# Pirouette - Theory

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## 1 Syntax

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Locations
Synchronization Labels d
                                               := L \mid R
Choreography
                                             := () \mid X \mid \ell.e \mid \ell_1.e \rightsquigarrow \ell_2; C \mid \text{if } \ell.e \text{ then } C_1 \text{ else } C_2
                                                      \ell_1[d] \leadsto \ell_2; \ C \mid \mathbf{let} \ \ell.x \coloneqq C_1 \ \mathbf{in} \ C_2 \mid \mathbf{fun} \ X \Rightarrow C \mid C_1 \ C_2
                                                      (C_1,C_2) \mid \text{fst } C \mid \text{snd } C \mid \text{left } C \mid \text{right } C
                                                      match C with left X \Rightarrow C_1; right Y \Rightarrow C_2
                                             := () | num \mid x \mid e_1 \ binop \ e_2 \mid \mathbf{let} \ x = e_1 \ in \ e_2 \mid (e_1, e_2) \mid \mathbf{fst} \ e
Local Expressions
                                                      snd e \mid \text{left } e \mid \text{right } e \mid \text{match } e \text{ with left } x \Rightarrow e_1; \text{ right } y \Rightarrow e_2
Network Expressions
                                        E ::= X \mid () \mid \mathbf{fun} \ X \Rightarrow E \mid E_1 \ E_2 \mid \mathsf{ret}(e)
                                                      let ret(x) = E_1 in E_2 | send e to \ell; E | receive x from \ell; E
                                                      if E_1 then E_2 else E_3 | choose d for \ell; E
                                                      allow \ell choice L \Rightarrow E_1; R \Rightarrow E_2 \mid (E_1, E_2)
                                                      fst E \mid \text{snd } E \mid \text{left } E \mid \text{right } E
                                                      match E with left X \Rightarrow E_1; right Y \Rightarrow E_2
                                              := unit \mid \ell.t \mid \tau_1 \rightarrow \tau_2 \mid \tau_1 \times \tau_2 \mid \tau_1 + \tau_2 \mid
Choreographic Types
                                              := unit | int | bool | string | t_1 \times t_2 \mid t_1 + t_2
Local Types
                                        t
                                        T ::= \mathbf{unit} \mid \boxed{t} \mid T_1 \to T_2 \mid T_1 \times T_2 \mid T_1 + T_2
Network Types
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# 2 Type System

### 2.1 Local Language

$$\begin{array}{lll} \text{Loc - unit} & \frac{\text{Loc - var}}{x:t\in\Gamma} & \frac{\text{Loc - pair}}{\Gamma\vdash e_1:t_1} & \frac{\text{Loc - pair}}{\Gamma\vdash e_2:t_2} & \frac{\text{Loc - fst}}{\Gamma\vdash e:t_1\times t_2} \\ \hline \Gamma\vdash (\ ): \text{ unit} & \frac{x:t\in\Gamma}{\Gamma\vdash e:t_1\times t} & \frac{\Gamma\vdash e_1:t_1}{\Gamma\vdash (e_1,e_2):t_1\times t_2} & \frac{\Gamma\vdash e:t_1\times t_2}{\Gamma\vdash \text{ fst }e:t_1} \\ \hline \\ \frac{\text{Loc - snd}}{\Gamma\vdash e:t_1\times t_2} & \frac{\Gamma\vdash e_1:t_1}{\Gamma\vdash \text{ left }e_1:t_1+t_2} & \frac{\text{Loc - right}}{\Gamma\vdash e_2:t_2} \\ \hline \\ \frac{\Gamma\vdash e:t_1\times t_2}{\Gamma\vdash \text{ right }e_2:t_1+t_2} \\ \hline \\ \frac{\text{Loc - match}}{\Gamma\vdash e:t_1+t_2} & \frac{\Gamma\vdash e_1:t_3}{\Gamma\vdash e_1:t_3} & \Gamma, \ y:t_2\vdash e_2:t_3} \\ \hline \\ \frac{\Gamma\vdash (\text{match e with left }\times\Rightarrow e_1 \ ; \ \text{right } y\Rightarrow e_2):t_3} \\ \hline \end{array}$$

