

Exercise Guide for *Linear Algebra* by Peter Lax

Muthu Chidambaram

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About

“A modern mathematical proof is not very different from a modern machine, or a modern test setup: the simple fundamental principles are hidden and almost invisible under a mass of technical details.”

- Hermann Weyl

These notes contain short summaries of my proof ideas for exercises from the book *Linear Algebra* by Peter Lax. Note that this is not the same book as Lax's more recent *Linear Algebra And Its Applications*. I think the latter book has solutions floating around, but I could not find solutions for this older book... So perhaps someone will find something useful in what follows.

1 Fundamentals

1.1 Exercise 1

$$x + z = x = x + z' \implies z = z'.$$

1.2 Exercise 2

$$0x + x = (0 + 1)x = x.$$

1.3 Exercise 3

Coefficients can be represented as row vectors.

1.4 Exercise 4

Function can be represented as row vector by letting $a_i = f(s_i)$ for each $s_i \in S$.

1.5 Exercise 5

Follows from exercises 3 and 4.

1.6 Exercise 6

$$y_1 + z_1 + y_2 + z_2 = (y_1 + y_2) + (z_1 + z_2) \text{ and } k(y_1 + z_1) = ky_1 + kz_1.$$

1.7 Exercise 7

$$a \in Y \cap Z \implies ka \in Y, ka \in Z \implies ka \in Y \cap Z.$$

1.8 Exercise 8

$$k0 = 0, 0 + 0 = 0.$$

1.9 Exercise 9

If S contains x_i then it must contain kx_i .

1.10 Exercise 10

If $x_i = 0$, k_i can be anything.

1.11 Exercise 11

$$x = \sum_{i=1}^m \sum_{j=1}^{\dim Y_i} y_j^{(i)}.$$

1.12 Exercise 12

Complete basis for W to U and V . Use W basis vectors and additional U and V basis vectors to get $\dim X = \dim U - \dim W + \dim V - \dim W + \dim W$.

1.13 Exercise 13

Send i^{th} basis vector to e_i , where e_i is vector of all zeroes except a one in the i^{th} place. Can permute mapping to get different isomorphisms.

1.14 Exercise 14

$$x_1 - x_2 + x_2 - x_3 = x_1 - x_3.$$

1.15 Exercise 15

$$x' = x + z_x, y' = y + z_y \implies x' + y' = x + y + (z_x + z_y).$$

1.16 Exercise 16

$$x \in X_1 \oplus X_2 \implies x = (x_1, x_2) = (x_1, 0) + (0, x_2).$$

1.17 Exercise 17

Construct a basis for X from Y : $y_1, \dots, y_j, x_{j+1}, \dots, x_n$.
Then $X/Y = \text{span}\{x_{j+1}, \dots, x_n\}$.

2 Duality

Theorem 1

$$x = \sum_{i=1}^n a_i x_i \implies k_i(x) = a_i.$$

2.1 Exercise 1

$$l_1, l_2 \in Y^\perp \implies l_1(y) + l_2(y) = 0 = (l_1 + l_2)(y).$$

2.2 Exercise 2

$$\forall \xi \in Y^{\perp\perp} \implies \forall l \in Y^\perp, \xi(l) = 0 = l(y) \forall y \in Y.$$

3 Linear Mappings

3.1 Exercise 1

- (a) $x \in X \implies x = \sum_{i=1}^n k_i x_i \implies T(x) = \sum_{i=1}^n k_i T(x_i) \in U$.
(b) $T(x), T(y) \in U \implies T(x+y) \in U \implies x+y \in X$.

Theorem 1

$$x \in X, y \in N_T \implies T(x+y) = T(x) + T(y) = T(x).$$

3.2 Exercise 2

- (a) Differentiation constant and sum rules imply linearity, and multiplication by s is distributive. Take $p(s) = 1$ to see that $ST \neq TS$.
(b) Rotation by 90 degrees amounts to swapping and negating coordinates, which is linear. Take $p = (1, 1, 0)$ to see that $ST \neq TS$.

