

Charge Station controller

Electric Vehicle charging station communication controller for DC and AC charging standards.

High versatility, thanks to support of user-written applications and industrial interfaces.

Characteristics

- EVSE / SECC (Supply Equipment Charge Controller)
- Supports simultaneous connection of several vehicles
- CCS protocol (DIN SPEC 70121 and ISO 15118)
- CHAdeMO protocol (with V2X extension coming)
- AC charging supported (J1772, IEC 61851-1)
- 4G connectivity modules available for all zones
- RS-485 (including Modbus-RTU)
- Ethernet, CAN bus for power modules control
- Users can deploy their own code (C/C++, Python)
- Relays for DC and AC contactors control
- Communication stacks included
- Compatible with different power modules
- OCPP interface possible

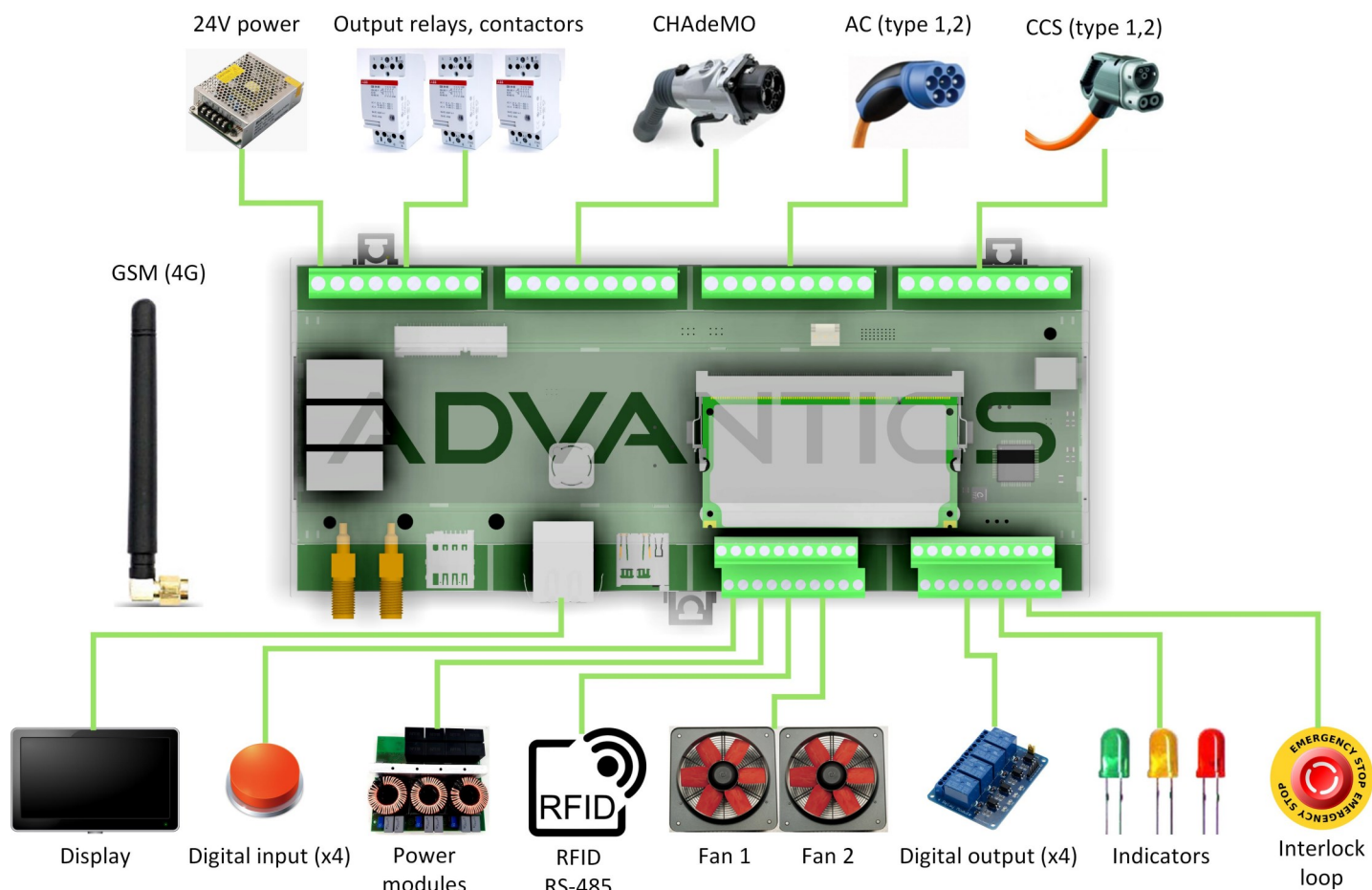
Applications

- EV DC and AC charging stations
- Industrial control
- Charging station simulation
- EV development



