

(unit - 3).

Oscillators -

(sinusoidal oscillator)

Non-sinusoidal

-Astable

multivib.

multivibrator

and

triangular wave generator

$$\begin{array}{c}
 j\omega_0 \\
 \leftarrow X \quad \rightarrow X \\
 (s+j\omega_0) \quad s-j\omega_0 \\
 K \quad \longrightarrow \quad K e^{-j\omega t} \\
 (s+j\omega_0) \quad (s-j\omega_0)
 \end{array}$$

stable

$$\begin{array}{c}
 K \\
 \leftarrow \quad \rightarrow \\
 (s+j\omega_0) \quad (s-j\omega_0)
 \end{array}$$

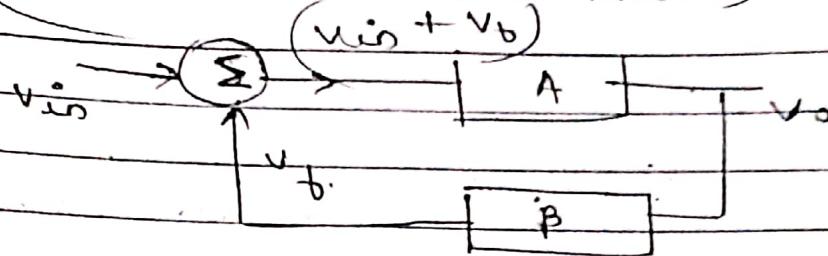
$$\frac{K_1}{(s+j\omega_0)} + \frac{K_2}{(s-j\omega_0)}$$

don't have real part

$$e^{-j\omega_0 t} \quad e^{j\omega_0 t}$$

To make system oscillator poles must be on imaginary axis

Bark-Hausen's criterion) —



$$v_f = \beta v_o.$$

$$v_o = A(v_{in} + v_f)$$

$$v_o = A[v_{in} + \beta v_o]$$

$$v_o(1 - A\beta) = A v_{in}$$

$$v_o = A v_{in} \quad \text{or} \quad \frac{v_o}{v_{in}} = \frac{A}{1 - A\beta}$$

Q.f. $(1 - A\beta) \neq 0.$

$$\frac{v_o}{v_{in}} \rightarrow \infty$$

$$(v_o \rightarrow \text{finite})$$

it means $v_{in} \rightarrow 0.$

it means v_o will be finite unless $v_{in} = 0$

$\checkmark (A\beta = 1)$.

(no op-amps)

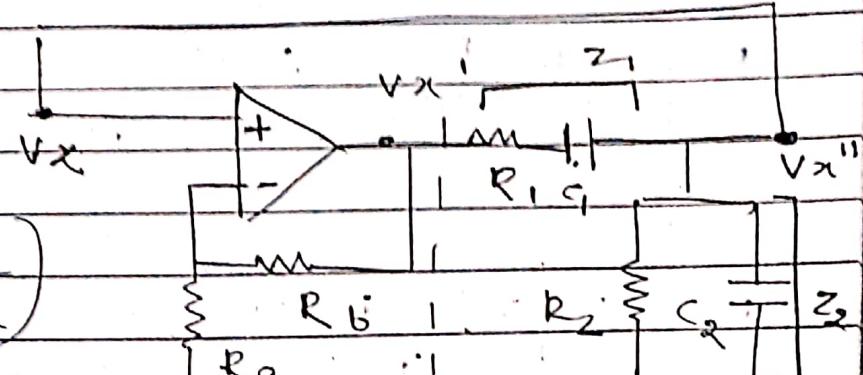
$$|A\beta| = 1 \quad \left(A\beta = 0^\circ \text{ or } 360^\circ \text{ or multiple of } 2\pi \right)$$

According to Bark-Hausen's criteria
the system will oscillate iff the
loop gain is 1. This means —

- (i) The magnitude of the loop gain is '1'
- (ii) The phase shift across the loop is ' 0° ' or multiple of ' 2π '

(Oscillators) :-

(1) (Wein Bridge oscillator)



$$Vx' = Vx \left(1 + \frac{R_b}{R_a} \right)$$

$$Vx'' = Vx' \cdot \frac{z_2}{z_1 + z_2} = A \cdot B.$$

$$z_1 = R_1 + \frac{1}{sC_1} = (R_1 C_1 s + 1)$$

$$z_2 = R_2 \cdot \frac{1}{sC_2} = \frac{R_2}{R_2 + \frac{1}{sC_2}} = \frac{R_2}{(1 + R_2 C_2 s)}$$

$$= Vx \left(1 + \frac{R_b}{R_a} \right) \cdot \frac{R_2}{(1 + R_2 C_2 s)} \cdot \frac{(R_1 C_1 s + 1) + R_2}{sC_1 (1 + R_2 C_2 s)}$$

$$= Vx \left(1 + \frac{R_b}{R_a} \right) \cdot \frac{R_2}{1 + R_2 C_2 s} \cdot \frac{(R_1 C_1 s + 1)(R_2 C_2 s + 1) + R_2 C_1 s}{(R_1 C_1 s + 1)(R_2 C_2 s + 1) + R_2 C_1 s}$$

$$= Vx \left(1 + \frac{R_b}{R_a} \right) \frac{R_2 C_1 s}{[(R_1 C_1 s + 1)(R_2 C_2 s + 1) + R_2 C_1 s]}$$

$$= Vx \left(1 + \frac{R_b}{R_a} \right) \frac{(R_2 C_1 s)}{R_1 C_1 C_2 s^2 + R_2 C_2 s + R_1 C_1 s + 1 + R_2 C_1 s}$$

$$V_{out} = \left(1 + \frac{R_b}{R_a}\right) V_x \frac{(R_2 C_1 s)}{R_1 R_2 C_1 C_2 s^2 + j[R_1 C_1 + R_2 C_2 + R_2 C_1] s}$$

