

I. Write down the Butcher tableaux of the modified Euler method, the improved Euler method, and Heun's third-order method

Solution:

improved Euler method

$$\begin{array}{c|cc} 0 & 0 & 0 \\ 1 & 1 & 0 \\ \hline & \frac{1}{2} & \frac{1}{2} \end{array}$$

modified Euler method

$$\begin{array}{c|cc} 0 & 0 & 0 \\ \frac{1}{2} & \frac{1}{2} & 0 \\ \hline & 0 & 1 \end{array}$$

Heun's third-order method

$$\begin{array}{c|ccc} 0 & 0 & 0 & 0 \\ \frac{1}{3} & \frac{1}{3} & 0 & 0 \\ \frac{2}{3} & 0 & \frac{2}{3} & 0 \\ \hline & \frac{1}{4} & 0 & \frac{3}{4} \end{array}$$

II. Verify that the RK method can be rewritten as

$$\begin{cases} \xi_i = U^n + k \sum_{j=1}^s a_{i,j} f(\xi_j, t_n + c_j k), \\ U^{n+1} = U^n + k \sum_{j=1}^s b_j f(\xi_j, t_n + c_j k), \end{cases}$$

where $i = 1, 2, \dots, s$

Solution:

令 $\xi_i = U^n + k \sum_{j=1}^s a_{i,j} f(\xi_j, t_n + c_j k)$, $i = 1, 2, \dots, s$

那么就有 $y_i = f(U^n + k \sum_{j=1}^s a_{i,j} y_j, t_n + c_j k) = f(\xi_i, t_n + c_i k)$

所以 $U^{n+1} = U^n + k \sum_{j=1}^s b_j y_j = U^n + k \sum_{j=1}^s b_j f(\xi_j, t_n + c_j k)$

III. There are three one-parameter families of third-order three-stage ERK methods, one of which is

$$\begin{array}{c|ccc} 0 & 0 & 0 & 0 \\ \frac{2}{3} & \frac{2}{3} & 0 & 0 \\ \frac{2}{3} & \frac{2}{3} - \frac{1}{4\alpha} & \frac{1}{4\alpha} & 0 \\ \hline & \frac{1}{4} & \frac{3}{4} - \alpha & \alpha \end{array}$$

where α is the free parameter. Derive the above family. Does Heun's third-order formula belong to this family?

Solution:

设 three-stage ERK

$$\begin{cases} y_1 = f(U^n, t_n) \\ y_2 = f(U^n + ka_{2,1}y_1, t_n + c_2k) \\ y_3 = f(U^n + ka_{3,1}y_1 + ka_{3,2}y_2, t_n + c_3k) \\ U^{n+1} = U^n + k(b_1y_1 + b_2y_2 + b_3y_3) \end{cases}$$

再设

$$\begin{aligned} y_1(t_n) &= f(u(t_n), t_n) \\ y_2(t_n) &= f(u(t_n) + ka_{2,1}y_1(t_n), t_n + c_2k) \\ y_3(t_n) &= f(u(t_n) + ka_{3,1}y_1(t_n) + ka_{3,2}y_2(t_n), t_n + c_3k) \end{aligned}$$

那么 $\mathcal{L}u(t_n) = u(t_{n+1}) - u(t_n) - k(b_1y_1(t_n) + b_2y_2(t_n) + b_3y_3(t_n))$

将 $u(t_{n+1})$ 展开到 k^3 项, $y_1(t_n) + y_2(t_n) + y_3(t_n)$ 展开到 k^2 项, 并用 f 表示 $f(u(t_n), t_n)$, 其他同理, 得

$$\begin{aligned} u(t_{n+1}) &= u + ku' + \frac{k^2}{2}u'' + \frac{k^3}{6}u''' + O(k^4) \\ y_1(t_n) &= f \\ y_2(t_n) &= f + kc_2(f_u f + f_t) + \frac{k^2}{2}c_2^2(f_{uu}f^2 + 2f_{ut}f + f_{tt}) + O(k^3) \\ y_3(t_n) &= f + k(a_{3,1} + a_{3,2})(f_u f + f_t) \\ &\quad + k^2\left(\frac{1}{2}(a_{3,1} + a_{3,2})^2(f_{uu}f^2 + 2f_{ut}f + f_{tt}) + a_{3,2}c_2(f_u^2 f + f_u f_t)\right) + O(k^3) \end{aligned}$$

