

# Multi-block ADMM Methods for Linear Programming

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## 1 Introduction

The alternating direction method of multipliers (ADMM) is a first-order method that can be used to solve various optimization problems. It splits the original problem into smaller pieces that are easier to handle during each iterative update. ADMM relies on the idea of the augmented Lagrangian method to robustify the problem and the splitting procedure makes it a proximal method that can be adopted in a wide range of optimization problems.

The goal of this project is to use ADMM to solve the primal linear programming (LP) problem:

$$\begin{aligned} & \text{minimize}_{\mathbf{x}} && \mathbf{c}^T \mathbf{x} \\ & \text{subject to} && A\mathbf{x} = \mathbf{b}, \\ & && \mathbf{x} \geq \mathbf{0} \end{aligned} \tag{OPT1}$$

or its dual

$$\begin{aligned} & \text{maximize}_{\mathbf{y}, \mathbf{s}} && \mathbf{b}^T \mathbf{y} \\ & \text{subject to} && A^T \mathbf{y} + \mathbf{s} = \mathbf{c}, \\ & && \mathbf{s} \geq \mathbf{0}. \end{aligned} \tag{OPT2}$$

In this report, we first re-formulate the problems to solve for closed form updates on the primal and the dual LP problems. We then approach each problem using the corresponding interior-point method. For each of these four approaches, we are specifically interested in the effect of preconditioning and block-splitting on the convergence rate and the accuracy of the solvers. We implemented all of the algorithms in MATLAB and ran extensive experiments to test how these methods perform on different simulated problems.

## Preconditioning

In this report, we demonstrate the effect of pre-conditioning on the various ADMM approaches mentioned above. To pre-condition a linear programming problem, one first computes

$$A' = (AA^T)^{-1/2}A, \quad \mathbf{b}' = (AA^T)^{-1/2}\mathbf{b}, \tag{1}$$

and then substitutes  $A'$  and  $\mathbf{b}'$  for  $A$  and  $\mathbf{b}$  in the original problems (OPT1) and (OPT2). Clearly, this re-formulation does not change the feasible regions for (OPT1) or (OPT2).

## Block-Splitting ADMM

In this report, we also demonstrate the effect of block-splitting ADMM. As we will show in Section 2, ADMM requires computation of a matrix inverse. Since matrix inversion is approximately cubic in complexity, this

pre-computation may slow down the algorithm for sufficiently large problems. By splitting the decision variables into blocks and updating the blocks sequentially, one can reduce the runtime by computing multiple small matrix inverses instead of a single large matrix inverse.

We demonstrate that block splitting with 3 or more blocks does not necessarily lead to a convergent solution. However, we demonstrate through experiments that randomly permuting the update order of the blocks at each iteration resolves this issue.

We also demonstrate that block splitting and preconditioning work well when used together. However, the preconditioning approach described above requires a matrix inverse computation. Therefore, one still may suffer from a slow matrix inversion if one uses preconditioning. However, one may use an inverse-free pre-conditioning method such as Cholesky pre-conditioning. We plan to study this procedure in a future work.

## Outline of Report

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## 2 Basic ADMM for LP

### Primal Re-formulation

We re-formulate the primal LP problem as:

$$\begin{aligned} & \text{minimize}_{\mathbf{x}_1, \mathbf{x}_2} && \mathbf{c}^T \mathbf{x}_1 \\ & \text{subject to} && A\mathbf{x}_1 = \mathbf{b} \\ & && \mathbf{x}_1 - \mathbf{x}_2 = \mathbf{0} \\ & && \mathbf{x}_2 \geq \mathbf{0} \end{aligned} \tag{OPT3}$$

and consider the split Lagrangian function:

$$L^P(\mathbf{x}_1, \mathbf{x}_2, \mathbf{y}, \mathbf{s}) = \mathbf{c}^T \mathbf{x}_1 - \mathbf{y}^T (A\mathbf{x}_1 - \mathbf{b}) - \mathbf{s}^T (\mathbf{x}_1 - \mathbf{x}_2) + \frac{\beta}{2} (\|A\mathbf{x}_1 - \mathbf{b}\|^2 + \|\mathbf{x}_1 - \mathbf{x}_2\|^2).$$