$(s = j\omega)$

$$I = \left(1 + \frac{R_b}{R_a}\right) \frac{j\omega R_2 C_1}{-R_1 R_2 C_1 C_2 \omega^2 + j[R_1 C_1 + R_2 C_2 + R_2 C_1] \omega t}$$

$$I = \frac{\left(1 + \frac{R_b}{R_a}\right) j\omega R_2 C_1}{\left(1 - \omega^2 R_1 R_2 C_1 C_2\right) + j\omega(R_1 C_1 + R_2 C_2 + R_2 C_1)}$$

To satisfy Barkhausen's criterion
 (or phase shift) $\left(1 - \omega^2 R_1 R_2 C_1 C_2\right) = 0$.

as $j\omega R_2 C_1$
 leading by $\frac{\pi}{2}$

and $j\omega(R_1 C_1 + R_2 C_2 + R_2 C_1)$

in lagging
 by $\frac{\pi}{2}$

$$\omega = \frac{1}{\sqrt{R_1 R_2 C_1 C_2}}$$

(or magnitude)

$$I = \left(1 + \frac{R_b}{R_a}\right) \frac{j\omega R_2 C_1}{j\omega(R_1 C_1 + R_2 C_2 + R_2 C_1)}$$

$$I = \left(1 + \frac{R_b}{R_a}\right) \frac{(R_2 C_1)}{R_1 C_1 + R_2 C_2 + R_2 C_1}$$

$$R_1 C_1 + R_2 C_2 + R_2 C_1 = \left(1 + \frac{R_b}{R_a}\right) R_2 C_1$$

$$\frac{R_1}{R_2} + \frac{C_2 + 1}{C_1} = \left(1 + \frac{R_b}{R_a}\right)$$

$$\frac{R_1}{R_a} = \frac{R_1 + C_2}{R_2 C_1}$$

H

Qb $R_1 = R_2$ and $C_1 = C_2 = C$

$$\omega_0 = \frac{1}{RC}$$

$$f_0 = \frac{1}{2\pi RC}$$

$$\left| \frac{R_b}{R_a} = 2 \right|$$

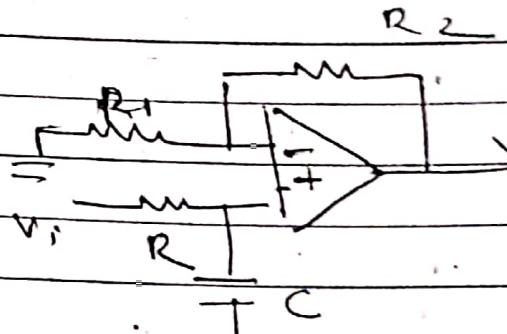
(i) To calculate the frequency of oscillation the phase shift criteria for Barkhausen must be satisfied.

(ii) The gain constraint will be calculated is to be calculated by satisfying the magnitude criteria of Barkhausen.

RC phaser shift oscillator)

Tutorial) -

Numerical) -



$$\frac{V_o(s)}{V_i(s)} = \frac{K \omega_c}{(s + \omega_c)} = \frac{K / R_C}{(s + 1 / R_C)}$$

$$f_c = 100 \text{ Hz}$$

$$\text{dc gain} = 10.$$

$$K = \frac{1 + R_2}{R_1}$$

$$\Rightarrow \frac{1 + R_2}{R_1} = 10$$

$$\frac{R_2}{R_1} = 10$$

$$R_2 = 9 R_1$$

$$\text{if } R_1 = 1 \text{ k} \quad (\text{dc gain}) \\ R_2 = 9 \text{ k}$$

$$f_c = \frac{1}{2\pi R C} = 100.$$

$$\text{if } R = 1 \text{ k}$$

$$C = \frac{1}{2\pi \times 10^3 \times 100} = 10^{-5} \text{ F} \\ = 2 \times 10^{-14} \\ = 0.6 \times 10^{-5} \\ = 1.6 \times 10^{-6}$$

(2)

~~cut off frequency = -3 dB frequency at which gain is 3 dB down.~~

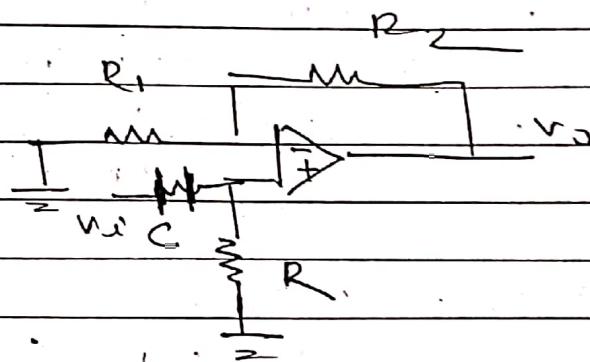
$$= 20 \log \left(\frac{V_o}{V_i} \right)$$

$$= 20 \log \left(\frac{1}{\sqrt{2}} \right)$$

$$= 20 \left(0 - \frac{1}{2} \log 2 \right)$$

$$= -3.01 \text{ dB}$$

(2)



ac. gain = 10.

