

# Exercise Guide for *Linear Algebra* by Peter Lax

Muthu Chidambaram

Last Updated: June 6, 2019

## Contents

<b>1</b>	<b>Fundamentals</b>	<b>4</b>
1.1	Exercise 1 . . . . .	4
1.2	Exercise 2 . . . . .	4
1.3	Exercise 3 . . . . .	4
1.4	Exercise 4 . . . . .	4
1.5	Exercise 5 . . . . .	4
1.6	Exercise 6 . . . . .	4
1.7	Exercise 7 . . . . .	4
1.8	Exercise 8 . . . . .	4
1.9	Exercise 9 . . . . .	4
1.10	Exercise 10 . . . . .	4
1.11	Exercise 11 . . . . .	4
1.12	Exercise 12 . . . . .	5
1.13	Exercise 13 . . . . .	5
1.14	Exercise 14 . . . . .	5
1.15	Exercise 15 . . . . .	5
1.16	Exercise 16 . . . . .	5
1.17	Exercise 17 . . . . .	5
<b>2</b>	<b>Duality</b>	<b>6</b>
2.1	Exercise 1 . . . . .	6
2.2	Exercise 2 . . . . .	6
<b>3</b>	<b>Linear Mappings</b>	<b>7</b>
3.1	Exercise 1 . . . . .	7
3.2	Exercise 2 . . . . .	7
3.3	Exercise 3 . . . . .	7
3.4	Exercise 4 . . . . .	7
3.5	Exercise 5 . . . . .	7
3.6	Exercise 6 . . . . .	8
3.7	Exercise 7 . . . . .	8

<b>4</b>	<b>Matrices</b>	<b>9</b>
4.1	Exercise 1 . . . . .	9
4.2	Exercise 2 . . . . .	9
<b>5</b>	<b>Determinant and Trace</b>	<b>10</b>
5.1	Exercise 1 . . . . .	10
5.2	Exercise 2 . . . . .	10
5.3	Exercise 3 . . . . .	10
5.4	Exercise 4 . . . . .	10
5.5	Exercise 5 . . . . .	10
5.6	Exercise 6 . . . . .	10
5.7	Exercise 7 . . . . .	11
5.8	Exercise 8 . . . . .	11
5.9	Exercise 9 . . . . .	11
5.10	Exercise 10 . . . . .	11
<b>6</b>	<b>Spectral Theory</b>	<b>12</b>
6.1	Exercise 1 . . . . .	12
6.2	Exercise 2 . . . . .	12
6.3	Exercise 3 . . . . .	12
6.4	Exercise 4 . . . . .	12

## About

*“A modern mathematical proof is not very different from a modern machine, or a modern test setup: the simple fundamental principles are hidden and almost invisible under a mass of technical details.”*

- Hermann Weyl

These notes contain short summaries of (my) proof ideas for exercises and some theorems from the book *Linear Algebra* by Peter Lax. I have tried to make the summaries as brief as possible; sometimes only one direction of proof, one line, or even one equation. My goal was to include enough information in the summaries so that someone reading would be able to reconstruct a full proof with all the details if necessary. However, these summaries are tuned to my own personal context, and as such I'm sure mileage will vary. I would greatly appreciate any feedback/fixes.

Also, I like when people include (what they presume to be) relevant quotes in their notes, so I have to ask you to forgive my haughtiness in starting these notes with a quote from Hermann Weyl.

## 1 Fundamentals

### 1.1 Exercise 1

$$x + z = x = x + z' \implies z = z'.$$

### 1.2 Exercise 2

$$0x + x = (0 + 1)x = x.$$

### 1.3 Exercise 3

Coefficients can be represented as row vectors.

### 1.4 Exercise 4

Function can be represented as row vector by letting  $a_i = f(s_i)$  for each  $s_i \in S$ .

### 1.5 Exercise 5

Follows from exercises 3 and 4.