#### 2.2Network Language

Network Language 
$$\frac{\text{Network Language}}{\Gamma; \Delta \vdash (\ ): \ \text{unit}} \frac{X: T \in \Delta}{\Gamma; \Delta \vdash X: T} \frac{\prod\limits_{\Gamma: \Delta \vdash e: t}^{\text{RET}} \Gamma; \Delta \vdash e: t}{\Gamma; \Delta \vdash e: t}$$

$$\frac{\Gamma; \Delta \vdash (e) : t}{\Gamma; \Delta \vdash \text{ret } (e) : t}$$
Network - fun 
$$\frac{\Gamma; \Delta, X: T_1 \vdash E: T_2}{\Gamma; \Delta \vdash \text{fun } X \Rightarrow E: T_1 \rightarrow T_2} \frac{\prod\limits_{\Gamma: \Delta \vdash E_1: T_1 \rightarrow T_2}^{\text{Network - APP}} \Gamma; \Delta \vdash E_1: T_1 \rightarrow T_2}{\Gamma; \Delta \vdash E_1: T_1 \rightarrow T_2} \frac{\Gamma; \Delta \vdash E_2: T_1}{\Gamma; \Delta \vdash E_1: T_2}$$
Network - IF

$$\frac{\Gamma; \Delta \vdash E_1 : T_1 \quad \Gamma; \Delta \vdash E_2 : T_2 \quad \Gamma; \Delta \vdash E_3 : T_2}{\Gamma; \Delta \vdash \text{if } E_1 \text{ then } E_2 \text{ else } E_3 : T_2}$$

$$\begin{array}{ll} \frac{\text{Network - Def}}{\Gamma; \Delta \vdash E_1 : \boxed{t}} & \Gamma, x : t; \Delta \vdash E_2 : T_2 \\ \hline \Gamma; \Delta \vdash \text{let ret } (x) = E_1 \text{ in } E_2 : T_2 \\ \hline \\ \frac{\text{Network - Rev}}{\Gamma; \Delta \vdash \text{ receive } x \text{ from } \ell; E : T} \\ \hline \end{array}$$

$$\begin{split} & \overset{\text{NETWORK - ALLOW}}{\Gamma; \Delta \vdash E_1 : T} \quad \Gamma; \Delta \vdash E_2 : T \\ \hline & \Gamma; \Delta \vdash \text{(allow $\ell$ choice L} \Rightarrow E_1 \; ; \; R \Rightarrow E_2 \text{)} : T \end{split}$$

$$\begin{array}{ll} \text{Network - Pair} \\ \frac{\Gamma; \Delta \vdash E_1 : T_1 \quad \Gamma; \Delta \vdash E_2 : T_2}{\Gamma; \Delta \vdash (E_1, E_2) : T_1 \times T_2} & \frac{\Gamma; \Delta \vdash E : T_1 \times T_2}{\Gamma; \Delta \vdash \text{fst } E : T_1} & \frac{\Gamma; \Delta \vdash E : T_1 \times T_2}{\Gamma; \Delta \vdash \text{snd } E : T_2} \\ \frac{\text{Network - Left}}{\Gamma; \Delta \vdash E_1 : T_1} & \frac{\text{Network - Right}}{\Gamma; \Delta \vdash E_2 : T_2} \\ \frac{\Gamma; \Delta \vdash \text{left } E_1 : T_1 + T_2}{\Gamma; \Delta \vdash \text{left } E_2 : T_1 + T_2} & \frac{\Gamma; \Delta \vdash \text{right } E_2 : T_1 + T_2}{\Gamma; \Delta \vdash \text{right } E_2 : T_1 + T_2} \end{array}$$

$$\frac{ \overset{\text{NETWORK - MATCH}}{\Gamma \vdash E: T_1 + T_2 \quad \Gamma; \Delta, X: T_1 \vdash E_1: T_3 \quad \Gamma; \Delta, Y: T_2 \vdash E_2: T_3}{\Gamma \vdash \text{(match E with left X} \Rightarrow E_1 \text{ ; right Y} \Rightarrow E_2\text{)}: T_3}$$

## 2.3 Choreography

## 3 Theorems

**Theorem 1.** (*Local Progress*): For every choreography  $\cdot \vdash e : t$  either  $\exists e'. e \rightarrow e'$  or e is a value

