# ***A study on Real Time Environmental Monitoring System***

## ABSTRACT

## *PARK MONITORING OF VISITORS*

Environmental monitoring in parks alongside visitor monitoring is crucial for preserving natural ecosystems. It involves tracking factors like air quality, water quality, wildlife populations, and vegetation health. This data helps park authorities make informed decisions to protect the environment while balancing the needs of visitors. It also aids in early detection of environmental issues and supports conservation efforts.

The level of pollution has increased with times by lot of factors like the increase in population, vehicle use, industrialization and urbanization which results in harmful effects on human wellbeing by directly affecting health of the people. This project is based on the wireless

sensor networks for collecting information about Environment. In order to monitor, we will develop an IOT Based Environmental Monitoring System, it can monitor the

Air Quality over a web server by using the Wi-Fi Technology. Recent advancements like Internet of Things provide support for the transmission of

huge and accurate amount of data regarding the Environment. In this IOT project, we can monitor the pollution level from anywhere through computer or mobile. This system not only calculates the pollutants present in the air, by using this we can forecast to avoid future pollution and can send the warning message to that particular polluted area. Keywords: IOT, WIFI

# 1. INTRODUCTION

An Embedded System is a combination of computer hardware

and software, and perhaps additional mechanical or other parts, designed to perform a specific function. An embedded system is a microcontroller-based, software

driven, reliable, real-time control system, autonomous, or human or network interactive, operating on diverse physical variables and in diverse environments and sold into a competitive and cost conscious market. An embedded system is not a computer system that is used primarily for processing, not a software system on

PC or

UNIX, not a traditional business or scientific application. High-end embedded & lower end embedded systems.

High-end embedded system - Generally 32, 64 Bit Controllers used with OS. Examples Personal Digital Assistant and Mobile phones etc. Lower end embedded systems - Generally 8,16 Bit Controllers used with an minimal operating systems and hardware layout designed for the specific purpose. Examples Small controllers and devices

in our everyday life like Washing Machine, Microwave Ovens, where they are embedded in.

## 2. LITERATURE SURVEY

In existing model, the Zigbee based wireless Sensor Networks used to monitor the physical and Environmental conditions. The system consists of a microcontroller, sensors and Zigbee which collects data from different

The informlocation readings tion at certain time of s along wi are for particular h coordinate‟s a day. averaged in a closed time and space. The Global Positioning System (GPS) module is attached to a system to provide accurate representation of pollution sources in an area. The

recorded data is periodically transferred to a computer through a Zigbee receiver and then the data will be displayed on the dedicated website with user acceptance. As a result large number of people can be benefited with the large. Which avoided the use of complex routing algorithm but local Computations are very minimal.

Due to miscellaneous interactions, limited protocol standardization, security of data storage and complex identification systems to access data, problems arises in field of monitoring. By using this Zigbee

protocol there must be a one receiver end. It transmits the data over the 10-100m. To overcome these problems we are designing and so on.

moni„IOT based pollution free future live.oring system‟,nvironmentto gain l pollution

## 3. PROPOSED SYSTEM

In this proposed model the climatic changes are frequently monitoring through IOT using sensor nodes. Internet of

Things (IoT) is a recent communication paradigm, in which the objects will be equipped with microcontrollers, transceivers and

suitable protocol stack that will make them to communicate with one another and with user. This paper designs a prototype of wireless environmental monitoring system to upload information from array of sensors to the database. This application allows us to observe or measuring the environmental parameters from anywhere in real time. This system consist of main three modules namely sensor nodes, the wireless communication and the web server. The sensor nodes in remote location collect the information from surrounding environmental conditions and

send the data wirelessly using Arduino microcontroller and ESP8266 Wi-Fi module to the server.

This paper presents a system that can be used to measure the toxic gases in surrounding area like Industrial area by using various sensor nodes. All sensors are connected on the arduino microcontroller and the status of the sensors is send to the control section continuously. The data uploading is done by ESP 8266 Wi-Fi module. The data is updated on internet. The values of sensors are displayed on LCD. The buzzer is used to make sound, if the sensor

beyond its threshold value for saving the people immediately. The device developed in this project is based

Arduino UNO. The Arduino board connects with Thing Speak platform using ESP8266 Wi-Fi Module. The Thing

Speak is a popular IOT platform which is easy to use and program.

The sensor data is also displayed on a character

LCD interfaced in the monitoring IOT device. The sensing of data and sending it to the Thing Speak server using

Wi-Fi module is managed by the Arduino Sketch. The Arduino sketch is written, compiled and loaded to the

Arduino board using Arduino IDE.

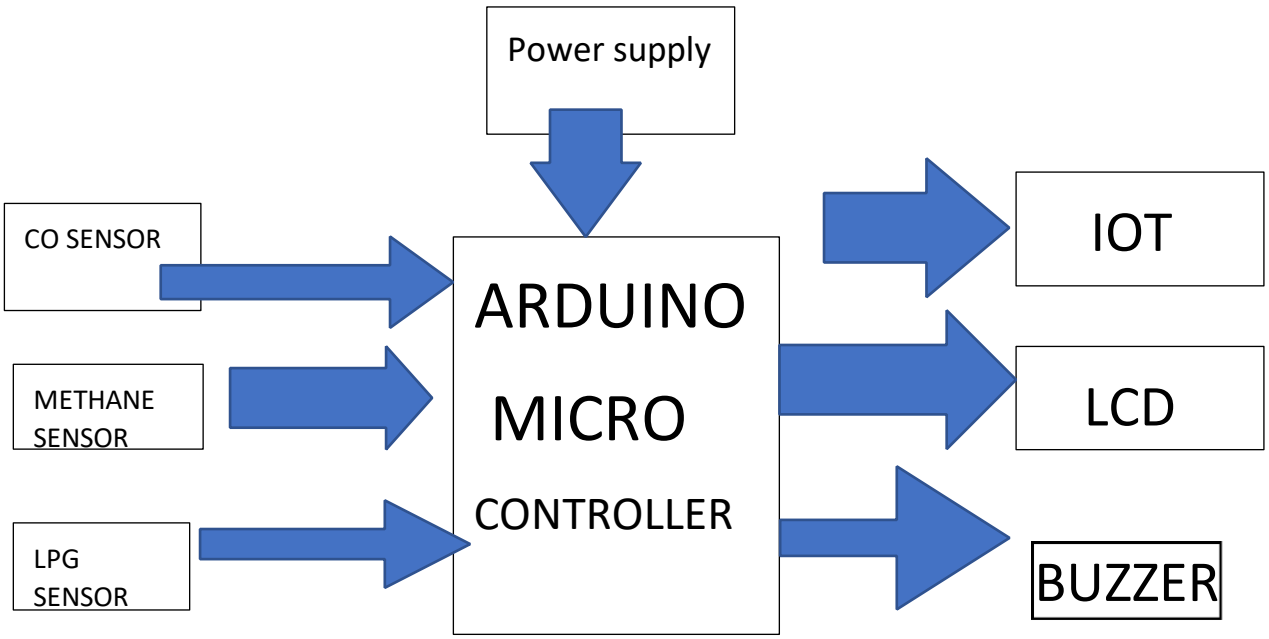
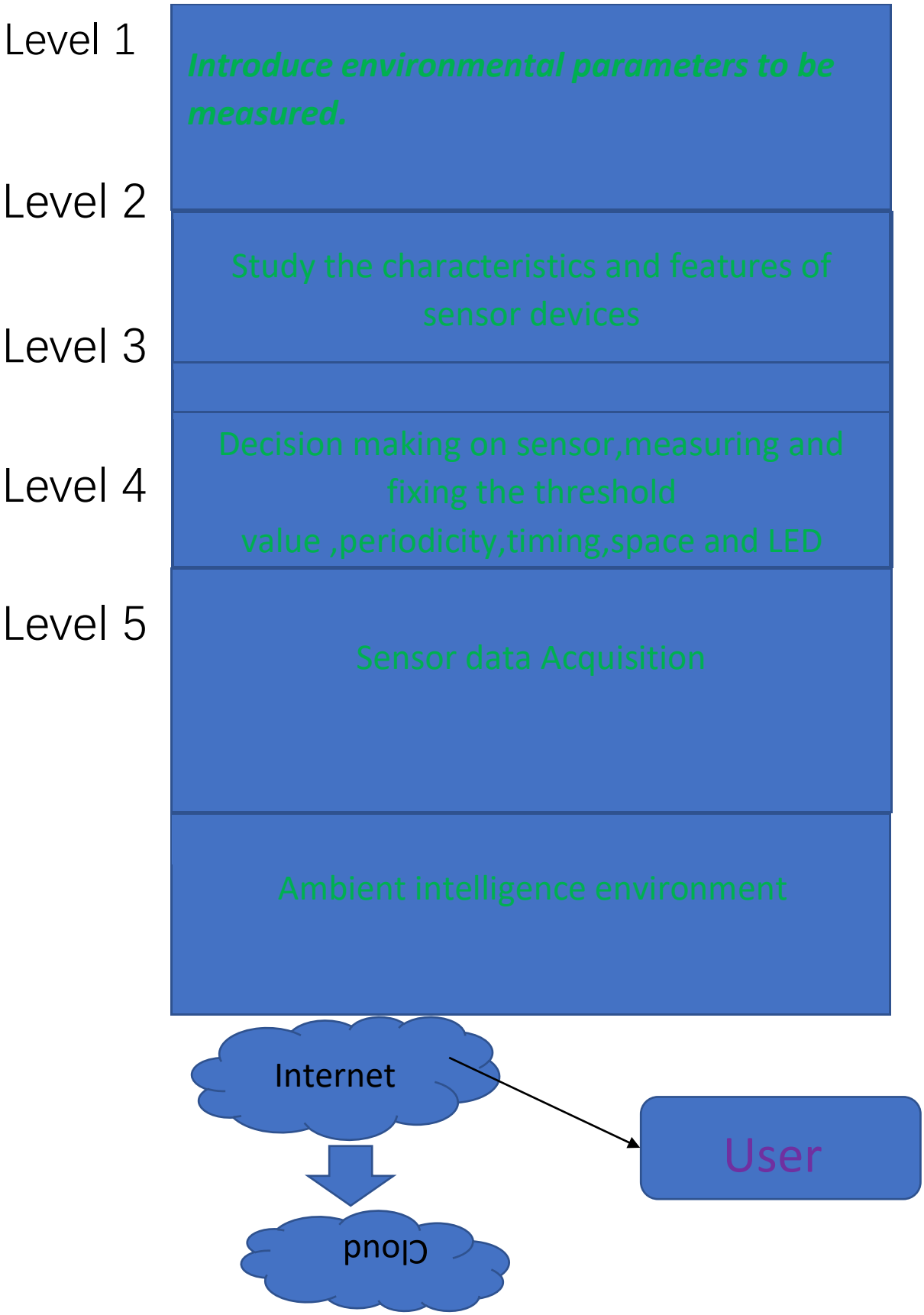