### 1.6 Exercise 6

$$y_1 + z_1 + y_2 + z_2 = (y_1 + y_2) + (z_1 + z_2) \text{ and } k(y_1 + z_1) = ky_1 + kz_1.$$

### 1.7 Exercise 7

$$a \in Y \cap Z \implies ka \in Y, ka \in Z \implies ka \in Y \cap Z.$$

### 1.8 Exercise 8

$$k0 = 0, 0 + 0 = 0.$$

### 1.9 Exercise 9

If  $S$  contains  $x_i$  then it must contain  $kx_i$ .

### 1.10 Exercise 10

If  $x_i = 0$ ,  $k_i$  can be anything.

### 1.11 Exercise 11

$$x = \sum_{i=1}^m \sum_{j=1}^{\dim Y_i} y_j^{(i)}.$$

### 1.12 Exercise 12

Complete basis for  $W$  to  $U$  and  $V$ . Use  $W$  basis vectors and additional  $U$  and  $V$  basis vectors to get  $\dim X = \dim U - \dim W + \dim V - \dim W + \dim W$ .

### 1.13 Exercise 13

Send  $i^{\text{th}}$  basis vector to  $e_i$ , where  $e_i$  is vector of all zeroes except a one in the  $i^{\text{th}}$  place. Can permute mapping to get different isomorphisms.

### 1.14 Exercise 14

$$x_1 - x_2 + x_2 - x_3 = x_1 - x_3.$$

### 1.15 Exercise 15

$$x' = x + z_x, y' = y + z_y \implies x' + y' = x + y + (z_x + z_y).$$

### 1.16 Exercise 16

$$x \in X_1 \oplus X_2 \implies x = (x_1, x_2) = (x_1, 0) + (0, x_2).$$

### 1.17 Exercise 17

Construct a basis for  $X$  from  $Y$ :  $y_1, \dots, y_j, x_{j+1}, \dots, x_n$ .  
Then  $X/Y = \text{span}\{x_{j+1}, \dots, x_n\}$ .

## 2 Duality

### Theorem 1

$$x = \sum_{i=1}^n a_i x_i \implies k_i(x) = a_i.$$

### 2.1 Exercise 1

$$l_1, l_2 \in Y^\perp \implies l_1(y) + l_2(y) = 0 = (l_1 + l_2)(y).$$

### 2.2 Exercise 2

$$\forall \xi \in Y^{\perp\perp} \implies \forall l \in Y^\perp, \xi(l) = 0 = l(y) \forall y \in Y.$$

### 3 Linear Mappings

#### 3.1 Exercise 1

- (a)  $x \in X \implies x = \sum_{i=1}^n k_i x_i \implies T(x) = \sum_{i=1}^n k_i T(x_i) \in U$ .  
(b)  $T(x), T(y) \in U \implies T(x+y) \in U \implies x+y \in X$ .

#### Theorem 1

$$x \in X, y \in N_T \implies T(x+y) = T(x) + T(y) = T(x).$$

#### 3.2 Exercise 2

- (a) Differentiation constant and sum rules imply linearity, and multiplication by  $s$  is distributive. Take  $p(s) = 1$  to see that  $ST \neq TS$ .  
(b) Rotation by 90 degrees amounts to swapping and negating coordinates, which is linear. Take  $p = (1, 1, 0)$  to see that  $ST \neq TS$ .

#### 3.3 Exercise 3

- (i)  $T^{-1}(T(a+b)) = T^{-1}(T(a)+T(b)) = a+b = T^{-1}(T(a)) + T^{-1}(T(b))$ .  
(ii) Composition of isomorphisms is an isomorphism, hence  $ST$  is invertible.

#### 3.4 Exercise 4

- (i) Let  $T : X \rightarrow U$ ,  $S : U \rightarrow V$  and  $l_v \in V'$ . Then  $(ST)'(l_v) = l_v(ST) = (l_v S)T = (S'l_v)T = T'S'l_v$ , since  $S'l_v \in U'$ .  
(ii) Follows from linearity of transpose (definition).  
(iii) Let  $T : X \rightarrow U$  be an isomorphism. Then  $l_x = l_u T \implies l_x T^{-1} = l_u$  for  $l_u \in U'$ ,  $l_x \in X'$ .

