

# Tidy Time Series & Forecasting in R

## 7. Exponential smoothing

[bit.ly/fable2020](https://bit.ly/fable2020)



# Outline

1 Exponential smoothing

2 Trend methods

3 Lab Session 14

4 Seasonal methods

5 ETS taxonomy

6 Lab Session 15

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6 Lab Session 15

# Pharmaceutical Benefits Scheme



# Pharmaceutical Benefits Scheme

The Pharmaceutical Benefits Scheme (PBS) is the Australian government drugs subsidy scheme.

- Many drugs bought from pharmacies are subsidised to allow more equitable access to modern drugs.
- The cost to government is determined by the number and types of drugs purchased. Currently nearly 1% of GDP.
- The total cost is budgeted based on forecasts of drug usage.

# Pharmaceutical Benefits Scheme



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### POLITICS

## Opp demands drug price restriction after PBS budget blow-out

The Federal Opposition has called for tighter controls on drug prices after the Pharmaceutical Benefits Scheme (PBS) budget blew out by almost \$800 million.

The money was spent on two new drugs including the controversial anti-smoking aid Zyban, which dropped in price from \$220 to \$22 after it was listed on the PBS.



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# Pharmaceutical Benefits Scheme

- In 2001: \$4.5 billion budget, under-forecasted by \$800 million.
- Thousands of products. Seasonal demand.
- Subject to covert marketing, volatile products, uncontrollable expenditure.
- Although monthly data available for 10 years, data are aggregated to annual values, and only the first three years are used in estimating the forecasts.
- All forecasts being done with the FORECAST function in MS-Excel!

# Historical perspective

- Developed in the 1950s and 1960s as methods (algorithms) to produce point forecasts.
- Combine a “level”, “trend” (slope) and “seasonal” component to describe a time series.
- The rate of change of the components are controlled by “smoothing parameters”:  $\alpha$ ,  $\beta$  and  $\gamma$  respectively.
- Need to choose best values for the smoothing parameters (and initial states).
- Equivalent ETS state space models developed in the 1990s and 2000s.



# A model for levels, trends, and seasonalities

We want a model that captures the level ( $\ell_t$ ), trend ( $b_t$ ) and seasonality ( $s_t$ ).

**How do we combine these elements?**

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**Additively?**

$$y_t = \ell_{t-1} + b_{t-1} + s_{t-m} + \varepsilon_t$$

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**Multiplicatively?**

$$y_t = \ell_{t-1} b_{t-1} s_{t-m} (1 + \varepsilon_t)$$

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**Perhaps a mix of both?**

$$y_t = (\ell_{t-1} + b_{t-1}) s_{t-m} + \varepsilon_t$$

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**Perhaps a mix of both?**

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**How do the level, trend and seasonal components evolve over time?**

# ETS models

General notation

ETS : ExponenTial Smoothing



Error Trend Season

The diagram shows three arrows pointing upwards from the words 'Error', 'Trend', and 'Season' to the letters 'E', 'T', and 'S' respectively in the 'ETS' part of the text above.

**Error:** Additive ("A") or multiplicative ("M")

# ETS models

General notation

ETS : ExponenTial Smoothing

Error Trend Season

**Error:** Additive ("A") or multiplicative ("M")

**Trend:** None ("N"), additive ("A"), multiplicative ("M"), or damped ("Ad" or "Md").

# ETS models

General notation

ETS : ExponenTial Smoothing



Error Trend Season

**Error:** Additive ("A") or multiplicative ("M")

**Trend:** None ("N"), additive ("A"), multiplicative ("M"), or damped ("Ad" or "Md").

**Seasonality:** None ("N"), additive ("A") or multiplicative ("M")



## ETS(A,N,N): SES with additive errors

Forecast equation

$$\hat{y}_{T+h|T} = \ell_T$$

Measurement equation

$$y_t = \ell_{t-1} + \varepsilon_t$$

State equation

$$\ell_t = \ell_{t-1} + \alpha \varepsilon_t$$

where  $\varepsilon_t \sim \text{NID}(0, \sigma^2)$ .