*Proof.* We will start with induction on e

#### Case e = ()

() is a value and we are done

### $Case\ e=num$

num is a value and we are done

## Case $e = e_1$ binop $e_2$

IH1  $e_1$  is either a value or  $\exists e_1'. e_1 \rightarrow e_1'$  if  $e_1 \rightarrow e_1'$  then  $e_1$  binop  $e_2 \rightarrow e_1'$  binop  $e_2$  if  $e_1$  is a value, IH2  $e_2$  is either a value or  $\exists e_2'. e_2 \rightarrow e_2'$  if  $e_2$  is a value, then  $e_1$  binop  $e_2 \rightarrow$  a value given  $e_1$  and  $e_2$  are numbers if  $e_2 \rightarrow e_2'$  then  $e_1$  binop  $e_2 \rightarrow e_1$  binop  $e_2'$ 

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Case \mathbf{e} = \mathbf{let} \ \mathbf{x} = e_1 \ \mathbf{in} \ e_2 \ //\mathbf{doubt}
IH e_1 is either a value or \exists \ e'_1. \ e_1 \to e'_1
if e_1 \to e'_1 then let \mathbf{x} = e_1 in e_2 \to \mathbf{let} \ \mathbf{x} = e'_1 in e_2
if e_1 is a value, IH2 e_2 is either a value or \exists \ e'_2. \ e_2 \to e'_2
if e_2 is a value, let \mathbf{x} = e_1 in e_2 \to e_2
if e_2 \to e'_2 then let \mathbf{x} = e_1 in e_2 \to e'_2[\mathbf{x} \mapsto e_1]

Case \mathbf{e} = (e_1, e_2)
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IH1  $e_1$  is either a value or  $\exists e_1'. e_1 \rightarrow e_1'$  if  $e_1 \rightarrow e_1'$  then  $(e_1, e_2) \rightarrow (e_1', e_2)$  if  $e_1$  is a value, IH2  $e_2$  is either a value or  $\exists e_2'. e_2 \rightarrow e_2'$  if  $e_2$  is a value, then  $(e_1, e_2)$  is a value if  $e_2 \rightarrow e_2'$  then  $(e_1, e_2) \rightarrow (e_1, e_2')$ 

#### Case $e = fst e_1$

IH  $e_1$  is either a value or  $\exists e_1'. e_1 \rightarrow e_1'$  if  $e_1 \rightarrow e_1'$  then fst  $e_1 \rightarrow$  fst  $e_1'$  if  $e_1$  is a value, this means  $e_1$  is a pair of values as  $e_1 : t_1xt_2$  so if  $e_1 = (v_1, v_2)$  then fst  $e_1 \rightarrow v_1$ 

#### Case $e = \text{snd } e_1$

IH  $e_1$  is either a value or  $\exists e'_1. e_1 \rightarrow e'_1$  if  $e_1 \rightarrow e'_1$  then snd  $e_1 \rightarrow$  snd  $e'_1$  if  $e_1$  is a value, this means  $e_1$  is a pair of values as  $e_1: t_1xt_2$  so if  $e_1 = (v_1, v_2)$  then snd  $e_1 \rightarrow v_2$ 

#### Case $e = left e_1$

IH  $e_1$  is either a value or  $\exists e'_1. e_1 \rightarrow e'_1$  if  $e_1 \rightarrow e'_1$  then left  $e_1 \rightarrow$  left  $e'_1$  if  $e_1$  is a value, then left  $e_1$  is a value

#### Case $e = right e_1$

IH  $e_1$  is either a value or  $\exists e'_1. e_1 \rightarrow e'_1$  if  $e_1 \rightarrow e'_1$  then right  $e_1 \rightarrow$  right  $e'_1$  if  $e_1$  is a value, then right  $e_1$  is a value

## Case e = match $e_1$ with left $x \Rightarrow e_2$ ; right $y \Rightarrow e_3$ //doubt

IH  $e_1$  is either a value or  $\exists e'_1. e_1 \rightarrow e'_1$  if  $e_1 \rightarrow e'_1$  then match  $e_1$  with left  $x \Rightarrow e_2$ ; right  $y \Rightarrow e_3 \rightarrow$  match  $e'_1$  with left  $x \Rightarrow e_2$ ; right  $y \Rightarrow e_3$  if  $e_1$  is a value