#### 3.5 Exercise 5

$T''(l_{x'}) = l_{x'} T'$  where  $l_{x'} \in X''$  and  $l_{x'} T' \in U''$ . Since we can identify elements in  $X''$  and  $U''$  with elements in  $X$  and  $U$  respectively, we have that  $T''$  assigns elements of  $U$  to  $X$ .

#### Theorem 2'

Since  $T' : U' \rightarrow X'$  we have  $l_u \in N_{T'} \implies T'(l_u) = l_u T = 0$ .  $N_{T'}^\perp$  consists of elements  $l_{u'} | l_{u'}(l_u) = 0$ . From  $l_u T x = 0$  we have that each  $l_{u'}$  is identified with a  $u \in R_T$ .

### 3.6 Exercise 6

The first two elements of  $x$  are already 0 after applying  $P$ , so  $P^2 = P$ . Linearity follows from linearity of vector addition.

### 3.7 Exercise 7

$P$  is linear since function addition is linear.  $P^2 f = \frac{f(x)+f(-x)}{4} + \frac{f(x)+f(-x)}{4} = Pf$ .



## 4 Matrices

### 4.1 Exercise 1

$$(P + T)_{ij} = ((P + T)e_j)_i = (Pe_j + Te_j)_i = P_{ij} + T_{ij}.$$

### 4.2 Exercise 2

Represent  $A$  as a column of row vectors  $A_i$  and  $B$  as a row of column vectors  $B_i$ . Denote blocks by parenthesized subscripts. Then the first block of  $AB$  looks like:

$$\begin{aligned} (AB)_{(11)} &= \begin{pmatrix} A_1 B_1 & & \\ & \ddots & \\ & & A_k B_k \end{pmatrix} \\ &= \begin{pmatrix} A_{1,:(k+1)} B_{1,:(k+1)} & & \\ & \ddots & \\ & & A_{k,:(k+1)} B_{k,:(k+1)} \end{pmatrix} \\ &+ \begin{pmatrix} A_{1,(k+1):} B_{1,(k+1):} & & \\ & \ddots & \\ & & A_{k,(k+1):} B_{k,(k+1):} \end{pmatrix} \\ &= A_{(11)} B_{(11)} + A_{(12)} B_{(21)} \end{aligned}$$

Where:

$$\begin{aligned} A_{i,:(k+1)} B_{i,:(k+1)} &= \sum_{j=1}^k A_{i,j} B_{i,j} \\ A_{i,(k+1):} B_{i,(k+1):} &= \sum_{j=k+1}^n A_{i,j} B_{i,j} \end{aligned}$$

The rest follow similarly.

## 5 Determinant and Trace

### 5.1 Exercise 1

(a) The discriminant already has ordered versions of all the  $(i, j)$  difference terms. Applying a permutation only changes the signs of some of the difference terms, hence  $\sigma(p) = 1, -1$ .

(b)  $\sigma(p_1 \circ p_2) = \text{sign}(P(p_1 \circ p_2(x_1, \dots, x_n))) = \sigma(p_1) \text{sign}(P(p_2(x_1, \dots, x_n)))$ .

### 5.2 Exercise 2

(c) A transposition swaps two indices, and hence flips the sign of their associated difference term in the discriminant.

(d) If  $p(i) = j$ , then we can start with the permutation  $(i\ j)$ . Next, if  $p(j) = k$ , we can compose with  $(i\ k)$  to get  $(i\ k) \circ (i\ j)$ . We can do this until we have completely reconstructed the permutation using transpositions.

### 5.3 Exercise 3

By starting with a different  $i$  in Exercise 2 (d), we can obtain a different decomposition of transpositions. However, the parity of the decomposition must be the same, as otherwise  $\sigma(p)$  will take on two different values for the same  $p$ .