$$\frac{V_o(s)}{V_i(s)} = \frac{k s}{s + \omega_c}$$

$$= \frac{k}{1 + \frac{1}{R_C C}}$$

$$\left(\frac{s + 1}{R_C C} \right)$$

$$k \cdot \left(1 + \frac{R_2}{R_1} \right) = 10$$

$$\frac{R_2}{R_1} = 9$$

$$R_2 = 9 R_1$$

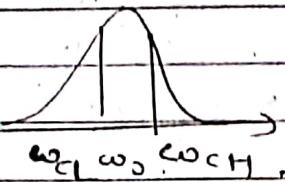
$$let R_1 = 1 k$$

$$R_2 = 9 k$$

$$f_c = \frac{1}{2\pi R C} = \frac{1}{2 \times 3.14 \times 1 \times C}$$

$$C = \frac{1}{2 \times 3.14 \times 1 \times 9} = 1.6 \mu F$$

(3)



$$b_0 = 100 \text{ Hz}$$

$$f_{CH} - f_{C1} = 50 \text{ Hz}$$

$$f_{CH} = 125 \text{ Hz} = \frac{1}{2\pi R_L C_1}$$

$$f_{C1} = 75 \text{ Hz} = \frac{1}{2\pi R_H C_1}$$

$$H(s) = \frac{K \omega_0 s}{s^2 + (\frac{\omega_0 s}{Q})^2 + \omega_0^2}$$

$$= \frac{K \omega_0 \omega}{-\omega^2 + (\frac{\omega_0}{Q}) \omega + \omega_0^2}$$

$$= K \cdot Q$$

$$K \cdot Q = 20$$

$$Q = \frac{b_0}{B \cdot \omega} = \frac{100}{50} = 2$$

$$K \cdot 2 = 20$$

$$(K = 10)$$

$$K^2 = 10$$

$$K = 3.3$$

$$K^2 = \left(1 + \frac{R_2}{R_1}\right)$$

$$3.3^2 = 1 + \frac{R_2}{R_1}$$

Design a band stop filter having
lower cut off frequency 75 Hz.
higher cut off frequency 125 Hz.
pass band gain 10.

$$\frac{V_o(s)}{V_i(s)} = -K \frac{s^2 + 2\omega_L s + \omega_L \omega_H}{s^2 + (\omega_L + \omega_H) s + \omega_L \omega_H}$$

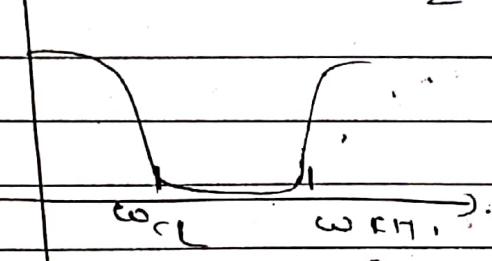
$$10 = 10 = \left(1 + \frac{R_2}{R_1} \right)$$

