



# Drive Away Fraudsters With Driverless AI

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# Agenda

Problem

Approach

Experiments

Conclusion

# PROBLEM

# Fraud Prevention @ PayPal



Robust feature engineering, machine learning and statistical models



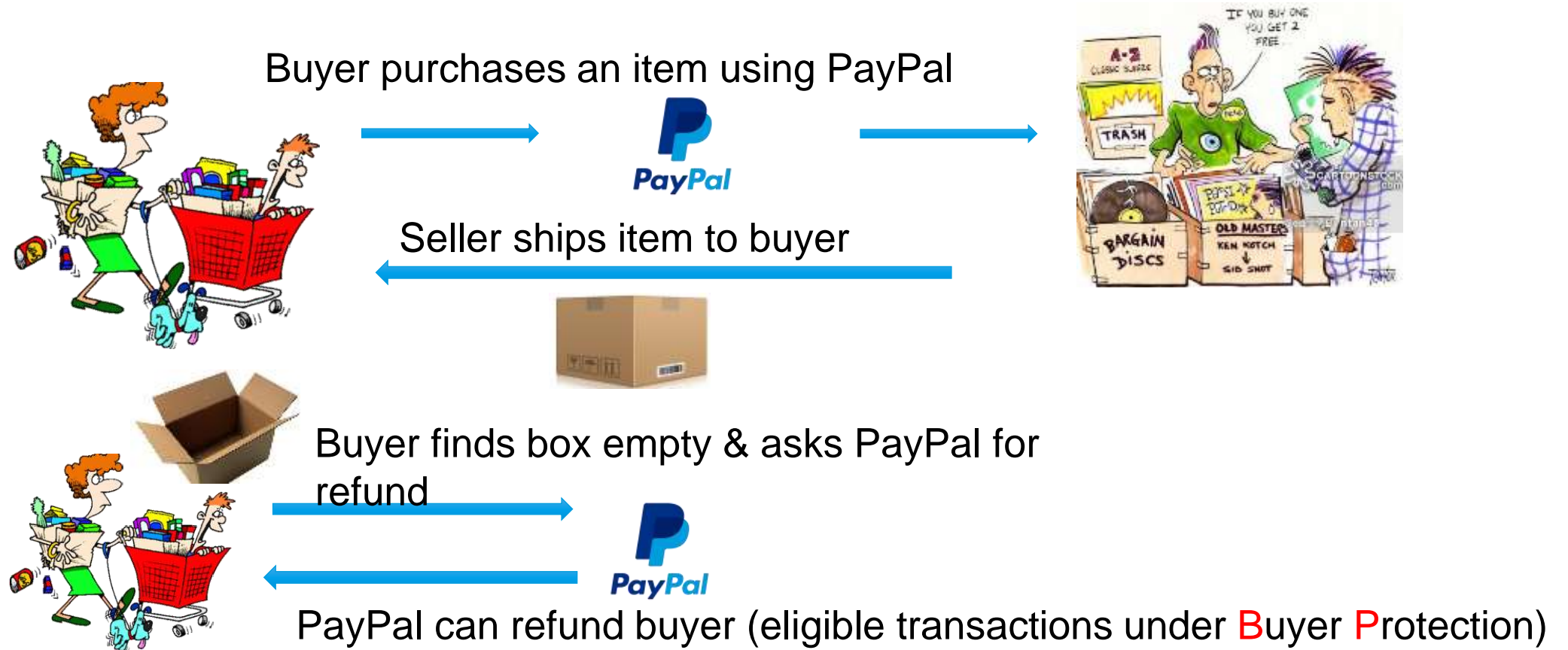
Highly scalable and multi-layered infrastructure software