### 5.4 Exercise 4

(Property II): Each term in  $D(a_1, \dots, a_n)$  contains exactly one element from each of the  $a_i$ . Thus, scaling any of the  $a_i$  by  $k$  scales the entire determinant by  $k$ . Similar logic for vector addition.

(Property III): The only non-zero term in  $D(e_1, \dots, e_n)$  is associated with the identity permutation, hence  $D(e_1, \dots, e_n) = 1$ .

(Property IV): Swapping two arguments is the same as applying a transposition to each of the terms in  $D(a_1, \dots, a_n)$ , which flips the sign of  $D$ .

### 5.5 Exercise 5

Suppose  $a_1 = a_2$ . Then:

$$\begin{aligned} D(a_1, a_2, \dots, a_n) &= -D(a_2, a_1, \dots, a_n) \\ D(a_1, a_2, \dots, a_n) + D(a_1, a_2, \dots, a_n) &= 0 \end{aligned}$$

### 5.6 Exercise 6

We can swap rows and columns until  $A$  is in the same form as in Lemma 2. Since each row and column swap is equivalent to applying a transposition, we

get that  $\det A = (-1)^{i+j} \det A_{ij}$ .

### 5.7 Exercise 7

Each term in the sum  $D(a_1, \dots, a_n) = \sum \sigma(p) a_{p_1 1} \dots a_{p_n n}$  consists of exactly one element from each column and each row; swapping rows and columns does not change the terms in the sum. However, the permutation associated with each term is changed. The permutation  $p$  that sends  $1 \rightarrow p_1$  becomes  $p'$  sending  $p_1 \rightarrow 1$ . This  $p'$  is exactly  $p^{-1}$ . Since  $\sigma(1) = \sigma(p^{-1} \circ p) = \sigma(p^{-1})\sigma(p)$ ,  $\sigma(p^{-1}) = \sigma(p)$  we are done.

### 5.8 Exercise 8

$P$  is the linear transformation such that  $P(e_j) = e_i$ ; in other words,  $P$  rearranges the representation of  $x$  by applying  $p$  to the components of  $x$ . We also have that  $PQx = Pq(x) = p \circ q(x)$ , since  $Qx$  permutes the components of  $x$  to produce  $q(x)$ , and  $Pq(x)$  permutes the components of  $q(x)$  to produce  $p \circ q(x)$ .

### 5.9 Exercise 9

$$\begin{aligned} \text{Tr } AB &= \sum_{i=1}^m (AB)_{ii} = \sum_{i=1}^m \sum_{j=1}^n a_{ij} b_{ji} \\ \text{Tr } BA &= \sum_{j=1}^n (BA)_{jj} = \sum_{j=1}^n \sum_{i=1}^m b_{ji} a_{ij} \end{aligned}$$

### 5.10 Exercise 10

$$\begin{aligned} \text{Tr } AA^\top &= \sum (AA^\top)_{ii} = \sum \sum a_{ij} a_{ji}^\top \\ &= \sum \sum a_{ij}^2 \end{aligned}$$

## 6 Spectral Theory

### 6.1 Exercise 1

(a) We can re-express  $h$  as a linear combination of its eigenvectors, from which we can see that  $A^n$  causes all of these components to go to 0.

(b) Same as in part (a), except all of the components now go to  $\infty$ .

### 6.2 Exercise 2

$$A(A^N f) = A(a^N f + Na^{N-1}h) = a^{N+1}f + a^N h + Na^N h.$$

### 6.3 Exercise 3

Suppose  $q(A) = \sum_{i=0}^N q_i A^i$ . Then  $q_i A^i f = q_i a^i f + q_i i a^{i-1} h$  by Exercise 2. From the linearity of the derivative it then follows that  $q(A)f = q(a)f + q'(a)h$ .

### 6.4 Exercise 4