



T: 604.822.9677 | F: 604.822.9676 | science.coop@ubc.ca | www.sciencecoop.ubc.ca

# Kyle Mackenzie

portfolio | 1mackenziekyle@gmail.com | github.com/1mackenziekyle | linkedin.com/in/kyle-mackenzie-url

# TECHNICAL SKILLS

Languages: Python, C/C++, Java, JavaScript, Matlab

Frameworks / Packages: Tensorflow, PyTorch, OpenCV, ROS, Numpy, Pandas, Matplotlib & Seaborn

Tools/Environments: Git, Jupyter Notebooks, Unix Command Line

## **EDUCATION**

## University of British Columbia

Vancouver, BC

Engineering Physics - Bachelor of Applied Science

Sep. 2020 - May 2025 (expected)

Coursework: Software Design, Microcomputers, Signals and Systems, Machine Learning, Calculus, PDEs.

## Relevant Experience

# Controls Systems Co-op

September 2023 – Present

Corvus Energy Richmond, BC

- Utilized MATLAB and Simulink to develop and test control algorithms for battery management systems.
- Developed a thermal model of the precharge system of the battery pack to control the precharge current.

Research Assistant May 2023 – Present

Cognitive Neuroscience of Schizophrenia Lab, BC Children's Hospital

Vancouver, BC

- Wrote a python script to perform Constrained Principal Component Analysis on brain fMRI data.
- Developed, refactored, and tested MATLAB code to perform CPCA on multiple datasets.

#### Full-Stack Developer Co-op

Jan. 2022 – Apr. 2022

ICBC

Vancouver, BC

- Reduced scripting development time by 50% using a new software library, Robot Framework.
- Developed prototype for automation of company process to reduce labour and resources spent and expedite results to customers.
- Prototyped a 3D, gamified version of current ICBC Knowledge Practice Test to increase customer engagement.

## Drivetrain Firmware Developer

Sep. 2022 – Present

UBC Formula Electric Student Design Team

Vancouver, BC

- Researched existing algorithms on torque vectoring algorithms for electric vehicles.
- Developed a high-level torque vectoring algorithm for the UBC Formula Electric vehicle.
- Wrote embedded-C code on an STM32F1 board to control torque requests to the motors.
- Led testing and iteration of the torque vectoring algorithm.

## TECHNICAL PROJECTS

## Robot Design & Fabrication | 4 person project - C/C++, OnShape

Oct. 2021

- Designed the CAD model, circuit boards, and wrote the firmware in C for a wheeled robot to navigate a course and collect objects as part of the ENPH 253 course.
- Fabricated robot using sheet metal parts, laser-cut hardboard, and 3D-printed components.

# **Rap-GPT** | Python, PyTorch

Aug. 2021

- Implemented and trained a Generative Transformer model from scratch to generate rap lyrics.
- Finetuned model to generate lyrics that rhyme and follow a specific style.

## Self-Driving with Deep-Q and Q-Learning | Python, Tensorflow

Sep. 2020 - Oct. 2020

• Developed a Reinforcement Learning agent first with a Q-Learning model, then a Q-Learning with neural net model (Deep-Q Learning) to take in a raw video feed and output driving commands.