**Theorem 2.** (Local Preservation): If  $\Gamma \vdash e : t$  and  $e \rightarrow e'$  then  $\Gamma \vdash e' : t$  Proof. We will start with induction on  $\Gamma \vdash e : t$ 

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Case \Gamma \vdash e : unit
\Gamma \vdash ( ) : unit. It doesn't take a step and we are done
Case e = x doubt
\Gamma \vdash x : t. It doesn't take a step and we are done
Case \Gamma \vdash e : t_1 X t_2
This means e = (e_1, e_2)
IH If \Gamma \vdash e_1 : t_1 \text{ and } e_1 \rightarrow e'_1 \text{ then } \Gamma \vdash e'_1 : t_1
Now we know, (e_1, e_2) \rightarrow (e'_1, e_2) and \Gamma \vdash (e_1, e_2) : t_1Xt_2
Using IH we can say \Gamma \vdash (e'_1, e_2) : t_1Xt_2
Case \Gamma \vdash fst e: t_1
This means e: t_1Xt_2
IH If \Gamma \vdash e : t_1 X t_2 and e \rightarrow e' then \Gamma \vdash e' : t_1 X t_2
Now we know, fst e \to \text{fst } e' and \Gamma \vdash \text{fst } e : t_1
Using IH we can say \Gamma \vdash \text{fst } e' : t_1
Case \Gamma \vdash \mathbf{snd} \ e : t_2
This means e: t_1Xt_2
IH If \Gamma \vdash e : t_1Xt_2 and e \rightarrow e' then \Gamma \vdash e' : t_1Xt_2
Now we know, snd e \to \operatorname{snd} e' and \Gamma \vdash \operatorname{snd} e : t_2
Using IH we can say \Gamma \vdash \text{snd } e' : t_2
Case \Gamma \vdash left e: t_1 + t_2
This means e:t_1
IH If \Gamma \vdash e : t_1 and e \rightarrow e' then \Gamma \vdash e' : t_1
Now we know, left e \to \text{left } e' and \Gamma \vdash \text{left } e: t_1 + t_2
Using IH we can say \Gamma \vdash \text{left } e' : t_1 + t_2
Case \Gamma \vdash \mathbf{right} \ e : t_1 + t_2
This means e:t_2
IH If \Gamma \vdash e : t_2 and e \rightarrow e' then \Gamma \vdash e' : t_2
Now we know, right e \to \text{right } e' and \Gamma \vdash \text{right } e : t_1 + t_2
Using IH we can say \Gamma \vdash \text{right } e' : t_1 + t_2
     Case \Gamma \vdash match e with left x \Rightarrow e_2; right y \Rightarrow e_3 : t_3
This means e: t_1 + t_2
IH If \Gamma \vdash e : t_1 + t_2 and e \rightarrow e' then \Gamma \vdash e' : t_1 + t_2
Now we know, match e with left x \Rightarrow e_2; right y \Rightarrow e_3 \rightarrow match e' with left
x \Rightarrow e_2; right y \Rightarrow e_3 and \Gamma \vdash match e with left x \Rightarrow e_2; right y \Rightarrow e_3 : t_3
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Using IH we can say  $\Gamma \vdash$  match e' with left  $x \Rightarrow e_2$ ; right  $y \Rightarrow e_3 : t_3$ 

## 4 Operational Semantics

### 4.1 Network Language

$$\mathsf{fst}(E_1,E_2) \to E_1 \qquad \qquad \mathsf{snd}(E_1,E_2) \to E_2$$
 (match inl E with inl X  $\Rightarrow$   $E_1$ ; inr Y  $\Rightarrow$   $E_2) \to E_1$  [X  $\mapsto$  E] (match inr E with inl X  $\Rightarrow$   $E_1$ ; inr Y  $\Rightarrow$   $E_2) \to E_2$  [Y  $\mapsto$  E]