3.3 Exercise 3

- (i) $T^{-1}(T(a+b)) = T^{-1}(T(a)+T(b)) = a+b = T^{-1}(T(a)) + T^{-1}(T(b))$.
(ii) Composition of isomorphisms is an isomorphism, hence ST is invertible.

3.4 Exercise 4

- (i) Let $T : X \rightarrow U$, $S : U \rightarrow V$ and $l_v \in V'$. Then $(ST)'(l_v) = l_v(ST) = (l_v S)T = (S'l_v)T = T'S'l_v$, since $S'l_v \in U'$.
(ii) Follows from linearity of transpose (definition).
(iii) Let $T : X \rightarrow U$ be an isomorphism. Then $l_x = l_u T \implies l_x T^{-1} = l_u$ for $l_u \in U'$, $l_x \in X'$.

3.5 Exercise 5

$T''(l_{x'}) = l_{x'} T'$ where $l_{x'} \in X''$ and $l_{x'} T' \in U''$. Since we can identify elements in X'' and U'' with elements in X and U respectively, we have that T'' assigns elements of U to X .

Theorem 2'

Since $T' : U' \rightarrow X'$ we have $l_u \in N_{T'} \implies T'(l_u) = l_u T = 0$. $N_{T'}^\perp$ consists of elements $l_{u'} | l_{u'}(l_u) = 0$. From $l_u T x = 0$ we have that each $l_{u'}$ is identified with a $u \in R_T$.

3.6 Exercise 6

The first two elements of x are already 0 after applying P , so $P^2 = P$. Linearity follows from linearity of vector addition.

3.7 Exercise 7

P is linear since function addition is linear. $P^2 f = \frac{f(x)+f(-x)}{4} + \frac{f(x)+f(-x)}{4} = Pf$.

4 Matrices

4.1 Exercise 1

$$(P + T)_{ij} = ((P + T)e_j)_i = (Pe_j + Te_j)_i = P_{ij} + T_{ij}.$$

4.2 Exercise 2

Represent A as a column of row vectors A_i and B as a row of column vectors B_i . Denote blocks by parenthesized subscripts. Then the first block of AB looks like:

$$\begin{aligned} (AB)_{(11)} &= \begin{pmatrix} A_1 B_1 & & \\ & \ddots & \\ & & A_k B_k \end{pmatrix} \\ &= \begin{pmatrix} A_{1,:(k+1)} B_{1,:(k+1)} & & \\ & \ddots & \\ & & A_{k,:(k+1)} B_{k,:(k+1)} \end{pmatrix} \\ &+ \begin{pmatrix} A_{1,(k+1):} B_{1,(k+1):} & & \\ & \ddots & \\ & & A_{k,(k+1):} B_{k,(k+1):} \end{pmatrix} \\ &= A_{(11)} B_{(11)} + A_{(12)} B_{(21)} \end{aligned}$$

Where:

$$\begin{aligned} A_{i,:(k+1)} B_{i,:(k+1)} &= \sum_{j=1}^k A_{i,j} B_{i,j} \\ A_{i,(k+1):} B_{i,(k+1):} &= \sum_{j=k+1}^n A_{i,j} B_{i,j} \end{aligned}$$

The rest follow similarly.

5 Determinant and Trace

5.1 Exercise 1

(a) The discriminant already has ordered versions of all the (i, j) difference terms. Applying a permutation only changes the signs of some of the difference terms, hence $\sigma(p) = 1, -1$.

(b) $\sigma(p_1 \circ p_2) = \text{sign}(P(p_1 \circ p_2(x_1, \dots, x_n))) = \sigma(p_1) \text{sign}(P(p_2(x_1, \dots, x_n)))$.

5.2 Exercise 2

(c) A transposition swaps two indices, and hence flips the sign of their associated difference term in the discriminant.

(d) If $p(i) = j$, then we can start with the permutation $(i\ j)$. Next, if $p(j) = k$, we can compose with $(i\ k)$ to get $(i\ k) \circ (i\ j)$. We can do this until we have completely reconstructed the permutation using transpositions.

