**GPIO BFM** –Quick Reference

**BFM**

|  |
| --- |
| gpio\_set (data\_value, msg, data\_port, [scope, msg\_id\_panel]) |
| Example: gpio\_set(C\_BAUD\_RATE, “Setting Baudrate to 9600”, v\_data\_port, C\_SCOPE, shared\_msg\_id\_panel); |

|  |
| --- |
| gpio\_get (data\_value, msg, data\_port, [scope, [msg\_id\_panel]) |
| Example: gpio\_get(v\_baudrate, “Read baudrate”, v\_data\_port, C\_SCOPE, shared\_msg\_id\_panel); |

*gpio\_bfm\_pkg.vhd*

|  |
| --- |
| gpio\_check (data\_exp, msg, data\_port, [alert-level, [ scope, [msg\_id\_panel, config]]]]) |
| Example: gpio\_check(x”3B”, “Check data from UART RX”, v\_data\_port, ERROR, C\_SCOPE, shared\_msg\_id\_panel); |

|  |
| --- |
| gpio\_expect (data\_exp, msg, data\_port, [timeout, [alert-level, [scope, [msg\_id\_panel, config]]]]]) |
| Example: gpio\_expect(x”0D”, “Read UART RX until CR is found”, v\_data\_port, 10 ms, ERROR, C\_SCOPE, shared\_msg\_id\_panel); |

|  |  |  |
| --- | --- | --- |
| BFM Configuration record ´**t\_gpio\_bfm\_config´** | | |
| **Record element** | **Type** | **C\_GPIO\_BFM\_CONFIG\_DEFAULT** |
| clock\_period | time | 10 ns |
| match\_strictness | t\_match\_strictness | MATCH\_EXACT |
| id\_for\_bfm | t\_msg\_id | ID\_BFM |
| id\_for\_bfm\_wait | t\_msg\_id | ID\_BFM\_WAIT |
| id\_for\_bfm\_poll | t\_msg\_id | ID\_BFM\_POLL |
|  |  |  |

|  |  |  |  |
| --- | --- | --- | --- |
| BFM non-signal parameters | | | |
| **Name** | **Type** | **Example(s)** | **Description** |
| data\_value | std\_logic\_vector | x”D3” | The data value to be written to the register. |
| data\_exp | std\_logic\_vector | x”0D” or C\_UART\_CR | The data value expected when reading the register. A mismatch results in an alert ‘alert\_level’. |
| timeout | time | 10 ms or C\_CLK\_PERIOD | The maximum time to pass before the expected data must be found.  A timeout result in an alert ‘alert\_level’. |
| alert\_level | string | ERROR or TB\_WARNING | Set the severity for the alert that may be asserted by the method. |
| msg | string | “Set baudrate to 1MHz” | A custom message to be appended in the log/alert. |
| scope | string | “GPIO BFM” or C\_SCOPE | A string describing the scope from which the log/alert originates. In a simple single sequencer typically “SBI BFM”. In a verification component, typically “GPIO\_VVC”. |
| msg\_id\_panel | t\_msg\_id\_panel | shared\_msg\_id\_panel | Optional msg\_id\_panel, controlling verbosity within a specified scope. Defaults to a common ID panel defined in the adaptations package. |
| config | t\_gpio\_bfm\_config | C\_GPIO\_BFM\_CONFIG\_DEFAULT | Configuration of BFM behaviour and restrictions. See section 2 for details. |