$$R_2 = 9 R_1$$

$$(R_2 = 9 R_1)$$

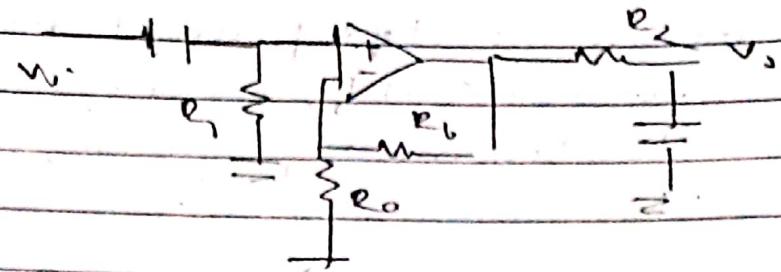
$$10 = R_1 K D$$

$$R_2 = 9 K D$$

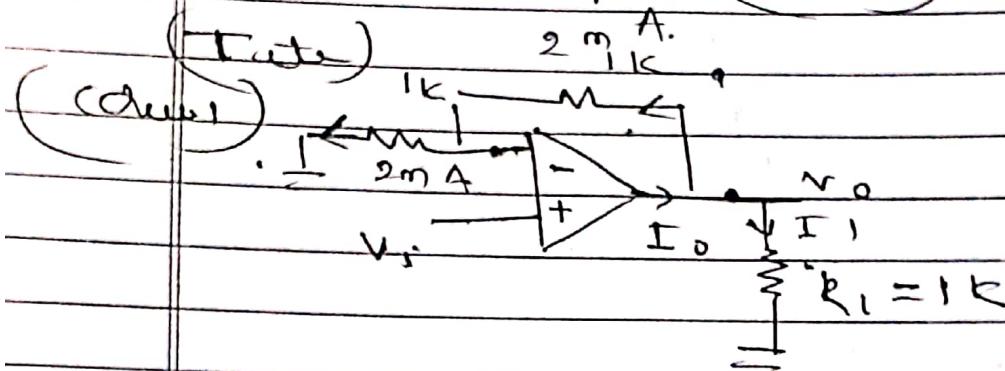


$$75 \text{ Hz} = \frac{1}{2\pi f_{cL} R_L C_1}$$

$$125 = \frac{1}{2\pi f_{cH} R_H C_H}$$



$$\left(1 + \frac{R_b}{R_a}\right) = \left(\frac{1 + R_2}{R_1}\right)^2$$



$$v_o = 2 v_i$$

$$I_o = ?$$

$$v_o = \left(1 + \frac{R_2}{R_1}\right) v_i$$

$$v_o = (1 + 1) v_i$$

$$= 2 \times 2$$

$$= 4 \text{ Volts}$$

$$I_o = \frac{V_o}{R_L}$$

$$= \frac{V_o}{1 \times 10^3}$$

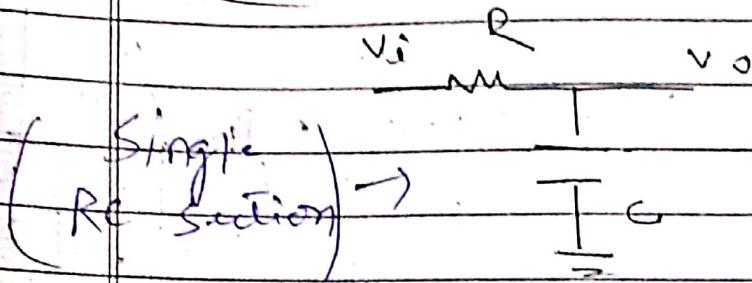
$$= 4 \times 10^{-3}$$

$$= 4 \text{ mA ans.}$$

$$I_o = (4 + 2)$$

$$= 6 \text{ mA ans.}$$

(2) (RC phase shift oscillator) -

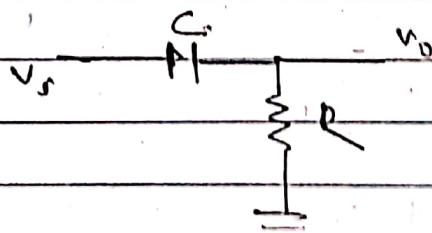


Analyzing for
Phase shift & Gain

$$H(s) = \frac{v_o(s)}{v_i(s)} = \frac{V_{SC}}{R + V_{SC}} = \frac{1}{1 + sCR}$$

$$H(j\omega) = \frac{1}{1 + j\omega CR}$$

$$\boxed{H(j\omega) = \tan^{-1}(\omega CR)}$$



$$H(s) = \frac{v_o(s)}{v_i(s)} = \frac{R}{(R + V_{SC})} = \frac{sCR}{sCR + 1}$$

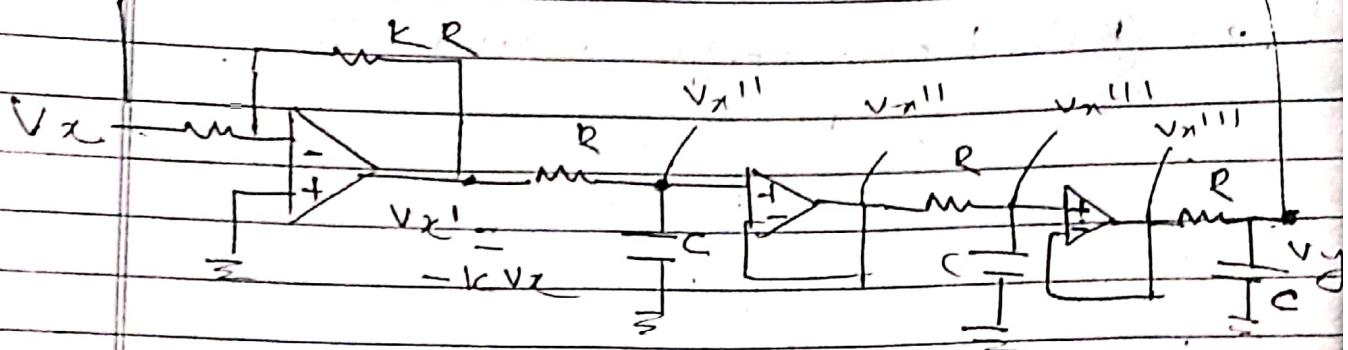
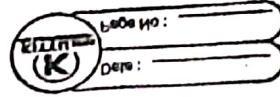
$$H(j\omega) = \frac{j\omega CR}{j\omega CR + 1}$$

$$\boxed{H(j\omega) = \frac{1}{2} + \tan^{-1}(\omega CR)}$$

Hence one RC section will provide maximum phase shift of 90° for $\omega \rightarrow 0$ & $\omega \rightarrow \infty$.

It means single RC section will always provide less than 90° phase shift.

RC Phase shift Oscillator



$$V_{x''} = V_x \left(\frac{1}{1 + sCR} \right)$$

$$V_{x'''} = V_{x''} \left(\frac{1}{1 + sCR} \right)$$

$$V_y = V_{x'''} = V_x \left(\frac{1}{1 + sCR} \right)^3$$

$$V_x = -1 \cdot V_x \left(\frac{1}{1 + sCR} \right)^3$$

$$V_x = -1 \cdot \left(\frac{1 + s^2 C^2 R^2 + 3sC R + 3s^2 C^2 R^2}{1 + s^2 C^2 R^2} \right)^3$$

