МИНИСТЕРСТВО НАУКИ И ВЫСШЕГО ОБРАЗОВАНИЯ РФ

Федеральное государственное бюджетное образовательное учреждение высшего образования «Московский Авиационный Институт» (Национальный Исследовательский Университет)

Институт: №8 «Информационные технологии и прикладная математика» Кафедра: 806 «Вычислительная математика и программирование»

Лабораторная работа № 7 по курсу «Численные методы»

Группа: М8О-407Б-21

Студент: Дубровин Д. К.

Преподаватель: Ю.В. Сластушенский

Оценка:

Дата: 24.12.2024

Вариант 7:

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = -2u,\tag{1}$$

$$U(0,y) = \cos(y), \tag{2}$$

$$U(\frac{\pi}{2}, y) = 0, (3)$$

$$U(x,0) = \cos(x), \tag{4}$$

$$U(x, \frac{\pi}{2}) = 0 \tag{5}$$

Аналитическое решение:

$$U(x,y) = \cos(x) \cdot \cos(y) \tag{6}$$

```
In [1]: import numpy as np
import matplotlib.pyplot as plt
```

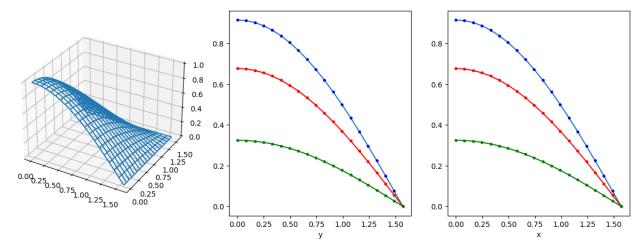
```
In [2]: def U0y(y: float):
             return np.cos(y)
        def Ux0(x: float):
             return np.cos(x)
        def Uly(y: float):
             return 0
        def Uxl(x: float):
             return 0
        def f(x:float, y:float):
             return 0
        def Uans(x:float, y:float):
             return np.cos(x)*np.cos(y)
        c = -2
        startx = 0
        starty = 0
        finishx = np.pi / 2
        finishy = np.pi / 2
        kx = 20
        ky = 20
        hx = (finishx - startx) / (kx - 1)
        hy = (finishy - starty) / (ky - 1)
        xs = np.linspace(startx, finishx, kx)
        ys = np.linspace(starty, finishy, ky)
        xgrid, ygrid = np.meshgrid(xs, ys)
        zans = np.zeros((kx, ky), dtype=np.float64)
        for i, x in enumerate(xs):
            for j, y in enumerate(ys):
                 zans[i][j] = Uans(x,y)
```

```
In [3]: answer_lib = np.zeros((kx, ky), dtype=np.float64)
         cur_step = np.zeros((kx, ky), dtype=np.float64)
         for i, y in enumerate(ys):
             cur_step[0][i] = U0y(y)
             cur_step[-1][i] = Uly(y)
         for i, x in enumerate(xs):
             cur\_step[i][0] = Ux0(x)
             cur_step[i][-1] = Uxl(x)
         for i in range(1, kx - 1):
             coef = (cur\_step[i][-1] - cur\_step[i][0]) / (ys[-1] - ys[0])
             for j in range(1, ky - 1):
                 \operatorname{cur\_step}[i][j] = \operatorname{cur\_step}[i][0] + \operatorname{coef}*(ys[j] - ys[0])
         next_step = np.array(cur_step, copy=True)
In [4]: def get_error(cur_step, next_step):
             return np.max(np.abs(next_step - cur_step))
In [5]: error = 1 * 10**(-5)
         count = 0
         while True:
             cur_step = np.array(next_step)
             for i in range(1, kx - 1):
                 for j in range(1, ky - 1):
                     next_step[i][j] = (
                         hx**2 * cur_step[i+1][j]
                         + hx**2 * cur_step[i-1][j]
                         + hy**2 * cur_step[i][j+1]
                         + hy**2 * cur_step[i][j-1]
                         - f(xs[i], ys[j]) * hx**2 * hy**2
                     ) / (2 * (hx**2 + hy**2) + hx**2 * hy**2 * c)
             count += 1
             if get_error(cur_step, next_step) < error:</pre>
                 break
         print("Conut iterations: {iterations}".format(iterations = count))
         answer_lib = np.array(next_step)
         plt.rcParams['figure.figsize'] = [15, 5]
         fig = plt.figure()
         ax_3d = fig.add_subplot(1,3,1, projection='3d')
         ax_3d.plot_wireframe(xgrid, ygrid, answer_lib.transpose())
         axx = fig.add subplot(1,3,2)
         axx.plot(ys, answer_lib[kx // 4])
         axx.plot(ys, zans[kx // 4], '.b')
         axx.plot(ys, answer_lib[kx // 4 * 2], 'r')
         axx.plot(ys, zans[kx // 4 * 2], '.r')
         axx.plot(ys, answer_lib[kx // 4 * 3], 'q')
         axx.plot(ys, zans[kx // 4 * 3], '.g')
         plt.xlabel('y')
         axy = fig.add_subplot(1,3,3)
         axy.plot(xs, answer_lib[:, ky // 4])
         axy.plot(xs, zans[:, ky // 4], '.b')
```

```
axy.plot(xs, answer_lib[:, ky // 4 * 2], 'r')
axy.plot(xs, zans[:, ky // 4 * 2], '.r')
axy.plot(xs, answer_lib[:, ky // 4 * 3], 'g')
axy.plot(xs, zans[:, ky // 4 * 3], '.g')
plt.xlabel('x')
```

