

Amir Yakubov

BD-2008

Task 2

Step 1.

/home/hpc2022/bda2008/ayakubov/Task 2/				
Имя	Размер	Изменено	Права	Владелец
↑ ..		20.10.2022 12:52:44	rw-rw-r-x	hpc2022
raytracing_threads.out	208 KB	21.10.2022 16:44:36	rw-rw-r-x	hpc2022
raytracing_threads.cpp	5 KB	21.10.2022 16:44:22	rw-rw-r--	hpc2022
raytracing_16.jpg	29 KB	21.10.2022 16:46:01	rw-rw-r--	hpc2022
raytracing_8.jpg	29 KB	21.10.2022 16:45:52	rw-rw-r--	hpc2022
raytracing_4.jpg	29 KB	21.10.2022 16:45:43	rw-rw-r--	hpc2022
raytracing_2.jpg	29 KB	21.10.2022 16:45:31	rw-rw-r--	hpc2022
raytracing_1.jpg	29 KB	21.10.2022 16:45:18	rw-rw-r--	hpc2022

(Forgot to make it in the beginning)

Step 2.

```
hpc2022@ubuntu-srv: ~/bda2008/ayakubov/Task 2
GNU nano 4.8 raytracing_threads.cpp

scene.addLight(PointLight({-15, 0, -15}, white));
scene.addLight(PointLight({1, 1, 0}, blue));
scene.addLight(PointLight({0, -10, 6}, red));

scene.setBackground({0.05, 0.05, 0.08});
scene.setAmbient({0.1, 0.1, 0.1});
scene.setRecursionLimit(20);

scene.setCamera(Camera({0, 0, -20}, {0, 0, 0}));

// This is a thread function for C++ threads.
// TODO: modify this function for a thread to be able to compute some specified part of the image.
// For example, now ranges of pixels by X and Y always start from 0.
// Think what additional arguments may be required to compute a range not starting from 0.
void threadFunc(Scene &scene, ViewPlane &viewPlane, Image &image, int sizeX, int sizeY, int numOfSamples, int start, int end) {
    for(int x = start; x < end; x++) {
        for(int y = 0; y < sizeY; y++) {
            const auto color = viewPlane.computePixel(scene, x, y, numOfSamples);
            image.set(x, y, color);
        }
    }
}

int main(int argc, char **argv) {
    // Number of threads to use is the first parameter now.
    // The other parameters are the same as in the sequential app.
    int numberOfThreads = (argc > 1 ? std::stoi(argv[1]) : 1);
    int viewPlaneResolutionX = (argc > 2 ? std::stoi(argv[2]) : 600);
    int viewPlaneResolutionY = (argc > 3 ? std::stoi(argv[3]) : 600);
    int numSamples = (argc > 4 ? std::stoi(argv[4]) : 1);
    std::string sceneFile = (argc > 5 ? argv[5] : "");

    Scene scene;
    if (sceneFile.empty()) {
        initScene(scene);
    } else {
        scene.loadFromFile(sceneFile);
    }

    const double backgroundSizeX = 4;
    const double backgroundSizeY = 4;
    const double backgroundDistance = 15;

    const double viewPlaneDistance = 5;
    const double viewPlaneSizeX = backgroundSizeX * viewPlaneDistance / backgroundDistance;
    const double viewPlaneSizeY = backgroundSizeY * viewPlaneDistance / backgroundDistance;

    ViewPlane viewPlane(viewPlaneResolutionX, viewPlaneResolutionY,
                        viewPlaneSizeX, viewPlaneSizeY, viewPlaneDistance);

    Image image(viewPlaneResolutionX, viewPlaneResolutionY); // computed image
    const double bl_s = viewPlaneResolutionX / numberOfThreads;
    vector<thread> threads;

    auto ts = hrc::now();

    // TODO: make each thread to compute different part of the image.
    // To do this first decide how the image should be partitioned.
    // then compute a partition and pass this information to each thread.
    for (int i = 0; i < numberOfThreads; i++) {
        int start = i * bl_s;
        int end = (i + 1) * bl_s;
        thread thr(threadFunc, ref(scene), ref(viewPlane), ref(image),
                  viewPlaneResolutionX, viewPlaneResolutionY, numSamples, start, end);
        threads.push_back(move(thr));
    }

    for (auto &thread : threads) {
        thread.join();
    }

    auto te = hrc::now();
    double time = duration<double>(te - ts).count();
}
```

```
hpc2022@ubuntu-srv: ~/bda2008/ayakubov/Task 2
GNU nano 4.8 raytracing_threads.cpp

int numSamples = (argc > 4 ? std::stoi(argv[4]) : 1);
std::string sceneFile = (argc > 5 ? argv[5] : "");

Scene scene;
if (sceneFile.empty()) {
    initScene(scene);
} else {
    scene.loadFromFile(sceneFile);
}

const double backgroundSizeX = 4;
const double backgroundSizeY = 4;
const double backgroundDistance = 15;

const double viewPlaneDistance = 5;
const double viewPlaneSizeX = backgroundSizeX * viewPlaneDistance / backgroundDistance;
const double viewPlaneSizeY = backgroundSizeY * viewPlaneDistance / backgroundDistance;

ViewPlane viewPlane(viewPlaneResolutionX, viewPlaneResolutionY,
                    viewPlaneSizeX, viewPlaneSizeY, viewPlaneDistance);

Image image(viewPlaneResolutionX, viewPlaneResolutionY); // computed image
const double bl_s = viewPlaneResolutionX / numberOfThreads;
vector<thread> threads;

auto ts = hrc::now();

// TODO: make each thread to compute different part of the image.
// To do this first decide how the image should be partitioned.
// then compute a partition and pass this information to each thread.
for (int i = 0; i < numberOfThreads; i++) {
    int start = i * bl_s;
    int end = (i + 1) * bl_s;
    thread thr(threadFunc, ref(scene), ref(viewPlane), ref(image),
              viewPlaneResolutionX, viewPlaneResolutionY, numSamples, start, end);
    threads.push_back(move(thr));
}

for (auto &thread : threads) {
    thread.join();
}

auto te = hrc::now();
double time = duration<double>(te - ts).count();
}
```