### Primal Update

The updates for the primal variables in ADMM requires computing the gradient of these variables and setting them to zero. Here we update  $\mathbf{x}_1$  and  $\mathbf{x}_2$  sequentially using the update function for each respectively:

$$\mathbf{x}_1^{k+1} = \arg \min_{\mathbf{x}_1^k} L^P(\mathbf{x}_1^k, \mathbf{x}_2^k, \mathbf{y}^k, \mathbf{s}^k), \tag{2}$$

$$\mathbf{x}_2^{k+1} = \arg \min_{\mathbf{x}_2^k \geq 0} L^P(\mathbf{x}_1^{k+1}, \mathbf{x}_2^k, \mathbf{y}^k, \mathbf{s}^k). \tag{3}$$

To solve for  $\mathbf{x}_1$ , we set the gradient to zero:

$$\nabla_{\mathbf{x}_1} L^P(\mathbf{x}_1, \mathbf{x}_2, \mathbf{y}, \mathbf{s}) = \mathbf{c} - A^T \mathbf{y} - \mathbf{s} + \beta (A^T (A\mathbf{x}_1 - \mathbf{b}) + (\mathbf{x}_1 - \mathbf{x}_2)) = \mathbf{0}$$

and we obtain the update step for  $\mathbf{x}_1$ :

$$\mathbf{x}_1^{k+1} = (A^T A + I)^{-1} \left( \frac{1}{\beta} A^T \mathbf{y}^k + \frac{1}{\beta} \mathbf{s}^k - \frac{1}{\beta} \mathbf{c} + A^T \mathbf{b}^k + \mathbf{x}_2^k \right) \tag{4}$$

Similarly, we solve the gradient

$$\nabla_{\mathbf{x}_2} L^P = \mathbf{s} + \beta(\mathbf{x}_2 - \mathbf{x}_1) = \mathbf{0}$$

to obtain the update for  $\mathbf{x}_2$ . Since the elements of  $\mathbf{x}_2$  are separable, we can update each one independently as follows:

$$x_{2,j}^{k+1} = \max \left\{ x_{1,j}^k - \frac{1}{\beta} s_j^k, 0 \right\} \text{ for } j = 1, \dots, n. \quad (5)$$

Next, we update the multipliers  $\mathbf{y}$  and  $\mathbf{s}$  using

$$\mathbf{y}^{k+1} = \mathbf{y}^k + \beta(A\mathbf{x}_1^{k+1} - \mathbf{b}) \quad (6)$$

$$\mathbf{s}^{k+1} = \mathbf{s}^k - \beta(\mathbf{x}_1^{k+1} - \mathbf{x}_2^{k+1}) \quad (7)$$

These two updates guarantee that  $(\mathbf{x}_1^{k+1}, \mathbf{x}_2^{k+1}, \mathbf{y}^{k+1}, \mathbf{s}^{k+1})$  dual feasible, i.e.,

$$\nabla_{\mathbf{x}_1, \mathbf{x}_2} L^P(\mathbf{x}_1^k, \mathbf{x}_2^k, \mathbf{y}^k, \mathbf{s}^k) = \mathbf{0}.$$

We terminate when the solution primal feasible, i.e.,  $A\mathbf{x}_1^{k+1} - \mathbf{b} \rightarrow \mathbf{0}$  and  $\mathbf{x}_1^{k+1} - \mathbf{x}_2^{k+1} \rightarrow \mathbf{0}$ .

## Dual Re-formulation

We convert the problem of the dual to a minimization problem to apply ADMM:

$$\begin{aligned} & \text{minimize}_{\mathbf{y}, \mathbf{s}} && -\mathbf{b}^T \mathbf{y} \\ & \text{subject to} && A^T \mathbf{y} + \mathbf{s} = \mathbf{c}, \\ & && \mathbf{s} \geq \mathbf{0}. \end{aligned} \quad (\text{OPT4})$$

The dual LP problem does not require additional re-formulation because the non-zero variable  $\mathbf{s}$  is already separable, which can be observed via the dual Lagrangian function:

$$L^d(\mathbf{y}, \mathbf{s}, \mathbf{x}) = -\mathbf{b}^T \mathbf{y} - \mathbf{x}^T (A^T \mathbf{y} + \mathbf{s} - \mathbf{c}) + \frac{\beta}{2} \|A^T \mathbf{y} + \mathbf{s} - \mathbf{c}\|^2.$$

Note that  $\mathbf{x}$  would be non-positive since we changed maximization to minimization and we would need to take the negative of  $\mathbf{x}$  of the final solution as the solution to the original LP.