## ETS(A,N,N): SES with additive errors

Forecast equation

$$\hat{y}_{T+h|T} = l_T$$

Measurement equation

$$y_t = l_{t-1} + \varepsilon_t$$

State equation

$$l_t = l_{t-1} + \alpha \varepsilon_t$$

where  $\varepsilon_t \sim \text{NID}(0, \sigma^2)$ .

- “innovations” or “single source of error” because equations have the same error process,  $\varepsilon_t$ .
- Measurement equation: relationship between observations and states.
- Transition/state equation(s): evolution of the state(s) through time.

## ETS(M,N,N): SES with multiplicative errors

Forecast equation	$\hat{y}_{T+h T} = \ell_T$
Measurement equation	$y_t = \ell_{t-1}(1 + \varepsilon_t)$
State equation	$\ell_t = \ell_{t-1}(1 + \alpha\varepsilon_t)$

where  $\varepsilon_t \sim \text{NID}(0, \sigma^2)$ .

## ETS(M,N,N): SES with multiplicative errors

Forecast equation	$\hat{y}_{T+h T} = \ell_T$
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where  $\varepsilon_t \sim \text{NID}(0, \sigma^2)$ .

- Models with additive and multiplicative errors with the same parameters generate the same point forecasts but different prediction intervals.

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# Holt's linear trend

## Additive errors: ETS(A,A,N)

Forecast equation  $\hat{y}_{T+h|T} = \ell_T + hb_T$

Measurement equation  $y_t = \ell_{t-1} + b_{t-1} + \varepsilon_t$

State equations  $\ell_t = \ell_{t-1} + b_{t-1} + \alpha\varepsilon_t$

$$b_t = b_{t-1} + \beta\varepsilon_t$$

# Holt's linear trend

## Additive errors: ETS(A,A,N)

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State equations  $\ell_t = \ell_{t-1} + b_{t-1} + \alpha\varepsilon_t$

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## Multiplicative errors: ETS(M,A,N)

Forecast equation  $\hat{y}_{T+h|T} = \ell_T + hb_T$

Measurement equation  $y_t = (\ell_{t-1} + b_{t-1})(1 + \varepsilon_t)$

State equations  $\ell_t = (\ell_{t-1} + b_{t-1})(1 + \alpha\varepsilon_t)$

$$b_t = b_{t-1} + \beta\varepsilon_t$$

# Example: Australian population

```
aus_economy <- global_economy %>%  
  filter(Code == "AUS") %>%  
  mutate(Pop = Population / 1e6)  
fit <- aus_economy %>% model(AAN = ETS(Pop))  
report(fit)
```

```
## Series: Pop  
## Model: ETS(A,A,N)  
## Smoothing parameters:  
##   alpha = 1  
##   beta  = 0.327  
##  
## Initial states:  
##   l      b  
## 10.1 0.222  
##  
## sigma^2: 0.0041  
##  
## AIC AICc BIC  
## -77.0 -75.8 -66.7
```