代回 $\mathcal{L}u(t_n)$ 得

$$\begin{aligned} \mathcal{L}u(t_n) &= k(1 - b_1 - b_2 - b_3)u' + k^2\left(\frac{1}{2} - b_2c_2 - b_3(a_{3,1} + a_{3,2})\right)u'' \\ &\quad + k^3\left(\frac{1}{6} - \frac{1}{2}b_2c_2^2 - \frac{1}{2}b_3(a_{3,1} + a_{3,2})^2\right)(f_{uu}f^2 + 2f_{ut}f + f_{tt}) \\ &\quad + k^3\left(\frac{1}{6} - b_3a_{3,2}c_2\right)(f_u^2 f + f_u f_t) + O(k^4) \end{aligned}$$

要达到三阶精度, 那么 k, k^2, k^3 的系数为 0 得到

$$\begin{cases} b_1 + b_2 + b_3 = 0 \\ b_2 c_2 + b_3 c_3 = \frac{1}{2} \\ b_2 c_2^2 + b_3 c_3^2 = \frac{1}{3} \\ b_3 a_{3,2} c_2 = \frac{1}{6} \end{cases}$$

四个方程六个未知量, 所以有两个自由参数, 设 $b_3 = \alpha$, $a_{3,2} = \beta$ 代入解得

$$\begin{cases} b_1 = -3\alpha\beta \mp \frac{\alpha}{2} \sqrt{48\alpha\beta^2 - 12\beta + 1} - \frac{\alpha}{2} + 1 \\ b_2 = 3\alpha\beta \pm \frac{\alpha}{2} \sqrt{48\alpha\beta^2 - 12\beta + 1} - \frac{\alpha}{2} \\ c_2 = \frac{1}{6\alpha\beta} \\ c_3 = \mp \frac{1}{12\alpha\beta} \sqrt{48\alpha\beta^2 - 12\beta + 1} + \frac{1}{12\alpha\beta} \end{cases}$$

将 $\beta = \frac{1}{4\alpha}$ 代入即得

$$\begin{cases} b_1 = \frac{1}{4} \\ b_2 = \frac{3}{4} - \alpha \\ b_3 = \alpha \\ a_{2,1} = c_2 = \frac{2}{3} \\ a_{3,1} = \frac{2}{3} - \frac{1}{4\alpha} \\ a_{3,2} = \frac{1}{4\alpha} \\ c_3 = \frac{2}{3} \end{cases}, \begin{cases} b_1 = \frac{1}{4} - \alpha \\ b_2 = \frac{3}{4} \\ b_3 = \alpha \\ a_{2,1} = c_2 = \frac{2}{3} \\ a_{3,1} = -\frac{1}{4\alpha} \\ a_{3,2} = \frac{1}{4\alpha} \\ c_3 = 0 \end{cases}$$

前面的即为所求的 family of third-order three-stage ERK

取 $\alpha = \frac{3}{4}$, 得 $a_{2,1} = \frac{2}{3}$, $a_{3,1} = a_{3,2} = \frac{1}{3}$, Heun's third-order formula 与其不符, 所以 Heun's third-order formula 不属于该 family

IV. Show that the quadrature formula of a RK method is exact for all polynomials f of degree $< r$, i.e.,

$$\forall f \in \mathcal{P}_{r-1}, \quad I_s(f) = \int_{t_n}^{t_n+k} f(t) dt,$$

if and only if the RK method is $B(r)$

Solution:

首先有 $\forall q \in \mathbb{N}$, $f(t) = t^q$

$$\begin{aligned} I(f) &= \int_{t_n}^{t_n+k} t^q dt \\ &= \frac{1}{q+1} t_n^{q+1} \Big|_{t_n}^{t_n+k} \\ &= \frac{1}{q+1} ((t_n+k)^{q+1} - t_n^{q+1}) \\ &= \frac{1}{q+1} \sum_{l=1}^{q+1} C_{q+1}^l k^l t_n^{q+1-l} \end{aligned}$$

以及

$$\begin{aligned}
 I_s(f) &= k \sum_{j=1}^s b_j (t_n + c_j k)^q \\
 &= k \sum_{j=1}^s b_j \sum_{l=0}^q C_q^l c_j^l k^l t_n^{q-l} \\
 &= \sum_{l=0}^q \left(\sum_{j=1}^s b_j c_j^l \right) C_q^l k^{l+1} t_n^{q-l} \\
 &= \sum_{l=1}^{q+1} \left(\sum_{j=1}^s b_j c_j^{l-1} \right) C_q^{l-1} k^l t_n^{q+1-l} \\
 &= \frac{1}{q+1} \sum_{l=1}^{q+1} \left(\sum_{j=1}^s b_j c_j^{l-1} \right) l C_{q+1}^l k^l t_n^{q+1-l}
 \end{aligned}$$