### 4.2 Choreography

$$\mathsf{fst}(C_1,C_2) \to C_1 \qquad \qquad \mathsf{snd}(C_1,C_2) \to C_2$$
 (match inl C with inl X  $\Rightarrow$   $C_1$ ; inr Y  $\Rightarrow$   $C_2$ )  $\to$   $C_1$   $[X \mapsto C]$  (match inr C with inl X  $\Rightarrow$   $C_1$ ; inr Y  $\Rightarrow$   $C_2$ )  $\to$   $C_2$   $[Y \mapsto C]$ 

## 5 Glossary

$$\ell$$
 involved in  $\tau = \ell \in locs(\tau)$ 

 $\ell \in locs(\tau) = \text{ getLoc}$  is a function that recursively traverses over  $\tau$  to construct  $locs(\tau)$ 

$$locs(\tau) = \left\{ \begin{array}{ll} \phi & \text{if } \tau = \mathbf{unit} \\ \{\ell\} & \text{if } \tau = \ell.e \\ \text{getLoc } \tau_1 \cup \text{getLoc } \tau_2 & \text{if } \tau = \tau_1 \rightarrow \tau_2 \text{ or } \tau_1 + \tau_2 \text{ or } \tau_1 \times \tau_2 \end{array} \right.$$

# 6 Endpoint Projection

$$\llbracket \mathbf{fst} \ C \rrbracket_{\ell} = \left\{ \begin{array}{ll} \mathbf{fst} \ \llbracket C \rrbracket_{\ell} & \text{if } C : \tau_1 \times \tau_2 \text{ and } \ell \text{ is involved in } C, \tau_1 \text{ and } \tau_2 \\ \llbracket C \rrbracket_{\ell} & \text{if } C : \tau_1 \times \tau_2 \text{ and } \ell \text{ is involved in } C \\ \mathbf{()} & \text{otherwise} \end{array} \right.$$

$$[\![\mathbf{snd}C]\!]_\ell = \left\{ \begin{array}{ll} \mathbf{snd} \ [\![C]\!]_\ell & \text{if } C: \tau_1 \times \tau_2 \text{ and } \ell \text{ is involved in } C, \tau_1 \text{ and } \tau_2 \\ [\![C]\!]_\ell & \text{if } C: \tau_1 \times \tau_2 \text{ and } \ell \text{ is involved in } C \\ () & \text{otherwise} \end{array} \right.$$

$$\llbracket \mathbf{inl} \ C \rrbracket_{\ell} = \left\{ \begin{array}{ll} \mathbf{inl} \ \llbracket C \rrbracket_{\ell} & \text{if } C : \tau_1 \text{ and } \ell \text{ is involved in } C \text{ and } \tau_1 \\ \llbracket C \rrbracket_{\ell} & \text{if } C : \tau_1 \text{ and } \ell \text{ is involved in } C \text{ but not in } \tau_1 \\ \mathbf{()} & \text{if } C : \tau_1 \text{ and } \ell \text{ is not involved in } C \text{ and } \tau_1 \end{array} \right.$$

$$\llbracket \mathbf{inr} \ C \rrbracket_{\ell} = \left\{ \begin{array}{ll} \mathbf{inr} \ \llbracket C \rrbracket_{\ell} & \text{if } C : \tau_2 \text{ and } \ell \text{ is involved in } C \text{ and } \tau_2 \\ \ \llbracket C \rrbracket_{\ell} & \text{if } C : \tau_2 \text{ and } \ell \text{ is involved in } C \text{ but not in } \tau_2 \\ \mathbf{()} & \text{if } C : \tau_2 \text{ and } \ell \text{ is not involved in } C \text{ and } \tau_2 \end{array} \right.$$

[match C in inl  $\mathbf{X} \Rightarrow C_1$ ; inr  $\mathbf{Y} \Rightarrow C_2$ ]<sub> $\ell$ </sub>

$$egin{aligned} &=\left\{egin{aligned} &\mathbf{match}\; \llbracket C
rbracket_\ell \;\mathbf{in}\;\mathbf{inl}\;\mathbf{X}\; &\Rightarrow \llbracket C_1
rbracket_\ell ;\;\mathbf{inr}\;\mathbf{Y}\; &\Rightarrow \llbracket C_2
rbracket_\ell \ & \llbracket C
rbracket_\ell ;\; \llbracket C_1
rbracket_\ell \sqcup \llbracket C_2
rbracket_\ell \ & \llbracket C_1
rbracket_\ell \sqcup \llbracket C_2
rbracket_\ell \end{aligned}
ight. \end{aligned}$$

if  $C: \tau_1+\tau_2$  and  $\ell$  is involved in both  $\tau_1$  and  $\tau_2$  if  $C: \tau_1+\tau_2$  and  $\ell$  is involved in  $\tau_1$  or  $\tau_2$  or C if  $C: \tau_1+\tau_2$  and  $\ell$  is not involved in C,  $\tau_1$  and  $\tau_2$ 