$$I = -k$$

$$1 + s^2 C^2 R^2 + 3sC R + 3s^2 C^2 R^2$$

$$I = \cancel{A_R}$$

$$I = -k$$

$$1 + j\omega^2 C^2 R^2 + 3j\omega R C + 3\omega^2 C^2 R^2$$

$$I = -k$$

$$(1 - 3\omega^2 C^2 R^2) + j(3\omega C R - \omega^2 C^2 R^2)$$

For oscillating phase condition

$$B \omega L R = \cos^2(\omega t) = 0$$

freq. of oscillation

$$\omega_0 = \frac{\sqrt{3}}{RC}$$

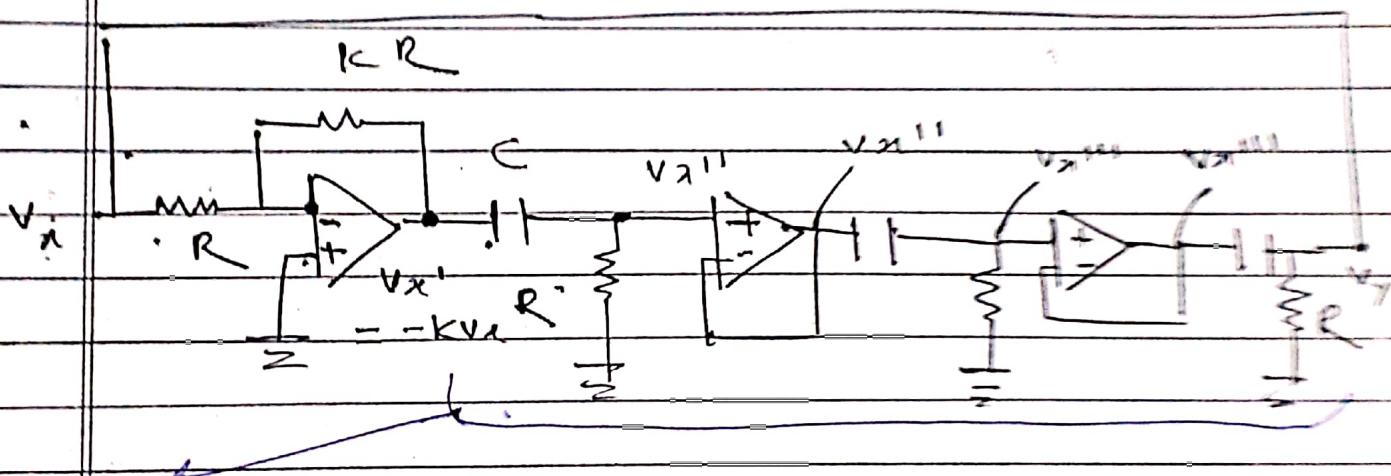
$$1 = -k \\ (1 - 3 \times 3)$$

gains \rightarrow

$$|k| = 8$$

$$\omega_0 = \frac{\sqrt{3}}{RC}$$

$$b_0 = \frac{\sqrt{3}}{2\pi RC}$$



in this feedback

$$N/W, \text{ the position } \frac{\pi}{2} - \tan^{-1}(\omega CR) = 60^\circ$$

if $R/F C$ has been changed

$$\tan^{-1}(\omega CR) = 30^\circ$$

$$\omega CR = \frac{1}{\sqrt{3}}$$

from previously

used feedback N/W

$$\omega = \frac{1}{\sqrt{3}RC}$$

\leftarrow freq of oscillation

$$\text{Fig. 2) } \frac{sCR}{1+sCR} = \frac{j\omega R}{1+j\omega CR} = j\frac{\omega}{\sqrt{3}}$$

$$|H(j\omega)| = \frac{K_B}{\sqrt{1 + (\frac{\omega}{\omega_B})^2}}$$

$$\Rightarrow \frac{1 \times \sqrt{3}}{\sqrt{3} \times \sqrt{4}} = \frac{\sqrt{3}}{2} = \frac{1}{2}$$

$$K \times \frac{1}{2} \times \frac{1}{2} \times \frac{1}{2} = 1$$

$$(K \times \frac{1}{8}) = 1$$

Gain \rightarrow K = 8

L.C oscillators:-

Tank circuit :-

→ first of all switch 1

is connected to ① (battery) \Rightarrow capacitor will be charged

→ After that switch is connected to ②

capacitor will start discharging, electrostatic energy ($\frac{q^2}{2C}$) is started to convert into magnetostatic energy ($\frac{1}{2}Li^2$)

applying KVL .

$$\frac{q}{C} - L \frac{di}{dt} = 0 \quad i' = -\frac{dq}{dt}$$

$$\frac{q}{C} - L \frac{d}{dt} \left[\frac{dq}{dt} \right] = 0 \Rightarrow L \frac{d^2q}{dt^2} + \frac{1}{C} q = 0$$

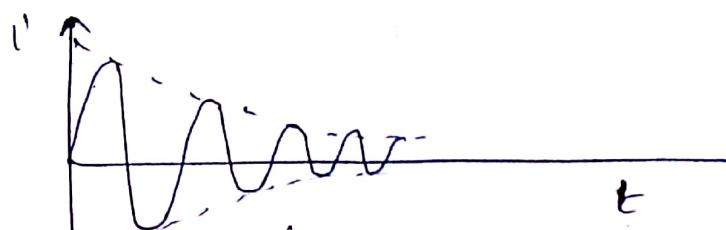
$$\boxed{\frac{d^2q}{dt^2} + \frac{1}{LC} q = 0}$$

→ This eqn will lead to sinusoidal oscillations (ideally)

→ But due to loss the oscillations generated will be damped in nature.

