

# Fundamentals



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# Overview

- Describe three main notation systems for describing social networks
- Introduce basic concepts in graph theory
  - Important building blocks for subsequent concepts and methods



Nodes and edges

# STARTING DEFINITIONS



# Actor/Node/Vertex

- Social entity that may be linked to other social entities
- Not limited to persons, may be organizations, political entities, animals, etc.
- 'Vertex' comes from graph theory; 'Node' used more often in social network analysis



# Relation/Link/Edge/Arc

- Any type of social tie that links two actors
- Two types of relations
  - Directional - indicates transmission or flow from one node to another
  - Non-directional - indicates the existence of connection or relationship between two nodes



Multiple ways to describe networks

# NOTATION



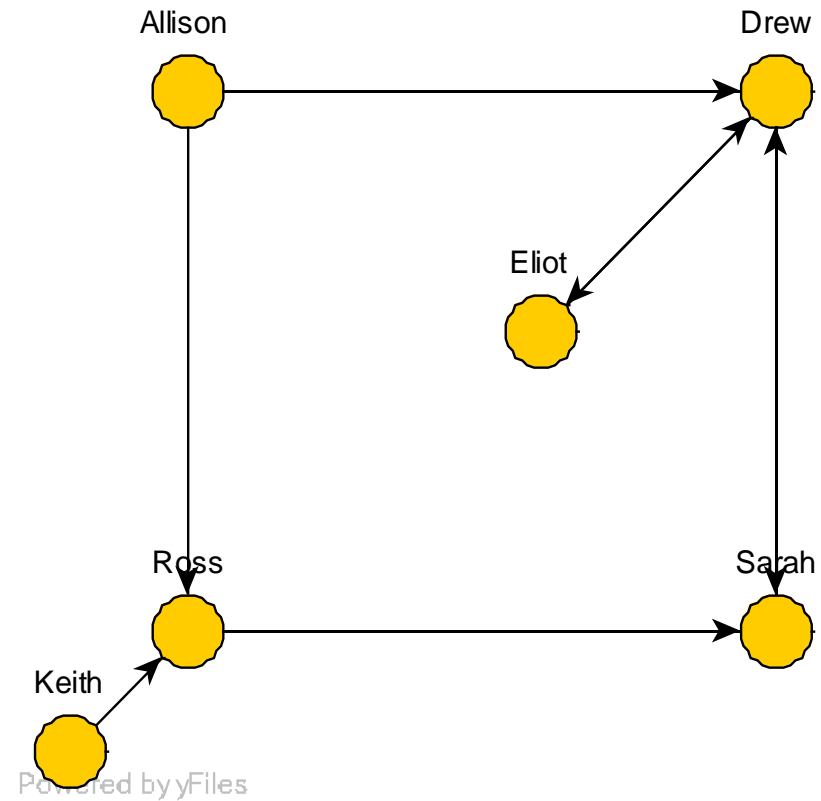
# Multiple ways to describe networks

- Interrelated--All approaches describe the same network
  - Graph theoretic
  - Sociometric
  - Algebra/Set theory
  - Edge list
- Some approaches are more conducive to certain types of operations on the networks than others
  - Calculations
  - Storage
  - Transformations



# Graph theoretic

- Basic way to present actors and relations
- A graph consists of nodes joined by lines
- Example (W&F, Fig. 3.1)