## Dual Update

Similar to the primal updates, we use the updates for the primal variables  $\mathbf{y}$  and  $\mathbf{s}$  according to

$$\mathbf{y}^{k+1} = \arg \min_{\mathbf{y}} L^d(\mathbf{y}^k, \mathbf{s}^k, \mathbf{x}^k), \quad (8)$$

$$\mathbf{s}^{k+1} = \arg \min_{\mathbf{s} \geq \mathbf{0}} L^d(\mathbf{y}^{k+1}, \mathbf{s}^k, \mathbf{x}^k). \quad (9)$$

Setting the gradients with respect to  $\mathbf{y}$  and  $\mathbf{s}$  to zero, i.e.,

$$\nabla_{\mathbf{y}} L^d(\mathbf{y}, \mathbf{s}, \mathbf{x}) = -\mathbf{b} - A\mathbf{x} + \beta A(A^T \mathbf{y} + \mathbf{s} - \mathbf{c}) = \mathbf{0}, \quad (10)$$

$$\nabla_{\mathbf{s}} L^d(\mathbf{y}, \mathbf{s}, \mathbf{x}) = -\mathbf{x} + \beta(A^T \mathbf{y} + \mathbf{s} - \mathbf{c}) = \mathbf{0}, \quad (11)$$

we have the updates for  $\mathbf{y}$  (least-squares problem) and  $\mathbf{s}$ :

$$\mathbf{y}^{k+1} = (AA^T)^{-1} \left( \frac{1}{\beta} (A\mathbf{x}^k + \mathbf{b}) - A\mathbf{s}^k + A\mathbf{c} \right), \quad (12)$$

$$s_j^{k+1} = \max \left\{ \frac{1}{\beta} x_j^k - (A^T \mathbf{y}^{k+1})_j + c_j, 0 \right\}. \quad (13)$$

We can update the multipliers  $\mathbf{x}$  by

$$\mathbf{x}^{k+1} = \mathbf{x}^k - \beta (A^T \mathbf{y}^{k+1} + \mathbf{s}^{k+1} - \mathbf{c}). \quad (14)$$

The termination condition for this dual would be  $A\mathbf{x}^{k+1} + \mathbf{b} \rightarrow \mathbf{0}$ .

### 3 Interior-Point ADMM for LP

#### Primal LP Updates

We can use the previous formulation in (OPT3) with  $\mathbf{x}_1$  and  $\mathbf{x}_2$  using the barrier function:

$$\begin{aligned} \text{minimize}_{\mathbf{x}_1, \mathbf{x}_2} \quad & \mathbf{c}^T \mathbf{x}_1 + \mu \sum_j \ln(x_{2,j}) \\ \text{subject to} \quad & A\mathbf{x}_1 = \mathbf{b}, \\ & \mathbf{x}_1 - \mathbf{x}_2 = \mathbf{0}, \\ & \mathbf{x}_2 > \mathbf{0}, \end{aligned} \quad (\text{OPT5})$$

where the Lagrangian function is given by

$$L_\mu^p(\mathbf{x}_1, \mathbf{x}_2, \mathbf{y}, \mathbf{s}) = \mathbf{c}^T \mathbf{x}_1 - \mu \sum_j \ln(x_{2,j}) - \mathbf{y}^T (A\mathbf{x}_1 - \mathbf{b}) - \mathbf{s}^T (\mathbf{x}_1 - \mathbf{x}_2) + \frac{\beta}{2} (\|A\mathbf{x}_1 - \mathbf{b}\|^2 + \|\mathbf{x}_1 - \mathbf{x}_2\|^2).$$

Setting the gradient of this to zero yields the same update for  $\mathbf{x}_1$  as in (4). However, the we need to modify the update for  $\mathbf{x}_2$  as now we have:

$$s_j - \frac{\mu}{x_{2,j}} + \beta(x_{2,j} - x_{1,j}) = 0 \quad (15)$$

which yields

$$x_{2,j} = \frac{1}{2\beta} \left( \beta x_{1,j} - s_j + \sqrt{\beta^2 x_{1,j}^2 - 2\beta s_j x_{1,j} + s_j^2 + 4\beta\mu} \right), \text{ for } j = 1, \dots, n \quad (16)$$

The update equation for  $\mathbf{y}$  and  $\mathbf{s}$  remain the same as in (6) and (7). The update equation for  $\mathbf{x}$  remain the same as in (14). At the end of each iteration, we update  $\mu^{k+1} = \gamma\mu^k$  for some constant  $\gamma$ , and the terminal condition remains the same as the non-interior-point method.