BFM details

# BFM procedure details and examples

|  |  |
| --- | --- |
| **Procedure** | **Description** |
| **gpio\_set()** | **gpio\_set (data\_value, msg, data\_port, [scope, [msg\_id\_panel]])**  The gpio\_set() procedure will write the given data in ‘data\_value’ to the DUT.  When called, the gpio\_set() procedure will write to the DUT register immediately, except bits set to “don’t care” (‘-‘).   * The default value of scope is C\_SCOPE (“GPIO BFM”) * The default value of msg\_id\_panel is shared\_msg\_id\_panel, defined in UVVM\_Util. * A log message is written if ID\_BFM ID is enabled for the specified message ID panel. * Data\_value is normalised to data\_port direction.     Example:  gpio\_set(C\_BAUDRATE\_9600, “Set baudrate to 9600”, v\_data\_port, C\_SCOPE, shared\_msg\_id\_panel, C\_GPIO\_BFM\_CONFIG\_DEFAULT);  Suggested usage (requires local overload, see section 5):  gpio\_set(C\_BAUDRATE\_9600, “Set baudrate to 9600”, v\_data\_port); |
| **gpio\_get()** | **gpio\_get (data\_value, msg, data\_port, [scope, [msg\_id\_panel]])**  The gpio\_get() procedure read the DUT register and return it in the data\_value parameter.   * The default value of scope is C\_SCOPE (“GPIO BFM”) * The default value of msg\_id\_panel is shared\_msg\_id\_panel, defined in UVVM\_Utli. * A log message is written if ID\_BFM ID is enabled for the specified message ID panel.   Example:  gpio\_get(v\_baudrate, “Read baudrate”, v\_data\_port, C\_SCOPE, shared\_msg\_id\_panel);  Suggested usage (requires local overload, see section 5):  gpio\_get(v\_baudrate, “Read baudrate”); |
| **gpio\_check()** | **gpio\_check (data\_exp, msg, data\_port, [alert\_level, [scope, [msg\_id\_panel, [config]]]])**  The gpio\_check() procedure read the DUT register and compares the data with the expected data in ‘data\_exp’. If the DUT data does not match the expected data, an alert with severity ‘alert\_level’ will be triggered. If the DUT data matches ‘data\_exp’, a message with ID config.id\_for\_bfm will be logged.   * The default value of scope is C\_SCOPE (“GPIO BFM”) * The default value of msg\_id\_panel is shared\_msg\_id\_panel, defined in UVVM\_Util. * A log message is written if ID\_BFM ID is enabled for the specified message ID panel. * The default value of alert\_level is ERROR. * Data\_exp is normalised to data\_port direction.   Example:  gpio\_check(x"3B", “Check data from UART RX”, v\_data\_port, ERROR, C\_SCOPE, shared\_msg\_id\_panel);  Suggested usage (requires local overload, see section 5):  gpio\_check(x”3B”, “Check data from UART RX”); |
| **gpio\_expect()** | **gpio\_expect (data\_exp, msg, data\_port, [timeout, [alert\_level, [scope, [msg\_id\_panel, [config]]]])**  The gpio\_expect() procedure reads a register until the expected data, ‘data\_exp’, is matched or until a timeout value is reached.  If the received data does not match the expected data within the timeout delay, an alert with severity   * The default value of scope is C\_SCOPE (“GPIO BFM”) * The default value of msg\_id\_panel is shared\_msg\_id\_panel, defined in UVVM\_Util. * A log message is written if ID\_BFM ID is enabled for the specified message ID panel. * The default value of alert\_level is ERROR. * The default timeout is 0 ns. * Data\_exp is normalised to data\_port direction.   Example:  gpio\_expect(x"0B", “Read UART RX until CR is found”, v\_data\_port, 10 ms, ERROR, C\_SCOPE, shared\_msg\_id\_panel);  Suggested usage (requires local overload, see section 5):  gpio\_expect(x”0B”, “Read UART RX until CR is found”, v\_data\_port, 10 ms); |

# BFM Configuration record

Type name: t\_gpio\_bfm\_config

|  |  |  |  |
| --- | --- | --- | --- |
| **Record element** | **Type** | **C\_SPI\_BFM\_CONFIG\_DEFAULT** | **Description** |
| clock\_period | time | 10 ns | Specifies the clock period |
| match\_strictness | t\_match\_strictness | MATCH\_EXACT | Specifies that the match need to be exact. See UVVM Utility Library Quick Reference |
| id\_for\_bfm | t\_msg\_id | ID\_BFM | The message ID used as a general message ID in the SPI BFM |
| id\_for\_bfm\_wait | t\_msg\_id | ID\_BFM\_WAIT | The message ID used for logging waits in the SPI BFM |
| id\_for\_bfm\_poll | t\_msg\_id | ID\_BFM\_POLL | The message ID used for logging polling in the SPI BFM |
|  |  |  |  |

# Compilation

The GPIO BFM may only be compiled with VHDL 2008. It is dependent on the UVVM Utility Library (UVVM-Util), which is only compatible with VHDL 2008.

See the separate UVVM-Util documentation for more info. After UVVM-Util has been compiled, the gpio\_bfm\_pkg.vhd BFM can be compiled into any desired library.

See UVVM Essential Mechanisms located in uvvm\_vvc\_framework/doc for information about compile scripts.

## Simulator compatibility and setup

See README.md for a list of supported simulators.

For required simulator setup see UVVM-Util Quick reference.

# Local BFM overloads

A good approach for better readability and maintainability is to make simple, local overloads for the BFM procedures in the TB process.

This allows calling the BFM procedures with the key parameters only

e.g.

gpio\_expect(x”F5”, “Read UART RX until 0xF5 is found”, v\_data\_port, 2 ms);

rather than

gpio\_expect(x”F5”, “Read UART RX until 0xF5 is found”, v\_data\_port, 2 ms, ERROR,

C\_SCOPE, shared\_msg\_id\_panel, C\_GPIO\_BFM\_CONFIG\_DEFAULT);

By defining the local overload as e.g.:

procedure gpio\_check(

constant data\_exp : in std\_logic\_vector;

constant msg : in string;

constant data\_port : in std\_logic\_vector;

constant timeout : in time) is

begin

gpio\_check(data\_exp, -- keep as is

msg, -- keep as is

data\_port, -- keep as is

timeout, -- keep as is

error, -- Just use the default

C\_SCOPE, -- Just use the default

shared\_msg\_id\_panel, -- Use global, shared msg id panel

C\_GPIO\_CONFIG\_LOCAL); -- Use locally defined configuration or C\_GPIO\_BFM\_CONFIG\_DEFAULT

end;

Using a local overload like this also allows the following – if wanted:

* Set up defaults for constants. May be different for two overloads of the same BFM
* Apply dedicated message ID panel to allow dedicated verbosity control

**INTELLECTUAL**

**PROPERTY**

Disclaimer: This IP and any part thereof are provided "as is", without warranty of any kind, express or implied, including but not limited to the warranties of merchantability, fitness for a particular purpose and noninfringement.  
In no event shall the authors or copyright holders be liable for any claim, damages or other liability, whether in an action of contract, tort or otherwise, arising from, out of or in connection with this IP.