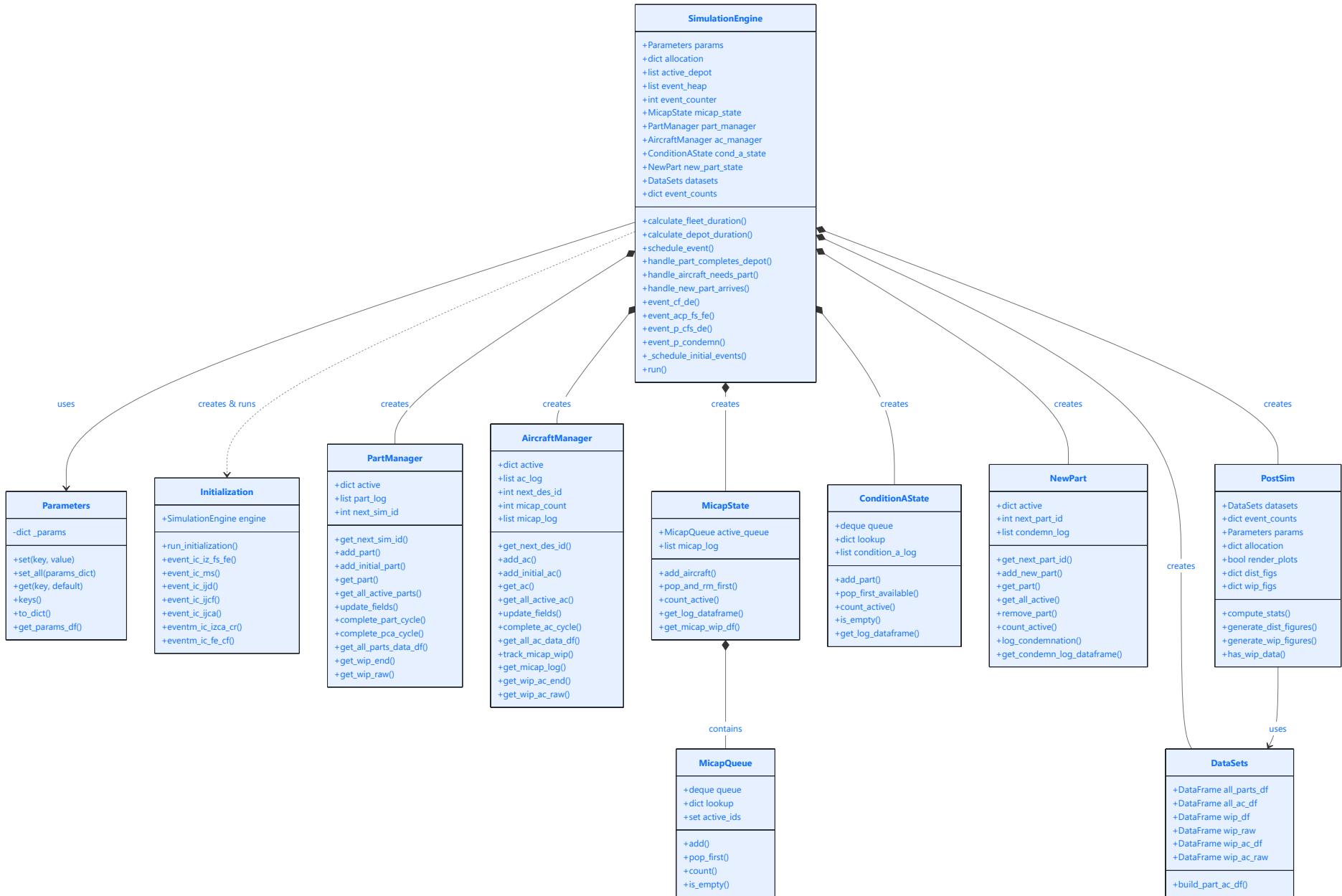
Method names use abbreviations for stages and events:

Abbreviation	Meaning
IC	Initial Condition (initialization phase)
IZ	Initialize
FS	Fleet Start
FE	Fleet End
CF	Condition F
CFS / CFE	Condition F Start / End
DE	Depot End
DS	Depot Start
CA / CAS / CAE	Condition A / Start / End
MS / ME	MICAP Start / End
IE	Install End

Abbreviation	Meaning
CR	Cycle Restart
Ij	Inject (add initial parts/aircraft)
DMR	Depot MICAP Resolve
NMR	New Part MICAP Resolve
NP	New Part

