$$m \coloneqq 1 \\ l \coloneqq 1 \qquad v_0 \coloneqq 2 \cdot \sqrt{g \cdot l}$$

$$g \coloneqq 9.80665$$
 
$$a \coloneqq l \qquad k \coloneqq 0.5 \qquad \boxed{v_0} \coloneqq 0$$

$$w_0$$
:=

$$\varphi_0 \coloneqq 5 \cdot \frac{\pi}{180}$$

$$y\!\coloneqq\!\begin{bmatrix}v_0\\\varphi_0\end{bmatrix}$$

$$y \coloneqq \begin{bmatrix} v_0 \\ \varphi_0 \end{bmatrix} \qquad \qquad D1\left(t,y\right) \coloneqq \begin{bmatrix} -w_0^2 \cdot \sin\left(y_1\right) - k \cdot y_0 \\ y_0 \end{bmatrix}$$

$$Z1 \coloneqq \text{rkfixed} ($$

$$D2(t,y) \coloneqq \begin{bmatrix} -w_0^2 \cdot y_1 - k \cdot y_0 \\ y_0 \end{bmatrix}$$

$$Z2 \coloneqq \text{rkfixed} ($$

$$\varphi_0 := 10 \cdot \frac{\pi}{180}$$

$$y \coloneqq \begin{bmatrix} v_0 \\ arphi_0 \end{bmatrix}$$

$$\mathbf{y} \coloneqq \begin{bmatrix} v_0 \\ \varphi_0 \end{bmatrix} \qquad D3(t,y) \coloneqq \begin{bmatrix} -w_0^2 \cdot \sin(y_1) - k \cdot y_0 \\ y_0 \end{bmatrix}$$

$$Z3 := \text{rkfixe}$$

$$D4(t,y) \coloneqq \begin{bmatrix} -w_0^2 \cdot y_1 - k \cdot y_0 \\ y_0 \end{bmatrix}$$

$$Z4 \coloneqq \text{rkfixe}$$

$$\varphi_0 := 20 \cdot \frac{\pi}{180}$$

$$y \coloneqq \begin{bmatrix} v_0 \\ \varphi_0 \end{bmatrix}$$

$$\mathbf{y} \coloneqq \begin{bmatrix} v_0 \\ \varphi_0 \end{bmatrix} \qquad D5(t,y) \coloneqq \begin{bmatrix} -w_0^2 \cdot \sin(y_1) - k \cdot y_0 \\ y_0 \end{bmatrix}$$

$$Z_5 := \text{rkfixe}$$

$$D6(t,y) \coloneqq \begin{bmatrix} -w_0^2 \cdot y_1 - k \cdot y_0 \\ y_0 \end{bmatrix}$$

$$Z6 := \text{rkfixe}$$

$$\varphi_0 \coloneqq 40 \cdot \frac{\pi}{180}$$

$$\mathbf{y} \coloneqq \begin{bmatrix} v_0 \\ \varphi_0 \end{bmatrix}$$

$$\widehat{\boldsymbol{\varphi}_{0}} \coloneqq 40 \cdot \frac{\pi}{180} \qquad \qquad \widehat{\boldsymbol{y}} \coloneqq \begin{bmatrix} \boldsymbol{v}_{0} \\ \boldsymbol{\varphi}_{0} \end{bmatrix} \qquad \qquad D7\left(t,\boldsymbol{y}\right) \coloneqq \begin{bmatrix} -\boldsymbol{w}_{0}^{\ 2} \cdot \sin\left(\boldsymbol{y}_{1}\right) - \boldsymbol{k} \cdot \boldsymbol{y}_{0} \\ \boldsymbol{y}_{0} \end{bmatrix}$$

$$Z7 \coloneqq \text{rkf}$$

$$D8(t,y) \coloneqq \begin{bmatrix} -w_0^2 \cdot y_1 - k \cdot y_0 \\ y_0 \end{bmatrix}$$

$$Z8 \coloneqq \text{rkf}$$

$$\varphi_0 := 80 \cdot \frac{\pi}{}$$

$$\left[-w_0^2 \cdot \sin(u) - k \cdot u\right]$$

$$y = \begin{vmatrix} v_0 \\ arphi_0 \end{vmatrix}$$

$$\mathcal{Y} \coloneqq \begin{bmatrix} v_0 \\ \varphi_0 \end{bmatrix} \qquad D9(t,y) \coloneqq \begin{bmatrix} v_0 \\ y_0 \end{bmatrix} \qquad \begin{bmatrix} v_0 \\ y_0 \end{bmatrix}$$

$$Z9 := rkt$$

$$D10\left(t\,,y\right)\!\coloneqq\!\begin{bmatrix}-{w_0}^2\boldsymbol{\cdot} y_{_1}\!-\!k\boldsymbol{\cdot} y_{_0}\\ y_{_0}\end{bmatrix}$$

$$Z10 \coloneqq rl$$

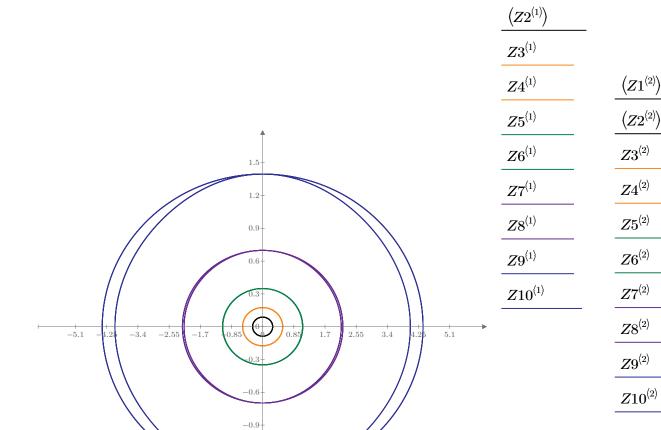
 $\left(Z1^{\langle 2 \rangle}\right)$ 

 $\left(Z2^{\langle 2 \rangle}\right)$ 

 $Z3^{\langle 2 
angle}$ 

 $Z7^{\langle 2 \rangle}$ 

 $(Z1^{\langle 1 \rangle})$ 



-1.2

-1.5-