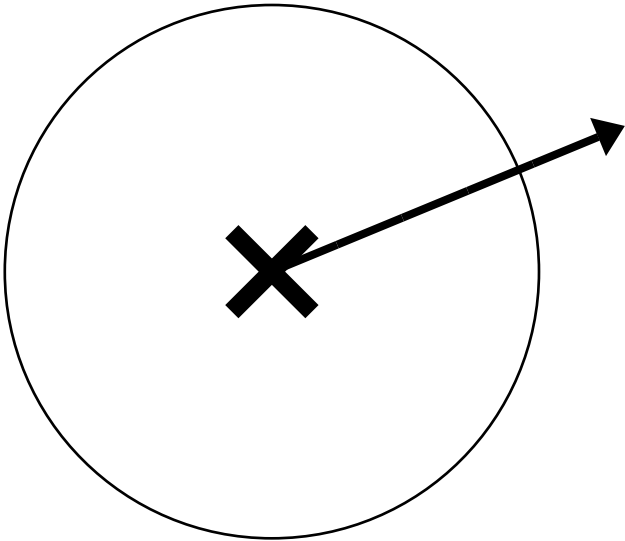


The Agent

step01_asimpleagent



```
Agent myAgent;

void setup() {
  size(320, 240);
  smooth();
  noFill();
  ellipseMode(CENTER);

  myAgent = new Agent();
  myAgent.position.set(width/2, height/2);
  myAgent.velocity.set(14, 18);
  myAgent.radius = 15;
}

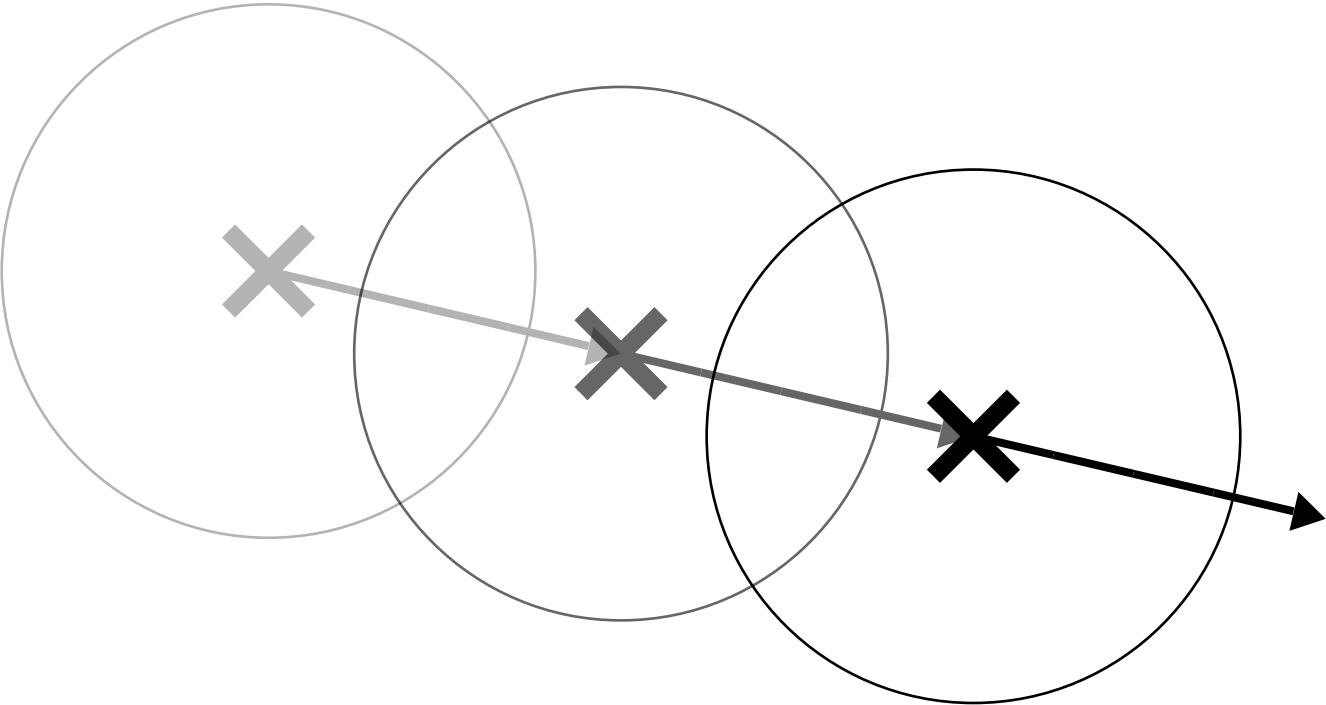
void draw() {
  background(255);
  myAgent.draw();
}

class Agent {

  Vector2f position = new Vector2f();
  Vector2f velocity = new Vector2f();
  float radius = 0;

  void draw() {
    stroke(0);
    ellipse(position.x, position.y, radius, radius);
    stroke(255, 0, 0);
    line(position.x, position.y,
         position.x + velocity.x, position.y + velocity.y);
  }
}
```

