

Topic 4 Graph Denoising

Set up: $G = (V, E)$

W_{ij} $n \times n$, positive, symmetric

(eg. $W_{ij} = e^{-\frac{\|x_i - x_j\|^2}{\epsilon}}$)

$$P = D^{-1}W$$

$$P = \Phi \Lambda \Phi^T$$

$$\Psi^T D \Psi = I$$

$$\Psi = [\psi_1, \dots, \psi_n]$$

$$\Phi = D \Psi$$

$$f \in \mathbb{R}^n, f: V \rightarrow \mathbb{R}$$

$$i \rightarrow f_i$$

assumption: f is "smooth" with graph.

- Generalized Fourier coefficient: $f = \sum_{k=1}^n c_k \psi_k$

c_k : generalized Fourier coef.

ψ_k : generalized Fourier basis

Remark. ψ_k are the eigenfunctions of graph Laplacian.

(e.g.) $\sin kx$ and $\cos kx$ are eigenfunctions of the Laplacian operator Δ .

Hence ψ_k 's are called Fourier basis.

Prop. If $f(x) \in C^1[0, 2\pi]$ then $\int_0^{2\pi} |f'(x)|^2 dx \leq C$.

$$\text{then } \sum_{k=-\infty}^{\infty} \int_0^{2\pi} |ik c_k \cdot e^{ikx}|^2 dx$$

$$\leq \sum_{k=-\infty}^{\infty} \cdot 2\pi |c_k|^2 \cdot k^2 \Rightarrow \text{meaning } |c_k| \text{ decays faster than } \frac{1}{k}.$$

Remark. The "Smoothness" (i.e. f is n -th differentiable how large the derivatives) of f implies the decaying property of $|c_k|$.

If $f^{(n)}(x)$ exists and $|f^{(n)}(x)| \leq C$.

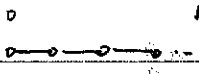
then c_k decays faster than $\frac{1}{k^n}$.

In graph Laplacian case, similar result holds.

Prop. Suppose $f = \sum_k c_k \psi_k$ and $f^T L f < \delta$, then $c_k^2 < \frac{\delta}{1 - \lambda_k}$ for $k > 1$

$1 = \lambda_1 > \lambda_2 > \dots > \lambda_n > 0$, are eigenvalues of $P = D^{-1}W$. ($L = D - W$)

Remark. $f^T L f = \frac{1}{2} \sum_{i,j} W_{ij} (f_i - f_j)^2$

eg. graph 1-D grid 

$$f^T L f \approx - \int_0^1 f(\Delta f) dx = \int |df|^2 dx$$

(consistency)

pf: $L = D - W = D(1 - P)$ $P\psi_k = \lambda_k \psi_k$

Then $f^T L f = f^T D(1 - P)f$

$$(1 - P)f = \sum_k c_k (1 - P)\psi_k = \sum_k c_k (1 - \lambda_k) \psi_k$$

$$f^T L f = (\sum_k c_k \psi_k)^T D (\sum_k c_k (1 - \lambda_k) \psi_k)$$

$$= \sum_{l,k} c_k c_l (1 - \lambda_l) \psi_k^T D \psi_l \quad (\Psi^T D \Psi = I)$$

$$= \sum_{l,k} c_k c_l (1 - \lambda_l) \delta_{kl}$$

$$= \sum_k c_k^2 (1 - \lambda_k) < \delta \quad c_k^2 (1 - \lambda_k) < \delta \text{ for all } k.$$

$$\Rightarrow c_k^2 (1 - \lambda_k) \text{ decays faster than } \sqrt{\frac{1}{1 - \lambda_k}}$$

Prmk. Suppose $\lambda_k \rightarrow 0$ fast, and δ small

then c_k has a good bound and decays to 0 fast.

