

2.7절

```
>> m = [83.6 60.2 72.1 91.1 92.9 65.3 80.9];  
>> vt = [53.4 48.5 50.9 55.7 54 47.7 51.1];  
>> g = 9.81;  
>> cd = g*m./vt.^2  
cd =  
  
    0.28760    0.25106    0.27300    0.28806    0.31253    0.28154    0.30393  
  
>> cdavg=mean(cd),cdmin=min(cd),cdmax=man(cd)  
cdavg = 0.28539  
cdmin = 0.25106  
error: 'man' undefined near line 1 column 36  
>> cdavg=mean(cd),cdmin=min(cd),cdmax=max(cd)  
cdavg = 0.28539  
cdmin = 0.25106  
cdmax = 0.31253
```

ex 3.1

```
scriptdemo.m ✖ |  
1 g=9.81; m=68.1; t=12; cd=0.25;  
2 v=sqrt(g*m/cd)*tanh(sqrt(g*cd/m)*t)|
```

```
>> scriptdemo  
v = 50.617  
>> |
```

```

function v = freefall(t,m,cd)
    %freefall : bungee velocrit with second-order drag
    %v = freefall(t.m.cd) computers the free-fall velocity with
    % second-order drag
    %input :
    % t = time(s)
    % m = mass (kg)
    % cd = second-order drag coefficient (kg/m)
    % output:
    % v = downward velocrit (m/s)
    g = 9.81; %acceleration of gravity
    v = sqrt(g*m/cd)*tanh(sqrt(g*cd/m)*t);
endfunction

```

```

>> freefall(12,68.1,0.25)
ans = 50.617
>> help freefall
'freefall' is a function from the file C:\Users\mi...

freefall : bungee velocrit with second-order drag
v = freefall(t.m.cd) computers the free-fall veloc...
second-order drag
input :
t = time(s)
m = mass (kg)
cd = second-order drag coefficient (kg/m)
output:
v = downward velocrit (m/s)

Additional help for built-in functions and operato...
available in the online version of the manual. Us...
'doc <topic>' to search the manual index.

Help and information about Octave is also availabl...
at https://www.octave.org and via the help@octave...
mailing list.
>> lookfor bungee
v = freefall(t.m.cd) compute: bungee velocrit wit...
t = t :-order drag rs the free-fall velocity of a...
output:cond-order drag coefficient (kg/m)
v = downward velocrit (m/s)

```

ex3.3

```
function freefalli
%freefalli : interactive bungee velocity
%freefalli interactive computation of the
% free-fall velocity of an object with second order
% differential equation

g = 9.81; %acceleration of gravity
m = input ('Mass (kg) : ');
cd = input ('Drag coefficient (kg/m) : ');
t = input ('Time (s) : ');
disp (' ')
disp ('Velocity (m/s) : ')
disp (sqrt(g*m/cd)*tanh(sqrt(g*cd/m)*t))
endfunction
```

```
>> freefalli
Mass (kg) : 68.1
Drag coefficient (kg/m) : 0.25
Time (s) : 12

Velocity (m/s) :
    50.617
>> |
```