step02_movinginadirection



```
class Agent {  
  
    Vector2f position = new Vector2f();  
    Vector2f velocity = new Vector2f();  
    float radius = 0;  
  
    void draw() {  
        stroke(0);  
        ellipse(position.x, position.y, radius, radius);  
        stroke(255, 0, 0);  
        line(position.x, position.y,  
            position.x + velocity.x, position.y + velocity.y);  
    }  
}
```

```
class Agent {  
  
    Vector2f position = new Vector2f();  
    Vector2f velocity = new Vector2f();  
    float radius = 0;  
  
    void draw() {  
        stroke(0);  
        ellipse(position.x, position.y, radius, radius);  
        stroke(255, 0, 0);  
        line(position.x, position.y,  
             position.x + velocity.x, position.y + velocity.y);  
    }  
  
    void loop() {  
        position.add(velocity);  
    }  
}
```

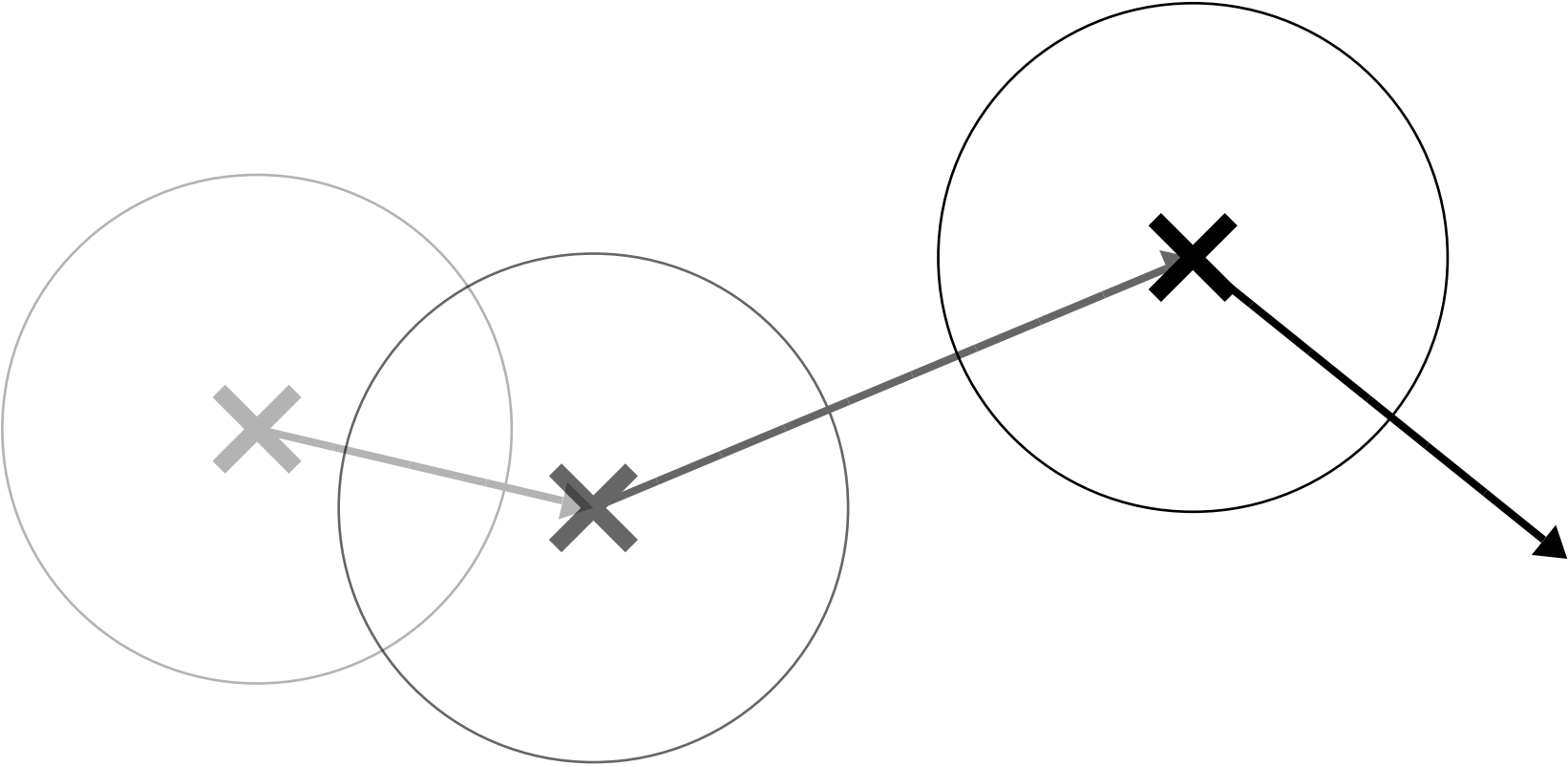
```
/* SIMPLE */
```

```
void loop() {  
    position.add(velocity);  
}
```