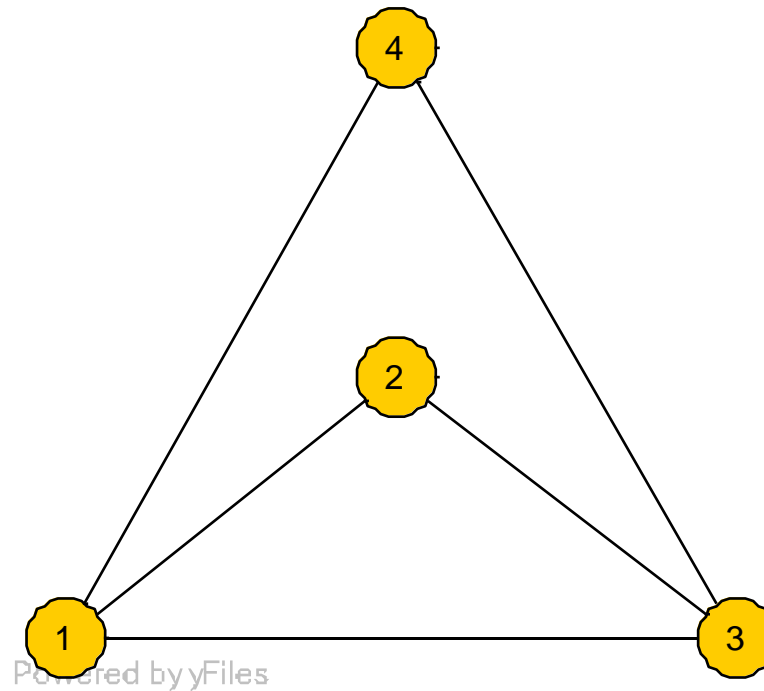
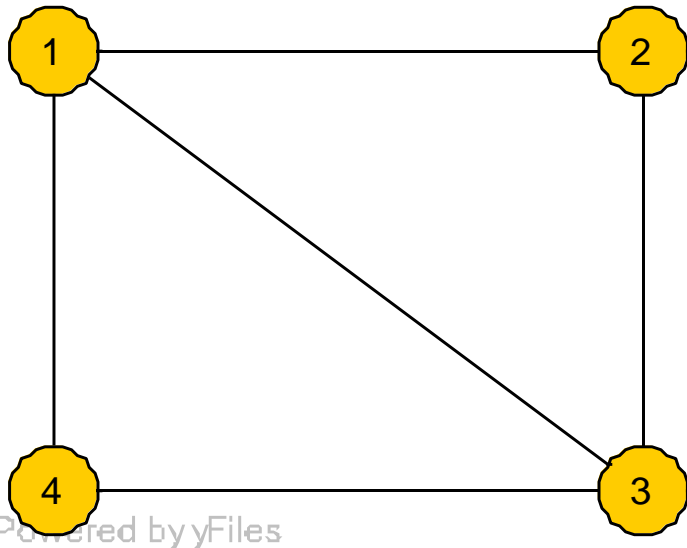
# Graph theoretic - details

- Two types of lines:
  - *Arcs* - lines connecting an ordered pair of actors. An arc is a directional line
  - *Edges* - lines connecting an unordered pair of actors. An edge is a non-directional line
- If a graph contains arcs, then it is called a directed graph, or a *digraph*
- If lines have values (other than 1), then the graph is called a *valued* graph
- Useful for centrality, prestige, subgroups



# Graph theoretic - caution

- Important - be careful when visually interpreting a graph. There are many equivalent ways of displaying exactly the same graph:



# Sociometric

- A data set that contains the relations among a set of actors is called *sociometric*.
- Sociometric data can be stored (and displayed) in a sociomatrix
- A one-mode network can use a square sociomatrix where the rows and columns represent the actors
- Useful for computer algorithms, structural equivalence



# Sociometric - continued

- The rows represent the sending actors, the columns represent the receiving actors (...*from* the row, *to* the column...)
- The cells of the matrix store the relational values
- $X_{ij}$  = the value of the tie from  $n_i$  to  $n_j$



# Sociometric - example

	Allison	Drew	Eliot	Keith	Ross	Sarah
Allison	-	1	0	0	1	0
Drew	0	-	1	0	0	1
Eliot	0	1	-	0	0	0
Keith	0	0	0	-	1	0
Ross	0	0	0	0	-	1
Sarah	0	1	0	0	0	-



# Algebraic/Set theoretic

- Uses *set theory* notation
  - $N = \{n_1, n_2, \dots, n_g\} = \{\text{Allison}, \text{Drew}, \dots, \text{Sarah}\}$
  - $L = \{l_1, l_2, \dots, l_L\} = \{(\text{Allison}, \text{Drew}), (\text{Allison}, \text{Ross}), \dots, (\text{Sarah}, \text{Drew})\}$
  - $G = \{N, L\}$
- Useful for multiple relations, developing more formal mathematical foundations of network methods (e.g., generalized blockmodels)