#### Dual LP Updates

We can use the previous formulation in (OPT4) using the barrier function:

$$\begin{aligned} \text{minimize}_{\mathbf{y}, \mathbf{s}} \quad & -\mathbf{b}^T \mathbf{y} + \mu \sum_j \ln(s_j) \\ \text{subject to} \quad & A^T \mathbf{y} + \mathbf{s} = \mathbf{c}, \\ & \mathbf{s} > \mathbf{0}. \end{aligned} \quad (\text{OPT6})$$

where the Lagrangian function is given by

$$L_\mu^d(\mathbf{y}, \mathbf{s}, \mathbf{x}) = -\mathbf{b}^T \mathbf{y} - \mu \sum_j \ln(s_j) - \mathbf{x}^T (A^T \mathbf{y} + \mathbf{s} - \mathbf{c}) + \frac{\beta}{2} \|A^T \mathbf{y} + \mathbf{s} - \mathbf{c}\|^2.$$

Setting the gradient of this to zero yields the same update for  $\mathbf{y}$  as in (12). However, we need to modify the update for  $\mathbf{s}$  as now we have:

$$-\frac{\mu}{s_j} + x_j + \beta (s_j - (\mathbf{c} - (A^T \mathbf{y}))_j) = 0 \quad (17)$$

which yields

$$s_j = \frac{1}{2\beta} \left( \beta(\mathbf{c} - (A^T \mathbf{y}))_j + x_j + \sqrt{\beta^2(\mathbf{c} - (A^T \mathbf{y}))_j^2 - 2\beta(\mathbf{c} - (A^T \mathbf{y}))_j x_j + x_j^2 + 4\beta\mu} \right), \text{ for } j = 1, \dots, n \quad (18)$$

The update equation for  $\mathbf{x}$  remain the same as in (14). At the end of each iteration, we update  $\mu^{k+1} = \gamma \mu^k$  for some constant  $\gamma$ , and the terminal condition remains the same as the non-interior-point method.

## Multi-Block ADMM

### Primal with Block Splitting

For simplicity, we first consider splitting the problem into 2 blocks of equal size as follows:

$$\mathbf{x}_1 = \begin{bmatrix} \mathbf{x}_{1,1} \\ \mathbf{x}_{1,2} \end{bmatrix}$$

$$A = \begin{bmatrix} A_1 & A_2 \end{bmatrix}$$

Then, the Lagrangian can be expressed as:

$$\begin{aligned} L^P(\mathbf{x}_1, \mathbf{x}_2, \mathbf{y}) &= \mathbf{c}_1^T \mathbf{x}_{1,1} + \mathbf{c}_2^T \mathbf{x}_{1,2} - \mathbf{y}^T (A_1 \mathbf{x}_{1,1} + A_2 \mathbf{x}_{1,2} - \mathbf{b}) - \mathbf{s}_1^T (\mathbf{x}_{1,1} - \mathbf{x}_{2,1}) - \mathbf{s}_2^T (\mathbf{x}_{1,2} - \mathbf{x}_{2,2}) \\ &\quad + \frac{\beta}{2} \left( \|A_1 \mathbf{x}_{1,1} + A_2 \mathbf{x}_{1,2} - \mathbf{b}\|^2 + \|\mathbf{x}_{1,1} - \mathbf{x}_{2,1}\|^2 + \|\mathbf{x}_{1,2} - \mathbf{x}_{2,2}\|^2 \right) \end{aligned}$$

Taking the gradient with respect to the 1st block of  $\mathbf{x}_1$ :

$$\nabla_{\mathbf{x}_{1,1}} L^P(\mathbf{x}_1, \mathbf{x}_2, \mathbf{y}) = \mathbf{c}_1 - A_1^T \mathbf{y} - \mathbf{s}_1 + \beta (A_1^T (A_1 \mathbf{x}_{1,1} + A_2 \mathbf{x}_{1,2} - \mathbf{b}) + (\mathbf{x}_{1,1} - \mathbf{x}_{2,1}))$$