Fig. Block Diagram of Proposed System

# SYSTEM MODEL:



From the above model, process is divided in 5 layers. The environmental parameters which are to be measured are introduced in layer 1. Study of the characteristics and features of sensor devices is in layer 2. In layer 3, there is

decision making on sensing, measuring and fixing the threshold value, periodicity of sensitivity, timing, space and LED.

Sensor data acquisition is done in layer 4. And layer 5 as ambient intelligence environment. The sensors can be operated by the microcontroller to retrieve the

data from them and it processes the analysis with the sensor data and

updates it to the Internet through Wi-Fi module connected to it. User can monitor the parameters on their smart  phones as well as pc or laptop.

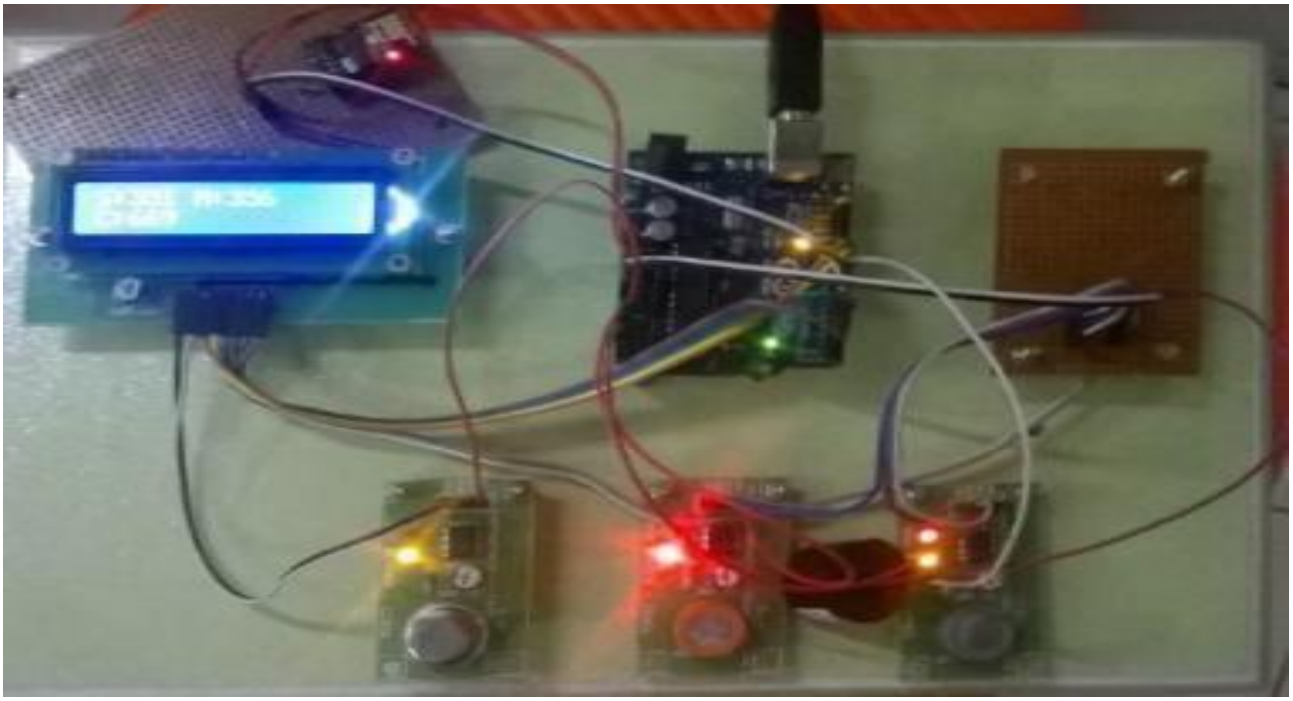
Fig. Top and Back view of Arduino

UNO

The Arduino Uno is a microcontroller board based on the ATmega328. It has 14 digital input/output pins (of which 6 can be used as PWM outputs), 6 analog inputs, a 16 MHz ceramic resonator, a USB connection, a power jack, an ICSP header, and a reset button.