# Edge list

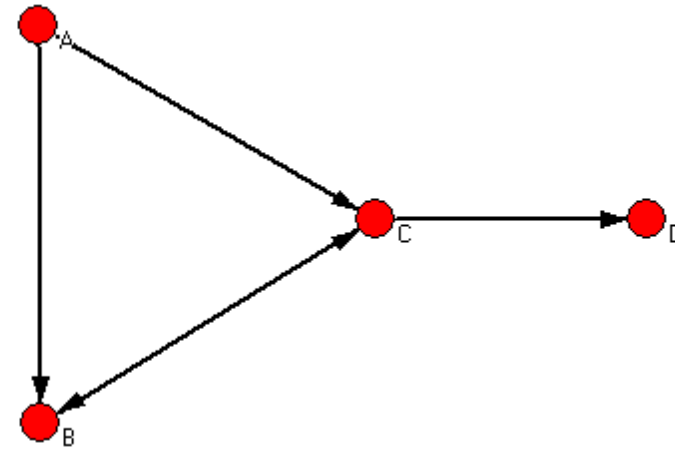
- Can specify a complete network with a list of network edges
- Example:
  - Allison-Drew
  - Allison-Ross
  - Drew-Eliot
  - Drew-Sarah
  - Keith-Ross
  - Ross-Sarah
- Useful for efficient storage of very large networks