Setting the gradient to 0, we obtain the update for  $\mathbf{x}_{1,1}$ :

$$\mathbf{x}_{1,1}^{k+1} = (A_1^T A_1 + I)^{-1} \left( \frac{1}{\beta} A_1^T \mathbf{y} + \frac{1}{\beta} \mathbf{s}_1 - \frac{1}{\beta} \mathbf{c}_1 + A_1^T \mathbf{b} + \mathbf{x}_{2,1}^k - A_1^T A_2 \mathbf{x}_{1,2}^k \right)$$

By symmetry, the update step for the 2nd block of  $\mathbf{x}_1$  is:

$$\mathbf{x}_{1,2}^{k+1} = (A_2^T A_2 + I)^{-1} \left( \frac{1}{\beta} A_2^T \mathbf{y} + \frac{1}{\beta} \mathbf{s}_2 - \frac{1}{\beta} \mathbf{c}_2 + A_2^T \mathbf{b} + \mathbf{x}_{2,2}^k - A_2^T A_1 \mathbf{x}_{1,1}^{k+1} \right)$$

Note that here we use  $\mathbf{x}_{1,1}^{k+1}$  to update  $\mathbf{x}_{1,2}$ . If we use a randomized update order, then we may end up updating  $\mathbf{x}_{1,2}$  first instead.

### Block Splitting (for a general number of blocks)

We can easily extend the above result to a general number of blocks. Let  $U$  denote the set of blocks which have already been updated at the current iteration. To update block  $i$  of  $\mathbf{x}_1$ , we compute:

$$\mathbf{x}_{1,i}^{k+1} = (A_i^T A_i + I)^{-1} \left( \frac{1}{\beta} A_i^T \mathbf{y} + \frac{1}{\beta} \mathbf{s}_i - \frac{1}{\beta} \mathbf{c}_i + A_i^T \mathbf{b} + \mathbf{x}_{2,i}^k - \sum_{j \neq i, j \in U} A_i^T A_j \mathbf{x}_{1,j}^{k+1} - \sum_{j \neq i, j \notin U} A_i^T A_j \mathbf{x}_{1,j}^k \right)$$

where  $A_i$  refers to the  $i^{\text{th}}$  block of columns of  $A$ .

### Dual ADMM

$$L^d(\mathbf{y}, \mathbf{s}, \mathbf{x}) = -\mathbf{b}^T \mathbf{y} - \mathbf{x}^T (A^T \mathbf{y} + \mathbf{s} - \mathbf{c}) + \frac{\beta}{2} \|A^T \mathbf{y} + \mathbf{s} - \mathbf{c}\|^2$$

### Dual ADMM With Block Splitting

For simplicity, we first consider splitting the problem into 2 blocks of equal size as follows:

$$\mathbf{y} = \begin{bmatrix} \mathbf{y}_1 \\ \mathbf{y}_2 \end{bmatrix}$$

$$\mathbf{b} = \begin{bmatrix} \mathbf{b}_1 \\ \mathbf{b}_2 \end{bmatrix}$$

$$A^T = \begin{bmatrix} A_1^T & A_2^T \end{bmatrix}$$

Then the Lagrangian can be expressed as:

$$L^d(\mathbf{y}, \mathbf{s}, \mathbf{x}) = -\mathbf{b}_1^T \mathbf{y}_1 - \mathbf{b}_2^T \mathbf{y}_2 - \mathbf{x}^T (A_1^T \mathbf{y}_1 + A_2^T \mathbf{y}_2 + \mathbf{s} - \mathbf{c}) + \frac{\beta}{2} \|A_1^T \mathbf{y}_1 + A_2^T \mathbf{y}_2 + \mathbf{s} - \mathbf{c}\|^2$$

Differentiating with respect to  $\mathbf{y}_1$ :

$$\nabla_{\mathbf{y}_1} L^d(\mathbf{y}, \mathbf{s}, \mathbf{x}) = -\mathbf{b}_1 - A_1 \mathbf{x} + \beta A_1 (A_1^T \mathbf{y}_1 + A_2^T \mathbf{y}_2 + \mathbf{s} - \mathbf{c})$$

