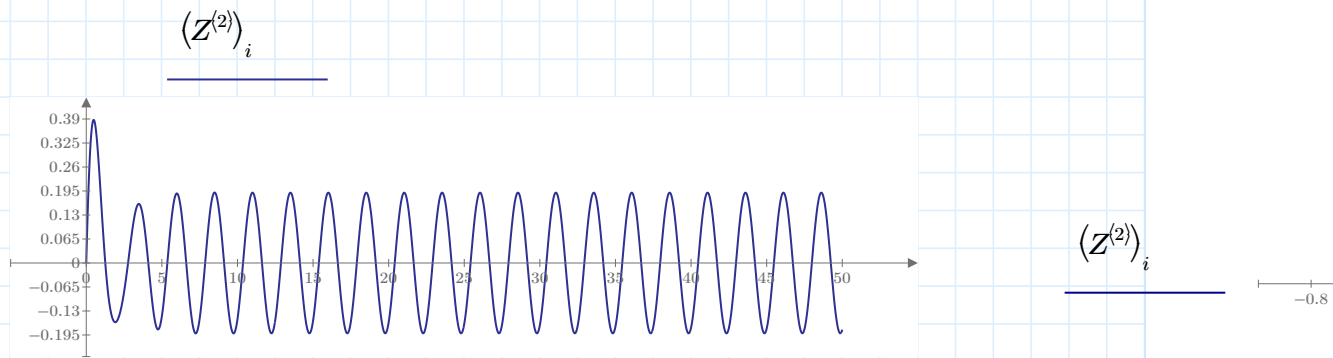


$$m:=1 \qquad l:=1 \qquad v_0:=2\cdot\sqrt{g\cdot l} \qquad \varphi_0:=0 \qquad a:=l \qquad g:=9.80665 \qquad k:=0.2 \qquad v_0:=\frac{\pi}{2} \qquad y:=\begin{bmatrix} v_0 \\ \varphi_0 \end{bmatrix} \qquad w_0$$

$$D(t,y):=\begin{bmatrix} -w_0\cdot y_1\cdot 0-1\cdot w_0^2\cdot\sin\left(y_1\right)-k\cdot y_0+a\cdot\sin\left(w_1\cdot t\right) \\ y_0 \end{bmatrix} \qquad Z:=\text{rkfixed}\left(y,0,50,2000,D\right)$$



$$h:=l-l\cdot\cos\left\langle Z^{(1)}\right\rangle = \begin{bmatrix} 1 \\ 0.936 \\ 0.867 \\ 0.794 \\ \vdots \end{bmatrix} \qquad n:=20 \qquad t:=0..n = \begin{bmatrix} 0 \\ \vdots \end{bmatrix} \qquad f(t):=1.5\cdot\frac{t}{n}$$

$$wr:=\left\| \begin{array}{l} ii\leftarrow 0 \\ \text{while } ii<n \\ \left\| \begin{array}{l} R(t,y)\leftarrow\begin{bmatrix} \frac{-g}{l}\cdot y_1\cdot 1-0\cdot w_0\cdot\sin\left(y_1\right)-k\cdot y_0+a\cdot\sin\left(w_{ii}\cdot t\right) \\ y_0 \end{bmatrix} \\ Q\leftarrow\text{rkfixed}\left(y,0,50,200,R\right) \\ wr_{ii}\leftarrow\max\left(l\cdot\sin\left\langle Q^{(2)}\right\rangle\right) \\ ii\leftarrow ii+1 \end{array} \right\| \\ wr \end{array} \right\| = \begin{bmatrix} 0.344 \\ 0.344 \\ 0.344 \\ 0.345 \\ \vdots \end{bmatrix}$$

$$Q:=\text{rkfixed}(y,0,10,2)$$

$$A:=\frac{1}{\sqrt{\left(w_0^2-w^2\right)^2+4\left(\delta^2\cdot w^2\right)}}= \begin{bmatrix} 0.102 \\ 0.102 \\ 0.102 \\ 0.102 \\ 0.102 \\ 0.102 \\ 0.102 \\ 0.102 \\ 0.102 \\ 0.102 \\ 0.103 \\ 0.103 \\ \vdots \end{bmatrix} \qquad \varphi:=\text{atan}\left(\frac{2\cdot\delta\cdot w}{w_0^2-w^2}\right)= \begin{bmatrix} 0 \\ 4.885\cdot 10^{-5} \\ 9.771\cdot 10^{-5} \\ 0.001 \\ 0.002 \\ 0.002 \\ 0.003 \\ 0.003 \\ 0.004 \\ 0.004 \\ 0.005 \\ 0.005 \\ \vdots \end{bmatrix}$$

$$\boxed{v_0}:=2\cdot\sqrt{g\cdot l} \qquad \boxed{\varphi_0}:=0 \quad \boxed{a}:=l \qquad \boxed{g}:=9.80665 \qquad \boxed{k}:=0.2 \qquad \boxed{v_0}:=\frac{\pi}{2} \qquad \boxed{y}:=\begin{bmatrix} v_0 \\ \varphi_0 \end{bmatrix}$$