# Network-data equivalency

	A	B	C	D
A		1	1	0
B	0		1	0
C	0	1		1
D	0	0	0	

Sociomatrix

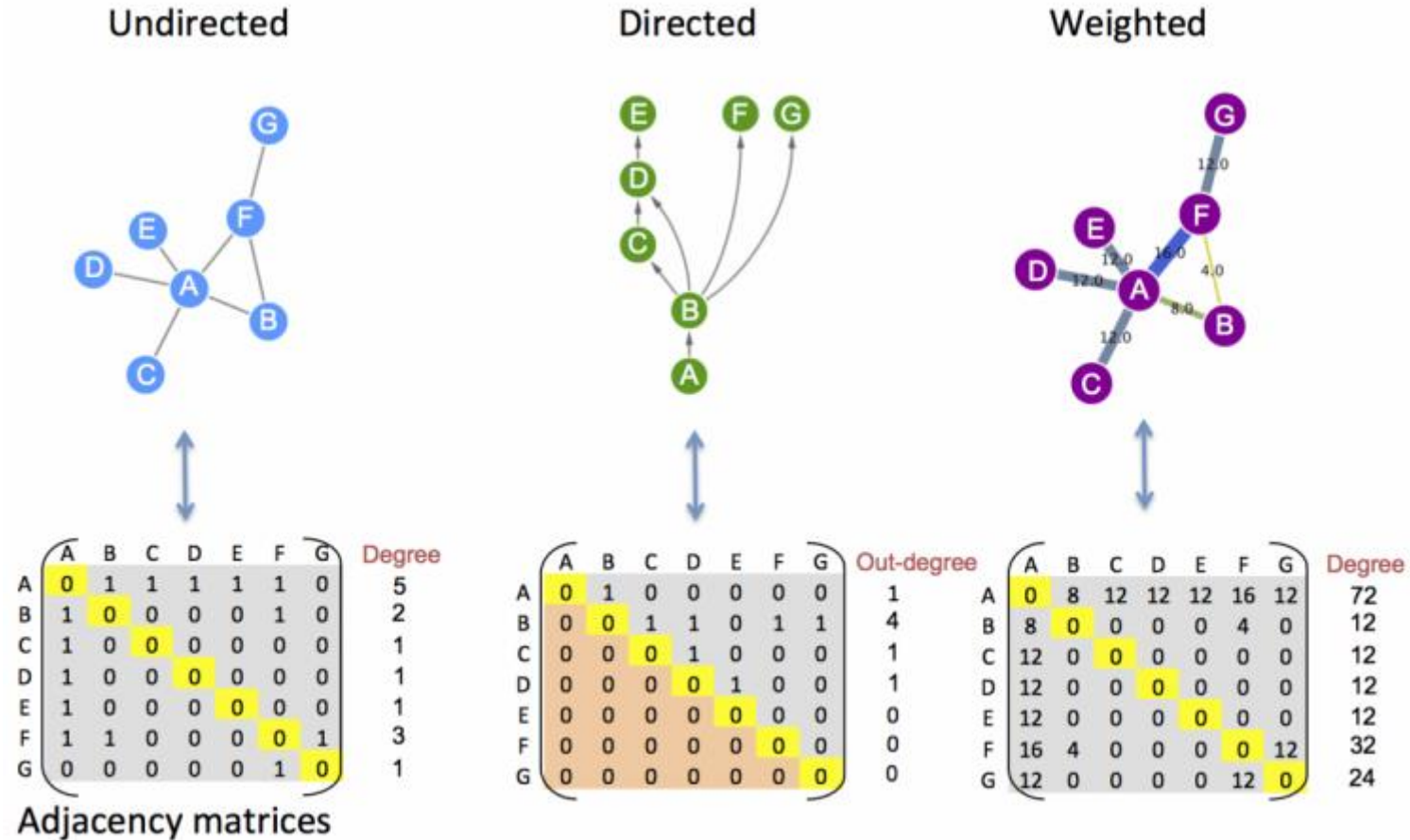


Graph





# Graph types and sociomatrices



Building blocks for understanding network depiction and characteristics

# GRAPH THEORY



# Non-directed graphs

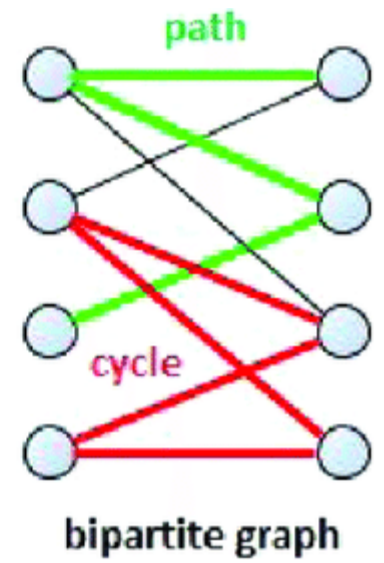
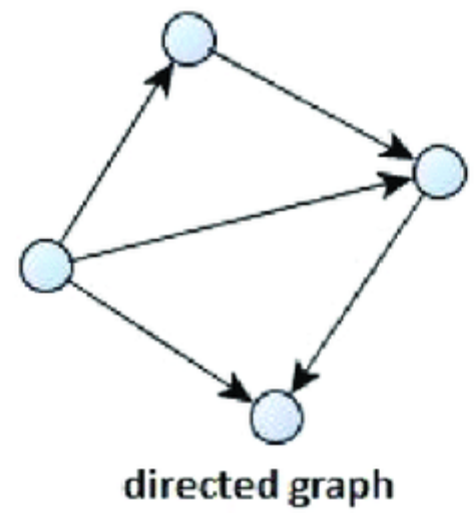
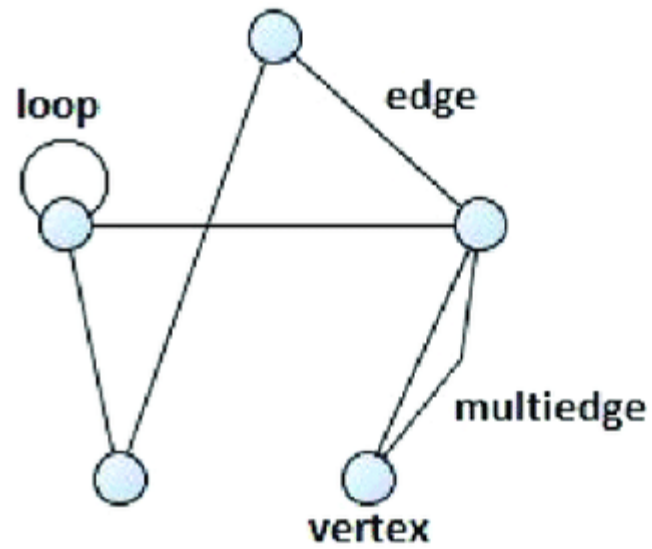
Edge	<ul style="list-style-type: none"><li>• line connecting two nodes (non-directed)</li></ul>
Loop	<ul style="list-style-type: none"><li>• line connecting a node to itself (often not allowed)</li></ul>
Simple graph	<ul style="list-style-type: none"><li>• no loops, and no more than one line between any pair of nodes</li></ul>
Adjacent	<ul style="list-style-type: none"><li>• adjacent nodes have a line connecting them</li></ul>
Incident	<ul style="list-style-type: none"><li>• a line connected to a node is incident to it</li></ul>
Complete	<ul style="list-style-type: none"><li>• all possible lines are present</li></ul>
Dyad	<ul style="list-style-type: none"><li>• two nodes, possibly connected</li></ul>
Triad	<ul style="list-style-type: none"><li>• three nodes, and their possible lines</li></ul>
Subgraph	<ul style="list-style-type: none"><li>• a subset of a graph, obtained by taking either a subset of the nodes or the lines of the graph</li></ul>