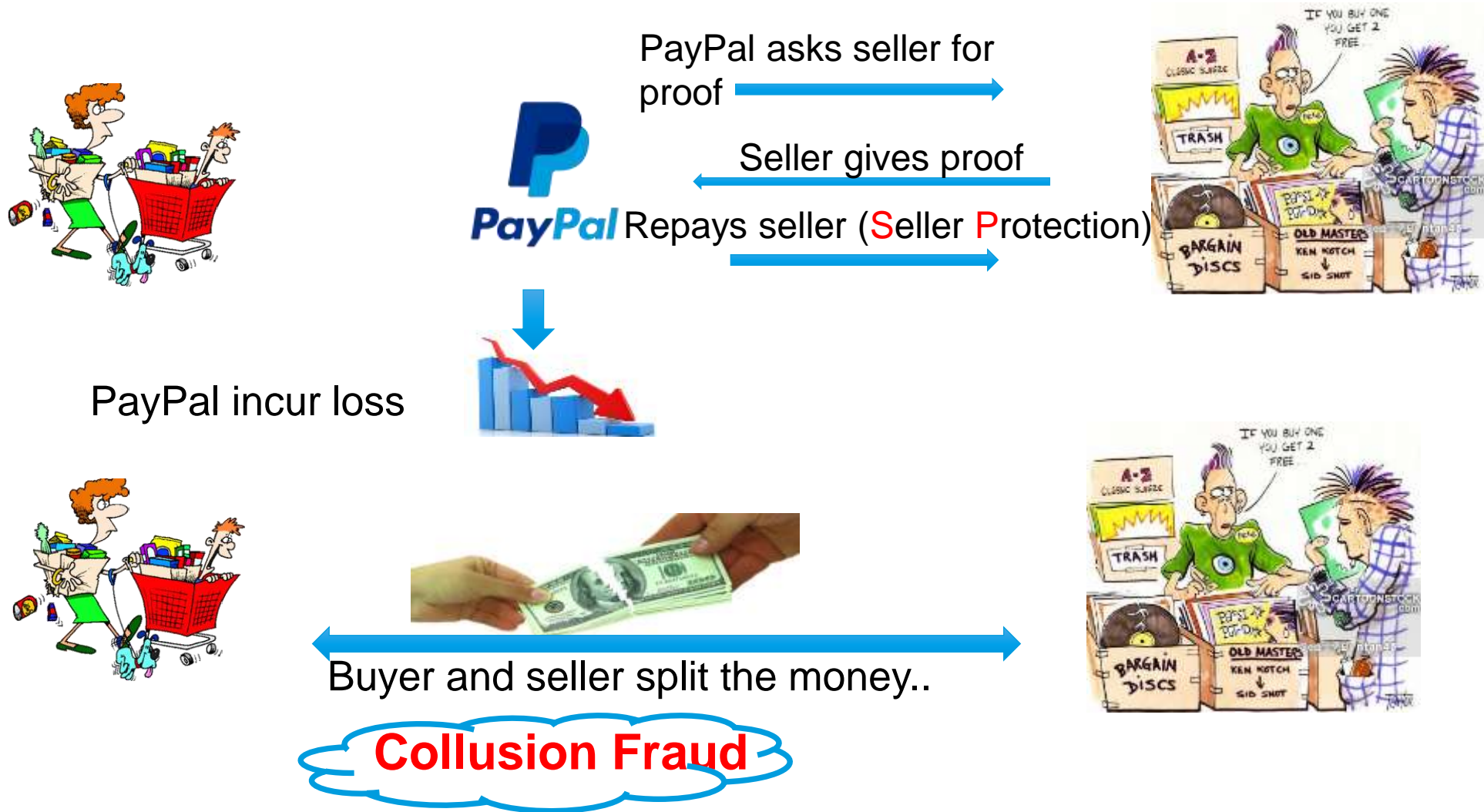
Superior team of data scientists, researchers, financial and intelligence analysts

Images source:

