

GPIO BFM – Quick Reference

gpio_set (data_value, msg, data_port, [scope, msg_id_panel])

Example: gpio_set(C_BAUD_RATE, "Setting Baudrate to 9600", v_data_port, C_SCOPE, shared_msg_id_panel);

gpio_get (data_value, msg, data_port, [scope, [msg_id_panel])

Example: gpio_get(v_baudrate, "Read baudrate", v_data_port, C_SCOPE, shared_msg_id_panel);

gpio_check (data_exp, msg, data_port, [alert-level, [scope, [msg_id_panel, config]]]])

Example: gpio_check(x"3B", "Check data from UART RX", v_data_port, ERROR, C_SCOPE, shared_msg_id_panel);

gpio_expect (data_exp, msg, data_port, [timeout, [alert-level, [scope, [msg_id_panel, config]]]]])

Example: gpio_expect(x"0D", "Read UART RX until CR is found", v_data_port, 10 ms, ERROR, C_SCOPE, shared_msg_id_panel);

BFM Configuration record 't apio bfm config'

| Bi in comigaration record t_gpic_bim_ceimg | | | | | |
|--|--------------------|---------------------------|--|--|--|
| Record element | Type | C_GPIO_BFM_CONFIG_DEFAULT | | | |
| clock_period | time | -1 ns | | | |
| match_strictness | t_match_strictness | MATCH_STD | | | |
| id_for_bfm | t_msg_id | ID_BFM | | | |
| id_for_bfm_wait | t_msg_id | ID_BFM_WAIT | | | |
| id_for_bfm_poll | t_msg_id | ID_BFM_POLL | | | |

BFM non-signal parameters

| Name | Туре | Example(s) | Description |
|--------------|-------------------|---------------------------|--|
| data_value | std_logic_vector | x"D3" | The data value to be written to the register. |
| data_exp | std_logic_vector | x"0D" or C_UART_CR | The data value expected when reading the register. A mismatch results in an alert 'alert_level'. |
| timeout | time | 10 ms or C_CLK_PERIOD | The maximum time to pass before the expected data must be found. |
| | | | A timeout result in an alert 'alert_level'. |
| alert_level | string | ERROR or TB_WARNING | Set the severity for the alert that may be asserted by the method. |
| msg | string | "Set baudrate to 1MHz" | A custom message to be appended in the log/alert. |
| scope | string | "GPIO BFM" or C_SCOPE | A string describing the scope from which the log/alert originates. |
| | | | In a simple single sequencer typically "SBI BFM". In a verification component, typically "GPIO_VVC". |
| msg_id_panel | t_msg_id_panel | shared_msg_id_panel | Optional msg_id_panel, controlling verbosity within a specified scope. Defaults to a common ID panel |
| | | | defined in the adaptations package. |
| config | t_gpio_bfm_config | C_GPIO_BFM_CONFIG_DEFAULT | Configuration of BFM behaviour and restrictions. See section 2 for details. |



gpio_bfm_pkg.vhd



Copyright © 2017 by Bitvis AS. All rights reserved.



BFM details

1 BFM procedure details and examples

Procedure Description gpio_set() gpio_set (data_value, msg, data_port, [scope, [msg_id_panel]]) The gpio set() procedure will write the given data in 'data value' to the DUT. When called, the gpio set() procedure will write to the DUT register immediately, except bits set to "don't care" ('-'). The default value of scope is C SCOPE ("GPIO BFM") The default value of msg id panel is shared msg id panel, defined in UVVM Util. A log message is written if ID_BFM ID is enabled for the specified message ID panel. Data value is normalised to data port direction. Example: gpio set(C BAUDRATE 9600, "Set baudrate to 9600", v data port, C SCOPE, shared msg id panel, C GPIO BFM CONFIG DEFAULT); Suggested usage (requires local overload, see section 5): gpio set (C BAUDRATE 9600, "Set baudrate to 9600", v data port);

gpio_get()

gpio_get (data_value, msg, data_port, [scope, [msg_id_panel]])

The gpio get() procedure read the DUT register and return it in the data value parameter.

- The default value of scope is C SCOPE ("GPIO BFM")
- The default value of msg id panel is shared msg id panel, defined in UVVM Utli.
- A log message is written if ID_BFM ID is enabled for the specified message ID panel.

```
gpio get(v baudrate, "Read baudrate", v data port, C SCOPE, shared msg id panel);
Suggested usage (requires local overload, see section 5):
    gpio get(v baudrate, "Read baudrate");
```

support@bitvis.no +47 66 98 87 59 www.bitvis.no

gpio_check()

GPIO BFM - Quick Reference

gpio_check (data_exp, msg, data_port, [alert_level, [scope, [msg_id_panel, [config]]]])



The gpio_check() procedure read the DUT register and compares the data with the expected data in 'data_exp'. If the DUT data does not match the expected data, an alert with severity 'alert_level' will be triggered. If the DUT data matches 'data_exp', a message with ID config.id_for_bfm will be logged.