# 4. RESULT AND DISCUSSION

## 4.1. HARDWARE OUTPUT

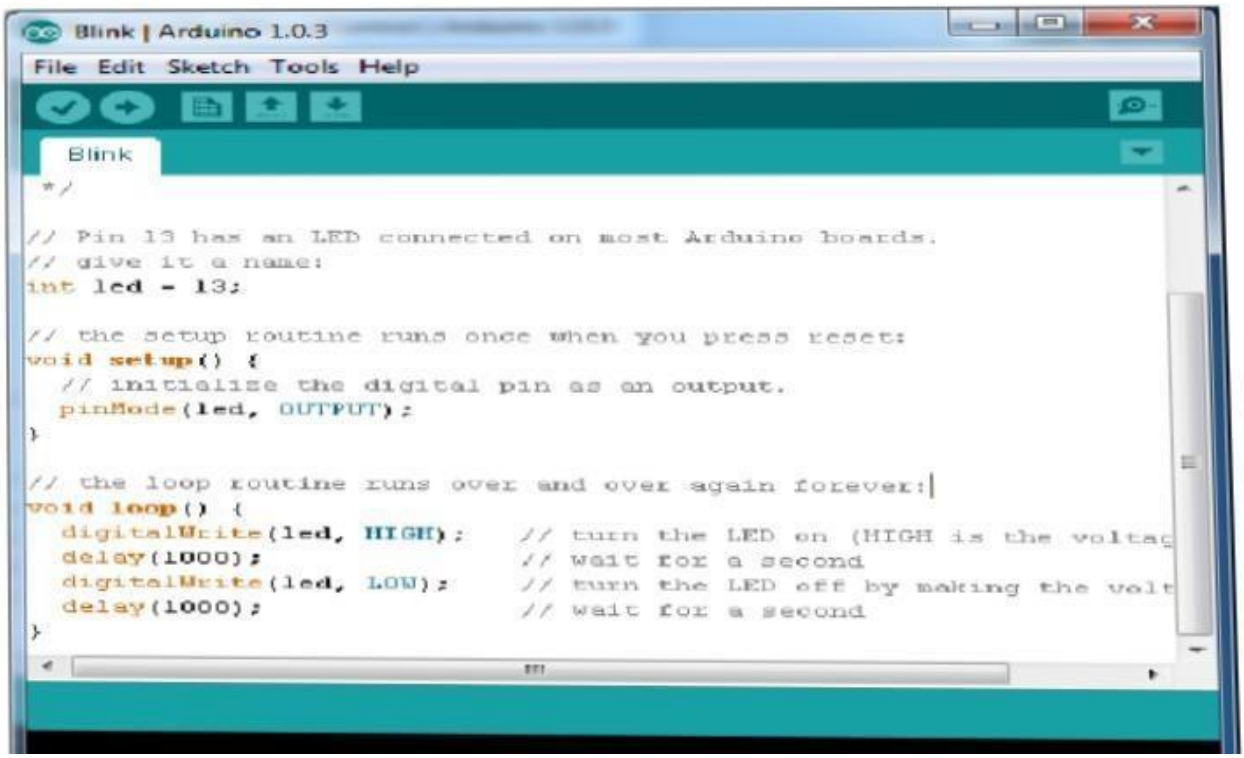


It represents the output we have obtained so far. The Hardware components used here includes Arduino microcontroller, ESP 8266 Wi-Fi module, LCD, Buzzer, CO sensor, SnO2 sensor and LPG sensor. LCD display
indicates density of gases in the air.

The Buzzer gave alarm when the gas level exceed the threshold value. ESP 8266 Wi-Fi module transmitted the data to the web server.

## 4.2. ARDUINO IDE

This is the software program of our project. The program was developed in the Arduino IDE software.
Arduino IDE  is the software used for Arduino applications. Then the program




dumped with our hardware.

## 4.3. THINGSPEAK

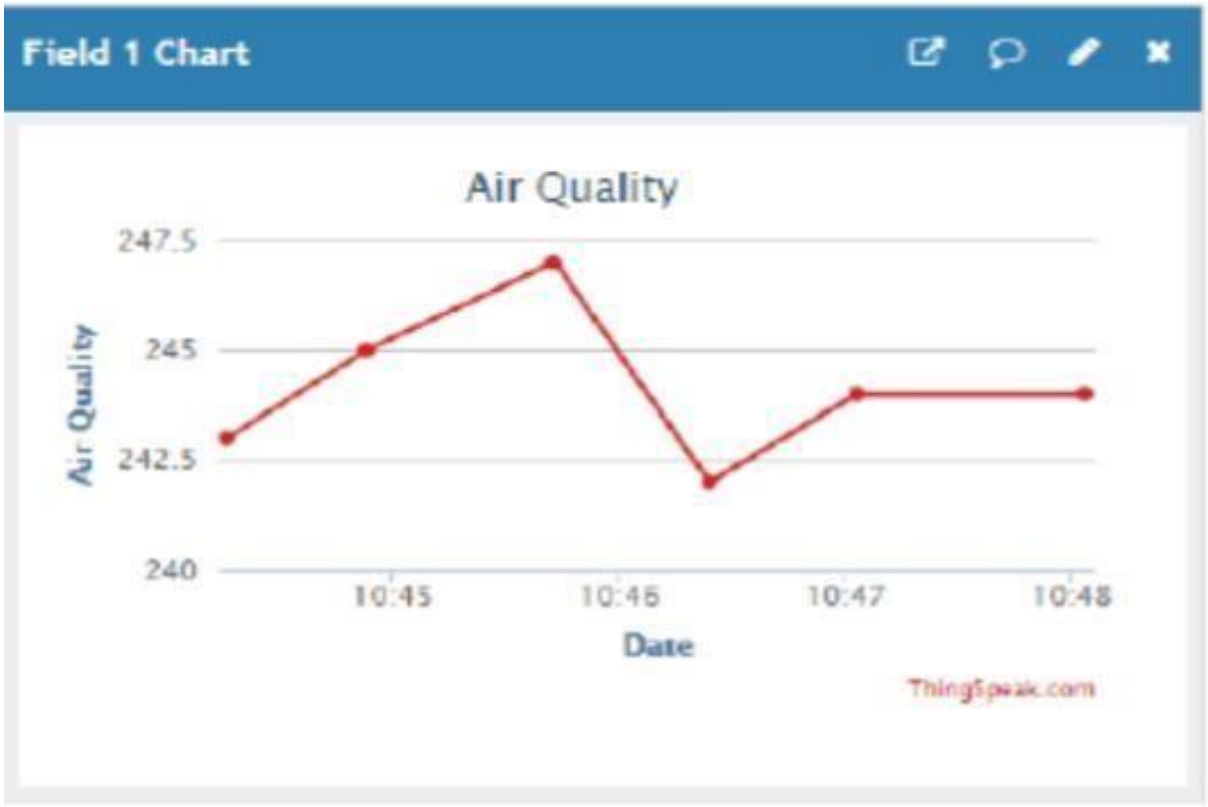
Thing Speak is the cloud based web server for IOT Applications. It is an open source. In which we created our own

channel for IOT based Environmental monitoring by providing username and password. The output is obtained by setting

the number of field we required for monitoring the Environment parameters. Then the sensors values are  updated to the server using ESP 8266.It provided the graph to show the density of gases in the air.

Fig. ThingSpeak

## 5.output on the webserver



## 6. CONCLUSION AND FUTURE WORK

Thus the IOT based Environmental Monitoring System has been designed and implemented. The Environmental parameters successfully transmitted via ESP 8266 Wi-Fi module. The density of the gases in the remote located area viewed through the ThingSpeak web server. This project will protect the people from the pollutant gases. It is

more useful for the Industries to control the air pollution in the surrounding area and for the workers safety. In future we can

implement this project with ESP 8266-12E Wi-Fi module and with the sensors which can sense the gas density in high level. ESP 826612E module has inbuilt Arduino microcontroller. It reduces the overall size of the device and simplifies the working mechanism.