5.3 Exercise 3

By starting with a different i in Exercise 2 (d), we can obtain a different decomposition of transpositions. However, the parity of the decomposition must be the same, as otherwise $\sigma(p)$ will take on two different values for the same p .

5.4 Exercise 4

(Property II): Each term in $D(a_1, \dots, a_n)$ contains exactly one element from each of the a_i . Thus, scaling any of the a_i by k scales the entire determinant by k . Similar logic for vector addition.

(Property III): The only non-zero term in $D(e_1, \dots, e_n)$ is associated with the identity permutation, hence $D(e_1, \dots, e_n) = 1$.

(Property IV): Swapping two arguments is the same as applying a transposition to each of the terms in $D(a_1, \dots, a_n)$, which flips the sign of D .

5.5 Exercise 5

Suppose $a_1 = a_2$. Then:

$$\begin{aligned} D(a_1, a_2, \dots, a_n) &= -D(a_2, a_1, \dots, a_n) \\ D(a_1, a_2, \dots, a_n) + D(a_1, a_2, \dots, a_n) &= 0 \end{aligned}$$

5.6 Exercise 6

We can swap rows and columns until A is in the same form as in Lemma 2. Since each row and column swap is equivalent to applying a transposition, we

get that $\det A = (-1)^{i+j} \det A_{ij}$.

5.7 Exercise 7

Each term in the sum $D(a_1, \dots, a_n) = \sum \sigma(p) a_{p_1 1} \dots a_{p_n n}$ consists of exactly one element from each column and each row; swapping rows and columns does not change the terms in the sum. However, the permutation associated with each term is changed. The permutation p that sends $1 \rightarrow p_1$ becomes p' sending $p_1 \rightarrow 1$. This p' is exactly p^{-1} . Since $\sigma(1) = \sigma(p^{-1} \circ p) = \sigma(p^{-1})\sigma(p)$, $\sigma(p^{-1}) = \sigma(p)$ we are done.

5.8 Exercise 8

P is the linear transformation such that $P(e_j) = e_i$; in other words, P rearranges the representation of x by applying p to the components of x . We also have that $PQx = Pq(x) = p \circ q(x)$, since Qx permutes the components of x to produce $q(x)$, and $Pq(x)$ permutes the components of $q(x)$ to produce $p \circ q(x)$.

5.9 Exercise 9

$$\begin{aligned} \text{Tr } AB &= \sum_{i=1}^m (AB)_{ii} = \sum_{i=1}^m \sum_{j=1}^n a_{ij} b_{ji} \\ \text{Tr } BA &= \sum_{j=1}^n (BA)_{jj} = \sum_{j=1}^n \sum_{i=1}^m b_{ji} a_{ij} \end{aligned}$$

5.10 Exercise 10

$$\begin{aligned} \text{Tr } AA^\top &= \sum (AA^\top)_{ii} = \sum \sum a_{ij} a_{ji}^\top \\ &= \sum \sum a_{ij}^2 \end{aligned}$$

6 Spectral Theory

6.1 Exercise 1

(a) We can re-express h as a linear combination of its eigenvectors, from which we can see that A^n causes all of these components to go to 0.

(b) Same as in part (a), except all of the components now go to ∞ .

6.2 Exercise 2

$$A(A^N f) = A(a^N f + Na^{N-1}h) = a^{N+1}f + a^N h + Na^N h.$$

6.3 Exercise 3

Suppose $q(A) = \sum_{i=0}^N q_i A^i$. Then $q_i A^i f = q_i a^i f + q_i i a^{i-1} h$ by Exercise 2. From the linearity of the derivative it then follows that $q(A)f = q(a)f + q'(a)h$.

6.4 Exercise 4

Applying Lemma 9 to $p_1 \dots p_k$ and p_{k+1} gives the desired result.

