Subhransu S. Bhattacharjee

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Bio: PhD researcher advancing generative and vision-language models to represent spatio-temporal uncertainty for reliable robotic decision-making; interests also include time-series uncertainty analysis in noisy regimes, convex optimization & optimal transport.

Education

Doctor of Philosophy Resident Scholar

School of Computing, Australian National University, Australia

Apr 2023 – Expected Apr 2027

- O Thesis Topic: Probabilistic 3D Spatio-Semantic autonomous reasoning under dynamic uncertainty with Generative Models
- O Supervisors: Dr. Rahul Shome, Dr. Dylan Campbell, and Prof. Stephen Gould

Bachelor of Engineering

First Class Honours

School of Engineering, Australian National University, Australia

Jul 2018 – Dec 2022

- o Major: Mechatronic Systems Engineering (Merit List in the Honours cohort)
- O Minors: Mathematics and Electronic Communication Systems
- O Certifications: Game Theory, Stanford; Machine Learning Production; Project Management, Google; Financial Markets, Yale
- O Thesis project: Whiplash Gradient Descent Dynamics (Supervisor: Prof. Ian Petersen)

Summer Schools: Robotic Vision Summer School (2024); London School of Economics (2019): Practical Machine Learning

Selected Publications & Preprints

Subhransu S. Bhattacharjee, Dylan Campbell & Rahul Shome: Believing is Seeing: Unobserved Object Detection using Generative Models. IEEE/CVF Conference on Computer Vision and Pattern Recognition (CVPR), 2025. paper | project page. Pre-trained generative models can infer spatio-semantic distributions of occluded and out-of-frame objects across 2D, 2.5D, and 3D scenes by implicitly learning contextual scene relationships.

Subhransu S. Bhattacharjee, Hao Lu, Dylan Campbell & Rahul Shome: Into the Unknown: Using Generative Models to Sample Priors of Environment Uncertainty for Planning in Configuration Spaces. arXiv:2510.11014, 2025 — under review at ICRA. arXiv.

Leveraging pre-trained generative model priors as uncertainty quantifiers enables motion planning algorithms to remain robust across distributions of partially observed plausible environment configurations.

Subhransu S. Bhattacharjee & Ian Petersen: Analysis of the Whiplash Gradient Descent Dynamics. Asian Journal of Control (Special Issue), Wiley, 2023. DOI: 10.1002/asjc.3153.

A feedback-based inertial gradient method with adaptive damping achieves provable polynomial and exponential convergence rates that extend classical optimization theory to high-dimensional settings.

Scholarships & Awards

- 2025 VC Travel Grant (Winner), Australian National University.
- 2025 Invited attendee (fully funded), Citadel & Citadel Securities PhD Summit, London.
- **2025** Residential Mentor Scholarship, ANU.
- 2024 Optiver PhD Quant Lab Program (select participant).
- 2023 ANU International University Research Scholarship.
- 2023 Higher Degree by Research Merit Stipend.
- 2022 Highly Recommended Paper, Asian Control Conference.
- 2022 Highest in ENGN4627: Robotics.
- 2021 High Commendation, Australia & New Zealand Control Conference.
- **2021** ANU Chancellor's International Scholarship.
- 2020 ANU-VIT International Transfer Program scholarship.
- 2019 Chancellor's Special Achiever Award, VIT.
- 2019 Google & HUL Hackathon Finalist.

Internships

Optiver APAC, Sydney

Quantitative Research Intern (Machine Learning)

Nov 2024 - Feb 2025

Analyzed large-scale market and microstructure data; identified inefficiencies in the **Korean** market & Co-built a proprietary real-time ML decision system; achieved **94%** accuracy in historical backtests.

Decimal Point Analytics, India

ML Research Intern — Financial NLP, Supervisor: Mr Paresh Sharma, MD

Dec 2020 - Jan 2021

Engineered and optimized a financial metadata store for a Transformer-based QA system for large scale document analysis, coordinated client reviews for product reassessment.