# Collusion Fraud – An Example Scenario



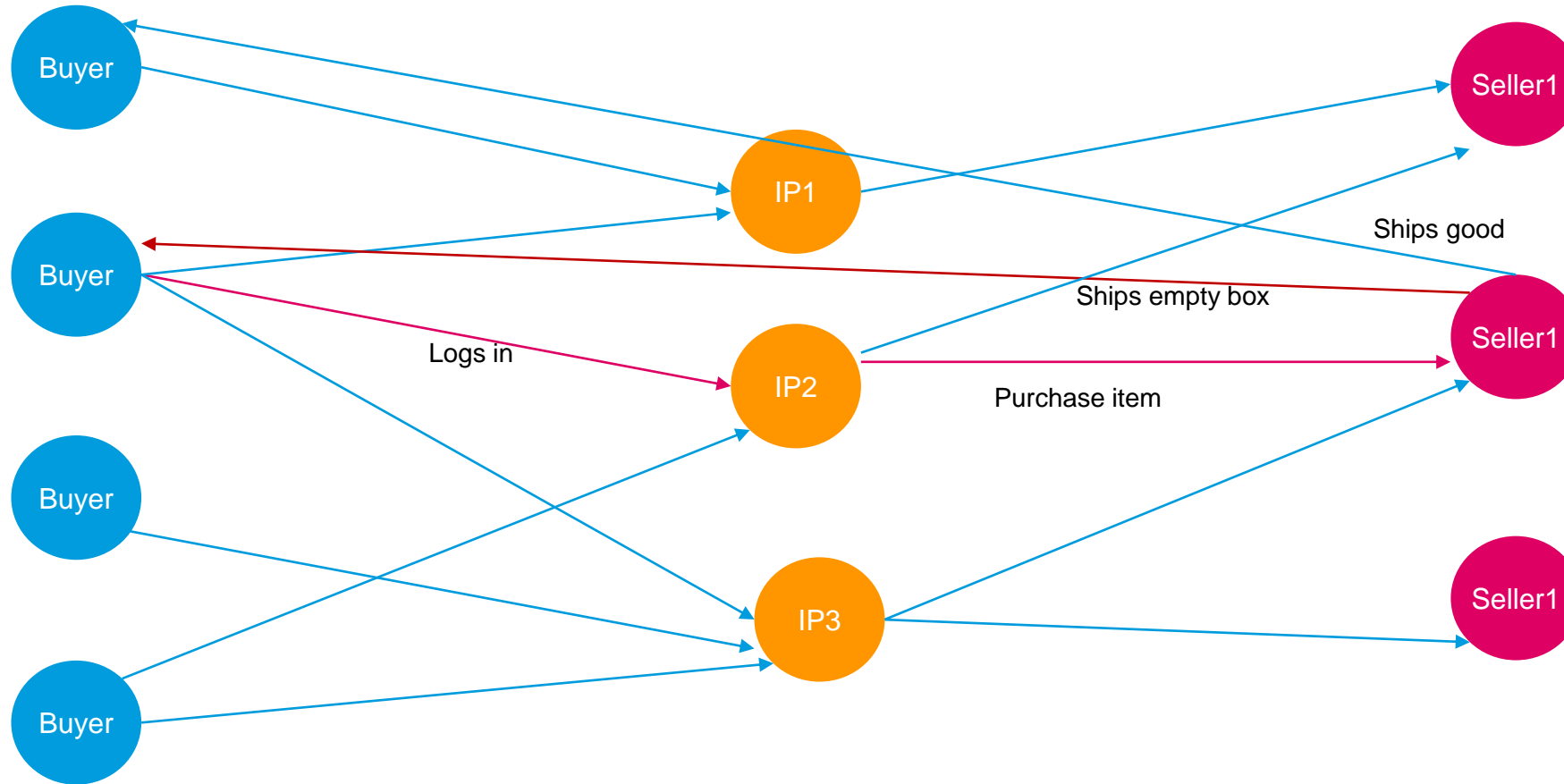
# Collusion Fraud – An Example Scenario



# Collusion Fraud

- What if there are many such buyers colluding with many such sellers?
- What if such buyers & sellers stay below the radar? (\$ Transaction < Threshold)?
- What if such sellers behave well with majority of the buyers & collude with a few?
- How do we detect if the buyers and sellers are legitimate or if they are colluding with each other?

