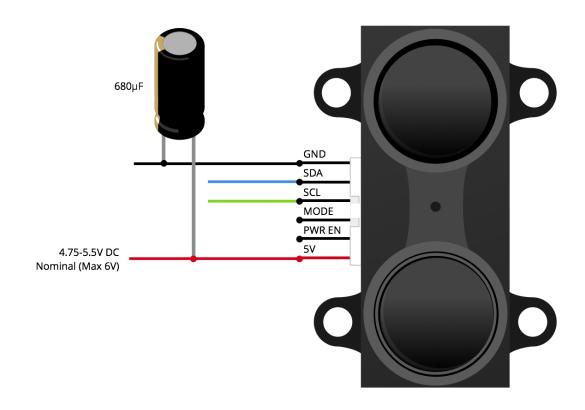
Connection Setup for I2C and PWM

There are two basic configurations for LIDAR-Lite

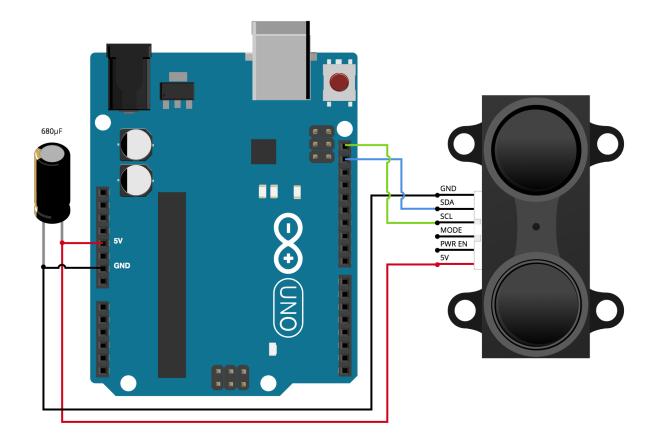
I2C Wiring



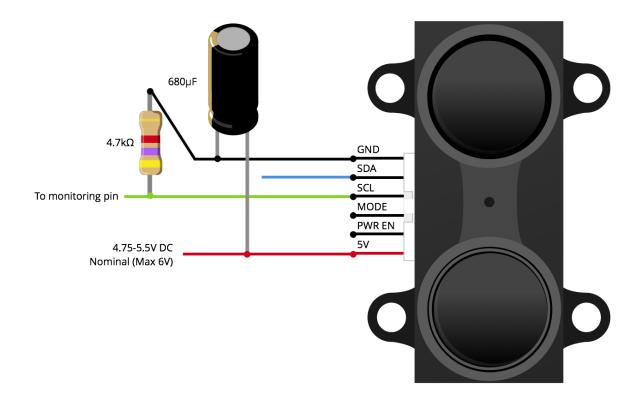
- 1. Connect power and ground pins. The sensor operates at 4.75-5.5V DC Nominal, Maximum 6V DC.
- 2. Place a $680\mu F$ Electrolytic Capacitor between 5V and GND
- 3. Connect I2C SCL/SDA pins.

Arduino I2C Connection

Connect the Arduino like the image below. *Be sure that the polarity of the elctrolytic capcitor is correct.*



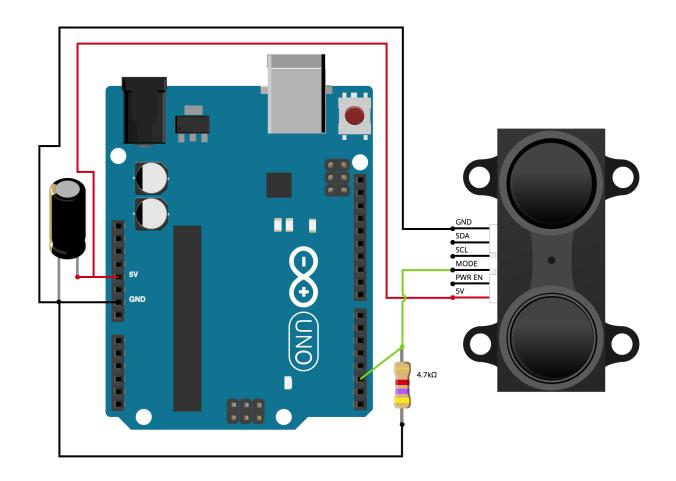
Continuous Mode Wiring



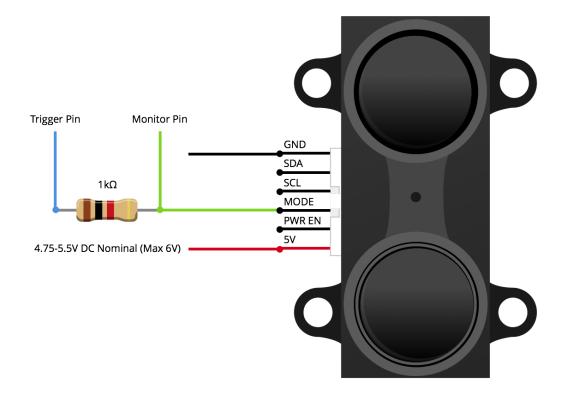
- 1. Connect power and ground pins. The sensor operates at 4.75-5.5V DC Nominal, Maximum 6V DC.
- 2. Place a 680µF Electrolytic Capacitor between 5V and GND
- 3. Connect I2C SCL/SDA pins.
- 4. Connect the MODE pin to a $4.7k\Omega$ resistor and to a monitoring pin on your microcontroller
- 5. Connect the other side of the $4.7k\Omega$ resistor to ground.

Arduino I2C Connection

Connect the Arduino like the image below. *Be sure that the polarity of the elctrolytic capcitor is correct.*



PWM Wiring



- 1. Connect power and ground pins. The sensor operates at 4.75-5.5V DC Nominal, Maximum 6V DC.
- 2. Connect the MODE pin to a $1k\Omega$ resistor and the monitor pin
- 3. Connect the other side of the $1k\Omega$ resistor to the trigger pin

Arduino PWM Connection

Connect the Arduino like the image below. Pin #2 is the Trigger Pin and Pin #3 is the Monitor Pin.