# 7 Type Projection

$$[\![\mathbf{unit}]\!]_\ell = \ \mathbf{unit}$$

$$[\![\ell_1.t]\!]_{\ell_2} = \left\{ \begin{array}{ll} t & \text{if } \ell_1 = \ell_2 \\ \mathbf{unit} & \text{otherwise} \end{array} \right.$$

$$\llbracket \tau_1 \to \tau_2 \rrbracket_\ell = \left\{ \begin{array}{ll} \llbracket \tau_1 \rrbracket_\ell \to \llbracket \tau_2 \rrbracket_\ell & \text{if $\ell$ is involved in $\tau_1$ or $\tau_2$ or both} \\ \mathbf{unit} & \text{otherwise} \end{array} \right.$$

$$\llbracket \tau_1 + \tau_2 \rrbracket_\ell = \left\{ \begin{array}{ll} \llbracket \tau_1 \rrbracket_\ell + \llbracket \tau_2 \rrbracket_\ell & \text{if $\ell$ is involved in $\tau_1$ or $\tau_2$ or both} \\ \mathbf{unit} & \text{otherwise} \end{array} \right.$$

$$\llbracket \tau_1 \times \tau_2 \rrbracket_\ell = \left\{ \begin{array}{ll} \llbracket \tau_1 \rrbracket_\ell \times \llbracket \tau_2 \rrbracket_\ell & \text{if $\ell$ is involved in $\tau_1$ and $\tau_2$} \\ \llbracket \tau_1 \rrbracket_\ell & \text{if $\ell$ is involved in $\tau_1$ but not $\tau_2$} \\ \llbracket \tau_2 \rrbracket_\ell & \text{if $\ell$ is involved in $\tau_2$ but not $\tau_1$} \\ \mathbf{unit} & \text{otherwise} \end{array} \right.$$

## 8 Lemmas

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Lemma 1 : If \ell is not involved in \tau then [\![\tau]\!]_{\ell} = \text{unit}
Proof: By Induction on \tau
Case \tau = \text{unit}:
   From type projection we know, [\![\mathbf{unit}]\!]_\ell = \mathsf{unit}
Case \tau = \ell.t:
   Here we know that, \ell_1 \neq \ell as \ell is not involved in \tau
   so using type projection for [\![\ell_1.t]\!]_\ell
   we can say, [\![\ell_1.t]\!]_\ell = \mathbf{unit}
Case \tau = [\![\tau_1 \to \tau_2]\!]_{\ell}:
   By IH, \ell is not involved in 	au_1 and \ell is not involved in 	au_2
   so using type projection for [\![\tau_1 \to \tau_2]\!]_\ell
   we can say, [\![\tau_1 \to \tau_2]\!]_\ell = \mathbf{unit}
Case \tau = [\![\tau_1 + \tau_2]\!]_{\ell}:
   By IH, \ell is not involved in 	au_1 and \ell is not involved in 	au_2
   so using type projection for [\![\tau_1+\tau_2]\!]_\ell
   we can say, \llbracket \tau_1 + \tau_2 \rrbracket_\ell = \mathbf{unit}
Case \tau = [\![\tau_1 \times \tau_2]\!]_{\ell}:
   By IH, \ell is not involved in \tau_1 and \ell is not involved in \tau_2
   so using type projection for [\![\tau_1 	imes 	au_2]\!]_\ell
   we can say, [\![\tau_1*\tau_2]\!]_\ell=\mathbf{unit}
Lemma 2 : If \ell \notin locs(C) then [\![C]\!]_{\ell} = ()
Lemma 3 : If \vdash C : \tau, then \vdash \llbracket C \rrbracket_{\ell} : \llbracket \tau \rrbracket_{\ell}
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