Step 3.

a)

```

hpc2022@ubuntu-srv:~/bda2008/ayakubov/Task 2
std::cout
In file included from raytracing_threads.cpp:4:
/usr/include/c++/9/iostream:61:18: note: 'std::cout' declared here
61 | extern ostream cout; /// Linked to standard output
    | ~~~~~
raytracing_threads.cpp:88:34: error: 'endl' was not declared in this scope; did you mean 'std::endl'?
88 |     cout << "Time = " << time << endl;
    |                                  ^~~~~
    |                                  std::endl
In file included from /usr/include/c++/9/iostream:39,
from /usr/local/include/minirt/vector_3d.h:3,
from /usr/local/include/minirt/point_3d.h:3,
from /usr/local/include/minirt/camera.h:3,
from /usr/local/include/minirt/minirt.h:3,
from raytracing_threads.cpp:1:
/usr/include/c++/9/ostream:599:5: note: 'std::endl' declared here
599 |     endl(basic_ostream<CharT, _Traits>& __os)
    |     ^~~~
raytracing_threads.cpp:89:36: error: 'to_string' was not declared in this scope; did you mean 'std::__cxx11::to_string'?
89 |     image.saveJPG("raytracing_" + to_string(numberOfThreads) + ".jpg");
    |                                  ^~~~~~
    |                                  std::__cxx11::to_string
In file included from /usr/include/c++/9/string:55,
from /usr/include/c++/9/bits/locale_classes.h:40,
from /usr/include/c++/9/bits/ios_base.h:41,
from /usr/include/c++/9/ios:42,
from /usr/include/c++/9/iostream:38,
from /usr/local/include/minirt/vector_3d.h:3,
from /usr/local/include/minirt/point_3d.h:3,
from /usr/local/include/minirt/camera.h:3,
from /usr/local/include/minirt/minirt.h:3,
from raytracing_threads.cpp:1:
/usr/include/c++/9/bits/basic_string.h:6601:3: note: 'std::__cxx11::to_string' declared here
6601 |     to_string(long double __val)
    |     ^~~~~~
hpc2022@ubuntu-srv:~/bda2008/ayakubov/Task 2$ ls
raytracing.cpp
hpc2022@ubuntu-srv:~/bda2008/ayakubov/Task 2$ nano raytracing_threads.cpp
hpc2022@ubuntu-srv:~/bda2008/ayakubov/Task 2$ g++ -O2 -o raytracing_threads.out raytracing_threads.cpp -lminirt -lpthread
hpc2022@ubuntu-srv:~/bda2008/ayakubov/Task 2$ ./raytracing_threads.out 1 640 480 10
Time = 7.00166
hpc2022@ubuntu-srv:~/bda2008/ayakubov/Task 2$ ./raytracing_threads.out 2 640 480 10
Time = 3.58596
hpc2022@ubuntu-srv:~/bda2008/ayakubov/Task 2$ ./raytracing_threads.out 4 640 480 10
Time = 2.99317
hpc2022@ubuntu-srv:~/bda2008/ayakubov/Task 2$ ./raytracing_threads.out 8 640 480 10
Time = 2.13144
hpc2022@ubuntu-srv:~/bda2008/ayakubov/Task 2$ ./raytracing_threads.out 16 640 480 10
Time = 1.69476
hpc2022@ubuntu-srv:~/bda2008/ayakubov/Task 2$

```

b, c)

Number of threads	Execution time	Speedup(N)	Efficiency
1	7.00166	1	1
2	3.58596	1,95252	0,97626
4	2.99317	2,33921	0,58480
8	2.13144	3,28494	0,41061
16	1.69476	4,13135	0,25820

Conclusion.

First, I created bl_s(block_size), start and end, this loop is needed in order to go through the threads. After compiling with arguments, I conclude that the more treads, the less time it takes to compile, regarding speedup(N), on the contrary, it increases, and the efficiency decreases, but efficiency ≤ 1 .

Link to GitHub: <https://github.com/Am1rrr/hpc/tree/main/Task%202>