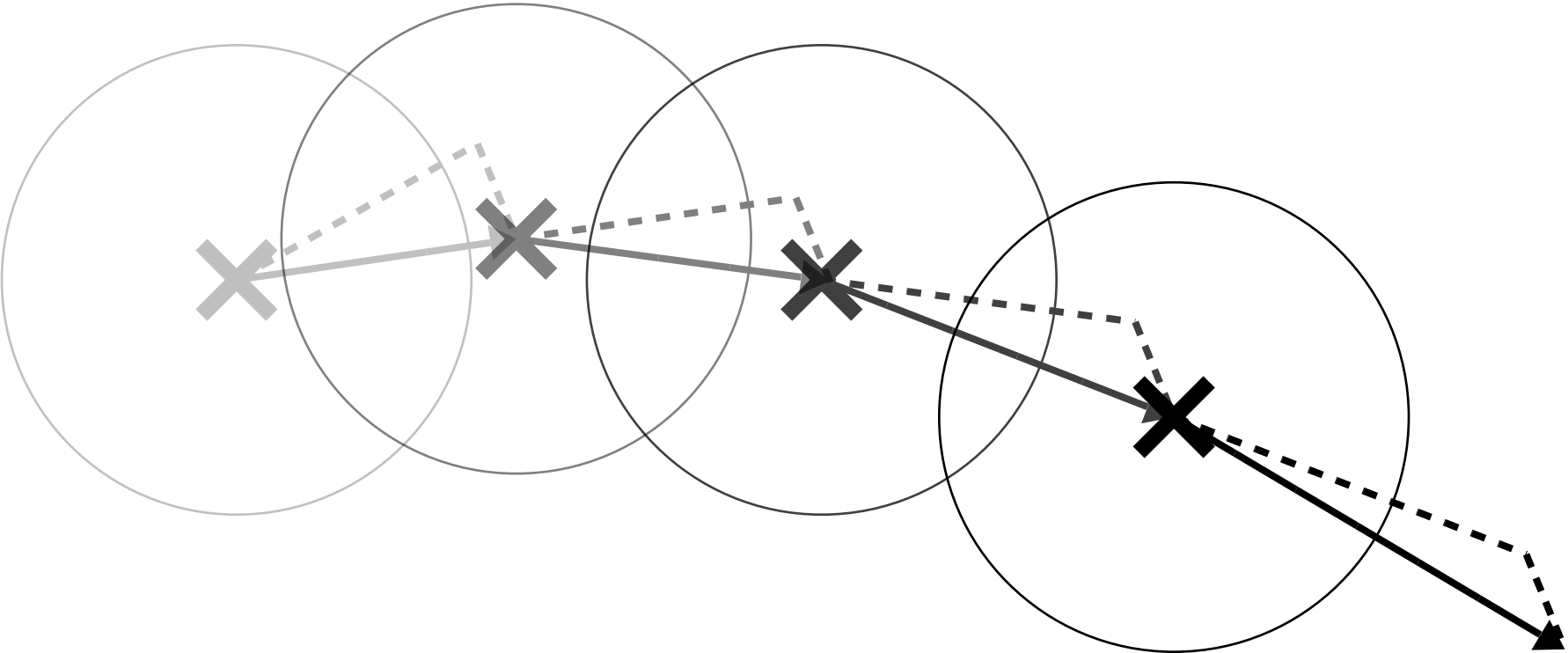
```
/* TIME BASED */
```

```
void loop(float theDeltaTime) {  
  
    float myAccelerationSpeed = acceleration.length();  
  
    if (myAccelerationSpeed > maxacceleration) {  
        acceleration.normalize();  
        acceleration.multiply(maxacceleration);  
    }  
  
    Vector2f myTimerAcceleration = new Vector2f();  
    myTimerAcceleration.set(acceleration);  
    myTimerAcceleration.multiply(theDeltaTime);  
  
    velocity.add(myTimerAcceleration);  
  
    float mySpeed = velocity.length();  
    if (mySpeed > maxspeed) {  
        velocity.normalize();  
        velocity.multiply(maxspeed);  
    }  
  
    Vector2f myTimerVelocity = new Vector2f();  
    myTimerVelocity.set(velocity);  
    myTimerVelocity.multiply(theDeltaTime);  
  
    position.add(myTimerVelocity);  
}
```