→ To get sustained oscillation, losses

should be compensated by extra energy by using amplification



(Damped oscillations)



(Sustained oscillations)

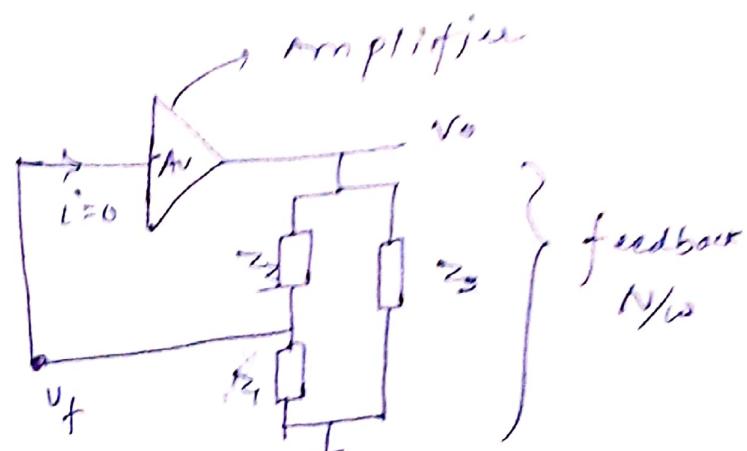
General Configuration of LC oscillation:

for amplifier

i/p impedance $z_i \rightarrow \infty$

o/p impedance $z_o \rightarrow R_o$

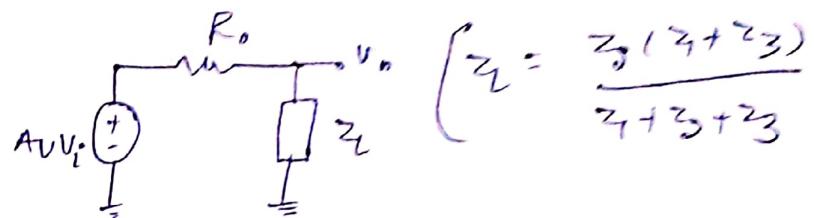
Gain $\rightarrow Av$ (180°)



as $z_i \rightarrow \infty \Rightarrow i=0 \Rightarrow z_1 \text{ & } z_3 \text{ are in series}$

for amplifier :

$$v_o = Av v_i \times \frac{z_L}{R_o + z_L}$$



forward gain $A = \frac{v_o}{v_i} = Av \frac{z_L}{R_o + z_L}$

$$\boxed{A = Av \frac{z_L}{R_o + z_L}}$$

for feedback factor $\beta = \frac{v_f}{v_o} = \frac{z_1}{z_1 + z_3}$

loop gain $AB = Av \frac{z_L}{R_o + z_L} \cdot \frac{z_1}{z_1 + z_3}$

$$AB = Av \cdot \frac{\frac{z_2(z_1 + z_3)}{(z_1 + z_2 + z_3)}}{\frac{R_o + \frac{z_2(z_1 + z_3)}{(z_1 + z_2 + z_3)}}{(z_1 + z_2 + z_3)}} \cdot \frac{z_1}{z_1 + z_3}$$

$$AB = \frac{Av \cdot z_2(z_1 + z_3)}{R_o(z_1 + z_2 + z_3) + z_2(z_1 + z_3)} \cdot \frac{z_1}{(z_1 + z_3)}$$

$$\boxed{AB = \frac{Av \cdot z_1 z_2}{R_o(z_1 + z_2 + z_3) + z_2(z_1 + z_3)}}$$

{ for all components used in feedback are Reactive
 in nature $\Rightarrow z = jx$
 if component is inductor $\Rightarrow x = \omega L$
 if component is capacitor $\Rightarrow x = -\frac{1}{\omega c}$

$$\text{Hence } z_1 = jx_1, z_2 = jx_2 \text{ & } z_3 = jx_3$$

\Rightarrow loop gain

$$A_{FB} = \frac{Av \cdot jx_1 \cdot jx_2}{R_o(jx_1 + jx_2 + jx_3) + jx_2(jx_1 + jx_3)}$$

$$A_{FB} = \frac{-Av x_1 x_2}{jR_o(x_1 + x_2 + x_3) - x_2(x_1 + x_3)}$$

for 180° phase shift

$$jR_o(x_1 + x_2 + x_3) = 0$$

$$\boxed{x_1 + x_2 + x_3 = 0} \quad (x_1 + x_3 = -x_2)$$

$$A_{FB} = -\frac{Av x_1 x_2}{-x_2(x_1 + x_3)} = -\frac{Av x_1}{x_2}$$

$$\text{for } |A_{FB}| = 1 \Rightarrow Av \frac{x_1}{x_2} = 1$$

$$\Rightarrow \boxed{Av = \frac{x_2}{x_1}}$$

① Colpitts Hartley oscillator :-

for Colpitts oscillator

- $Z_1 \rightarrow$ capacitor ($X_1 = -\frac{1}{\omega_1}$)
- $Z_2 \rightarrow$ capacitor ($X_2 = -\frac{1}{\omega_2}$)
- $Z_3 \rightarrow$ Inductor ($X_3 = j\omega L_3$)

for freq. of oscillation

$$X_1 + X_2 + X_3 = 0$$

$$-\frac{1}{\omega_1} - \frac{1}{\omega_2} + j\omega L_3 = 0$$

$$\frac{1}{\omega} \left(\frac{C_1 + C_2}{C_{eq}} \right) = \omega L_3$$

$$\omega^2 = \frac{1}{L_3 \left(\frac{C_1 + C_2}{C_{eq}} \right)} = \frac{1}{L_3 C_{eq}} \quad (C_{eq} = \frac{C_1 C_2}{C_1 + C_2})$$