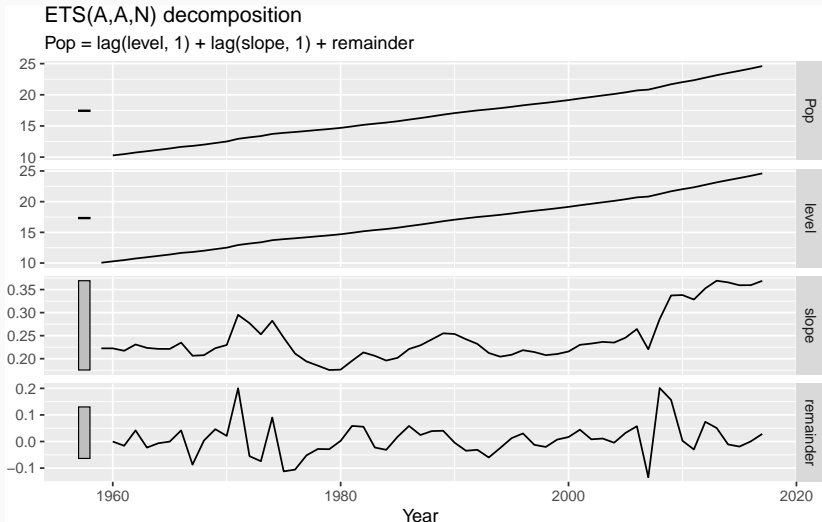
# Example: Australian population

```
components(fit)
```

```
## # A dable:                59 x 7 [1Y]
## # Key:                    Country, .model [1]
## # ETS(A,A,N) Decomposition: Pop = lag(level, 1) + lag(slope, 1)
## #   remainder
##   Country   .model  Year   Pop level slope remainder
##   <fct>     <chr>   <dbl> <dbl> <dbl> <dbl>      <dbl>
## 1 Australia AAN     1959   NA    10.1 0.222   NA
## 2 Australia AAN     1960  10.3  10.3 0.222 -0.000145
## 3 Australia AAN     1961  10.5  10.5 0.217 -0.0159
## 4 Australia AAN     1962  10.7  10.7 0.231  0.0418
## 5 Australia AAN     1963  11.0  11.0 0.223 -0.0229
## 6 Australia AAN     1964  11.2  11.2 0.221 -0.00641
## 7 Australia AAN     1965  11.4  11.4 0.221 -0.000314
## 8 Australia AAN     1966  11.7  11.7 0.235  0.0418
## 9 Australia AAN     1967  11.8  11.8 0.206 -0.0869
## 10 Australia AAN     1968  12.0  12.0 0.208  0.00350
```

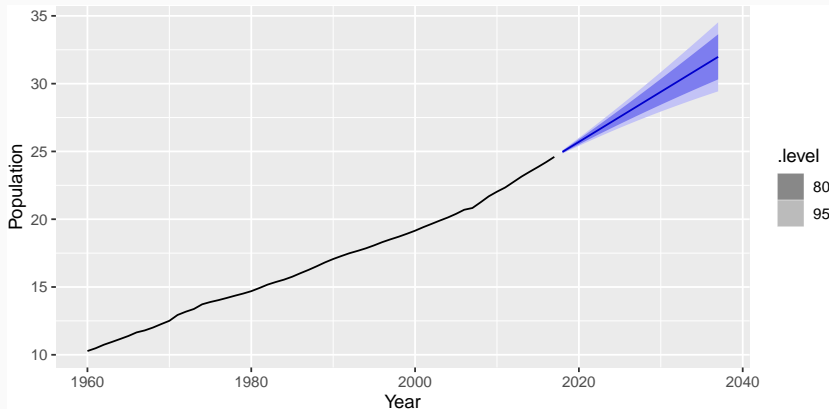
# Example: Australian population

```
components(fit) %>% autoplot()
```



# Example: Australian population

```
fit %>%  
  forecast(h = 20) %>%  
  autoplot(aus_economy) +  
  ylab("Population") + xlab("Year")
```