Recall. given $x = f + \epsilon$ $f, x \in \mathbb{R}^n$

f is the unknown true signal.

$$\epsilon \sim N(0, \Sigma^2 I) \quad \epsilon_i \stackrel{iid}{\sim} N(0, \delta^2)$$

Proposal. $\hat{f} = P x$

$$x = \sum g_k \psi_k \quad |g_k| \text{ does not decay}$$

$$= \Psi g \quad \text{for } g \in \mathbb{R}^n$$

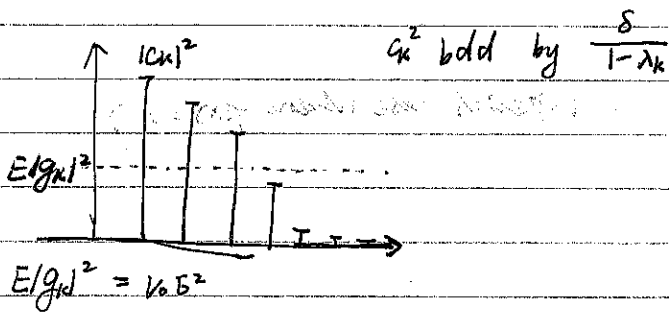
If Ψ is unitary, then $g \sim N(0, \delta^2 I)$

To simplify analysis, as $\Psi^T D \Psi = I$,

we assume $D = I$ (a regular graph)

and then $I = \Psi^T \Psi$, i.e. $\sqrt{I} \Psi$ is unitary.

$$g = \Psi^{-1} \varepsilon \quad g_k \sim N(0, \sigma_g^2)$$



$$\text{SNR} = \frac{|C_k|^2}{E|g_k|^2}$$

(signal noise ratio)

$$\hat{f} = P \hat{f} = P(f + \varepsilon) = P\left(\sum_k (C_k + g_k) \psi_k\right)$$

$$= \sum_k (C_k + g_k) \lambda_k \psi_k$$

$$\text{Bias: } E\hat{f} - f = 0 \cdot \sum_k C_k \lambda_k \psi_k - \sum_k C_k \psi_k$$

$$= -\sum_k C_k (1 - \lambda_k) \psi_k$$

$$\text{Variance: } E\|\hat{f} - E\hat{f}\|^2 = E\|P\varepsilon\|^2$$

$$= E\|P\left(\sum_k g_k \psi_k\right)\|^2$$

$$= E\left\|\sum_k g_k \lambda_k \psi_k\right\|^2$$

$$= \sum_k \lambda_k^2 \cdot \sigma_g^2 \ll \sigma_g^2 \cdot n$$

$$\| \text{Bias} \|^2 = \sum_k C_k^2 (1 - \lambda_k)^2 \cdot \frac{1}{\sigma_g^2} \leq \sum_k C_k^2 (1 - \lambda_k) \cdot \frac{1}{\sigma_g^2} \leq \frac{\sigma}{\sigma_g^2}$$

MLM.

$$\text{given } \{x_i\}_{i=1}^n \in \mathbb{R}^D$$

$$\hat{x}_i = \frac{\sum_{j=1}^n w_{ij} \cdot x_j}{\sum_{j=1}^n w_{ij}} \quad (\text{denoised patch})$$

$$\text{Rmk. } \hat{x}_i(1) = \frac{\sum_{j=1}^n w_{ij} x_j(1)}{\sum_{j=1}^n w_{ij}}$$

$$f: i \rightarrow x_i(1) \quad \hat{f} = (D^{-1}W) \cdot f$$

(spectral filtering)

$$P = \Phi \Lambda \Phi^T$$

$$\hat{f} = \sum_k \lambda_k \Phi_k^T P x$$

$$= \sum_k \lambda_k \Phi_k \langle \Phi_k, x \rangle \quad (\text{special case where } f(\lambda) = \lambda)$$

generalized version.

$$\sum_k f(\lambda_k) \langle \Phi_k, x \rangle \Phi_k$$

$$SNR_k = \frac{|c_k|^2}{\sigma^2}$$

Remark. P is global Fourier Transform

The "optimal" denoising strategy: wavelet shrinkage

$x \rightarrow c_k(x)$ wavelet transform

$$\tilde{x} \sim \sum_k c_k(x) \Phi_k$$

\rightarrow change c_k to be cut off at δ $T_\delta(c_k) = \hat{c}_k$

$$\rightarrow \tilde{x} \sim \sum_k \hat{c}_k \Phi_k \quad \hat{c}_k = \begin{cases} c_k & \text{if } |c_k| \geq \delta \\ 0 & \text{else} \end{cases}$$