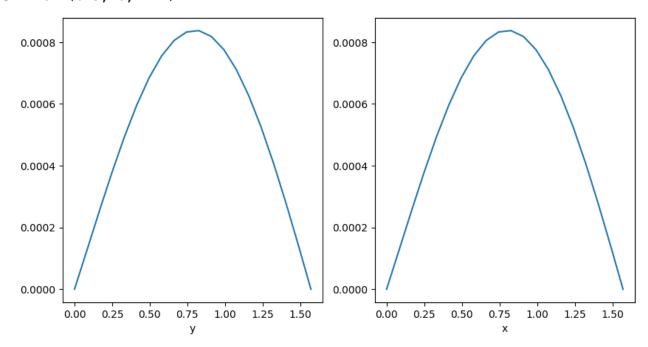
Conut iterations: 507

Out[5]: Text(0.5, 0, 'x')



```
In [6]: plt.rcParams['figure.figsize'] = [10, 5]
    plt.subplot (1, 2, 1)
    plt.plot(ys, np.max(np.abs(answer_lib - zans), axis=0))
    plt.xlabel('y')
    plt.subplot (1, 2, 2)
    plt.plot(xs, np.max(np.abs(answer_lib - zans), axis=1))
    plt.xlabel('x')
```

Out[6]: Text(0.5, 0, 'x')