# ETS(A,Ad,N): Damped trend method

## Additive errors

Forecast equation  $\hat{y}_{T+h|T} = \ell_T + (\phi + \dots + \phi^{h-1})b_T$

Measurement equation  $y_t = (\ell_{t-1} + \phi b_{t-1}) + \varepsilon_t$

State equations  $\ell_t = (\ell_{t-1} + \phi b_{t-1}) + \alpha \varepsilon_t$

$$b_t = \phi b_{t-1} + \beta \varepsilon_t$$

# ETS(A,Ad,N): Damped trend method

## Additive errors

Forecast equation  $\hat{y}_{T+h|T} = \ell_T + (\phi + \dots + \phi^{h-1})b_T$

Measurement equation  $y_t = (\ell_{t-1} + \phi b_{t-1}) + \varepsilon_t$

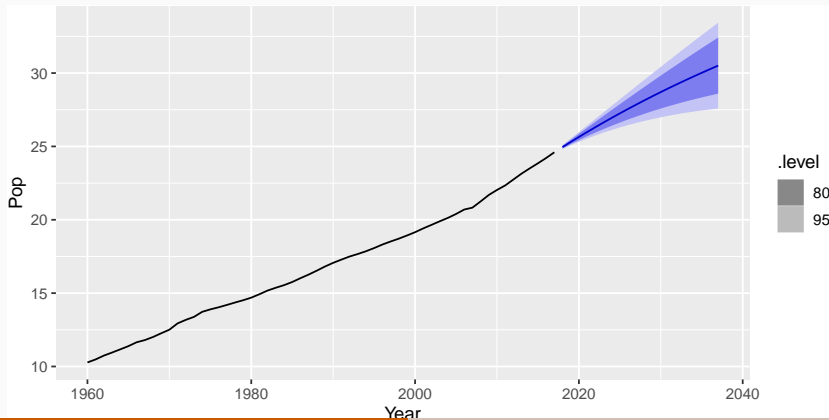
State equations  $\ell_t = (\ell_{t-1} + \phi b_{t-1}) + \alpha \varepsilon_t$

$$b_t = \phi b_{t-1} + \beta \varepsilon_t$$

- Damping parameter  $0 < \phi < 1$ .
- If  $\phi = 1$ , identical to Holt's linear trend.
- As  $h \rightarrow \infty$ ,  $\hat{y}_{T+h|T} \rightarrow \ell_T + \phi b_T / (1 - \phi)$ .
- Short-run forecasts trended, long-run forecasts constant.

# Example: Australian population

```
aus_economy %>%  
  model(holt = ETS(Pop ~ trend("Ad"))) %>%  
  forecast(h = 20) %>%  
  autoplot(aus_economy)
```



# Example: National populations

```
fit <- global_economy %>%  
  mutate(Pop = Population / 1e6) %>%  
  model(ets = ETS(Pop))  
fit
```

```
## # A mable: 263 x 2  
## # Key:      Country [263]  
##   Country      ets  
##   <fct>        <model>  
## 1 Afghanistan <ETS(A,A,N)>  
## 2 Albania     <ETS(M,A,N)>  
## 3 Algeria     <ETS(M,A,N)>  
## 4 American Samoa <ETS(M,A,N)>  
## 5 Andorra     <ETS(M,A,N)>  
## 6 Angola      <ETS(M,A,N)>  
## 7 Antigua and Barbuda <ETS(M,A,N)>  
## 8 Arab World  <ETS(M,A,N)>  
## 9 Argentina  <ETS(A,A,N)>  
## 10 Armenia    <ETS(M,A,N)>  
## # ... with 253 more rows
```

# Example: National populations

```
fit %>%  
  forecast(h = 5)
```

```
## # A tibble: 1,315 x 5 [1Y]  
## # Key:      Country, .model [263]  
##   Country      .model Year   Pop .distribution  
##   <fct>        <chr>   <dbl> <dbl> <dist>  
## 1 Afghanistan ets      2018  36.4 N(36, 0.012)  
## 2 Afghanistan ets      2019  37.3 N(37, 0.059)  
## 3 Afghanistan ets      2020  38.2 N(38, 0.164)  
## 4 Afghanistan ets      2021  39.0 N(39, 0.351)  
## 5 Afghanistan ets      2022  39.9 N(40, 0.644)  
## 6 Albania     ets      2018   2.87 N(2.9, 0.00012)  
## 7 Albania     ets      2019   2.87 N(2.9, 0.00060)  
## 8 Albania     ets      2020   2.87 N(2.9, 0.00169)  
## 9 Albania     ets      2021   2.86 N(2.9, 0.00362)
```



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## Lab Session 14

Try forecasting the Chinese GDP from the `global_economy` data set using an ETS model.

Experiment with the various options in the `ETS()` function to see how much the forecasts change with damped trend, or with a Box-Cox transformation. Try to develop an intuition of what each is doing to the forecasts.

[Hint: use `h=20` when forecasting, so you can clearly see the differences between the various options when plotting the forecasts.]