ex3.5

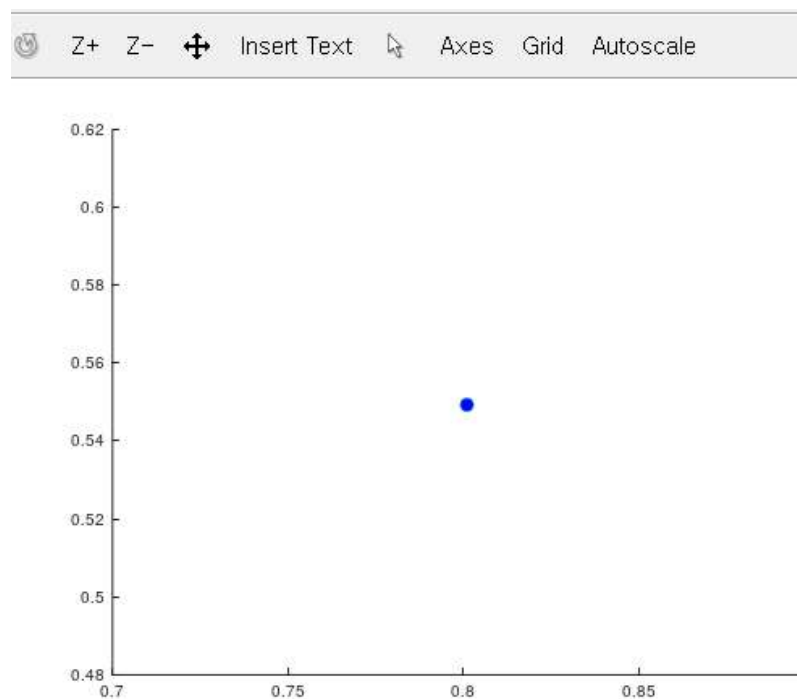
```
function fout = factor(n)
%factor(n) :
% computes the product of all the integers :
x = 1;
for i = 1:n
    x = x*i;
end
fout = x;
endfunction
```

```
error: called from
    factor at line 5 column 3
>> factor(5)
ans = 120
>> |
```

```

clc, clf, clear
g=9.81; theta0=45*pi/180; v0=5;
t(1)=0;x=0;y=0;
plot(x,y,'o','MarkerFaceColor','b','MarkerSize',10);
axis([0 3 0 0.8])
M(1)=getframe;
dt=1/128;
for j = 2:1000
    t(j)=t(j-1)+dt;
    x=v0*cos(theta0)*t(j);
    y=v0*sin(theta0)*t(j)-0.5*g*t(j)^2;
    plot(x,y,'o','MarkerFaceColor','b','MarkerSize',10);
    axis([0 3 0 0.8])
    M(j)=getframe;
    if y<=0, break, end
end
pause
movie(M,1)

```



ex 3.7

```

function quadroots(a, b, c)
%quadroots: roots of quadratic equation
% quadroots(a, b, c) : real and complex roots
%of quadratic equation

% input :
% a = second-order coefficient
% b = first-order coefficient
% c = zero-order coefficient
% output :
% r1 = real part of first root
% r2 = imaginary part of first root
% r3 = real part of second root
% r4 = imaginary part of second root
if a == 0
%special cases
if b ~= 0
%single root
ri = -c / b
else
%trivial solution
disp('Trivial solution. Try again')
end

else
%quadratic formula
d = b ^ 2 - 4 * a * c; %discriminant
if d >= 0
%real roots
r1 = (-b + sqrt(d)) / (2*a)
r2 = (-b - sqrt(d)) / (2*a)
else
% complex roots
r1 = -b / (2*a)
i1 = sqrt(abs(d)) / (2*a)
r2 = r1
i2 = -i1
end
end
endfunction

```

```

>> ex37(1,1,1)
r1 = -0.50000
i1 = 0.86603
r2 = -0.50000
i2 = -0.86603

```

ex 3.8

```
function favg = funcavg(a,b,n)
% funcavg : average function height
%   favg = funcavg(a,b,n) : computes average value
%   of function over a range
% input :
% a = lower bound of range
% b = upper bound of range
% n = number of intervals
% output :
%   favg = average value of function
x = linspace(a,b,n);
y = func(x);
favg = mean(y);
end
function f = func(t)
f = sqrt(9.81*69.1/0.25)*tanh(sqrt(9.81*0.25/68.1)*t);
end
```

```
>> ex38(0,12,60)
warning: function
ans = 36.276
>> |
```

3.6 절

```
function vend = velocity1(dt,ti,tf,vi)
% velocity1 : Euler solution for bungee velocity1
%   vend = velocity1(dt,ti,tf,vi)
%           Euler method solution of bungee
%           jumper velocity
% input :
%   dt = time step (s)
%   ti = initial time(s)
%   tf = final time (s)
%   vi = initial value of dependent variable (m/s)
% output :
%   vend = velocity at tf (m/s)
t = ti;
v = vi;
n = (tf - ti) / dt;
for i = 1:n
    dvdt = deriv(v);
    v = v + dvdt*dt;
    t = t + dt;
end
vend = v;
end
function dv = deriv(v)
dv = 9.81 - (0.25/68.1)*v*abs(v);
end
```

```
>> velocity1(0.5,0,12,0)
ans = 50.926
\\ |
```