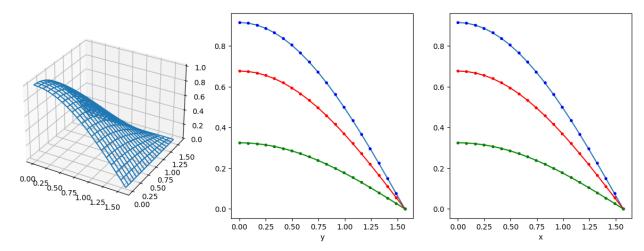
Итерационный метод с релаксацией

```
In [7]: answer_relax = np.zeros((kx, ky), dtype=np.float64)
    relax_coef = 0.5
    cur_step = np.zeros((kx, ky), dtype=np.float64)
```

```
for i, y in enumerate(ys):
            cur_step[0][i] = U0y(y)
            cur_step[-1][i] = Uly(y)
        for i, x in enumerate(xs):
            cur step[i][0] = Ux0(x)
             cur_step[i][-1] = Uxl(x)
        for i in range(1, kx - 1):
            coef = (cur\_step[i][-1] - cur\_step[i][0]) / (ys[-1] - ys[0])
            for j in range(1, ky - 1):
                 cur\_step[i][j] = cur\_step[i][0] + coef*(ys[j] - ys[0])
        next_step = np.array(cur_step, copy=True)
In [8]: error = 1 * 10**(-5)
        count = 0
        while True:
             cur_step = np.array(next_step)*relax_coef + (1 - relax_coef)*cur_step
            for i in range(1, kx - 1):
                 for j in range(1, ky - 1):
                     next_step[i][j] = (
                         hx**2 * cur_step[i+1][j]
                         + hx**2 * cur_step[i-1][j]
                         + hy**2 * cur step[i][j+1]
                         + hy**2 * cur_step[i][j-1]
                         - f(xs[i], ys[j]) * hx**2 * hy**2
                     ) / (2 * (hx**2 + hy**2) + hx**2 * hy**2 * c)
            count += 1
            if get_error(cur_step, next_step) < error:</pre>
        print("Conut iterations: {iterations}".format(iterations = count))
        answer_relax = np.array(next_step)
        plt.rcParams['figure.figsize'] = [15, 5]
        fig = plt.figure()
        ax 3d = fig.add subplot(1,3,1, projection='3d')
        ax_3d.plot_wireframe(xgrid, ygrid, answer_relax.transpose())
        axx = fig.add_subplot(1,3,2)
        axx.plot(ys, answer_relax[kx // 4])
        axx.plot(ys, zans[kx // 4], '.b')
        axx.plot(ys, answer_relax[kx // 4 * 2], 'r')
        axx.plot(ys, zans[kx // 4 * 2], '.r')
        axx.plot(ys, answer relax[kx // 4 * 3], 'g')
        axx.plot(ys, zans[kx // 4 * 3], '.g')
        plt.xlabel('y')
        axy = fig.add_subplot(1,3,3)
        axy.plot(xs, answer_relax[:, ky // 4])
        axy.plot(xs, zans[:, ky // 4], '.b')
        axy.plot(xs, answer_relax[:, ky // 4 * 2], 'r')
        axy.plot(xs, zans[:, ky // 4 * 2], '.r')
        axy.plot(xs, answer_relax[:, ky // 4 * 3], 'g')
        axy.plot(xs, zans[:, ky // 4 * 3], '.g')
        plt.xlabel('x')
```

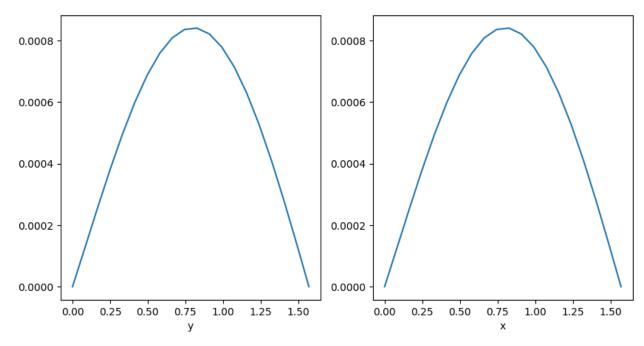
Conut iterations: 1015

```
Out[8]: Text(0.5, 0, 'x')
```



```
In [9]: plt.rcParams['figure.figsize'] = [10, 5]
    plt.subplot (1, 2, 1)
    plt.plot(ys, np.max(np.abs(answer_relax - zans), axis=0))
    plt.xlabel('y')
    plt.subplot (1, 2, 2)
    plt.plot(xs, np.max(np.abs(answer_relax - zans), axis=1))
    plt.xlabel('x')
```

Out[9]: Text(0.5, 0, 'x')