$$\omega_0 = \frac{1}{\sqrt{L_3 C_{eq}}}$$

or

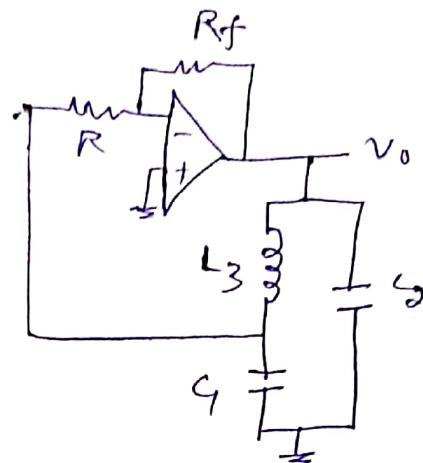
$$f_0 = \frac{1}{2\pi\sqrt{L_3 C_{eq}}}$$

for gain

$$Av = \frac{X_2}{X_1} = \frac{R_f}{R}$$

$$\frac{R_f}{R} = \frac{Y_{SC_2}}{Y_{SC_1}}$$

$$\frac{R_f}{R} = \frac{C_1}{C_2}$$



② Hartley
~~Coupled~~ oscillator →

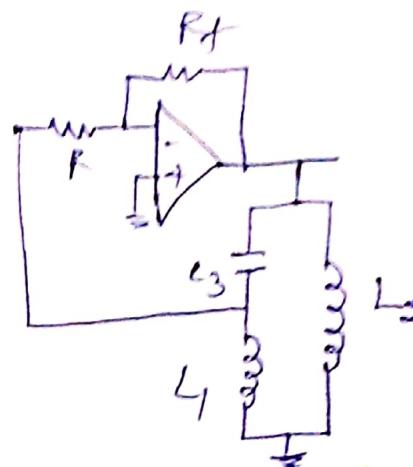
Hartley
 for ~~Coupled~~ oscillator

$z_1 \rightarrow$ Inductor ($X_1 = \omega L_1$)

$z_2 \rightarrow$ Inductor ($X_2 = \omega L_2$)

$z_3 \rightarrow$ Capacitor ($X_3 = -\frac{1}{\omega C_3}$)

for freq. of oscillations



$$X_1 + X_2 + X_3 = 0$$

$$\omega L_1 + \omega L_2 - \frac{1}{\omega C_3} = 0$$

$$\omega (L_1 + L_2) = \frac{1}{\omega C_3}$$

$$\omega^2 = \frac{1}{(L_1 + L_2)C_3} = \frac{1}{L_{eq}C_3} \quad (L_{eq} = L_1 + L_2)$$

$$\boxed{\omega_0 = \frac{1}{\sqrt{L_{eq}C_3}}} \quad \text{or} \quad \boxed{f_0 = \frac{1}{2\pi\sqrt{L_{eq}C_3}}}$$

for gain

$$AV = \frac{X_2}{X_1} = \frac{R_f}{R}$$

$$\frac{\omega L_2}{\omega L_1} = \frac{R_f}{R}$$

$$\boxed{\frac{R_f}{R} = \frac{L_2}{L_1}}$$

③ Clapp oscillator:

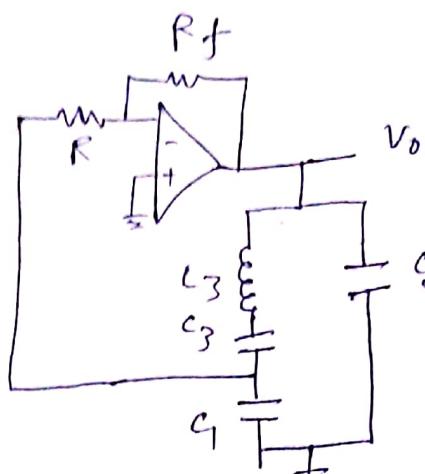
it is modified Colpitt's oscillator

where

$$X_1 \rightarrow -\frac{1}{\omega C_1}$$

$$X_2 \rightarrow -\frac{1}{\omega S}$$

$$X_3 \rightarrow \omega L_3 - \frac{1}{\omega C_3}$$



for frequency of oscillations:

$$X_1 + X_2 + X_3 = 0$$

$$-\frac{1}{\omega C_1} - \frac{1}{\omega S} + \omega L_3 - \frac{1}{\omega C_3} = 0$$

$$\frac{1}{\omega} \left(\frac{1}{C_1} + \frac{1}{S} + \frac{1}{C_3} \right) = \omega L_3 \quad (\text{if } \frac{1}{C_{eq}} = \frac{1}{C_1} + \frac{1}{S} + \frac{1}{C_3})$$