# Collusion Fraud



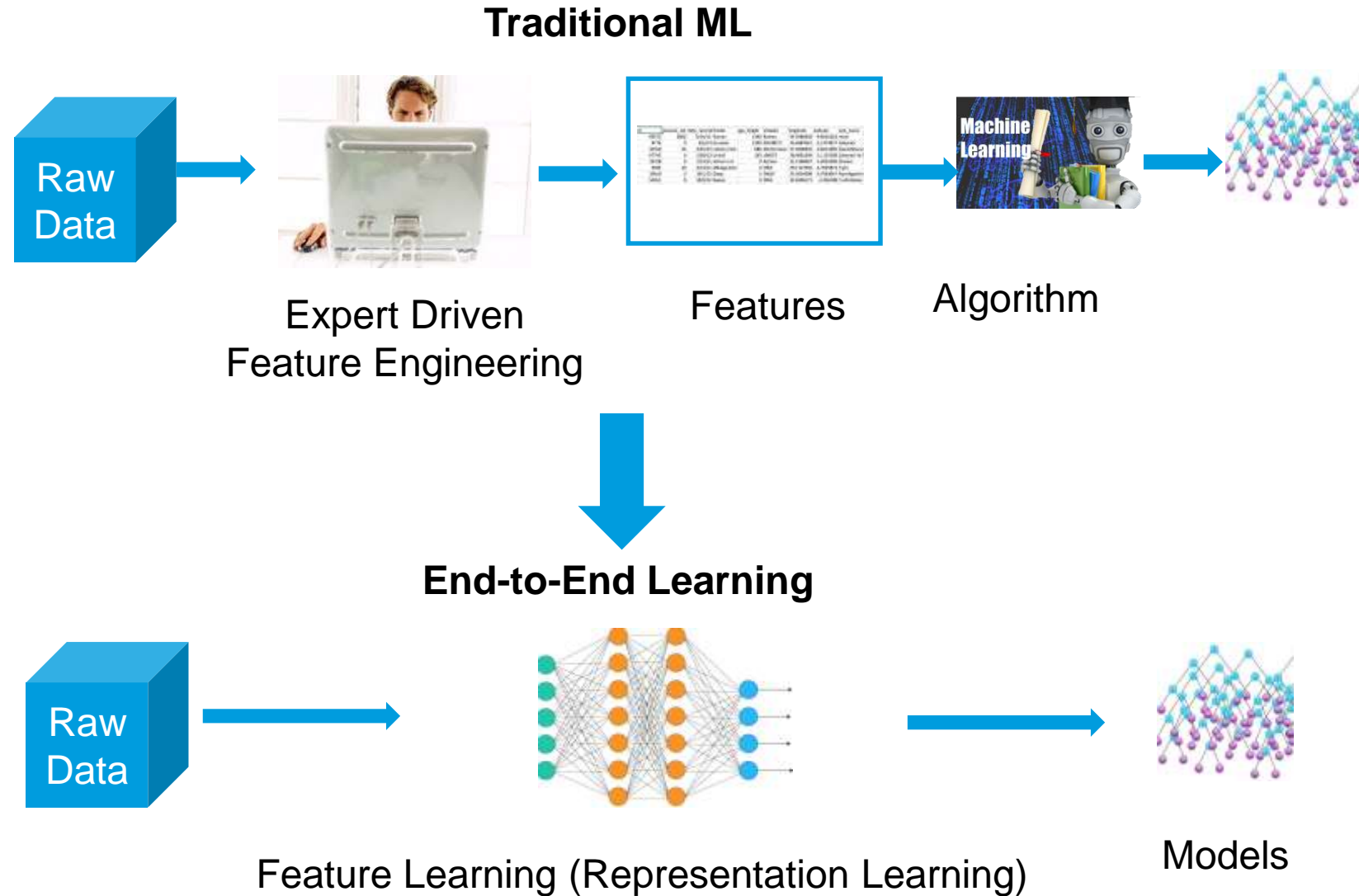
- **Can we exploit network structure of fraudsters to solve collusion fraud?**



