#### REPORT ON DESIGNING A JAMMING SYSTEM FOR 3 kHz TO 3 GHz RANGE

#### INTRODUCTION

A jamming system is engineered to disrupt communication channels by emitting interference signals within a specified frequency spectrum. This report provides an indepth analysis of the design and implementation of a jamming system capable of operating across a frequency range from 3 kHz to 3 GHz, ensuring comprehensive coverage and effective disruption of targeted signals.

#### SYSTEM OVERVIEW

The jamming system consists of the following main components:

**Signal Generator**: Generates the jamming signal.

**Power Amplifier:** Amplifies the signal to the desired power level.

**Antenna:** Radiates the amplified signal to cover the intended area.

**Control Unit:** Manages the operation of the system.

#### **COMPONENTS**

### **Signal Generator**

The signal generator should be capable of producing signals over a wide frequency range. A Direct Digital Synthesis (DDS) generator is recommended due to its high frequency accuracy and stability.

### **Specifications:**

Frequency range: 3 kHz to 3 GHz

Output power: Adjustable, suitable for the amplifier stage

Modulation capabilities: AM, FM, PM (to effectively jam different types of signals)

Recommended Model: Analog Devices AD9959 (4-Channel, 500 MSPS DDS)

## **Power Amplifier**

The power amplifier must be capable of amplifying the signal from the generator across the entire frequency range. A broadband RF amplifier is suitable for this purpose.

## **Specifications:**

Frequency range: 3 kHz to 3 GHz

Gain: >30 dB

Output power: Up to 100W (adjustable according to the application)

Recommended Model: Mini-Circuits ZHL-100W-52+ (Broadband High-Power

Amplifier)

#### Antenna

To effectively radiate the jamming signal, a broadband antenna is required. A log-periodic antenna is a good choice due to its wide frequency range and relatively uniform gain.

# **Specifications:**

Frequency range: 3 kHz to 3 GHz

Gain: 6-10 dBi (typical)

Polarization: Vertical or horizontal (adjustable)

Recommended Model: Aaronia HyperLOG 7025 (Log-Periodic Antenna)

#### **Control Unit**

The control unit orchestrates the operation of the jamming system, including frequency selection, power adjustment, and modulation settings. A microcontroller or FPGA-based system is suitable for this purpose.

# **Specifications:**

Microcontroller: ARM Cortex-M4 or similar

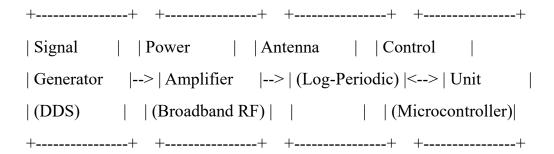
Interfaces: UART, I2C, SPI (for communication with DDS and other peripherals)

User interface: LCD display, buttons or touch interface for user input

Recommended Model: STM32F4 Discovery Kit (ARM Cortex-M4)

#### **SYSTEM DESIGN**

# **Block Diagram**



# **Circuit Design**

#### **Signal Generator Circuit:**

Connection: Connect the AD9959 DDS to the STM32F4 via SPI.

Power Supply and Noise Filtering Ensure proper power supply and filtering for low-noise operation.

## **Power Amplifier Circuit:**

Connection: Connect the output of the DDS to the input of the ZHL-100W-52+ amplifier.

Heat Management: Attach heat sinks to the amplifier and ensure proper ventilation.

Antenna Circuit:

Connection: Connect the amplifier output to the log-periodic antenna using appropriate RF connectors.

Positioning: Position the antenna to optimize the coverage area.

#### **Control Unit Circuit:**

Interfacing: Interface the STM32F4 microcontroller with the DDS via SPI.

User Interface: Add LCD, buttons, or touch interface for user input.

Power Supply and Noise Filtering: Ensure proper power supply and filtering for stable operation.

# **Detailed Circuit Design**

## **Signal Generator Circuit**

## **Theory:**

Signal Generation: DDS generates signals by using a digital waveform stored in memory. This digital signal is then converted to an analog signal using a Digital-to-Analog Converter (DAC).

Frequency Determination: The frequency of the output signal is controlled by the rate at which the waveform is read from memory.

Modulation Capabilities: DDS can provide different modulation techniques (AM, FM, PM).

## **Implementation:**

Frequency Control: Varying the phase increment in the DDS adjusts the output frequency.

Amplitude Control: Allows for adjusting the signal power.

Modulation Control: Provides flexibility to disrupt different communication systems.

# **Power Amplifier Circuit**

# **Theory:**

Signal Amplification: Amplifiers increase the power of the signal generated by the DDS without significantly altering its frequency or phase characteristics.

Broadband Performance: Broadband amplifiers can operate over a wide range of frequencies, ensuring consistent amplification across the entire frequency range.

Gain: Sufficient gain ensures the amplified signal is strong enough to effectively jam the target signals.

## **Implementation:**

Broadband Performance: Ensures consistent amplification across the desired frequency range.

Power Output: High output power ensures effective jamming over larger areas.

#### **Antenna Circuit**

## **Theory:**

Design: Log-periodic antennas have elements of varying lengths, enabling them to operate over a broad range of frequencies.

Polarization: The polarization (vertical or horizontal) can be adjusted to match the polarization of the target signals.

# **Implementation:**

Frequency Coverage: Ensures effective jamming from 3 kHz to 3 GHz.

Gain: Sufficient gain to cover the desired area.

#### **Control Unit Circuit**

### **Theory:**

Interfaces: Microcontrollers provide necessary interfaces (SPI, I2C) to communicate with the DDS and other peripherals.

Programmability: The control unit can be programmed to adjust frequency, modulation, and power output based on user inputs or pre-set conditions.

User Interface: User interfaces (LCD, buttons) allow for real-time adjustments and monitoring of the jamming system.

# **Implementation:**

Processing Power: ARM Cortex-M4 provides sufficient processing capability.

Interfaces: SPI for DDS communication, GPIO for user inputs.

#### ASSEMBLY AND TESTING

## **Step-by-Step Instructions:**

# 1 Assemble the Signal Generator:

Connect the AD9959 to the STM32F4 via SPI.

Program the STM32F4 to generate signals over the desired frequency range.

# 2. Connect the Power Amplifier:

- Wire the output of the DDS to the input of the ZHL-100W-52+ amplifier.
- Ensure proper cooling for the amplifier.

#### 3. Attach the Antenna:.

Connect the amplifier output to the log-periodic antenna.

Position the antenna for optimal signal dispersion.

### 4.. Configure the Control Unit:

- Write firmware for the STM32F4 to control the DDS.
- Implement user interface for frequency selection and power adjustment.

### 5. Testing:

- Power up the system and verify signal generation at different frequencies.
- Measure the output power and ensure it is within desired limits.
- Test the jamming effectiveness across different frequencies and distances.

### **Safety and Legal Considerations**

Regulations: Ensure compliance with local regulations regarding signal jamming.

Safety: Implement safeguards to prevent unintended interference with critical communication systems.

### **CONCLUSION**

This report outlines the design of a jamming system capable of covering the frequency range of 3 kHz to 3 GHz. By following the detailed instructions and specifications provided, the system can be built and operated effectively.