Html

```
<html lang="en">
<head>
  <title>project work</title>
  <meta charset="utf-8">
  <meta name="viewport" content="width=device-width, initial-scale=1">
  <link rel="stylesheet"
href="https://maxcdn.bootstrapcdn.com/bootstrap/3.3.7/css/bootstrap.min.css">
  <script
src="https://ajax.googleapis.com/ajax/libs/jquery/3.1.1/jquery.min.js"></script>
  <script
src="https://maxcdn.bootstrapcdn.com/bootstrap/3.3.7/js/bootstrap.min.js"></script>
  <link href="HowItWorks.css" rel="stylesheet">
    <!--IIT Logo Style Link-->
    <link rel="stylesheet" href="Logo.css">
</head>
<body>
<div class="navbar navbar-inverse navbar-fixed-top" role="navigation">
 <div class="container">
  <div class="navbar-header">
    <button type="button" class="navbar-toggle" data-toggle="collapse"
datatarget=".navbar-collapse">
          <span class="sr-only">Toggle navigation</span>
          <span class="icon-bar"></span>
          </button>
         </div>
        <div class="collapse navbar-collapse">
      <ul class="nav navbar-nav">
      <li><a href="home.php" class="image_navbar"></a></li>
         <li><a href="#"><font size=5" color="yellow"><b> Air Pollution Monitoring
System</b></font></a></li>
      <li><a href="home.php">Home</a></li>
```

```
     <!-- <li><a href="team.html">The Team</a></li>
          <li><a href="export.html">Data</a></li>
      <li><a href="project.html">The Project</a></li>  -->
          <li class="active"><a href="#hiw" rel="m_PageScroll2id">How It Works</a></li>
          </ul>
        <!--  <ul class="nav navbar-nav navbar-right visible-lg">
          <li>
            <a href="http://iitism.ac.in/index.php/home/"><div id="IIT(ISM)-logosmall"
class ="visible-lg"></a>
                        <!-- <a style="width:5px;
height:5px;"href="http://iitism.ac.in/index.php/home/"><img src="C:\Users\Abhishek
Upadhyay\Desktop\bootstrap\ismlogo.png" id="ismlogo"/></a>

         <!--   <div id="divider-large-reversed"></div>
            <a href="http://csesociety.in/"><div id="CSES-logo-web-large"></div></a>
</div>
        </li>
      </ul>      -->
    </div>
  </div>
  </div>
  <!-- <div id="logoContainer">
                         <a style="width:auto;
height:10px;"href="http://iitism.ac.in/index.php/home/"><img src="C:\Users\Abhishek
Upadhyay\Desktop\bootstrap\ismlogo.png" id="ismlogo"/></a>
                    </div>       -->

<!-- Photo Header -->
<div class="container">
 <div class="jumbotron">

   <!-- Photo Header -->
<div class="container" style="padding-top:120px">
  <div class="col-md-12 col-sm-12 team-image-display">
    <img id="hiw" src="howitworks_new.jpg">
  </div>

  </div>
  <!-- line divider -->
    <div class="col-md-12 line-break"></div>
    <div class="col-md-12 line-break"></div>
    <div class="col-md-12 line-break-border"></div>
    <div class="col-md-12 line-break"></div>
    <div class="col-md-12 line-break"></div>

<!-- Information about the System -->

<div class="row featurette" style="padding-left: 20px; padding-right: 20px; paddingtop:
110px">
  <h2 class="featurette-heading">
    <font color="#1560ac">What does each node consist of?</font>
  </h2>
  <br>
  <p class="lead">
   Each node consists of several parts:
 </p>
   <ul>
    <li class="lead">A Dylos system</li>
    <p>Every node has a dylos that consists of a small computer fan, a laser system
that measures particulate matter and a screen that displays the results. This original
setup was modified to also channel air over a RH/Temp Sensor and through a 3D printed
infrastructure that houses the four alphasense sensors.</p>
    <li class="lead">alphasense sensors</li>
```

```
    <p>
      Alphasense sensors are electrochemical sensors that measure the concentration of
pollutants. Our sensors include CO, NO and NO<sub>2</sub>  sensors along with a RH
Temperature sensor.
    </p>
    <li class="lead">printed circuit boards</li>
    <p>       The PCB, or printed circuit board, is a mini computer that serves two
purposes.
It distributed power to various components of the node and communicates the data
collected by the alphasense sensors and RH/Temperature sensor to the ADC board.
    </p>
         <li class="lead">an analog to digital converter</li>
<p>
       The ADC, or analog to Digital converter, received analog input and then converts
it into digital data that the Raspberry Pi can read.
     </p>

    <li class="lead">a raspberry pi</li>
<p>
          The Raspberry Pi receives digital data from the ADC board through the ribbon
cable. Ultimately, this information is transferred wirelessly to a database.
</p>
</ul>
</div>

<br><br>
<div>
  <h3 style="text-align: left">
  <font color="#1560ac">A 3D Visualization of the Node</font></h3>
</div>
<div>
  <p class="lead">
 Our sensors include CO, NO and NO<sub>2</sub> sensors along with a RH Temperature
sensor.
  This 3D visualization let's you see what is inside each node's casing. It represents
the Dylos particle sensor, the alphasense sensors, the Raspberry Pi, and the electronic
boards. Feel free to rotate and zoom to get a better look!
</p>
</div>
<!-- line divider -->
    <div class="col-md-12 line-break"></div>
    <div class="col-md-12 line-break"></div>
    <div class="col-md-12 line-break-border"></div>
    <div class="col-md-12 line-break"></div>
    <div class="col-md-12 line-break"></div>
       <!-- Pollutants Section -->
<div class="row featurette" style="padding-left: 20px; padding-right: 20px; paddingtop:
80px">
  <h2 class="featurette-heading">
    <span class="text-muted">
      <font color="#1560ac">What will we measure?</font></span>
</h2>
  <br>
  <p class="lead">
We are measuring five pollutants: nitric oxide, nitrogen dioxide, carbon monoxide,
ozone, and particulate matter. The NOx group (nitric oxide and nitrogen dioxide) is
emitted from automobiles, power plants, and turbines. Carbon monoxide comes from
automobile exhaust and burning fuel. Particulate matter is the result of a wide range
of manmade and natural sources, while ozone is the result of reactions between
chemicals already in our air.
Together, these pollutants paint a comprehensive picture of air quality impacts from
the interaction of human activity with natural processes.

  </p>
```

```
</div>
        <!-- Pollutant Descriptions -->

<!-- POLLUTANTS SECTIONN -->

<div id="pollutants"></div>
<hr>
<br><br>
<!-- first row of pollutants -->

<!--CARBON MONOXIDE -->
<div class="row">
  <div class="col-sm-6 col-md-4">
   <div class="thumbnail">
    <img src="CO.png">
    <h3>Carbon Monoxide</h3>
    <p>
     <font size="2"> CO is an odorless, colorless gas that is highly toxic in when
encountered in high concentrations! The main contribution of CO is vehicle exhaust but
other sources include fuel combustion, fires, and volcanoes. Harmful health effects of
CO occur when it enters the bloodstream through the lungs and binds to hemoglobin,
reducing the amount of oxygen that reaches the bodys' tissues and organs.
   </font> </p>
    <p>
     <a class="btn" data-toggle="modal" data-target="#COModal" href="#">Learn More</a>
   </p>
 </div>
</div>
<!-- CO Modal -->
<div class="modal fade" id="COModal" tabindex="-1" role="dialog"
arialabelledby="myModalLabel" aria-hidden="true">
  <div class="modal-dialog">
    <div class="modal-content">
      <div class="modal-header">
        <button type="button" class="close" data-dismiss="modal"
ariahidden="true">&times;</button>
        <h4 class="modal-title" id="myModalLabel">Carbon Monoxide</h4>
      </div>
      <div class="modal-body">
        <p>
          What is it?  Carbon monoxide (CO) is an odorless, colorless, and toxic gas
that is often a byproduct of combustion in gas ranges, automobiles, or unvented
kerosene heaters. CO can also be an important indoor pollution concern, because it is
often produced from indoor heaters, chimneys and furnaces, fireplaces, and water
heaters.          </p>
        <p>
          Why does it matter?  Because carbon monoxide is difficult to detect and might
be a critical indoor pollution problem, our network is especially useful for CO
detection. At low concentrations, it can cause mild chest pain in people with heart
problems or fatigue in healthy people. CO can be fatal at high concentrations, because
of its ability to limit oxygen intake in blood. Other potential issues include angina,
impaired vision, and reduced brain function.
        </p>
      </div>
      <div class="modal-footer">
        <button type="button" class="btn btn-default"
datadismiss="modal">Close</button>
      </div>
    </div>
  </div>
</div>
<!-- NITRIC OXIDE -->
<div class="col-sm-6 col-md-4">
 <div class="thumbnail">
```

```
   <img src="NO.png">
   <h3>Nitric Oxide</h3>
   <p>
   <font size="2"> Nitric Oxide is colorless and odorless, and of the nitrogen oxides
(NOx) emitted, NO is the primary pollutant. While NO is non-toxic by itself, it quickly
converts to NO2 in the air.
  </font></p>
  <p>
   <a class="btn" data-toggle="modal" data-target="#NOModal" href="#">Learn More</a>
 </p>
</div>
</div>
<!-- NO Modal -->
<div class="modal fade" id="NOModal" tabindex="-1" role="dialog"
arialabelledby="myModalLabel" aria-hidden="true">
  <div class="modal-dialog">
    <div class="modal-content">
      <div class="modal-header">
        <button type="button" class="close" data-dismiss="modal"
ariahidden="true">&times;</button>
        <h4 class="modal-title" id="myModalLabel">Nitric Oxide</h4>
      </div>
      <div class="modal-body">
        <p>
          What is it?  Nitric oxide (NO) is a byproduct of combustion of air in manmade
systems such as automobile engines and fossil fuel power plants, or in natural
processes such as thunderstorms. NO is a free radical (it has one unpaired electron),
which means that it is highly unstable and likely rapidly reacts with surrounding
gases. Usually, NO converts into nitrogen dioxide (NO2), which will enter a complex
chain of reactions that may produce ozone or acid rain.
        </p>
        <p>
          Why does it matter? NO is not included in the Air Quality Index (AQI)
produced by the Environmental Protection Agency. However, it is an important precursor
to nitrogen dioxide (NO2), which is known to have detrimental effects on human
respiratory health. NO2 can also likely produce ozone or acid rain.
        </p>
      </div>
      <div class="modal-footer">
        <button type="button" class="btn btn-default"
datadismiss="modal">Close</button>
      </div>
    </div>
  </div>
</div>
  </div>
</div>
<!-- NITROGEN DIOXIDE -->
<div class="col-sm-6 col-md-4">
 <div class="thumbnail">
   <img src="NO2.png">
   <h3>Nitrogen Dioxide</h3>
   <p>
  <font size="2">  Nitrogen Dioxide (NO<sub>2</sub>) is strongly tied to the presence
of O3 and particulate matter. The largest sources of NO2 are combustion processes, such
as heating and power generation. Long-term exposure to NO2 has been linked to adverse
respiratory effects.
 </font> </p>
  <p>
   <a class="btn" data-toggle="modal" data-target="#NO2Modal" href="#">Learn More</a>
  </p>
</div>
</div>
<!-- NO2 Modal -->
```

```
<div class="modal fade" id="NO2Modal" tabindex="-1" role="dialog"
arialabelledby="myModalLabel" aria-hidden="true">
  <div class="modal-dialog">
    <div class="modal-content">
      <div class="modal-header">
        <button type="button" class="close" data-dismiss="modal"
ariahidden="true">&times;</button>
        <h4 class="modal-title" id="myModalLabel">Nitrogen Dioxide</h4>
      </div>
      <div class="modal-body">
        <p>
          What is it? Nitrogen dioxide (NO<sub>2</sub>) is a suffocating, brownish gas
that belongs to a family of highly reactive species known as nitrogen oxides (NOx). NO2
is usually produced after nitric oxide, which is produced from automobiles and
industrial processes, rapidly decomposes to NO2. The NOx gases form when fuel is burned
at high temperatures  as a result of motor vehicle exhaust, electric utilities, and
industrial boilers. NO2 can react with other gases in the atmosphere to form nitric
acid, which leads to acid rain, and ozone.
        </p>
        <p>
          Why does it matter?  At moderate levels, NO2 can cause lung irritation and
make one more susceptible to respiratory illnesses such as influenza. Nitrogen dioxide,
when present for prolonged time periods, can make children more susceptible to acute
respiratory illness. NO2 can increase acid rain and formation of zone. Finally, NO2 can
result in eutrophication in waters, which decreases water oxygen and threatens the
livelihood of aquatic wildlife.
        </p>
      </div>
      <div class="modal-footer">
        <button type="button" class="btn btn-default"
datadismiss="modal">Close</button>
      </div>
    </div>
  </div>
  </div>
  </div>
<br><br><br>

<!-- line divider -->
    <div class="col-md-12 line-break"></div>
    <div class="col-md-12 line-break"></div>
    <div class="col-md-12 line-break-border"></div>
    <div class="col-md-12 line-break"></div>
    <div class="col-md-12 line-break"></div>

<!-- CALIBRATION SECTION -->

<div class="row featurette" style="padding-left: 20px; padding-right: 20px; paddingtop:
110px">
  <h2 class="featurette-heading">
    <font color="#1560ac">How have we calibrated our sensors?</font>
  </h2>
  <br>

  <p class="lead">
    Every node is outfitted with 4 electrochemical sensors, which output millivolt
readings. The goal of the calibration process was to provide a precise conversion of
the electrochemical sensor millivolt readings to a parts per billion unit of
measurement for the individual gas species. Using an airtight metal chamber which fit
two nodes at a time, we created a system where air was pumped in through tubing to the
nodes and out through tubing to the equipment, so that both the nodes and the equipment
could measure the same gas pulses. Using a linear regression, the relationship between
the millivolt readings from the sensors and the ppb concentrations from the instruments
created.    </p>
```

```
</div>

<!-- line divider -->
    <div class="col-md-12 line-break"></div>
    <div class="col-md-12 line-break"></div>
    <div class="col-md-12 line-break-border"></div>
    <div class="col-md-12 line-break"></div>
    <div class="col-md-12 line-break"></div>

      <!-- CONTACT SECTION -->

<div class="row featurette" style="padding-left: 2%; padding-right: 2%">
  <h2 class="featurette-heading">
    <font color="#000">Contact Us</font>
    <span class="text-muted"></span>
  </h2>
  <br>
  <p class="lead">
  </p>
</div>

<div class="col-md-12 line-break"></div>
<div class="col-md-12 line-break-border"></div>
<div class="col-md-12 line-break"></div>

</div>
<!--</div>
</div>
</div>  -->

</div>
</div>
</body>
</html>
```