Setting the gradient to 0, we obtain the update for  $\mathbf{y}_1$ :

$$\begin{aligned} A_1 (A_1^T \mathbf{y}_1^{k+1} + A_2^T \mathbf{y}_2^k + \mathbf{s} - \mathbf{c}) &= \frac{1}{\beta} (A_1 \mathbf{x} + \mathbf{b}_1) \\ A_1 A_1^T \mathbf{y}_1^{k+1} &= \frac{1}{\beta} (A_1 \mathbf{x} + \mathbf{b}_1) - A_1 (A_2^T \mathbf{y}_2^k + \mathbf{s} - \mathbf{c}) \\ \mathbf{y}_1^{k+1} &= (A_1 A_1^T)^{-1} \left( \frac{1}{\beta} (A_1 \mathbf{x} + \mathbf{b}_1) - A_1 (A_2^T \mathbf{y}_2^k + \mathbf{s} - \mathbf{c}) \right) \end{aligned}$$

By symmetry, the update for  $\mathbf{y}_2$  is:

$$\mathbf{y}_2^{k+1} = (A_2 A_2^T)^{-1} \left( \frac{1}{\beta} (A_2 \mathbf{x} + \mathbf{b}_2) - A_2 (A_1^T \mathbf{y}_1^{k+1} + \mathbf{s} - \mathbf{c}) \right)$$

assuming that we update  $\mathbf{y}_2$  after  $\mathbf{y}_1$ .

## Dual Block Splitting (for a general number of blocks)

We can easily extend the above result to a general number of blocks. Let  $U$  denote the set of blocks which have already been updated at the current iteration. To update block  $i$  of  $\mathbf{y}$ :

$$\mathbf{y}_i^{k+1} = (A_i A_i^T)^{-1} \left( \frac{1}{\beta} (A_i \mathbf{x} + \mathbf{b}_i) - \sum_{j \neq i, j \in U} A_i A_j^T \mathbf{y}_j^{k+1} - \sum_{j \neq i, j \notin U} A_i A_j^T \mathbf{y}_j^k - A_i (\mathbf{s} - \mathbf{c}) \right)$$

## Block-Splitting and Preconditioning

When applying ADMM, it may be useful to split variables (such as the primal variables for the primal LP) into blocks to save the computation of doing large inverses. However, splitting a set of variables into blocks is helpful only when these variables are *not* separable. Otherwise, updating variables a block simultaneously would yield the same result as updating the variables in the block one at a time, which means updating block by block would yield the same result as updating all the variables one at a time. At the end of each iteration, if these variables are separable, they would take identical values no matter how they are grouped or updated. Therefore, it only makes sense to split  $\mathbf{x}_1$  in the primal problems (i.e., (OPT3) and (OPT5)), or to split  $\mathbf{y}$  in the primal problems (i.e., (OPT4) and (OPT6)).

A sufficient condition for the variables to be separable is when the coefficient of these variables the gradient function is the identity matrix. Interestingly, we show that when preconditioning is applied to the dual LP problem (whether or not implemented with the interior point method), the variables  $\mathbf{y}$  become separable. To see this, consider the update equation (10), where the coefficient of  $\mathbf{y}$  is  $AA^T$ . When pre-conditioning is applied, we have

$$A'(A')^T = (AA^T)^{-1/2} AA^T (AA^T)^{-1/2} = (AA^T)^{-1/2} (AA^T)^{1/2} (AA^T)^{1/2} (AA^T)^{-1/2} = I.$$

## 4 Experiments and Results

To evaluate the different implementations of ADMM LP solvers, we simulated LP problems given by (OPT1) with random matrix  $A$  with dimension  $m \times n$ ,  $n$ -dimensional column vector  $\mathbf{c}$ , and  $m$ -dimensional column vector  $\mathbf{b}$ . We focused on feasible problems, so we generated a random feasible point  $\mathbf{x}_0 \geq 0$  and let  $\mathbf{b} = A\mathbf{x}_0$ .

### Pre-conditioning

We first evaluated the effect of pre-conditioning on ADMM LP solvers that do not perform splitting on variables, and varied the tuning parameter  $\beta$  in the augmented Lagrangian function. **NICO: please fill in a figure and some description.**

### Baseline Block-splitting

### Block-splitting with Random Permutation

### Block-splitting with Pre-conditioning

### Structured Problems

## 5 Conclusions and Future Work







