DOC-simulnet

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I. A 2 MINUTES TUTORIAL

This notebbok explains how to run a simation from the simulnet module.

A. Running the simulation

Once the following configuration files have been filled : simulnet.ini agent.ini emsolver.ini communication.ini

The simulation can be started with the method runsimul

```
wait 0.1
wait 0.1
Processing save results, please wait
```

<pylayers.mobility.agent.Agent at 0x36a2890>, <pylayers.mobility.agent.Agent at 0x36a2810>] Agent ID: 1 Agent name: Person_ID1 Agent mass: 80 position vector: (30.0533, 2.7772, 0.0000) velocity vector: (0.1494, 0.8244, 0.0000)

[<pylayers.mobility.agent.Agent at 0x36a2790>,

acceleration vector: (-0.0915, 0.4152, 0.0000)

<pylayers.mobility.agent.Agent at 0x36a2950>,

```
Layout graphs are loaded from /home/uguen/Bu\end{are}iti/pq \forall imequin room: 1.0
                                                 coordinates of its target: (30.1670, 4.9950, 0.0000)
                                                 a list coordinates of its intermediate target: [(18.9000
```

B. Analysis of the saved results

Data are stored into S.save.save dictionnary. If asked in simulnet.ini, those data are stored in a matfile in '

```
Node # 1
emitted power {'rat1': 0}
sensitivity node {'rat1': -80}
type ag
At time stamp 0:
true position [ 18.90762689
                              2.53145395]
estimated position [ nan nan]
On rat1
Received powers [-90.7282282
                                3.
TOA [ 63.25263999
                     0.3
```

C. Description of inner organization of the Simulation object

1) list of involved agents: All agents (mobile and anchors) are gathered in a list of agents. Notice that anchors are static agents.

All moving agents have the following mechanical attributes which have an influence on mobility.

II. NETWORK ATTRIBUTES

The network is a graph:

- · Nodes of the graph represent Agents or access
- Edges of the graph represent radio link between

The node is a dictionnary which contains the following keys:

- 'PN': Personnal Network (described in the follow-
- 'RAT': A list of RAT of which it belongs
- 'p': true position
- 'pe': estimated position if it has been computed by the node itself (cf. location tutorial)
- 't' : A time stamp
- 'type': Its type ('ag' : for agent or 'ap' for access point)

example with node '1'

Each node are link by the edge of the graph The edge is a dictionnary which contains the following

example with node '1'