# Css

```
/*.graph{
}*/


/*#map{
   Height: 100%;
   Width:       100%;
Position:    absolute;
z-index: -1;
}*/


#valuesTable{
          Background-color: #6699FF;
          Background: rgba(0, 0, 0, 0.7);
```

```
        Position: fixed;
        Left: 1%;
        Top: 50px;
        Height: 100%;
        Width: 23%;
Color: white;       z-index: 1;
overflow: auto;
}

#lastupdated{
        Position: relative;
        Left: 10px;
        Font-size: 10px;
}
#locationheader{
        Font-family: “Helvetica Neue”, Helvetica, Arial, sans-serif;
        Font-style: bold;
        Font-size: 25px;
        Position: relative;
}

/*#legend{
        Position: relative;
        Left: 77%;
        Top: 60%;
        Width: 20%;

        Background-color: #6699FF;
        Background: rgba(0, 0, 0, 0.7);
        Color: white;
        Font-family: “Helvetica Neue”, Helvetica, Arial, sans-serif;
        Font-style: bold;
}

.sublegend{
        Display: inline-block;
```

```
}

#legend_container{
        Position: absolute;
        Margin-left: 5px;
}

#legendtable{
        Position: absolute;
        Bottom: 70px;
}

#graphContainer{ z-index:
        -10;    position:
        fixed;  top:
        90px;   width:
        100%;
}


#toGraph{
        Color: black;
        Position: relative;
        Top: 10px;
}

#graphButton{
        Position: relative;
}

#logo{
        Height: 25%;
        Width: 25%;
}

#backToMap{
        Float: right;
```

```
        Position: relative;
        Right: 1%;
        Background-color: white;
        Height: 30px;
Width: 40px;    z-index:
5;      color: gray;
font-size: x-small;
line-height: 10px;
text-align: center;
cursor: hand;
}
*/
.values{
        Font-size: 22px;
}

/*#contactLink {
        Font-size: 10px;
}
*/
Table{
        Border-collapse:separate;
        Border-spacing:0px 0px;
        Font-style: bold;
}


Table.table#temprh > tbody > tr > td {
        Border: 0;
}

/*.leaflet-google-layer{
        z-index: 0;
}

.leaflet-map-pane{
        z-index: 100;
```

```
}

.image_navbar {
	Padding: 10px 5px;
}*/

#temprh {
	Padding-top: 10px;
	Font-size: 12px;
}

.table>tbody>tr>td.pollutantName {	Border-top: 0px;

}

.table-condensed>tbody>tr>td {
	Padding: 0.5px;
}

.table-condensed>tbody>tr>td.pollutantFull {
	Padding-bottom: 5px;
	Font-size: 10px;
}

.pollutantValue {
	Text-align: right;
}

/*#xButton {
	Line-height: 30px;
}

.unitlabel {
	Text-align: right;
	Font-size: 10px;
}
```

```
#dylos{
        Color: white;
}*/
```