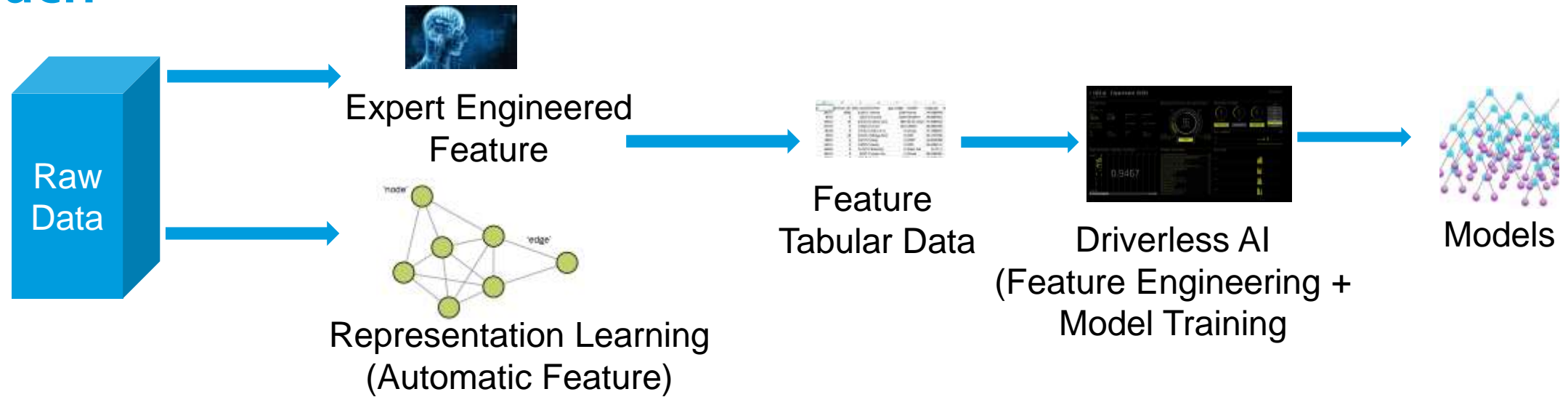
# APPROACH

# Traditional ML vs End-to-End Learning

- Traditional ML – Significant human effort in engineering features & labelling
- End-to-End Learning – Use algorithm (such as Deep learning) to learn feature representations automatically
  - need tabular data



# Approach



- Learn features from graphs & use Driverless AI to engineer additional features and build model.
- Feature learning on graphs is fairly new research area & its full potential has not been realized.
- Graph based feature learning helps to understand fraud network & thus prevent collusion and other organized crimes

# Approach – Graph Based Representation Learning

- Idea
  - You shall know a word (node) by the company (neighbor) it keep(s)\* (Firth, J. R. 1957)
- Word2Vec\* - Continuous feature representation for words
  - Suppose user searches for “hotel”, we want to also match “motel”
  - One hot representation (discrete)