$$\begin{array}{l} \parallel w0\leftarrow\sqrt{\frac{g}{l}} \\ \parallel h\leftarrow0.025 \\ \parallel d\leftarrow0.1 \\ \parallel w\leftarrow w0\cdot0.1 \\ \parallel v\leftarrow\frac{\pi}{24} \\ \parallel phi\leftarrow0 \\ \parallel i\leftarrow0 \\ \parallel m\leftarrow l\cdot\sin(phi) \\ \parallel \text{while } i<n \\ \parallel \parallel t\leftarrow h\cdot(a\cdot\sin(w\cdot i\cdot h)-w0^2\cdot\sin(phi)) \\ \parallel \parallel phi\leftarrow phi+h\cdot v \\ \parallel \parallel v\leftarrow v+t \\ \parallel \parallel i\leftarrow i+1 \\ \parallel \parallel \text{if } (l\cdot\sin(phi)>m) \\ \parallel \parallel \parallel m\leftarrow l\cdot\sin(phi) \\ \parallel m \end{array} \qquad =1 \qquad R(t,y):=\begin{bmatrix} \frac{-g}{l}\cdot y_1\cdot 0-1\cdot w_0\cdot\sin(y_1) \\ y_0 \end{bmatrix}$$

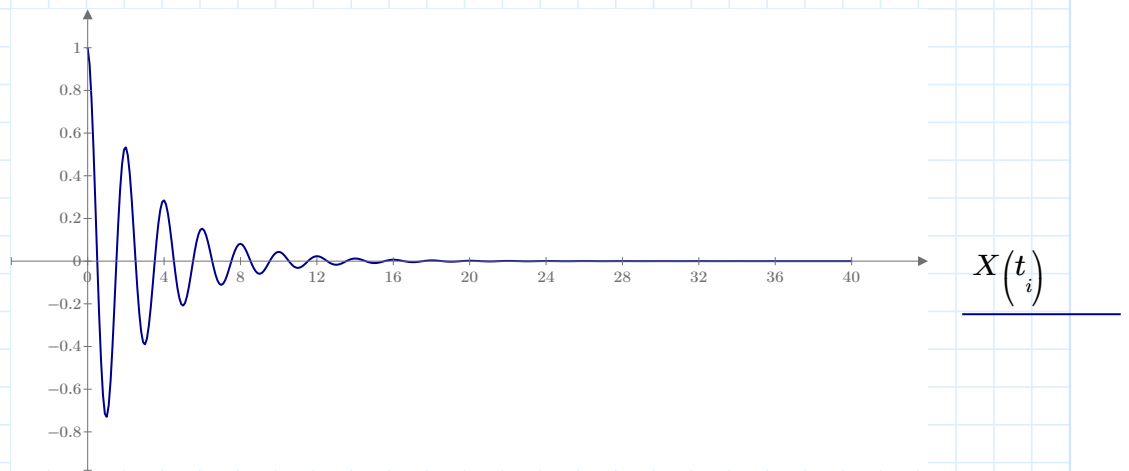
$$\boxed{A^{(i)}}_j:=\frac{A0}{m\cdot\sqrt{\left(w0^2-w_j^2\right)^2+4\,b_i^2\cdot w_j^2}}$$

$$\boxed{t}:=0,0.1..40=\begin{bmatrix} 0 \\ \vdots \end{bmatrix}$$

$$d:=0.1 \qquad w0:=\sqrt{\frac{g}{l}} \qquad \boxed{w}:=w0 \qquad \boxed{f}:=0$$

$$A0 := l \qquad b := d \cdot w0$$

$$X(t) := A0 \cdot e^{-b \cdot t} \cdot \cos(w \cdot t + f)$$



$$\underline{t_i}$$

$$\boxed{n} := 1000$$

$$\boxed{m} := 3 \qquad step := \frac{m}{n}$$

$$\boxed{k} := 0, step .. m = \begin{bmatrix} 0 \\ 0.003 \\ 0.006 \\ \vdots \end{bmatrix}$$

$$z(t) := 3 \cdot \frac{t}{m}$$

$$z(k) = \begin{bmatrix} 0 \\ 0.003 \\ 0.006 \\ \vdots \end{bmatrix}$$

$$\boxed{w} := w0 \cdot k = \begin{bmatrix} 0 \\ 0.009 \\ 0.019 \\ \vdots \end{bmatrix}$$

$$\boxed{d} := 0, 0.01 .. 10 = \begin{bmatrix} 0 \\ \vdots \end{bmatrix}$$

$$\boxed{b} := w0 \cdot d$$

$$A_1 := \left\| \begin{array}{l} j \leftarrow 0 \\ \text{while } i < n \end{array} \right\|$$

$$A_2 := \left\| \begin{array}{l} j \leftarrow 0 \\ \text{while } i < n \end{array} \right\|$$