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## ETS(A,A,A): Holt-Winters additive method

Forecast equation  $\hat{y}_{t+h|t} = \ell_t + hb_t + s_{t+h-m(k+1)}$

Observation equation  $y_t = \ell_{t-1} + b_{t-1} + s_{t-m} + \varepsilon_t$

State equations  $\ell_t = \ell_{t-1} + b_{t-1} + \alpha\varepsilon_t$

$$b_t = b_{t-1} + \beta\varepsilon_t$$

$$s_t = s_{t-m} + \gamma\varepsilon_t$$

- $k = \text{integer part of } (h - 1)/m$ .
- $\sum_i s_i \approx 0$ .
- Parameters:  $0 \leq \alpha \leq 1$ ,  $0 \leq \beta \leq 1$ ,  $0 \leq \gamma \leq 1 - \alpha$  and  $m = \text{period of seasonality (e.g. } m = 4 \text{ for quarterly data)}$ .

## ETS(M,A,M): Holt-Winters multiplicative method

Forecast equation  $\hat{y}_{t+h|t} = (\ell_t + hb_t)s_{t+h-m(k+1)}$

Observation equation  $y_t = (\ell_{t-1} + b_{t-1})s_{t-m}(1 + \varepsilon_t)$

State equations  $\ell_t = (\ell_{t-1} + b_{t-1})(1 + \alpha\varepsilon_t)$

$$b_t = b_{t-1}(1 + \beta\varepsilon_t)$$

$$s_t = s_{t-m}(1 + \gamma\varepsilon_t)$$

- $k$  is integer part of  $(h - 1)/m$ .
- $\sum_i s_i \approx m$ .
- Parameters:  $0 \leq \alpha \leq 1$ ,  $0 \leq \beta^* \leq 1$ ,  $0 \leq \gamma \leq 1 - \alpha$  and  $m =$  period of seasonality (e.g.  $m = 4$  for quarterly data).

# Example: Australian holiday tourism

```
holidays <- tourism %>%  
  filter(Purpose == "Holiday")  
fit <- holidays %>% model(ets = ETS(Trips))  
fit
```

```
## # A mable: 76 x 4  
## # Key:      Region, State, Purpose [76]  
##   Region                State                Purpose ets  
##   <chr>                  <chr>                  <chr>  <model>  
## 1 Adelaide              South Australia    Holiday <ETS(A,N,A~  
## 2 Adelaide Hills        South Australia    Holiday <ETS(A,A,N~  
## 3 Alice Springs         Northern Territo~ Holiday <ETS(M,N,A~  
## 4 Australia's Coral Coast Western Australia Holiday <ETS(M,N,A~  
## 5 Australia's Golden Outba~ Western Australia Holiday <ETS(M,N,M~  
## 6 Australia's North West Western Australia Holiday <ETS(A,N,A~  
## 7 Australia's South West Western Australia Holiday <ETS(M,N,M~  
## 8 Ballarat              Victoria          Holiday <ETS(M,N,A~  
## 9 Barkly                Northern Territo~ Holiday <ETS(A,N,A~  
## 10 Barossa              South Australia    Holiday <ETS(A,N,N~
```

# Example: Australian holiday tourism

```
fit %>%  
  filter(Region == "Snowy Mountains") %>%  
  report()
```

```
## Series: Trips  
## Model: ETS(M,N,A)  
## Smoothing parameters:  
##   alpha = 0.157  
##   gamma = 1e-04  
##  
## Initial states:  
##   l   s1   s2   s3   s4  
## 142 -61 131 -42.2 -27.7  
##  
##   sigma^2: 0.0388  
##  
## AIC AICc BIC  
## 852 854 869
```