必要性:

quadrature formula 对于阶数小于 r 多项式严格成立, 那么 $\forall q \in \mathbb{N}, q < r, f(t) = t^q, I(f) = I_s(f)$
依次取 $q = 0, 1, 2, \dots, r-1$, 代入上面得式子就能得到

$$\forall l = 1, 2, \dots, r, \left(\sum_{j=1}^s b_j c_j^{l-1} \right) l = 1 \Rightarrow \sum_{j=1}^s b_j c_j^{l-1} = \frac{1}{l}$$

所以 RK method 是 $B(r)$

充分性:

RK method 是 $B(r)$, 那么有

$$\forall l = 1, 2, \dots, r, \sum_{j=1}^s b_j c_j^{l-1} = \frac{1}{l}$$

就可以得到 $\forall q \in \mathbb{N}, q < r, f(t) = t^q, I(f) = I_s(f)$

那么 $\forall f \in \mathbb{P}_{r-1}, f(t) = \sum_{i=0}^{r-1} a_i t^i$, 也成立 $I(f) = I_s(f)$

V. Show that an s-stage collocation method is at least s-order accurate

Solution:

设 s 阶插值节点为 $t_n, t_n + c_1 k, t_n + c_2 k, \dots, t_n + c_s k$ 的插值多项式 $p(t)$ 满足

$$\begin{cases} p(t_n) = u(t_n) \\ \forall i = 1, 2, \dots, s, \quad p'(t_n^{(i)}) = f(p(t_n^{(i)}), t_n^{(i)}) = u'(t_n^{(i)}) \end{cases}, \text{ where } t_n^{(i)} = t_n + c_i k$$

那么

$$u(t_n) + k\Phi(u(t_n), t_n; k) = p(t_{n+1})$$

所以

$$\begin{aligned}
 \mathcal{L}u(t_n) &= u(t_{n+1}) - u(t_n) - k\Phi(u(t_n), t_n; k) \\
 &= u(t_{n+1}) - p(t_{n+1}) \\
 &= R_s(u; t_{n+1}) \\
 &= \frac{u^{(s+1)}(\xi)}{(s+1)!} ((t_n + k) - t_n) \prod_{i=1}^s ((t_n + k) - (t_n + c_i k)) \\
 &= \frac{u^{(s+1)}(\xi)}{(s+1)!} (\prod_{i=1}^s (1 - c_i)) k^{s+1}
 \end{aligned}$$

所以 s-stage collocation method 至少是 s 阶精度的

VI. Prove that the collocation method viewed as an RK method satisfies

$$c_i = \sum_{j=1}^s a_{i,j}, \quad i = 1, 2, \dots, s \quad \text{and} \quad \sum_{i=1}^s b_i = 1$$

Solution:

Lagrange 插值多项式基函数 $\ell_j(\tau) = \prod_{i \neq j; i=1}^s \frac{\tau - c_i}{c_j - c_i}$ 满足 $\sum_{j=1}^s \ell_j(\tau) = 1$

$$\begin{aligned}
 \forall i = 1, 2, \dots, s, \quad \sum_{j=1}^s a_{i,j} &= \sum_{j=1}^s \int_0^{c_i} \ell_j(\tau) d\tau = \int_0^{c_i} \sum_{j=1}^s \ell_j(\tau) d\tau = \int_0^{c_i} 1 d\tau = c_i \\
 \sum_{j=1}^s b_j &= \sum_{j=1}^s \int_0^1 \ell_j(\tau) d\tau = \int_0^1 \sum_{j=1}^s \ell_j(\tau) d\tau = \int_0^1 1 d\tau = 1
 \end{aligned}$$

VII. Derive the three-stage IRK method that corresponds to the collocation points $c_1 = \frac{1}{4}$, $c_2 = \frac{1}{2}$, $c_3 = \frac{3}{4}$

Solution:

对于所给节点 $c_1 = \frac{1}{4}$, $c_2 = \frac{1}{2}$, $c_3 = \frac{3}{4}$, 有

$$\ell_1(\tau) = \frac{\tau - \frac{1}{2}}{\frac{1}{4} - \frac{1}{2}} \frac{\tau - \frac{3}{4}}{\frac{1}{4} - \frac{3}{4}} = 8\tau^2 - 10\tau + 3$$

$$\ell_2(\tau) = \frac{\tau - \frac{1}{4}}{\frac{1}{2} - \frac{1}{4}} \frac{\tau - \frac{3}{4}}{\frac{1}{2} - \frac{3}{4}} = -16\tau^2 + 16\tau - 3$$

$$\ell_3(\tau) = \frac{\tau - \frac{1}{4}}{\frac{3}{4} - \frac{1}{4}} \frac{\tau - \frac{1}{2}}{\frac{3}{4} - \frac{1}{2}} = 8\tau^2 - 6\tau + 1$$