Order code: ADM-CS-SECC

Charging Standards	AC	SAE J1772, IEC 61851-1
	CHAdeMO	1.x, with V2G and 2.0 coming
	CCS (Combo 1,2)	DIN SPEC 70121, ISO 15118
Power input	Input voltage min / max	20 V / 28 V
	Input voltage max	28 V
	Recommended nominal	24 V
	Typical / Peak consumption	5 W / 20W
Interfaces (user side)	CAN bus	CAN 2.0B, extended addresses
	Interlock	20mA current loop, 24V
	Ventilator PWM	2 independent PWM channels
	Digital Outputs	4 outputs, 24V, PLC style
	Digital Inputs	4 inputs, PLC style, 24V tolerant
	LEDs	3 LED outputs, 12V, overcurrent protected
	RS-485	Modbus-RTU stack available
	Ethernet	100Mbps RJ45. Modbus TCP available
	SD memory card	16 GB card standard
	4G network connectivity	Mini PCIE slot, populated with 4G modem
	4G regions (per user request)	EMEA/Korea/Thailand, NA, Australia, Japan
	SIM slot	Micro SIM, user supplied
AC interface	Communication wires	CP (Control Pilot), PP (Proximity Pilot)
	Temperature measurements	2 PT1000 inputs
	Locking mechanism	Standard AC inlet locking interface
	Output contactor driver	1 relay for driving output AC contactors
	Protection	HW interlocked relay (CP state monitor)
CCS interface	Communication wires	CP (Control Pilot), PP (Proximity Pilot)
	Temperature measurements	2 PT1000 inputs
	PLC (Powerline Communication)	MStar GreenPHY
	Output contactor driver	1 relay for driving output DC contactors
	Protection	HW interlocked relay (CP state monitor)
CHAdeMO interface	Communication wires	SEQ1, SEQ2, PROX, PERM, CANH, CANL
	Temperature measurements	1 PT1000 input
	Locking mechanism	Solenoid driver
	Output contactor driver	1 relay for driving output DC contactors
	Protection	HW interlocked relay (PERM state monitor)
Mechanical	Module dimensions	212 x 90 x 58 mm
	Connections	Screw wire terminals
	Weight	350 g



		top-row		bottom-row	
AC + CCS	EVSE CP A	19	interlock line	20	GND (interlock)
	EVSE PP A	18	c loop in	19	
	(CCS A) GND	17	c loop out	18	
	EVSE CP B	16	LED 3	17	GND (LED3)
	EVSE PP B	15	LED 2	16	GND (LED2)
	(CCS B) GND	14	LED 1	15	GND (LED1)
	lock pos B	13	digital output 4	14	GND (digital output 4)
	lock neg B	12	digital output 3	13	GND (digital output 3)
	lock fb B	11	digital output 2	12	GND (digital output 2)
		10	digital output 1	11	GND (digital output 1)
CHADEMO	PT1000 ch1 A	19	fan PWM ch1	20	GND (fan PWM ch1)
	(PT1000 ch1 A) GND	18	fan PWM ch2	19	GND (fan PWM ch2)
	PT1000 ch2 A	17	RS485 -	18	GND (RS485)
	(PT1000 ch2 A) GND	16	RS485 +	17	GND (CAN)
	PT1000 ch1 B	15	CAN H	16	120Q bridge CAN
	(PT1000 ch1 B) GND	14	CAN L	15	120Q bridge CAN
	PT1000 ch2 B	13	digital input 4	14	GND (digital input 4)
	(PT1000 ch2 B) GND	12	digital input 3	13	GND (digital input 3)
	(ChaDeMo PT1000) GND	11	digital input 2	12	GND (digital input 2)
		10	digital input 1	11	GND (digital input 1)
RELAIS	PT1000				
	solenoid P				
	(solenoid) GND				
	EVSE SEQ1				
	EVSE SEQ2				
	EVSE PROX				
	EVSE PERM				
	CAR CAN L				
	CAR CAN H				
	(ChaDeMo) GND				
PWR	relais 1 - com				
	relais 1 - no				
	relais 2 - com				
	relais 2 - no				
	relais 3 - com				
	relais 3 - no				
	24V in				
	(24V) GND				

1mm² terminals
1,5mm² terminals