# Example: Australian holiday tourism

```
fit %>%  
  filter(Region == "Snowy Mountains") %>%  
  components(fit)
```

```
## # A dable:                84 x 9 [1Q]  
## # Key:                    Region, State, Purpose, .model [1]  
## # ETS(M,N,A) Decomposition: Trips = (lag(level, 1) + lag(season,  
## #   4)) * (1 + remainder)  
##   Region State Purpose .model   Quarter Trips level season  
##   <chr>  <chr> <chr>  <chr>      <qtr> <dbl> <dbl> <dbl>  
## 1 Snowy~ New ~ Holiday ets    1997 Q1  NA      NA   -27.7  
## 2 Snowy~ New ~ Holiday ets    1997 Q2  NA      NA   -42.2  
## 3 Snowy~ New ~ Holiday ets    1997 Q3  NA      NA   131.  
## 4 Snowy~ New ~ Holiday ets    1997 Q4  NA     142.  -61.0  
## 5 Snowy~ New ~ Holiday ets    1998 Q1 101.    140.  -27.7  
## 6 Snowy~ New ~ Holiday ets    1998 Q2 112.    142.  -42.2  
## 7 Snowy~ New ~ Holiday ets    1998 Q3 310.    148.   131.  
## 8 Snowy~ New ~ Holiday ets    1998 Q4  89.8   148.  -61.0  
## 9 Snowy~ New ~ Holiday ets    1999 Q1 112.    147.  -27.7
```

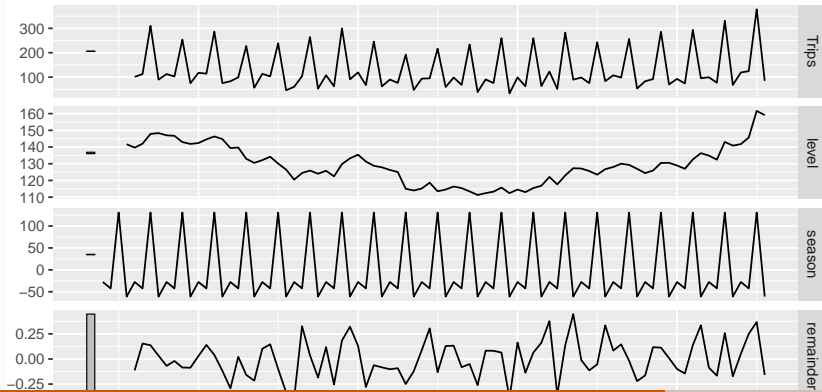


# Example: Australian holiday tourism

```
fit %>%  
  filter(Region == "Snowy Mountains") %>%  
  components(fit) %>%  
  autoplot()
```

ETS(M,N,A) decomposition

$\text{Trips} = (\text{lag}(\text{level}, 1) + \text{lag}(\text{season}, 4)) * (1 + \text{remainder})$



# Example: Australian holiday tourism

```
fit %>% forecast()
```

```
## # A tibble: 608 x 7 [1Q]
```

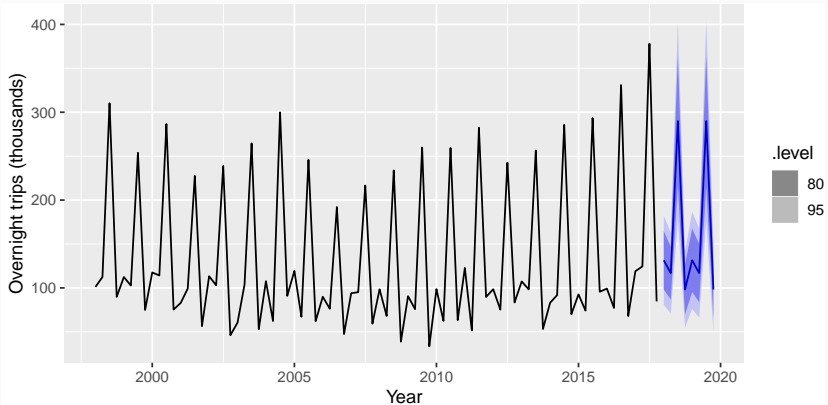
```
## # Key:      Region, State, Purpose, .model [76]
```