Example: `event_ic_iz_fs_fe` = Initial Condition, Initialize, Fleet Start to Fleet End

UML Class Diagram



Class Responsibilities

Core Classes

Class	File	Purpose
SimulationEngine	<code>simulation_engine.py</code>	Main simulation loop, event processing, coordination
Parameters	<code>parameters.py</code>	Centralized parameter storage with dict-style access
Initialization	<code>initialization.py</code>	Initial conditions setup (fleet start, depot injection, etc.)
PostSim	<code>post_sim.py</code>	Post-simulation statistics and figure generation
DataSets	<code>ds/data_science.py</code>	Output data storage (DataFrames for export)

Entity Managers (O(1) Dictionary Lookups)

Class	File	Purpose
PartManager	<code>entity_part.py</code>	Track active parts, log completed cycles
AircraftManager	<code>entity_ac.py</code>	Track active aircraft, log completed cycles

State Managers (Queue-based)

Class	File	Purpose
MicapState	<code>ph_micap.py</code>	MICAP queue (FIFO), aircraft waiting for parts
MicapQueue	<code>ph_micap.py</code>	Internal queue implementation for MicapState
ConditionAState	<code>ph_cda.py</code>	Available parts inventory (FIFO)
NewPart	<code>ph_new_part.py</code>	Condemned part replacement tracking

Method Explanations

SimulationEngine Methods

Method	Purpose
calculate_fleet_duration()	Draw random fleet stage duration (Normal or Weibull)
calculate_depot_duration()	Draw random depot repair duration (Normal or Weibull)
schedule_event(time, type, id)	Add event to priority queue (heap)
handle_part_completes_depot(sim_id)	Part finishes depot: check MICAP or go to Condition A
handle_aircraft_needs_part(des_id)	Aircraft needs part: take from CA or enter MICAP
handle_new_part_arrives(part_id)	New part arrives: check MICAP or go to Condition A
event_cf_de(sim_id)	Condition F to Depot End (schedules depot_complete)
event_acp_fs_fe(...)	Aircraft-Part Fleet Start to Fleet End (new cycle start)
event_p_cfs_de(sim_id)	Part Condition F Start to Depot End (depot capacity check, then condemn check)
event_p_condemn(sim_id)	Handle condemned part, order replacement
_schedule_initial_events()	Schedule all events after initialization phase
run()	Main event loop - process heap until time limit

Initialization Methods

Method	Purpose
run_initialization()	Orchestrate all initialization steps
event_ic_iz_fs_fe()	Initialize parts/aircraft in Fleet (paired 1:1)

Method	Purpose
<code>event_ic_ms()</code>	Inject aircraft starting in MICAP status
<code>event_ic_ijd()</code>	Inject parts starting in Depot
<code>event_ic_ijcf()</code>	Inject parts starting in Condition F
<code>event_ic_ijca()</code>	Inject parts starting in Condition A
<code>eventm_ic_izca_cr()</code>	Resolve initial MICAP with available CA parts
<code>eventm_ic_fe_cf()</code>	Handle initial fleet_end to condition_f transitions

Output DataFrames

DataFrame	Description
<code>all_parts_df</code>	Complete part event log (all cycles, all stages)
<code>all_ac_df</code>	Complete aircraft event log (all cycles)
<code>wip_df</code>	Work-in-progress snapshots (parts by stage over time)
<code>wip_raw</code>	Raw WIP data before aggregation
<code>wip_ac_df</code>	Aircraft WIP snapshots over time
<code>wip_ac_raw</code>	Raw aircraft WIP data

Key Design Patterns

Dictionary-based Entity Tracking

Both `PartManager` and `AircraftManager` use dictionaries keyed by ID (`sim_id`, `des_id`) for O(1) lookups, replacing slower DataFrame operations.

Queue-based State Management

`MicapState` and `ConditionAState` use `deque` + `dict` combinations for:

- FIFO ordering (chronological processing)
- O(1) lookups by ID
- Event logging for debugging

Event-Driven Architecture

The simulation uses a priority queue (heap) to process events chronologically:

- Events scheduled with `(time, counter, event_type, entity_id)`
- Counter ensures FIFO for same-time events
- Each handler schedules future events

Composition Pattern

`SimulationEngine` creates and owns all manager classes:

- Creates `PartManager`, `AircraftManager`, `MicapState`, `ConditionAState`, `NewPart`, `DataSets` in `__init__`
- Creates `Initialization` in `run()` and passes `self` reference
- Managers don't know about each other - engine coordinates