# Java script

```
var serverURL = "http://clairity.mit.edu/latest/all/";
 var sensors = []; var
new_sensor; var
nodesDrawn = false; var
firstUpdate = false; var
update_int = 11000;
//milliseconds, 11
seconds;

var mapBig = true;

var alpha1_thresholds = [0, 4500, 9500]; //CO
var alpha2_thresholds = [100000, 500000, 900000, 1300000, 1500000]; //NO
var alpha3_thresholds = [100000, 500000, 900000, 1300000, 1500000]; //NO2
var alpha4_thresholds = [0, 2000, 3000]; //O3 var pm25_thresholds = [0,
600, 2100];
var pm10_thresholds = [10000, 50000, 90000, 130000, 150000];
var alpha_thresholds = [alpha1_thresholds, alpha2_thresholds, alpha3_thresholds,
alpha4_thresholds, pm25_thresholds, pm10_thresholds];

var drawNodes;

function sensor(lat,lon,location,id,in_out,offline) {
this.node_id = id;      this.lat = lat;   this.lon =
lon;  this.location = location;     this.indoor =
in_out;     this.alpha1 = null;     this.alpha2 =
null;       this.alpha3 = null;     this.alpha4 =
null;
        this.color = [0,0,0,0,0,0,0];
 //Overall color, alpha1 color, alpha2 color, alpha3 color, alpha4 color, pm2.5 color,
pm10 color
        // 0 = green, 1 = yellow, 2 = red
      this.pm25 = null;
this.pm10 = null;
this.functioning = true;
this.alphaFunctioning = true;
this.dylosFunctioning = true;
this.alpha1Functioning = true;
this.alpha2Functioning = true;
this.alpha3Functioning = true;
this.alpha4Functioning = true;
        this.offline = offline;
}

function RequestNodes(sidebarNode) {
        $.getJSON(serverURL, function (data) {
            if(!nodesDrawn){
for(i=0; i<data.length; i++){
                                new_sensor = new
sensor(data[i]["latitude"],data[i]["longitude"],data[i]["name"],data[i]["node_id"],data
[i]["indoor"],data[i]["offline"]);
```

```
                        sensors.push(new_sensor);
                         if(sensors[i].offline){
sensors[i].alphaFunctioning = false;
sensors[i].dylosFunctioning = false;
                                        console.log(sensors[i].location+"
"+sensors[i].offline);
                                }
                        }
                        drawNodes();
                        nodesDrawn=true;
                        console.log(sensors[3].location+"
"+sensors[3].alphaFunctioning);
                }
                if(nodesDrawn){
                        for(i=0; i<sensors.length; i++){
                         sensors[i].color = [0,0,0,0,0,0,0];
            for(j=1; j<7; j++){
                                        addAlphasenseData(i,j,data);
                                }
                         sensors[i].temp = data[i]["temperature"];
            sensors[i].rh = data[i]["rh"];
                                var tempDate = data[i]["last_modified"].split(/[\s*\-
\s*,":"]/,5);
                                sensors[i].lastUpdated =
tempDate[1]+"/"+tempDate[2]+"/"+tempDate[0]+" "+tempDate[3]+":"+tempDate[4];
                                if(!sensors[i].alpha1Functioning &&
!sensors[i].alpha2Functioning && !sensors[i].alpha3Functioning &&
!sensors[i].alpha4Functioning){
                                        sensors[i].alphaFunctioning = false;
                                }
                                if(!sensors[i].alphaFunctioning &&
!sensors[i].dylosFunctioning){
                                        sensors[i].functioning = false;
                                }
                                setColor(i);
                        }
                        displaySidebar(sidebarNode);
                        if(firstUpdate){
                                 sensors[sidebarNode].circ.setStyle({fillOpacity: "1"});
                                firstUpdate = false;
                        }
                }
        });
}

function addAlphasenseData(i,j,data){
      if(j==1){          var toAdd =
data[i]["co"];           sensors[i].alpha1
= toAdd;
                if(toAdd < 1 && toAdd > -1 || toAdd > 5000 || toAdd < -500){
                        sensors[i].alpha1Functioning = false;
                }
                findColor(i,1,toAdd);
        }
      else if(j==2){           var toAdd =
data[i]["no"];            sensors[i].alpha2
= toAdd;
                 if(toAdd < 1 && toAdd > -1 || toAdd > 1000 || toAdd < -500){
                        sensors[i].alpha2Functioning = false;
                }
```

```
                        findColor(i,2,toAdd);
        }
      else if(j==3){          var toAdd =
data[i]["no2"];
                sensors[i].alpha3 = toAdd;
                if(toAdd < 1 && toAdd > -1 || toAdd > 5000 || toAdd < -500){
                        sensors[i].alpha3Functioning = false;
                }
                findColor(i,3,toAdd);
        }
      else if(j==4){          var toAdd =
data[i]["o3"];          sensors[i].alpha4
= toAdd;
                if(toAdd < 1 && toAdd > -1 || toAdd > 5000 || toAdd < -500){
                        sensors[i].alpha4Functioning = false;
                }
                findColor(i,4,toAdd);
        }
        else if(j==5){
                        var toAdd = data[i]["small_particles"];
                   sensors[i].pm25 = toAdd;
            findColor(i,5,toAdd);         if(toAdd <
        1 ){
                                sensors[i].dylosFunctioning = false;
                        }
        }
        else{
             if(data[i]["big_particles"]){             var
toAdd = data[i]["big_particles"];
sensors[i].pm10 = toAdd;
                }
        }
}

function findColor(i, j, value) {   if(value
> alpha_thresholds[j-1][2]){
sensors[i].color[j] = 2;
        }
      else if(value > alpha_thresholds[j-1][1]){
sensors[i].color[j] = 1;
        }
}

function setColor(i){
      var circColor = null;
if(sensors[i].lat){
                if(sensors[i].dylosFunctioning && sensors[i].alphaFunctioning){
                   index = [1,4,5];
for(k=1;k<4;k++){
                                z = index[k-1];
                                if(sensors[i].color[z]>sensors[i].color[0]){
                                        sensors[i].color[0]=sensors[i].color[z];
                                }
                        }
                        if(sensors[i].color[0] == 0){ circColor = "green"; }
                        else if(sensors[i].color[0] == 1){ circColor = "yellow"; }
                        else{ circColor = "red"; }
                }
                else{
                        circColor = "grey";
```

```
                }
                sensors[i].circ.setStyle({color: circColor, fillColor: circColor});
        }
}

function displaySidebar(i){
      $("#locationheader").html(String(sensors[i].location));
if(!sensors[i].alphaFunctioning){
                var alpha_color = "grey";
                co_color = "grey";
                $(".alpha1").html("--");
                $(".alpha2").html("--");
                $(".alpha3").html("--");
                $(".alpha4").html("--");
        }
        else{
                alpha_color = "white";
                $(".alpha1").html(String(Math.round(sensors[i].alpha1)));
                $(".alpha2").html(String(Math.round(sensors[i].alpha2)));
                $(".alpha3").html(String(Math.round(sensors[i].alpha3)));
                $(".alpha4").html(String(Math.round(sensors[i].alpha4)));
                if(sensors[i].color[1]==1){
                        co_color = "yellow";
                }
                else if(sensors[i].color[1]==2){
                        co_color = "red";
                }
                else{
                        co_color = "green";
                }
        }
        doc = document.getElementById("no2a").style.color=alpha_color; doc
        = document.getElementById("no2b").style.color=alpha_color; doc =
        document.getElementById("o3a").style.color="grey"; doc =
        document.getElementById("o3b").style.color="grey";
      doc = document.getElementById("coa").style.color=co_color;
doc = document.getElementById("cob").style.color=co_color;
      doc = document.getElementById("noa").style.color=alpha_color;
doc = document.getElementById("nob").style.color=alpha_color;

      if(!sensors[i].dylosFunctioning){         doc =
document.getElementById("dylos1").style.color="grey";             doc =
document.getElementById("dylos2").style.color="grey";             doc =
document.getElementById("dylosa").style.color="grey";             doc =
document.getElementById("dylosb").style.color="grey";
                $(".pm25").html("--");
                $(".pm10").html("--");
        }
        else{
            if(sensors[i].color[5]==1){               doc =
document.getElementById("dylos1").style.color="yellow";                 doc =
document.getElementById("dylosa").style.color="yellow";
                }
            else if(sensors[i].color[5]==2){                doc =
document.getElementById("dylos1").style.color="red";               doc =
document.getElementById("dylosa").style.color="red";
                }
                else{
                    doc = document.getElementById("dylos1").style.color="green";
                    doc = document.getElementById("dylosa").style.color="green";
                }
```

```
                doc = document.getElementById("dylos2").style.color="white";
                doc = document.getElementById("dylosb").style.color="white";
                $(".pm25").html(String(Math.round(sensors[i].pm25)));
                $(".pm10").html(String(Math.round(sensors[i].pm10)));
        }
        $("#lastupdated").html("Last Updated: "+sensors[i].lastUpdated + " UTC");
};


$(document).ready(function(){
    //Leaflet Map
        var googleLayer = new L.Google('ROADMAP',mapStylesArray);

      var sWBound = L.latLng(42.336976,-71.153984);   var nEBound =
L.latLng(42.381880,-71.052017);     var map = new L.Map('map', {center:
[42.3590000, -71.095500], zoom: 16, minZoom: 14, maxBounds:[sWBound,nEBound],
zoomControl: false, attributionControl:
false, layers: [googleLayer] });

        map.addLayer(googleLayer);
      var zoomBar = L.control.zoom({ position: 'topright' }).addTo(map);      var
attribution = L.control.attribution({position: 'topright'}).addTo(map);
 map.doubleClickZoom.disable();
        map.scrollWheelZoom.disable();
        var sidebarNode = 14;

        drawNodes = function(){
        for(var i=0; i<sensors.length; i++){
            if(sensors[i].lat){           var
        delt_lat = 0.00015;         var
        delt_lon = 0.00028;
            if(sensors[i].indoor){
                  sensors[i].circ =
L.polygon([[sensors[i].lat+delt_lat,sensors[i].lon],[sensors[i].lat-
delt_lat,sensors[i].lon+delt_lon],[sensors[i].lat-delt_lat,sensors[i].lon-delt_lon]],{
                        color: 'red',
fillColor: "#f03",
                                fillOpacity: 0.5
                                }).addTo(map);
                                sensors[i].circ.bindPopup(sensors[i].location,
{closeButton: false,'offset': L.point(-12,-15)});
                        }
                        else{
                                sensors[i].circ =
L.circle([sensors[i].lat,sensors[i].lon], 16, {
                        color: 'red',
fillColor: "#f03",
                                fillOpacity: 0.5
                                }).addTo(map);
                                sensors[i].circ.bindPopup(sensors[i].location,
{closeButton: false,'offset': L.point(0,-5)});
                        }

                        sensors[i].circ.number = i;

                        sensors[i].circ.on('mouseover', function(evt) {
                                evt.target.openPopup();
                        });
                        sensors[i].circ.on('mouseout', function(evt){
```

```
                                evt.target.closePopup();
                        });

                    sensors[i].circ.on('click', function(evt){
            displaySidebar(this.number);
sidebarNode = this.number;
                                for(var i=0; i<sensors.length; i++){
                                        if(sensors[i].lat){
                                        sensors[i].circ.setStyle({fillOpacity: "0.5"});
                                        }
                                }
                                this.setStyle({fillOpacity: "1"});
                        });

                };
        };
}

        RequestNodes(sidebarNode);
        var reset = setInterval(function() {RequestNodes(sidebarNode)}, update_int);

});
```