6.5 Exercise 5

$$(A - aI)^d x = 0 \implies A(A - aI)^d x = 0 \implies (A - aI)^d (Ax) = 0 \implies Ax \in N_d.$$

6.6 Exercise 6

Since m_A divides the characteristic polynomial of A (by definition of d_i), $m_A(A) = 0$ by Cayley-Hamilton. Suppose there is some polynomial $q(A) = 0$ with $\deg(q) < \deg(m_A)$. The roots of q must contain all of the eigenvalues of A , since for any eigenvector h we have that $q(A)h = q(a_h)h$ (where a_h denotes the eigenvalue associated with h). Thus, the roots of q can only differ in multiplicity from m_A . However, if any root of q has multiplicity $d'_i < d_i$, then we can choose an element $x \in N_{d_i}$ such that $q(A)x \neq 0$, which is a contradiction (since $N_{d'_i} \subset N_{d_i}$).

6.7 Exercise 7

The columns of A are Ax_i .

6.8 Exercise 8

By induction.

6.9 Exercise 9

The minimal polynomial of A divides the minimal polynomial of A^\top , and vice versa, so they must be the same. Thus, the indices of each eigenvalue of A and A^\top must be the same, which means we can apply Theorem 12 to see that they are similar.

6.10 Exercise 10

$(\xi^{(i)}, x) = \sum k_j(\xi^{(i)}, x^{(j)}) = k_i(\xi^{(i)}, x^{(i)})$ since $(\xi^{(i)}, x^{(j)}) = 0$ by Theorem 17.

7 Euclidean Structure

7.1 Exercise 1

Applying Cauchy-Schwarz gives that $(x, y) \leq \|x\|\|y\| = \|x\|$, which yields the desired result.

7.2 Exercise 2

Both of these just follow from the fact that a linear space with Euclidean structure is isomorphic to \mathbb{R}^k , which has the desired properties. The following feel like cop-out solutions, but I feel they're fair given this isn't supposed to be a real analysis text.

(i) Let $x_k = \sum_i a_i^{(k)} x^{(i)}$ and $x_j = \sum_i a_i^{(j)} x^{(i)}$. Then we have that $\|x_k - x_j\| \rightarrow 0 \implies \left| a_i^{(k)} - a_i^{(j)} \right| \rightarrow 0$. Since \mathbb{R} is complete, $a_i^{(n)} \rightarrow a_i$ for some $a_i \in \mathbb{R}$. Thus $x_k \rightarrow x = \sum a_i x^{(i)}$.

(ii) Same logic as (i): the individual $a_i^{(n)}$ have convergent subsequences.

7.3 Exercise 3

We also need to assume X is finite dimensional (I think).

(i) Since X is finite dimensional, we have that $x = \sum a_i e^{(i)}$ for some basis $e^{(i)}$. Let v be the vector whose components are $v_i = \|Ae^{(i)}\|$. Then

$$\begin{aligned}\|Ax\| &= \left\| \sum a_i Ae^{(i)} \right\| \\ &= \|(x, v)\| \\ &\leq \|x\|\|v\|\end{aligned}$$

Since $\|v\|$ is a constant, $\|Ax\|$ is bounded on the unit sphere.

(ii) We have that $\|A\| = \max_x \frac{\|Ax\|}{\|x\|} = \max_x \|Ax\|$. The result then follows from $(Ax, y) \leq \|Ax\|$.

(iii) Let v be as in (i). Then $\|Ax_i - Ax_j\| \leq \|A\|\|x_i - x_j\|$. Since $\|A\| \leq \|v\|$ from (i), we are done (we can make $\|x_i - x_j\|$ as small as we'd like).

7.4 Exercise 4

Follows immediately from $(Ax, y) = (x, A^*y)$ and Exercise 3 (ii).

7.5 Exercise 5

Let $x = y_1 + y_1^\perp$ and $z = y_2 + y_2^\perp$. Then

$$\begin{aligned}(P_Y x, z) &= (y_1, y_2 + y_2^\perp) \\ &= (y_1, y_2) + 0 \\ &= (y_1, y_2) + (y_1^\perp, y_2) \\ &= (x, P_Y z)\end{aligned}$$