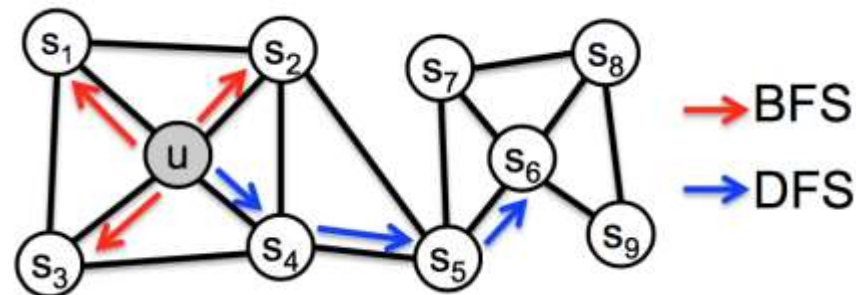
motel  $[0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 1 \ 0 \ 0 \ 0 \ 0]^T$   
hotel  $[0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 1 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0] = 0$
  - Build a dense vector to predict other words from context
  - Two algorithms – Skip Gram (SG) (Predict context words from target) & Continuous Bag of Words (CBOW) (Predict target from context)
- Graph Based Representation Learning
  - Learn continuous feature representation for nodes
  - Representation incorporates community a node belong to & role they play

# Algorithm – node2vec\*

Grover & Leskovec, 2016

- Node2Vec

- $s_1, s_2, s_3, s_4, u$  - same community
- $u$  &  $s_6$  also play the role of hub
- “neighborhood preserving” graph based objective function optimized using SGD
- MLE optimization problem
- BFS & DFS sampling to generate neighbors



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**Algorithm 1** The *node2vec* algorithm.

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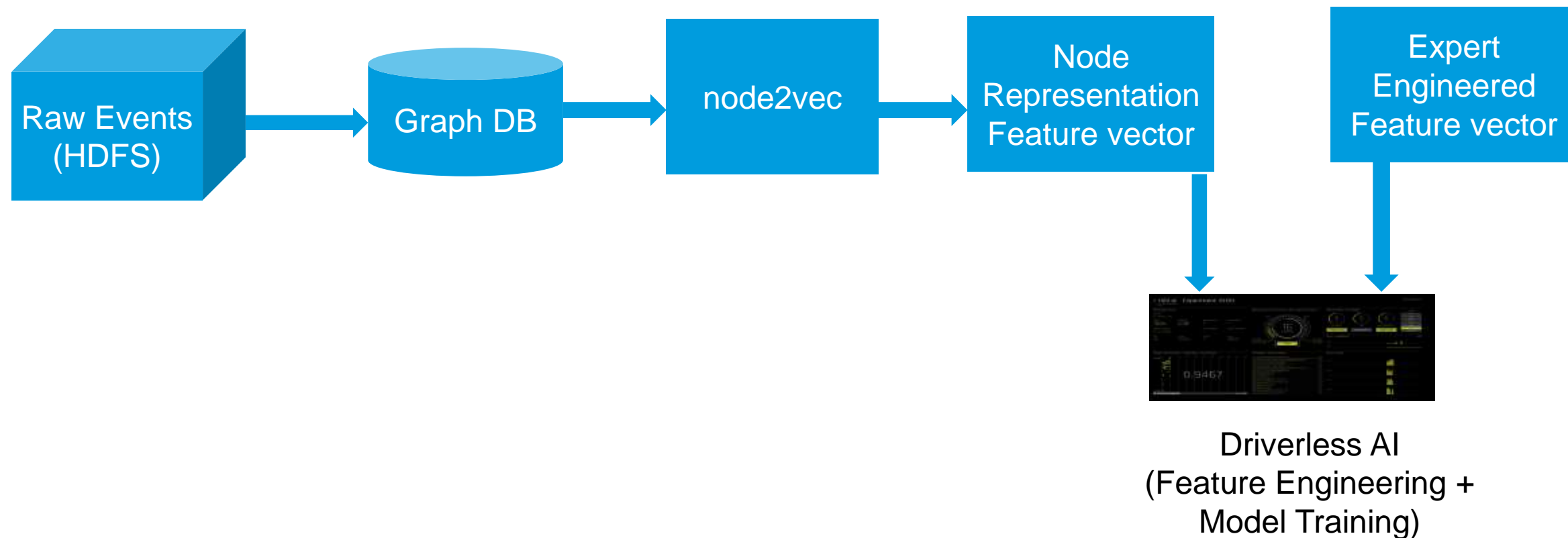
**LearnFeatures** (Graph  $G = (V, E, W)$ , Dimensions  $d$ , Walks per node  $r$ , Walk length  $l$ , Context size  $k$ , Return  $p$ , In-out  $q$ )  
 $\pi = \text{PreprocessModifiedWeights}(G, p, q)$   
 $G' = (V, E, \pi)$   
Initialize *walks* to Empty  
**for** *iter* = 1 **to**  $r$  **do**  
    **for all** nodes  $u \in V$  **do**  
         $walk = \text{node2vecWalk}(G', u, l)$   
        Append *walk* to *walks*  
 $f = \text{StochasticGradientDescent}(k, d, \text{walks})$   
**return**  $f$