# Non-directed graph connections

Degree	<ul style="list-style-type: none"><li>• number of lines incident to a node</li></ul>
Walk	<ul style="list-style-type: none"><li>• sequence of nodes and lines in which each node is incident with the lines preceding it and following it in the walk</li></ul>
Length	<ul style="list-style-type: none"><li>• length of a walk is the number of lines in it</li></ul>
Path	<ul style="list-style-type: none"><li>• a walk in which all lines and nodes are distinct</li></ul>
Reachable	<ul style="list-style-type: none"><li>• if a path exists between two nodes A and B, then A and B are reachable</li></ul>
Closed walk	<ul style="list-style-type: none"><li>• walk that begins and ends at the same node</li></ul>
Cycle	<ul style="list-style-type: none"><li>• closed walk where all lines and nodes (except the first) are distinct</li></ul>
Connected graph	<ul style="list-style-type: none"><li>• a connected graph has a path between every pair of nodes</li></ul>
Component	<ul style="list-style-type: none"><li>• a maximally connected subgraph</li></ul>





# Non-directed graph connections

<b>Component</b>	<ul style="list-style-type: none"><li>• a maximally connected subgraph</li></ul>
<b>Cutpoint</b>	<ul style="list-style-type: none"><li>• a node that, if removed, would create additional components</li></ul>
<b>Bridge</b>	<ul style="list-style-type: none"><li>• a line that, if removed, would create additional components</li></ul>
<b>Density</b>	<ul style="list-style-type: none"><li>• in a graph (or subgraph), the proportion of observed ties to maximum possible number of ties</li></ul>



# Non-directed graph distances

Geodesic	• shortest path between two nodes
Distance	• length of the geodesic
Diameter	• the diameter of a connected graph is the largest geodesic distance between any pair of nodes (i.e., the longest, shortest path!)



# Directed graphs

<b>Arc</b>	<ul style="list-style-type: none"><li>• directed line connecting two nodes</li></ul>
<b>Indegree</b>	<ul style="list-style-type: none"><li>• number of arcs terminating at a particular node</li></ul>
<b>Outdegree</b>	<ul style="list-style-type: none"><li>• number of arcs originating at a particular node</li></ul>
<b>Directed walk</b>	<ul style="list-style-type: none"><li>• sequence of nodes and arcs, following the direction of the arcs</li></ul>
<b>Directed path</b>	<ul style="list-style-type: none"><li>• a directed walk with no repeating segments</li></ul>
<b>Semipath, semiwalk</b>	<ul style="list-style-type: none"><li>• removes the restriction of following the arcs in their normal directions</li></ul>
<b>Reachable</b>	<ul style="list-style-type: none"><li>• if there is a directed path from A to B, then B is reachable from A</li></ul>
<b>Others</b>	<ul style="list-style-type: none"><li>• digraphs lead to more complicated definitions of connectivity, geodesics, distance, diameter, etc. See W&amp;F, pp. 132-134</li></ul>





# Familiar network



# Simpsons - size & density