Метод Зейделя

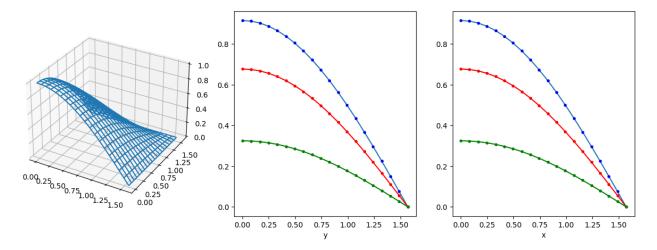
```
In [10]: answer_zeydel = np.zeros((kx, ky), dtype=np.float64)
    cur_step = np.zeros((kx, ky), dtype=np.float64)

for i, y in enumerate(ys):
        cur_step[0][i] = U0y(y)
        cur_step[-1][i] = Uly(y)

for i, x in enumerate(xs):
        cur_step[i][0] = Ux0(x)
```

```
cur_step[i][-1] = Uxl(x)
         for i in range(1, kx - 1):
             coef = (cur\_step[i][-1] - cur\_step[i][0]) / (ys[-1] - ys[0])
             for j in range(1, ky - 1):
                 cur step[i][j] = cur step[i][0] + coef*(ys[j] - ys[0])
         next_step = np.array(cur_step, copy=True)
In [11]: error = 1 * 10**(-5)
         count = 0
         while True:
             cur step = np.array(next step)
             for i in range(1, kx - 1):
                 for j in range(1, ky - 1):
                      next_step[i][j] = (
                          hx**2 * cur_step[i+1][i]
                          + hx**2 * next step[i-1][j]
                          + hy**2 * cur_step[i][j+1]
                          + hy**2 * next_step[i][j-1]
                          - f(xs[i], ys[j]) * hx**2 * hy**2
                      ) / (2 * (hx**2 + hy**2) + hx**2 * hy**2 * c)
             count += 1
             if get_error(cur_step, next_step) < error:</pre>
                 break
         print("Conut iterations: {iterations}".format(iterations = count))
         answer_zeydel = np.array(next_step)
         plt.rcParams['figure.figsize'] = [15, 5]
         fig = plt.figure()
         ax_3d = fig.add_subplot(1,3,1, projection='3d')
         ax_3d.plot_wireframe(xgrid, ygrid, answer_zeydel.transpose())
         axx = fig.add_subplot(1,3,2)
         axx.plot(ys, answer_zeydel[kx // 4])
         axx.plot(ys, zans[kx // 4], '.b')
         axx.plot(ys, answer_zeydel[kx // 4 * 2], 'r')
         axx.plot(ys, zans[kx // 4 * 2], '.r')
         axx.plot(ys, answer_zeydel[kx // 4 * 3], 'g')
         axx.plot(ys, zans[kx // 4 * 3], '.g')
         plt.xlabel('y')
         axy = fig.add_subplot(1,3,3)
         axy.plot(xs, answer_zeydel[:, ky // 4])
         axy.plot(xs, zans[:, ky // 4], '.b')
         axy.plot(xs, answer zeydel[:, ky // 4 * 2], 'r')
         axy.plot(xs, zans[:, ky // 4 * 2], '.r')
         axy.plot(xs, answer_zeydel[:, ky // 4 * 3], 'g')
         axy.plot(xs, zans[:, ky // 4 * 3], '.g')
         plt.xlabel('x')
        Conut iterations: 285
```

Out[11]: Text(0.5, 0, 'x')



```
In [12]: plt.rcParams['figure.figsize'] = [10, 5]
   plt.subplot (1, 2, 1)
   plt.plot(ys, np.max(np.abs(answer_zeydel - zans), axis=0))
   plt.xlabel('y')
   plt.subplot (1, 2, 2)
   plt.plot(xs, np.max(np.abs(answer_zeydel - zans), axis=1))
   plt.xlabel('x')
```

Out[12]: Text(0.5, 0, 'x')