所以

$$\begin{aligned}
 a_{1,1} &= \int_0^{\frac{1}{4}} \ell_1(\tau) d\tau = \frac{23}{48}, \quad a_{1,2} = \int_0^{\frac{1}{4}} \ell_2(\tau) d\tau = -\frac{1}{3}, \quad a_{1,3} = \int_0^{\frac{1}{4}} \ell_3(\tau) d\tau = \frac{5}{48} \\
 a_{2,1} &= \int_0^{\frac{1}{2}} \ell_1(\tau) d\tau = \frac{7}{12}, \quad a_{2,2} = \int_0^{\frac{1}{2}} \ell_2(\tau) d\tau = -\frac{1}{6}, \quad a_{2,3} = \int_0^{\frac{1}{2}} \ell_3(\tau) d\tau = \frac{1}{12}
 \end{aligned}$$

$$a_{3,1} = \int_0^{\frac{3}{4}} \ell_1(\tau) d\tau = \frac{9}{16}, \quad a_{3,2} = \int_0^{\frac{3}{4}} \ell_2(\tau) d\tau = 0, \quad a_{3,3} = \int_0^{\frac{3}{4}} \ell_3(\tau) d\tau = \frac{3}{16}$$

$$b_1 = \int_0^1 \ell_1(\tau) d\tau = \frac{2}{3}, \quad b_2 = \int_0^1 \ell_2(\tau) d\tau = -\frac{1}{3}, \quad b_3 = \int_0^1 \ell_3(\tau) d\tau = \frac{2}{3}$$

所以其对应的 three-stage IRK method 的 Butcher tubeau 为

$\frac{1}{4}$	$\frac{23}{48}$	$-\frac{1}{3}$	$\frac{5}{48}$
$\frac{1}{2}$	$\frac{7}{12}$	$-\frac{1}{6}$	$\frac{1}{12}$
$\frac{3}{4}$	$\frac{9}{16}$	0	$\frac{3}{16}$
	$\frac{2}{3}$	$-\frac{1}{3}$	$\frac{2}{3}$

VIII. Show $B(s+r)$ and $C(s)$ imply $D(r)$ via multiplying the two vectors $u_j := \sum_{i=1}^s b_i c_i^{m-1} a_{i,j}$ and $v_j := \frac{1}{m} b_j (1 - c_j^m)$ by the Vandermonde matrix $V(c_1, c_2, \dots, c_s)$ in Definition 2.3.

Solution:

由 $B(s+r)$ 和 $C(r)$ 可知

$$\forall m = 1, 2, \dots, s+r, \quad s.t. \sum_{j=1}^s b_j c_j^{m-1} = \frac{1}{m}$$

$$\left\{ \begin{array}{l} \forall i = 1, 2, \dots, s, \\ \forall m = 1, 2, \dots, s, \end{array} \quad s.t. \sum_{j=1}^s a_{i,j} c_j^{m-1} = \frac{c_i^m}{m} \right.$$

$$\text{设 } \mathbf{u} := \left[\sum_{j=1}^s b_j c_j^{m-1} a_{j,1}, \sum_{j=1}^s b_j c_j^{m-1} a_{j,2}, \dots, \sum_{j=1}^s b_j c_j^{m-1} a_{j,s} \right]^T$$

$$\text{以及 } \mathbf{v} := \left[\frac{1}{m} b_1 (1 - c_1^m), \frac{1}{m} b_2 (1 - c_2^m), \frac{1}{m} b_2 (1 - c_2^m) \right]^T$$

那么

$$\begin{aligned} (V(c_1, c_2, \dots, c_s) \mathbf{u})_i &= \sum_{k=1}^s c_k^{i-1} \sum_{j=1}^s b_j c_j^{m-1} a_{j,k} \\ &= \sum_{j=1}^s b_j c_j^{m-1} \sum_{k=1}^s c_k^{i-1} a_{j,k} \\ &= \sum_{j=1}^s b_j c_j^{m-1} \frac{c_j^i}{i} \\ &= \frac{1}{i} \sum_{j=1}^s b_j c_j^{i+m-1} \\ &= \frac{1}{i(i+m)} \end{aligned}$$

