

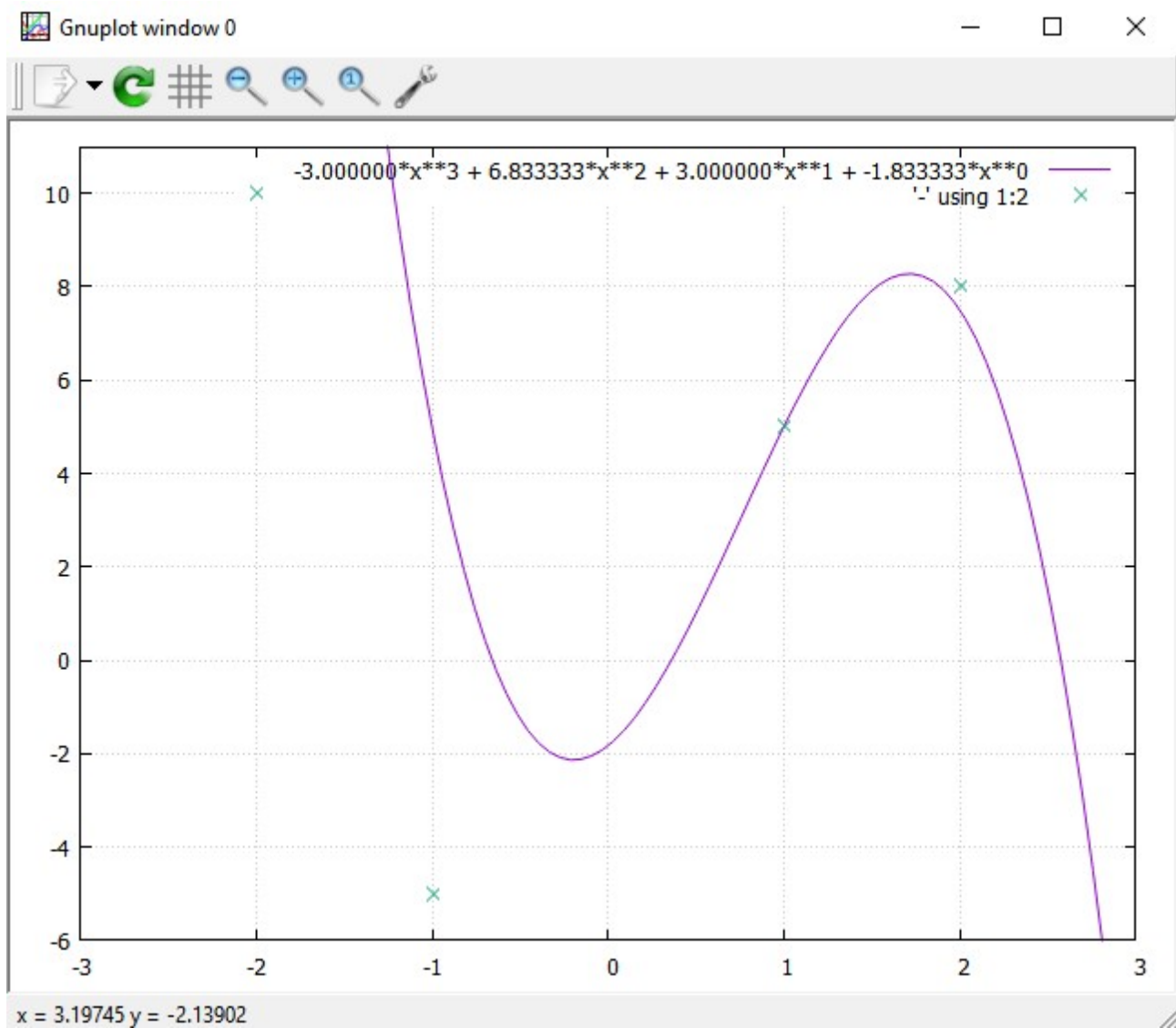
Analytical Geometry and Linear Algebra II

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DSAI-03

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Experimental data:

t	b
2.0	8.0
1.0	5.0
-1.0	-5.0
-2.0	10.0

Main function:

```
int main() {
    #ifdef WIN32
        FILE* pipe = _popen(GNUPLOT_NAME, "w");
    #else
        FILE* pipe = popen(GNUPLOT_NAME, "w");
    #endif

    int size;
    cin >> size;

    double* t = new double[size];
    double* b = new double[size];

    for (int i = 0; i < size; i++) {
        cin >> t[i] >> b[i];
    }

    int polynomial_degree;
    cin >> polynomial_degree;

    Matrix A(size, polynomial_degree + 1);
    Matrix B(size, 1);

    for (int i = 0; i < size; i++) {
        for (int j = 0; j < polynomial_degree + 1; j++) {
            A(i, j) = pow(t[i], j);
        }
        B(i, 0) = b[i];
    }

    cout << "A:\n" << A;

    Matrix A_transpose = A.transpose();

    cout << "A_T*A:\n" << A_transpose * A;

    Matrix A_inverse = (A_transpose * A).inverse();

    cout << "(A_T*A)^-1:\n" << A_inverse;

    Matrix A_transpose_B = A_transpose * B;

    cout << "A_T*b:\n" << A_transpose_B;

    Matrix x = A_inverse * A_transpose_B;

    cout << "x~:\n" << x;

    double min_t = t[0];
    double max_t = t[0];
    for (int i = 1; i < size; i++) {
        if (t[i] < min_t) {
            min_t = t[i];
        }
        if (t[i] > max_t) {
            max_t = t[i];
        }
    }

    fprintf(pipe, "set xrange [%lf:%lf]\n", min_t - 1, max_t + 1);

    double min_b = b[0];
    double max_b = b[0];
```

```

for (int i = 1; i < size; i++) {
    if (b[i] < min_b) {
        min_b = b[i];
    }
    if (b[i] > max_b) {
        max_b = b[i];
    }
}

fprintf(pipe, "set yrange [%lf:%lf]\n", min_b - 1, max_b + 1);

fprintf(pipe, "set grid\n");
fprintf(pipe, "plot %lf*x**3 + %lf*x**2 + %lf*x**1 + %lf*x**0 , '-' using 1:2 with points\n",
    x(0, 0), x(1, 0), x(2, 0), x(3, 0));
for (int i = 0; i < size; i++) {
    fprintf(pipe, "%f\t%f\n", t[i], b[i]);
}
fprintf(pipe, "e\n");
fflush(pipe);

#ifdef WIN32
    _pclose(pipe);
#else
    pclose(pipe);
#endif

return 0;
}

```

GitHub link: <https://github.com/1kkiRen/ALGAJoint2>