- The default value of scope is C SCOPE ("GPIO BFM")
- The default value of msg_id_panel is shared_msg_id_panel, defined in UVVM_Util.
- A log message is written if ID BFM ID is enabled for the specified message ID panel.
- The default value of alert_level is ERROR.
- Data exp is normalised to data port direction.

Example:

```
gpio_check(x"3B", "Check data from UART RX", v_data_port, ERROR, C_SCOPE, shared_msg_id_panel);
Suggested usage (requires local overload, see section 5):
   gpio check(x"3B", "Check data from UART RX");
```

gpio_expect()

gpio_expect (data_exp, msg, data_port, [timeout, [alert_level, [scope, [msg_id_panel, [config]]]])

The gpio_expect() procedure reads a register until the expected data, 'data_exp', is matched or until a timeout value is reached. If the received data does not match the expected data within the timeout delay, an alert with severity

- The default value of scope is C_SCOPE ("GPIO_BFM")
- The default value of msg_id_panel is shared_msg_id_panel, defined in UVVM_Util.
- A log message is written if ID_BFM ID is enabled for the specified message ID panel.
- The default value of alert level is ERROR.
- The default timeout is 0 ns.
- Data_exp is normalised to data_port direction.

Example:

```
gpio_expect(x"0B", "Read UART RX until CR is found", v_data_port, 10 ms, ERROR, C_SCOPE, shared_msg_id_panel);
Suggested usage (requires local overload, see section 5):
   gpio expect(x"0B", "Read UART RX until CR is found", v data port, 10 ms);
```

2 BFM Configuration record

Type name: t gpio bfm config

| Record element | Туре | C_SPI_BFM_CONFIG_DEFAULT | Description |
|------------------|--------------------|--------------------------|---|
| clock_period | time | -1 ns | Specifies the clock period |
| match_strictness | t_match_strictness | MATCH_STD | Specifies that the match need to be exact. See UVVM Utility Library Quick Reference |
| id_for_bfm | t_msg_id | ID_BFM | The message ID used as a general message ID in the SPI BFM |
| id_for_bfm_wait | t_msg_id | ID_BFM_WAIT | The message ID used for logging waits in the SPI BFM |
| id_for_bfm_poll | t_msg_id | ID_BFM_POLL | The message ID used for logging polling in the SPI BFM |

3 Compilation

The GPIO BFM may only be compiled with VHDL 2008. It is dependent on the UVVM Utility Library (UVVM-Util), which is only compatible with VHDL 2008.



See the separate UVVM-Util documentation for more info. After UVVM-Util has been compiled, the gpio bfm pkg.vhd BFM can be compiled into any desired library. See UVVM Essential Mechanisms located in uvvm vvc framework/doc for information about compile scripts.

Simulator compatibility and setup

See README.md for a list of supported simulators. For required simulator setup see UVVM-Util Quick reference.

Local BFM overloads

A good approach for better readability and maintainability is to make simple, local overloads for the BFM procedures in the TB process. This allows calling the BFM procedures with the key parameters only e.g.

```
gpio expect(x"F5", "Read UART RX until 0xF5 is found", v data port, 2 ms);
rather than
         gpio expect(x"F5", "Read UART RX until 0xF5 is found", v data port, 2 ms, ERROR,
                     C SCOPE, shared msg id panel, C GPIO BFM CONFIG DEFAULT);
```

By defining the local overload as e.g.:

```
procedure gpio check(
  constant data exp : in std logic vector;
  constant timeout : in time) is
begin
  gpio check(data exp,
                              -- keep as is
                             -- keep as is
           msg,
                            -- keep as is
           data port,
           timeout,
                             -- keep as is
           error,
                             -- Just use the default
           C SCOPE,
                             -- Just use the default
           shared msg id panel, -- Use global, shared msg id panel
           C GPIO CONFIG LOCAL); -- Use locally defined configuration or C GPIO BFM CONFIG DEFAULT
end;
```

Using a local overload like this also allows the following – if wanted:

- Set up defaults for constants. May be different for two overloads of the same BFM
- Apply dedicated message ID panel to allow dedicated verbosity control



Disclaimer: This IP and any part thereof are provided "as is", without warranty of any kind, express or implied, including but not limited to the warranties of merchantability, fitness for a particular purpose and noninfringement. In no event shall the authors or copyright holders be liable for any claim, damages or other liability, whether in an action of contract, tort or otherwise, arising from, out of or in connection with this IP.