$$\frac{1}{\omega C_{eq}} = \omega L_3$$

$$\Rightarrow \omega_0^2 = \frac{1}{L_3 C_{eq}}$$

$$\boxed{\omega_0 = \frac{1}{\sqrt{L_3 C_{eq}}}}$$

$$\text{or} \quad \boxed{f_0 = \frac{1}{2\pi\sqrt{L_3 C_{eq}}}}$$

$$\text{for Gain} \quad A_V = \frac{X_2}{X_1} = \frac{R_f}{R}$$

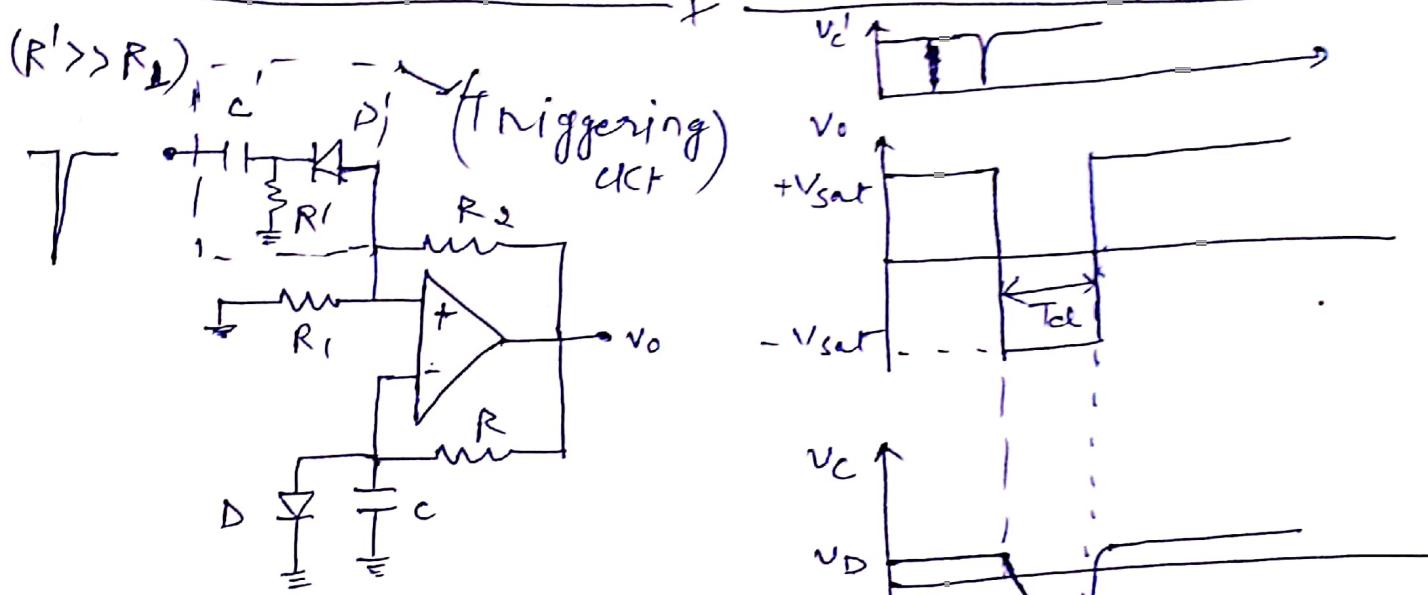
$$\frac{R_f}{R} = \frac{-Y_{ws}}{-Y_{wq}}$$

$$\boxed{\frac{R_f}{R} = \frac{G_1}{G_2}}$$

Non Sinusoidal Oscillators :-

- ① Square Wave Generator or Astable Multivibrator
 - ② Triangular Wave Generator
 - ③ Monostable Multivibrator or Pulse Generator
 - ④ Bistable Multivibrator (or Schmitt Trigger)
- (①, ② + ④) \Rightarrow Already covered in unit - 5

③ Monostable Multivibrator or Pulse Generator :-



$$v_+ = \frac{R_1}{R_1 + R_2} v_o = \beta v_o \quad (\beta = \frac{R_1}{R_1 + R_2})$$

As there is a +ve feedback

Hence $v_o = +V_{sat}$ if $v_{id} > 0$ ($v_+ > v_-$)
 $= -V_{sat}$ if $v_{id} < 0$ ($v_+ < v_-$)

if $v_o = +V_{sat} \Rightarrow v_+ = \frac{R_1}{R_1 + R_2} V_{sat}$ or βV_{sat}

Diode is forward Biased, Hence the capacitor voltage is fixed to diode voltage (0.7 or V_D)

when a negative impulse is applied to triggering circuit, D' will be forward biased and $V_f < V_D$, such that $V_{id} < 0$

$\Rightarrow V_o$ will switch to $-V_{sat}$ from $+V_{sat}$. capacitor will start Discharging.

$$v_f = -\beta V_{sat}$$

$$V_c(t) = V_f - (V_f - V_i) e^{-t/Rc}$$

$$V_f = -V_{sat}, \quad V_i = V_D$$

$$\text{at } t = T_d, \quad V_c(t) = -\beta V_{sat}$$

$$-\beta V_{sat} = -V_{sat} - (-V_{sat} - V_D) e^{-T_d/Rc}$$

$$(V_{sat} + V_D) e^{-T_d/Rc} = V_{sat} (1 - \beta)$$

$$T_d = R_c \ln \frac{V_D + V_{sat}}{V_{sat} (1 - \beta)}$$

$$T_d = R_c \ln \frac{1 + V_D/V_{sat}}{1 - \beta}$$

Pulse width $T = T_d$

$$T = R_c \ln \frac{1 + V_D/V_{sat}}{1 - \beta}$$

as $V_D \ll V_{sat}$ $\Rightarrow V_D/V_{sat} \ll 1$

$$\Rightarrow \boxed{\text{Pulse width } T = R_c \ln \frac{1}{1 - \beta}}$$