If f is "smooth", we would expect it to be approximately "flat" in a small interval \Rightarrow we look at f in small windows

Synchronization.

$$G = (V, E)$$

goal: recover unknown signs on V .

$$\tilde{z}_i \in \{-1, 1\}$$

from pairwise measurement on E

$$(i, j) \in E \quad G_{ij} = \tilde{z}_i \tilde{z}_j = \begin{cases} 1 & \tilde{z}_i = \tilde{z}_j \\ -1 & \text{otherwise} \end{cases}$$

A is the adjacency matrix of G .

$$G = (\tilde{z} \tilde{z}^T) \odot A = \tilde{z} \tilde{z}^T \odot A$$

$$(A \odot B)_{ij} = A_{ij} \cdot B_{ij}$$

- we can recover the unknown signs by simply exploring the graph.
(when the graph is connected, + there exists true signs (without conflict))
- can recover up to flipping all signs in a connected component.

Next, we corrupt some of the observations. \Rightarrow which may result in contradiction.

$$G_{ij} = \begin{cases} z_i z_j & (i,j) \in E \quad (A_{ij} = 1) \\ \text{Bernoulli}(\frac{1}{2}) & (A_{ij} = 0) \end{cases} \quad W_{ij} = \begin{cases} 1 & \text{with prob } \frac{1}{2} \\ -1 & \text{prob } \frac{1}{2} \end{cases}$$

$$G = z z^T \odot A + W \odot (1 \cdot 1^T - A)$$

Task: given G , need to recover z .

Method: take the first eigenvector of G , v_1 .

$$\hat{z}_i = \text{sgn}(v_{1i})$$

rank. SDP relaxation of the problem:

$$\max \langle G, X \rangle$$

$$\text{s.t. } X \succeq 0, \quad X_{ii} = 1.$$

$$\langle G, X \rangle = \text{Tr}(GX)$$

$$X^* = z \cdot z^T$$

$$\text{Tr}(GX^*) = \text{Tr}(G \cdot z \cdot z^T) = z^T G z$$

$$X_{ii}^* = z_i^2 = 1.$$

Relax the rank constrain $\text{rank}(X) = 1$.

Suppose A is a random graph, i, j i.i.d. (independent of z and w)

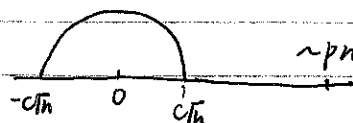
$$A_{ij} = \begin{cases} 1 & \text{with prob. } p \\ 0 & \text{with prob. } 1-p \end{cases}$$

$$EAG = (z z^T) \odot EA + W \odot (1 \cdot 1^T - A)$$

$$= \underbrace{p \cdot z z^T}_{\text{rank 1 matrix, with } \lambda = pn} + \underbrace{(1-p)W}_{\| (1-p)W \| \leq C\sqrt{n}}$$

$$C = (1-p) \sqrt{\text{Var}(w_{ij})} \cdot 2$$

when pn is large enough, ($pn > C\sqrt{n}$)
the correlation between the eigenvector of the large eigenvalue ($\sim pn$) and the vector of λ approaches 1.



deterministic $A_{ij} = 1$

$$\# \{ \text{good edge } (i,j) \} \sim p n^2$$

eg1. \mathbb{Z}_2 signs

eg2. S_1 signs $\theta \in [0, 2\pi]$

$$\theta_{ij} = \begin{cases} t_i - t_j & \text{w.p. } p \\ U([0, 2\pi)) & \text{w.p. } 1-p \end{cases}$$

$$\bar{z}_i = e^{it_i}$$

$$e^{i(t_i - t_j)} = \bar{z}_i \cdot \bar{z}_j$$