

$$A_1B_1 = A_2B_2 = A_3B_3 = 100 = l.$$

$$O_1G = O_2G = O_3G = R$$

$$EB_1 = EB_2 = EB_3 = r$$

Config. vector: $q_1, q_2, q_3 \Rightarrow$ prismatic joints.

a) Points B_1, B_2, B_3 w.r.t G .

We know pt. E , we can write point B_1 as.

$$E_{T_{B_1}} = \begin{bmatrix} 1 & 0 & 0 & R_C 210^\circ \\ 0 & 1 & 0 & R_S 210^\circ \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$E_{T_{B_2}} = \begin{bmatrix} 1 & 0 & 0 & R_C 90^\circ \\ 0 & 1 & 0 & R_S 90^\circ \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$E_{T_{B_3}} = \begin{bmatrix} 1 & 0 & 0 & R_C (-30^\circ) \\ 0 & 1 & 0 & R_S (-30^\circ) \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$G \quad G_{T_{B_1}} = G_T E_{T_{B_1}} \quad \checkmark$$

b) $G_{T_0} = \begin{bmatrix} I_{3 \times 3} & R_C(210^\circ) \\ 0_{1 \times 3} & 1 \end{bmatrix}$

$$G_{T_2} = \begin{bmatrix} I_{3 \times 3} & R_C 90^\circ \\ 0_{1 \times 3} & 1 \end{bmatrix}$$

c) ${}^{0_1}T_{A_1} = \begin{bmatrix} I_{3 \times 3} & q_1 \\ 0_{1 \times 3} & 1 \end{bmatrix}$

$$G_{T_3} = \begin{bmatrix} I_{3 \times 3} & R_C(-30^\circ) \\ 0_{1 \times 3} & 1 \end{bmatrix}$$

$${}^{0_2}T_{A_2} = \begin{bmatrix} I_{3 \times 3} & q_2 c 120^\circ \\ & q_2 s 120^\circ \\ 0_{1 \times 3} & 1 \end{bmatrix}$$

$${}^{0_3}T_{A_3} = \begin{bmatrix} I_{3 \times 3} & q_3 c 240^\circ \\ & q_3 s 240^\circ \\ 0_{1 \times 3} & 1 \end{bmatrix}$$

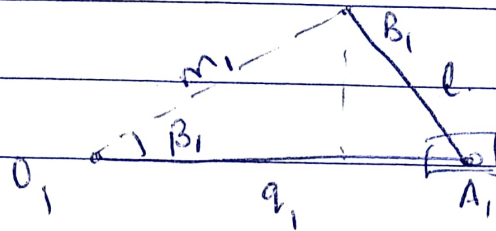
$$G_{T_{A_1}} = G_{T_0} {}^{0_1}T_{A_1}$$

$$G_{T_{A_2}} = G_{T_2} {}^{0_2}T_{A_2}; \quad G_{T_{A_3}} = G_{T_3} {}^{0_3}T_{A_3}$$

\therefore We know all positions, pt. $G, E, B_1, B_2, B_3, O_1, O_2, O_3$ and A_1, A_2 and A_3 with the prismatic joints in terms of q_1, q_2, q_3 .

Let us consider one by one:-

① O, A, B_1



$$\|O, B_1\|_2 = m_1 \quad (\text{distance b/w } O_1 \text{ and } B_1)$$

$$\beta_1 = \tan^{-1} \left(\frac{B_{1y} - O_{1y}}{B_{1x} - O_{1x}} \right)$$

Applying cosine rule:-

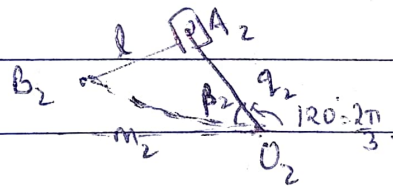
$$l^2 = m^2 + q_1^2 - 2m_1 q_1 \cos \beta_1$$

$$\therefore q_1^2 - 2m_1 q_1 \cos \beta_1 + (m_1^2 - l^2) = 0$$

$$\therefore \text{Quadratic equation} \Rightarrow q_1 = \frac{2m_1 \cos \beta_1 \pm \sqrt{(2m_1 \cos \beta_1)^2 - 4(m_1^2 - l^2)}}{2}$$

Here, we know, m_1, β_1 and l . We can find q_1 .

Similarly,

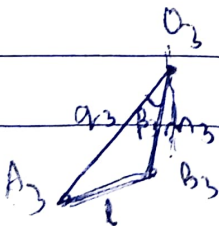


$$m_2 = \|O_2 B_2\|_2$$

$$\beta_2 = \frac{\pi}{3} - \tan^{-1} \left(\frac{B_{2y} - O_{2y}}{B_{2x} - O_{2x}} \right)$$

$$q_2^2 - 2m_2 q_2 \cos \beta_2 + (m_2^2 - l^2) = 0$$

2 lastly



$$m_3 = \|O_3 B_3\|_2$$

$$\beta_3 = \frac{\pi}{6} \text{ can be found.}$$

$$q_3^2 - 2m_3 q_3 \cos \beta_3 + (m_3^2 - l^2) = 0$$