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**node2vecWalk** (Graph  $G' = (V, E, \pi)$ , Start node  $u$ , Length  $l$ )  
Initialize *walk* to  $[u]$   
**for** *walk\_iter* = 1 **to**  $l$  **do**  
     $curr = \text{walk}[-1]$   
     $V_{curr} = \text{GetNeighbors}(curr, G')$   
     $s = \text{AliasSample}(V_{curr}, \pi)$   
    Append  $s$  to *walk*  
**return** *walk*

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# Implementation Framework



# EXPERIMENTS

# Datasets

- Training Data
  - Subset of 1 year transactions
  - 1.5 billion edges & 0.5 million nodes
- Test Data
  - 3 months
- # of features
  - 400 - 600



# Environment & Tools

- Node2Vec – Node representation learning
- Driverless AI – Feature Engineering & Model Training
- Spark – Data Preparation/Pre-processing
- Hardware – GPU server
  - 4 Pascal 100 GPU
  - 160 cores CPUs
  - 1 TB RAM

# Experiment

- Training time (subset of data) – Driverless AI on GPU 6x faster
  - laptop (accuracy 1) - ~ 2 hours
  - GPU (accuracy 1) – 21 minutes; (accuracy 5) – 58 minutes

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1.0.9

Datasets overview | Interpret Models

Experiments

+ NEW EXPERIMENT

	TARGET	TRAIN SCORE	TEST SCORE	SCORER	ACCURACY	TIME	INTERPRETABILITY	STATUS	TIME
13c6ca c_test.csv	is_cc_bad	0.94703	NA	AUC	1	1	1	Done	01:53:29

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1.0.10+local\_14c8f55-dirty

DATASETS EXPERIMENTS INTERPRET H2O-3 HELP LOGOUT

Experiments

+ NEW EXPERIMENT

067d32 c_test.csv	TARGET is_cc_bad	TRAIN SCORE 0.94773	TEST SCORE NA	SCORER AUC	ACCURACY 5	TIME 5	INTERPRETABILITY 5	STATUS Done	TIME 00:58:39
e55a93 c_test.csv	TARGET is_cc_bad	TRAIN SCORE 0.94658	TEST SCORE NA	SCORER AUC	ACCURACY 1	TIME 1	INTERPRETABILITY 1	STATUS Done	TIME 00:21:59

# Experiment

- Top 5 variables from DAI
- AUC – 0.9477



# CONCLUSIONS

# Conclusions

- Graph based representation learning yield robust feature set for complex fraud patterns such as collusion fraud
- Driverless AI not only help to engineer additional features automatically but also significantly improve model training time (under 2 hours).
- Journey into DAI just beginning...
- Next steps
  - Evaluate Driverless AI results on out-of-time data sets.
  - Evaluate Driverless AI directly on raw data
  - Evaluate representation learning on edges and weighted graphs
  - Machine learning on graphs

# Acknowledgements

**Driverless AI Team @ H2O.ai**