##	Region	State	Purpose	.model	Quarter	Trips	.distribution
##	<chr>	<chr>	<chr>	<chr>	<qtr>	<dbl>	<dist>
## 1	Adelaide	South	A~ Holiday	ets	2018 Q1	210.	N(210, 457)
## 2	Adelaide	South	A~ Holiday	ets	2018 Q2	173.	N(173, 473)
## 3	Adelaide	South	A~ Holiday	ets	2018 Q3	169.	N(169, 489)
## 4	Adelaide	South	A~ Holiday	ets	2018 Q4	186.	N(186, 505)
## 5	Adelaide	South	A~ Holiday	ets	2019 Q1	210.	N(210, 521)
## 6	Adelaide	South	A~ Holiday	ets	2019 Q2	173.	N(173, 537)
## 7	Adelaide	South	A~ Holiday	ets	2019 Q3	169.	N(169, 553)
## 8	Adelaide	South	A~ Holiday	ets	2019 Q4	186.	N(186, 569)
## 9	Adelaide~	South	A~ Holiday	ets	2018 Q1	19.4	N(19, 36)
## 10	Adelaide~	South	A~ Holiday	ets	2018 Q2	19.6	N(20, 36)

```
## # ... with 598 more rows
```

# Example: Australian holiday tourism

```
fit %>%  
  forecast() %>%  
  filter(Region == "Snowy Mountains") %>%  
  autoplot(holidays) +  
  xlab("Year") + ylab("Overnight trips (thousands)")
```



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# Exponential smoothing models

## Additive Error

		Seasonal Component		
		N (None)	A (Additive)	M (Multiplicative)
Trend Component	N (None)	A,N,N	A,N,A	<del>A,N,M</del>
	A (Additive)	A,A,N	A,A,A	<del>A,A,M</del>
	A <sub>d</sub> (Additive damped)	A,A <sub>d</sub> ,N	A,A <sub>d</sub> ,A	<del>A,A<sub>d</sub>,M</del>

## Multiplicative Error

		Seasonal Component		
		N (None)	A (Additive)	M (Multiplicative)
Trend Component	N (None)	M,N,N	M,N,A	M,N,M
	A (Additive)	M,A,N	M,A,A	M,A,M
	A <sub>d</sub> (Additive damped)	M,A <sub>d</sub> ,N	M,A <sub>d</sub> ,A	M,A <sub>d</sub> ,M

# Estimating ETS models

- Smoothing parameters  $\alpha$ ,  $\beta$ ,  $\gamma$  and  $\phi$ , and the initial states  $\ell_0$ ,  $b_0$ ,  $s_0$ ,  $s_{-1}$ ,  $\dots$ ,  $s_{-m+1}$  are estimated by maximising the “likelihood” = the probability of the data arising from the specified model.
- For models with additive errors equivalent to minimising SSE.
- For models with multiplicative errors, **not** equivalent to minimising SSE.

# Model selection

## Akaike's Information Criterion

$$\text{AIC} = -2 \log(L) + 2k$$

where  $L$  is the likelihood and  $k$  is the number of parameters initial states estimated in the model.

# Model selection

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$$\text{AIC} = -2 \log(L) + 2k$$

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## Corrected AIC

$$\text{AIC}_c = \text{AIC} + \frac{2(k+1)(k+2)}{T-k}$$

which is the AIC corrected (for small sample bias).



# Model selection

## Akaike's Information Criterion

$$\text{AIC} = -2 \log(L) + 2k$$

where  $L$  is the likelihood and  $k$  is the number of parameters initial states estimated in the model.

## Corrected AIC

$$\text{AIC}_c = \text{AIC} + \frac{2(k+1)(k+2)}{T-k}$$

which is the AIC corrected (for small sample bias).

## Bayesian Information Criterion

$$\text{BIC} = \text{AIC} + k(\log(T) - 2).$$

# AIC and cross-validation

Minimizing the AIC assuming Gaussian residuals is asymptotically equivalent to minimizing one-step time series cross validation MSE.

# Automatic forecasting

## From Hyndman et al. (IJF, 2002):

- 1 Apply each model that is appropriate to the data. Optimize parameters and initial values using MLE.
  - 2 Select best method using AICc.
  - 3 Produce forecasts using best method.
  - 4 Obtain forecast intervals using underlying state space model.
- Method performed very well in M3 competition.
  - Used as a benchmark in the M4 competition.

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# Lab Session 15

Find an ETS model for the Gas data from `aus_production`.

- Why is multiplicative seasonality necessary here?
- Experiment with making the trend damped.  
Does it improve the forecasts?