

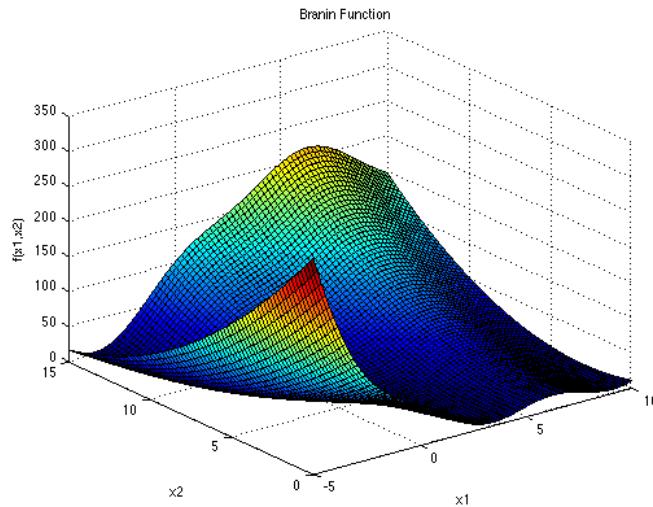
Virtual Library of Simulation Experiments:

Test Functions and Datasets

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BRANIN FUNCTION



$$f(\mathbf{x}) = a(x_2 - bx_1^2 + cx_1 - r)^2 + s(1 - t)\cos(x_1) + s$$

Description:

Dimensions: 2

The Branin, or Branin-Hoo, function has three global minima. The recommended values of a , b , c , r , s and t are: $a = 1$, $b = 5.1/(4\pi^2)$, $c = 5/\pi$, $r = 6$, $s = 10$ and $t = 1/(8\pi)$.

Input Domain:

This function is usually evaluated on the square $x_1 \in [-5, 10]$, $x_2 \in [0, 15]$.

Global Minimum:

$$f(\mathbf{x}^*) = 0.397887, \text{ at } \mathbf{x}^* = (-\pi, 12.275), (\pi, 2.275) \text{ and } (9.42478, 2.475)$$

Modifications and Alternate Forms:

Picheny et al. (2012) use the following rescaled form of the Branin-Hoo function, on $[0, 1]^2$:

$$f(\mathbf{x}) = \frac{1}{51.95} \left[\left(\bar{x}_2 - \frac{5.1\bar{x}_1^2}{4\pi^2} + \frac{5\bar{x}_1}{\pi} - 6 \right)^2 + \left(10 - \frac{10}{8\pi} \right) \cos(\bar{x}_1) - 44.81 \right], \text{ where}$$

$$\bar{x}_1 = 15x_1 - 5, \bar{x}_2 = 15x_2$$

This rescaled form of the function has a mean of zero and a variance of one. The authors also add a small Gaussian error term to the output.

For the purpose of Kriging prediction, Forrester et al. (2008) use a modified form of the Branin-Hoo function, in which they add a term $5x_1$ to the response. As a result, there are two local minima and only one global minimum, making it more representative of engineering functions.

Code:

[MATLAB Implementation](#)
[R Implementation](#)
[MATLAB Implementation, Rescaled](#)
[R Implementation, Rescaled](#)
[MATLAB Implementation, Modified](#)
[R Implementation, Modified](#)

References:

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Forrester, A., Sobester, A., & Keane, A. (2008). *Engineering design via surrogate modelling: a practical guide*. Wiley.

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Picheny, V., Wagner, T., & Ginsbourger, D. (2012). A benchmark of kriging-based infill criteria for noisy optimization.

For questions or comments, please email Derek Bingham at: dbingham@stat.sfu.ca.

Authors: Sonja Surjanovic & Derek Bingham, Simon Fraser University
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