而

$$\begin{aligned}
 (V(c_1, c_2, \dots, c_s)\mathbf{v})_i &= \sum_{j=1}^s c_j^{i-1} \frac{1}{m} b_j (1 - c_j^m) \\
 &= \frac{1}{m} \left(\sum_{j=1}^s b_j c_j^{i-1} - \sum_{j=1}^s b_j c_j^{i+m-1} \right) \\
 &= \frac{1}{im} - \frac{1}{(i+m)m} \\
 &= \frac{1}{i(i+m)}
 \end{aligned}$$

所以

$$V(c_1, c_2, \dots, c_s)\mathbf{u} = V(c_1, c_2, \dots, c_s)\mathbf{v} \Leftrightarrow V(c_1, c_2, \dots, c_s)(\mathbf{u} - \mathbf{v}) = \mathbf{0}$$

因为 $V(c_1, c_2, \dots, c_s)$ 满秩, 只有 0 解, 所以 $\mathbf{u} = \mathbf{v}$

又因为上面的等式只对 $\forall m, i = 1, 2, \dots, s, i+m \leq s+r$ 成立, 所以 $m = 1, 2, \dots, r$

$$\Rightarrow \begin{cases} \forall i = 1, 2, \dots, s, & \sum_{j=1}^s b_j c_j^{m-1} a_{j,i} = \frac{b_i}{m} (1 - c_i^m) \\ \forall m = 1, 2, \dots, r, & \end{cases}$$

IX. Determine the order of accuracy of the collocation method in Exercise 10.213

Solution:

由 Exercise 10.213 可知其 Butcher tableau 为

$\frac{1}{4}$	$\frac{23}{48}$	$-\frac{1}{3}$	$\frac{5}{48}$
$\frac{1}{2}$	$\frac{7}{12}$	$-\frac{1}{6}$	$\frac{1}{12}$
$\frac{3}{4}$	$\frac{9}{16}$	0	$\frac{3}{16}$
	$\frac{2}{3}$	$-\frac{1}{3}$	$\frac{2}{3}$

取 $l = 1, 2, 3, 4, 5$ 可得

$$\begin{aligned}
 \sum_{j=1}^s b_j c_j^0 &= 1 \\
 \sum_{j=1}^s b_j c_j^1 &= \frac{1}{2} \\
 \sum_{j=1}^s b_j c_j^2 &= \frac{1}{3} \\
 \sum_{j=1}^s b_j c_j^3 &= \frac{1}{4} \\
 \sum_{j=1}^s b_j c_j^4 &= \frac{37}{192} \neq \frac{1}{5}
 \end{aligned}$$

可知该方法是 $B(4)$ 但是不是 $B(5)$ 的

由 RK order conditions 可知, 若 RK method 是 p 阶精度的, 那么一定是 $B(p)$ 的 (取 $m = 0$)

所以该方法最多为 4 阶精度

下面将验证该方法是 $C(3)$ 的, 取 $m = 1, 2, 3$

• $m = 1$ 时, $\sum_{j=1}^s a_{i,j} = c_i$ 成立

• $m = 2$ 时,

$$i = 1, a_{1,1}c_1 + a_{1,2}c_2 + a_{1,3}c_3 = \frac{1}{32} = \frac{c_1^2}{2}$$

$$i = 2, a_{2,1}c_1 + a_{2,2}c_2 + a_{2,3}c_3 = \frac{1}{8} = \frac{c_2^2}{2}$$

$$i = 3, a_{3,1}c_1 + a_{3,2}c_2 + a_{3,3}c_3 = \frac{9}{32} = \frac{c_3^2}{2}$$

• $m = 3$ 时,

$$i = 1, a_{1,1}c_1^2 + a_{1,2}c_2^2 + a_{1,3}c_3^2 = \frac{1}{192} = \frac{c_1^3}{3}$$

$$i = 2, a_{2,1}c_1^2 + a_{2,2}c_2^2 + a_{2,3}c_3^2 = \frac{1}{24} = \frac{c_2^3}{3}$$

$$i = 3, a_{3,1}c_1^2 + a_{3,2}c_2^2 + a_{3,3}c_3^2 = \frac{9}{64} = \frac{c_3^3}{3}$$

所以该方法是 $C(3)$ 的, 所以该方法是 $D(1)$ 的

又由 $4 \leq 2 * 3 + 2$ 以及 $4 \leq 1 + 3 + 1$ 可知该方法至少为 4 阶精度

综上所述, 该方法是 4 阶精度的