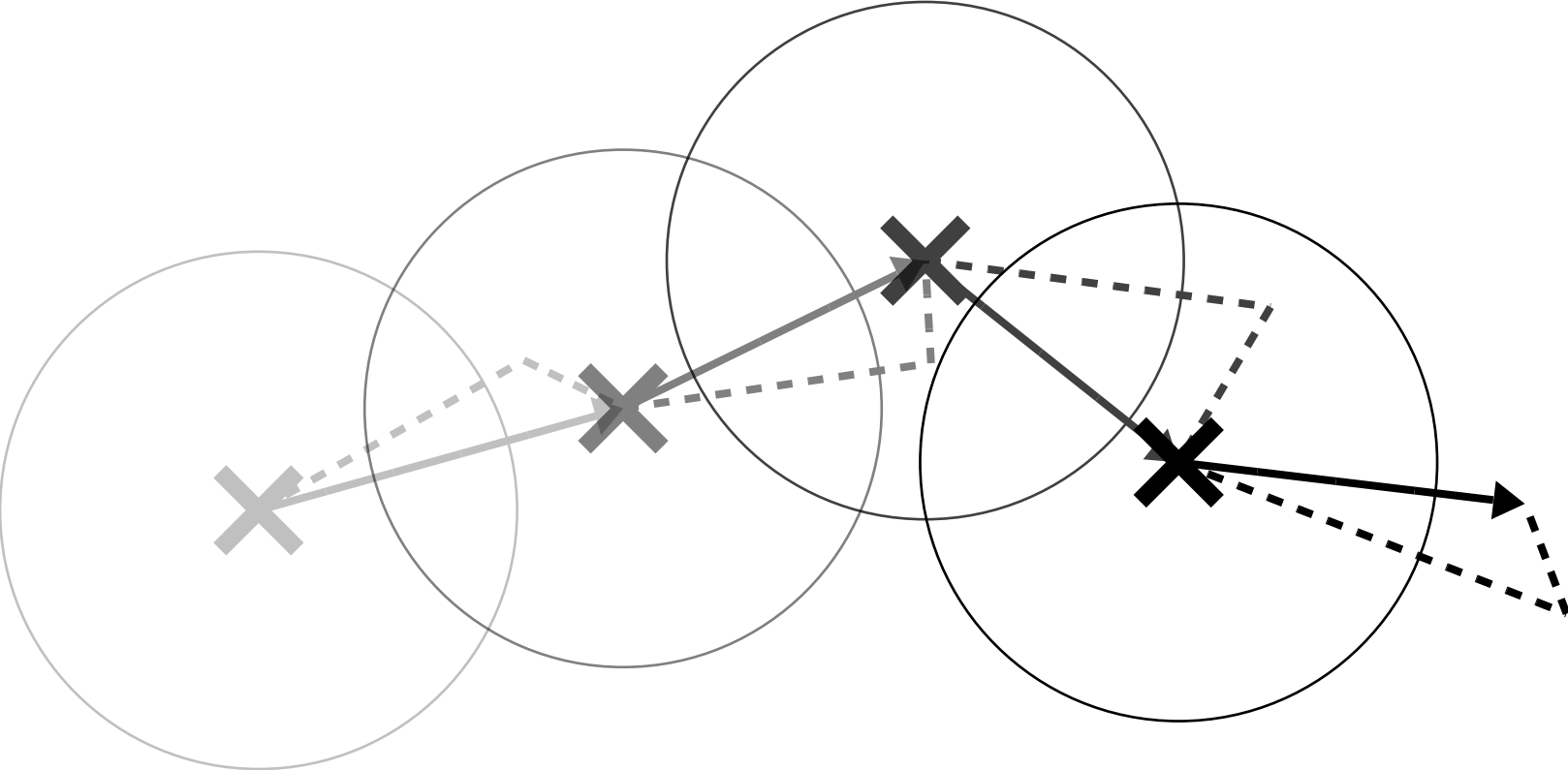
step03_movingindifferentdirections



step04_movingsmoothlyindifferentdirections



step05_movingatconstantspeed



step06_turningatconstantspeed
step07_introducingtime