# *PYTHON PROGRAMMING*

### *Source*

```
[[source]]
url = "https://pypi.org/simple"
verify_ssl = true
name = "pypi"

[packages]
alembic = "1.8.1"
Faker = "14.2.0"
importlib-resources = "5.10.0"
ipdb = "0.13.9"
pytest="7.1.3"
SQLAlchemy = "1.4.41"

[requires]
python_full_version = "3.8.13"
```

# *Classes*

```
#National park
from .trip import Trip

class NationalPark:

    def __init__(self):
        pass
```

### *#trip*

```
class Trip:
    all = []

    def __init__(self):
        pass
```

### *#visitor*

```
class Visitor:
```

```
    def __init__(self):
        pass
```

### *#ipdb*

```
import ipdb

from classes.national_park import NationalPark
from classes.visitor import Visitor
from classes.trip import Trip

if __name__ == '__main__':
    print("HELLO! :) let's debug :vibing_potato:
```

# *TESTING*

# *#pytest*

```
def pytest_itemcollected(item):
    par = item.parent.obj
    node = item.obj
    pref = par.__doc__.strip() if par.__doc__ else par.__class__.__name__
    suf = node.__doc__.strip() if node.__doc__ else node.__name__
    if pref or suf:
        item._nodeid = ' '.join((pref, suf))
```