Academic Research

Research School of Management, Australian National University

Commonwealth Bank of Australia

Graduate Research Assistant — FinTech & Al, Pl: Dr Priya Muthukannan

Sep 2023 - Sep 2024

- O Analyzed open-banking regimes using a dynamic-capabilities lens to inform strategy.
- O Delivered introductory data-analysis instruction for Business Information Systems.
- O Built assessment frameworks for banks AI adoption and responses to technological shifts.

School of Computing, Australian National University

Undergraduate Researcher — Foundational Deep Learning, Supervisor: Prof Richard Hartley, FAA Mar 2022 – Jun 2022

- Studied invertibility of differentiable mappings with neural networks; achieved a 72% hit rate (RMSE criterion) using dense positional encodings.
- O Demonstrated limitations of normalizing flows for global invertibility, highlighting locality of neural function approximation.

School of Engineering, Australian National University

Undergraduate Researcher — Control & Optimisation, Supervisor: Prof Ian Petersen, FAA

Dec 2021 - Mar 2022

- Designed Lyapunov-based approaches for predicting convergence rates in high-resolution ODE models; developed a complexity model for feedback systems without closed-form solutions.
- Selected papers:
 - Analysis of Closed-Loop Inertial Gradient Dynamics Asian Control Conference (ASCC) 2022.
 - A Closed-Loop Gradient Descent Algorithm Applied to Rosenbrocks Function ANZCC 2021.
- Open-source code: 1ssb/Whiplash.

Teaching & Service

- Head Tutor, Building Cyber-Physical Systems School of Cybernetics, ANU (Mar 2025–Nov 2025): Co-designed and delivered project-based modules across microprocessors/robotics/ML; led NAO labs; coordinated assessments.
- o **Tutor, Introduction to Machine Learning** School of Computing, ANU (Jun 2025–Nov 2025): Taught ML mathematics and optimization; marked exams for **250** students; ran tutorials and assessed projects.
- o **Tutor, Power Systems & Control Theory** School of Engineering, ANU (Jul 2022–Sep 2023): Ran labs (ENGN8824, **12** MSc); led workshops (ENGN4628, **34**); delivered targeted tutoring (ENGN4625, **16**).
- Reviewer: CVPR 2026; AAAI 2025; IROS 2025; ICRA 2025–2026; Asian Journal of Control (2023); American Control Conference (2022); Australia & New Zealand Control Conference (2021–2022).
- Volunteering Experience: Friends of Tribal Society, 2017-18; Set4ANU Mentor 2023-24; Techlauncher Manager 2024

Skills

- Languages: Python; C/C++; CUDA; Embedded C; MATLAB; JavaScript; HTML/CSS; LATEX
- **LLM/VLM APIs & Models:** OpenAl API (GPT-4o/4.1); Anthropic (Claude 3.5 *Sonnet*/Haiku); Google Al Studio (Gemini 1.5 Pro/Vision); Alibaba (Qwen2/Qwen2-VL); Meta (Llama 3/3.1); Mistral (Large; Pixtral); LLaVA 1.6; Florence-2; BLIP-2; CLIP; GroundingDINO; SAM/SAM2; Hugging Face Inference; Replicate; AWS Bedrock; Azure OpenAl
- Vision & 3D & Generative: Diffusion; segmentation/detection; 3D reconstruction; TorchVision; OpenCV; Open3D; PyTorch3D; trimesh
- Performance/Systems: Mixed precision (AMP); torch.compile; Inductor/TorchDynamo; custom CUDA kernels; Numba; CuPy; ONNX Runtime; TensorRT; Triton (GPU DSL); Nsight Systems/Compute
- Data/Cloud/MLOps: PySpark; SQL; Airflow; FastAPI; REST; Weights&Biases; Git/GitHub; CI/CD (Actions)
- Containers & HPC: Docker; Podman; Apptainer (Singularity); NVIDIA Container Toolkit; Conda/Mamba; Lmod; SLURM

Selected Open Source Contributions: TorchKAN: Simplified KAN Model with Variations; Depth Anything V1/V2; Mangrove: A Dynamic Data Management System for Advanced AI Applications; Webcamdinov2: Video Inferencing with Webcam using DINOv2; Camera Ray Transformation Visualizer: A StreamLit App; RGB-Depth Cropper NPMv2.5.0