# *#National park visitor*

```
from classes.national_park import NationalPark
from classes.visitor import Visitor
from classes.trip import Trip
import pytest

class TestNationalParks:
    '''NationalPark in national_park.py'''

    def test_has_name(self):
        '''NationalPark is initialized with a name'''
        np = NationalPark("Flatirons")
        assert (np.name == "Flatirons")

    def test_name_is_string(self):
        '''NationalPark is initialized with a name of type str'''
        np = NationalPark("Wild West")
        assert (isinstance(np.name, str))
        np_2 = NationalPark(2)
        assert (not hasattr(np_2, "_name"))

    def test_name_setter(self):
        '''Cannot change the name of the NationalPark'''
        np = NationalPark("under the sea")
        np.name = "over the sea"
        assert (np.name == "under the sea")

    def test_has_many__trips(self):
        '''NationalPark has many Trips.'''
        p1 = NationalPark("Yosemmette")
        p2 = NationalPark("Rocky Mountain")
        vis = Visitor('Steve')
        t_1 = Trip(vis, p1, "May 5th", "May 9th")
        t_2 = Trip(vis, p1, "May 20th","May 27th")
        t_3 = Trip(vis, p2, "January 5th","January 20th")

        assert (len(p1.trips()) == 2)
```

```
        assert (t_1 in p1.orders())
        assert (t_2 in p1.orders())
        assert (not t_3 in p1.orders())

    def test_trips_of_type_trips(self):
        '''National Park trips are of type '''
        vis = Visitor("Phil")
        p1 = NationalPark('Yellow Stone')
        t_1 = Trip(vis, p1, "May 5th", "May 9th")
        t_2 = Trip(vis, p1, "May 20th","May 27th")

        assert (isinstance(p1.trips()[0], Trip))
        assert (isinstance(p1.trips()[1], Trip))

    def test_has_many_visitors(self):
        '''National Parks has many visitors.'''
        vis = Visitor("Tammothy")
        vis2 = Visitor('Bryce')

        p1 = NationalPark('Alaska Wilds')

        t_1 = Trip(vis, p1, 2)
        t_2 = Trip(vis2, p1, 5)

        assert (p1 in vis.nationalparks())
        assert (p1 in vis2.nationalparks())

    def test_has_unique_visitors(self):
        '''NationalParks has unique list of all the visitors that have visited.'''

        p1 = NationalPark("Yosemmette")
        vis = Visitor('Steeve')
        vis2 = Visitor('Wolfe')

        t_1 = Trip(vis, p1, "May 5th", "May 9th")
        t_2 = Trip(vis, p1, "May 20th","May 27th")
        t_3 = Trip(vis2, p1, "January 5th","January 20th")

        assert (len(set(p1.visitors())) == len(p1.visitors()))
        assert (len(p1.visitors()) == 2)

    def test_total_visits(self):
        '''Correct total visits'''
        p1 = NationalPark("Yosemmette")
        vis = Visitor('Sheryl')
        t_1 = Trip(vis, p1, "May 5th", "May 9th")
        t_2 = Trip(vis, p1, "June 20th", "July 4th")
        t_3 = Trip(vis, p1, "January 5th","January 20th")
        assert (len(p1.total_visits()) == 3)

    def test_best_visitor(self):
        '''Get the visitor that visited the park the most'''
        p1 = NationalPark("Yosemmette")
        vis = Visitor('Tom')
        vis2 = Visitor('Mark')
        t_1 = Trip(vis, p1, "May 5th", "May 9th")
        t_3 = Trip(vis, p1, "January 5th","January 20th")
        t_3 = Trip(vis2, p1, "January 5th","January 20th")
        assert(p1.best_visitor().name == "Tom")
```

# #VISITOR

```
from classes.national_park import NationalPark
from classes.visitor import Visitor
from classes.trip import Trip
```

```
import pytest

class TestNationalParks:
    '''NationalPark in national_park.py'''

    def test_has_name(self):
        '''NationalPark is initialized with a name'''
        np = NationalPark("Flatirons")
        assert (np.name == "Flatirons")

    def test_name_is_string(self):
        '''NationalPark is initialized with a name of type str'''
        np = NationalPark("Wild West")
        assert (isinstance(np.name, str))
        np_2 = NationalPark(2)
        assert (not hasattr(np_2, "_name"))

    def test_name_setter(self):
        '''Cannot change the name of the NationalPark'''
        np = NationalPark("under the sea")
        np.name = "over the sea"
        assert (np.name == "under the sea")

    def test_has_many__trips(self):
        '''NationalPark has many Trips.'''
        p1 = NationalPark("Yosemmette")
        p2 = NationalPark("Rocky Mountain")
        vis = Visitor('Steve')
        t_1 = Trip(vis, p1, "May 5th", "May 9th")
        t_2 = Trip(vis, p1, "May 20th","May 27th")
        t_3 = Trip(vis, p2, "January 5th","January 20th")

        assert (len(p1.trips()) == 2)
        assert (t_1 in p1.orders())
        assert (t_2 in p1.orders())
        assert (not t_3 in p1.orders())

    def test_trips_of_type_trips(self):
        '''National Park trips are of type '''
        vis = Visitor("Phil")
        p1 = NationalPark('Yellow Stone')
        t_1 = Trip(vis, p1, "May 5th", "May 9th")
        t_2 = Trip(vis, p1, "May 20th","May 27th")

        assert (isinstance(p1.trips()[0], Trip))
        assert (isinstance(p1.trips()[1], Trip))

    def test_has_many_visitors(self):
        '''National Parks has many visitors.'''
        vis = Visitor("Tammothy")
        vis2 = Visitor('Bryce')

        p1 = NationalPark('Alaska Wilds')

        t_1 = Trip(vis, p1, 2)
        t_2 = Trip(vis2, p1, 5)

        assert (p1 in vis.nationalparks())
        assert (p1 in vis2.nationalparks())

    def test_has_unique_visitors(self):
        '''NationalParks has unique list of all the visitors that have visited.'''

        p1 = NationalPark("Yosemmette")
        vis = Visitor('Steeve')
        vis2 = Visitor('Wolfe')
```

```
        t_1 = Trip(vis, p1, "May 5th", "May 9th")
        t_2 = Trip(vis, p1, "May 20th","May 27th")
        t_3 = Trip(vis2, p1, "January 5th","January 20th")

        assert (len(set(p1.visitors())) == len(p1.visitors()))
        assert (len(p1.visitors()) == 2)

    def test_total_visits(self):
        '''Correct total visits'''
        p1 = NationalPark("Yosemmette")
        vis = Visitor('Sheryl')
        t_1 = Trip(vis, p1, "May 5th", "May 9th")
        t_2 = Trip(vis, p1, "June 20th", "July 4th")
        t_3 = Trip(vis, p1, "January 5th","January 20th")
        assert (len(p1.total_visits()) == 3)

    def test_best_visitor(self):
        '''Get the visitor that visited the park the most'''
        p1 = NationalPark("Yosemmette")
        vis = Visitor('Tom')
        vis2 = Visitor('Mark')
        t_1 = Trip(vis, p1, "May 5th", "May 9th")
        t_3 = Trip(vis, p1, "January 5th","January 20th")
        t_3 = Trip(vis2, p1, "January 5th","January 20th")
        assert(p1.best_visitor().name == "Tom")
```

## *#py.in*

```
[pytest]
pythonpath = . lib
```

## *BENEFITS:*

- *improve air quality* – monitoring helps to identify areas with poor air quality and the pollutants responsible for it. This information can be used to implement air pollution control measures to improve air quality. Reducing the levels of pollutants in the air can lead to improved health outcomes for the population and a better quality of life.
- *monitor compliance with regulations* – air quality sensors and other devices make it possible to keep an eye on the emissions from industrial sources, such as power plants and factories, to ensure they meet the standards set by government agencies and adjust your outdoor activities accordingly. **One of the main benefits of air quality monitoring is that it helps us to ensure that the air we breathe is safe.**

- *monitor climate change* – changes in weather patterns, such as increased frequency of heat waves and wildfires, can affect the levels of pollutants in the air. By monitoring these changes, air quality monitoring can help to identify the impact of climate change on air quality and take action to mitigate it.
- *support research and development* – collected data on air quality is a unique source of inspiration for research and development of new pollution control technologies that have the potential to reduce emissions from industrial
- Parks, greenways, and trails enable and encourage people to exercise. Exposure to nature improves psychological and social health. Play is critical for child development. Parks help build healthy, stable communities

## *5 Benefits of Outdoor Activities*

- Boost Immunity. Since outdoor activities offer cardiovascular fitness and Vitamin D supply from the sun, your immune system will naturally improve and strengthen. ...
- Improves Sleep Quality. ...
- Reduces Stress and Anxiety. ...
- Improves Social Skills. ...
- Burns Unwanted Fats. ...
- Conclusion.

**Submitted by**

**Team members**

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