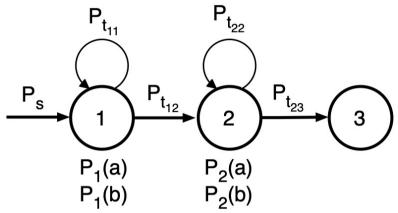
Hidden Markov Model 2

learning HMM parameters

- when we know the state path for each training sequence, learning the model parameters is simple
 - estimate the parameters by counting
 - normalize to get probability

- when we do not know the path for each training sequence, how can we determine the counts
 - estimate the counts by considering every path weight by its probability

Review: Hidden Markov model



 $M = (S, A, P_e, P_{tr}, P_s)$

- 1. States $S = \{S_i | 1 \le i \le N\}$.
- 2. Symbols $A = \{A_j | 1 \le j \le M\}$.
- 3. Emission probability distribution $P_e = \{E_{ij} | P(O_t = A_j | Q_t = S_i), 1 \le i \le N, 1 \le j \le M\}$, which is the probabilities of emitting A_j in a state S_i at any time t.
- 4. Transition probability distribution, $P_{tr} = \{T_{ik} | P(Q_t = S_k | Q_{t-1} = S_i), 1 \leq i \leq N, 1 \leq k \leq N\}$, which is the probabilities of transiting from hidden state S_i to S_k .
- 5. Initial state probability distribution, $P_s = {\pi_i | P(Q_1 = S_i), 1 \leq i \leq N}$, which is the probabilities that the initial state is the state S_i .

Review: Hidden Markov model

Forward algorithm

1) Initialization

$$\alpha_1(i) = \pi_i b_i(O_1), \ 1 \le i \le N$$

2) Induction

$$\alpha_{t+1}(j) = \begin{bmatrix} \sum_{i=1}^{N} \alpha_t(i)a_{ij} \\ i = 1 \end{bmatrix} b_j(O_{t+1}) \qquad 1 \le t \le T - 1$$

$$1 \le j \le N$$

3) Termination

$$P(O|\lambda) = \sum_{i=1}^{N} \alpha_T(i)$$

Perform for all states for given t, then advance t.

Hidden Markov model

Backward algorithm

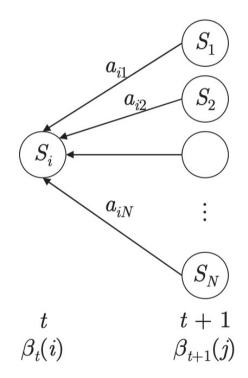
1) Initialization (arbitrarily define $eta_{\it T}(i)$ to be 1 for all i) $eta_{\it T}(i)=1, \ 1\leq i\leq N$

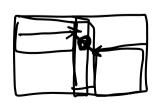
2) Induction

$$\beta_t(i) = \sum_{j=1}^{N} a_{ij} b_j(O_{t+1}) \beta_{t+1}(j)$$

$$t = T - 1, T - 2, \dots, 1$$

$$1 \le i \le N$$





learning HMM parameters

Supervised

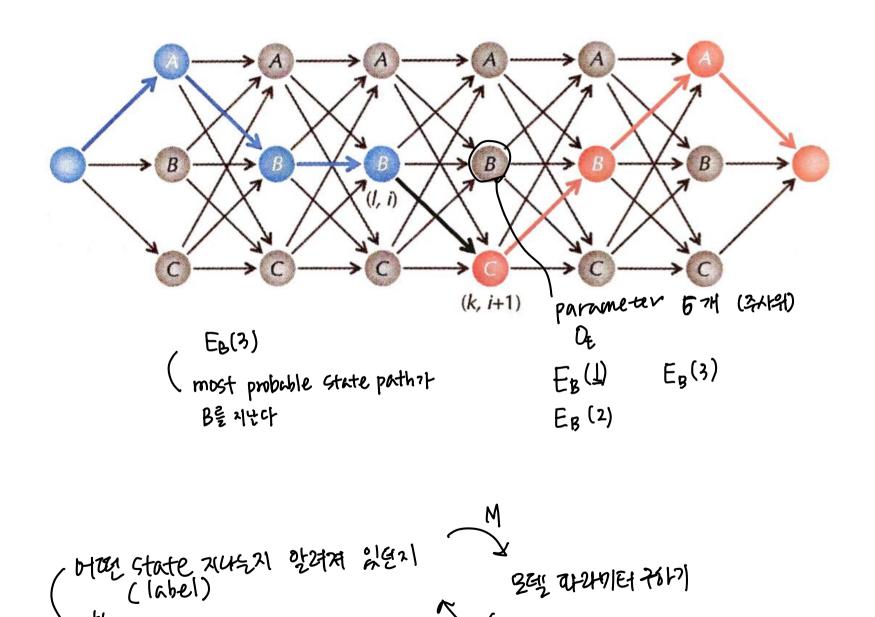
$$X = THTHHHTHTTH$$

Unsupervised

$$X = THTHHHTHTTH$$

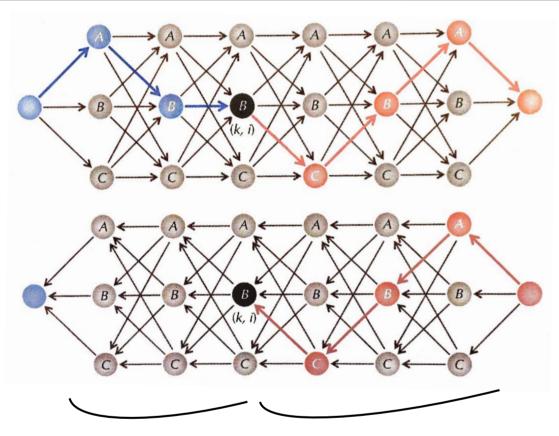
M step
$$b_B(H) = ?$$
B state and H symbol $4 \pm 9 + \frac{3}{2}$

learning HMM parameters by soft decision



' most probable path 致了

learning HMM parameters by soft decision



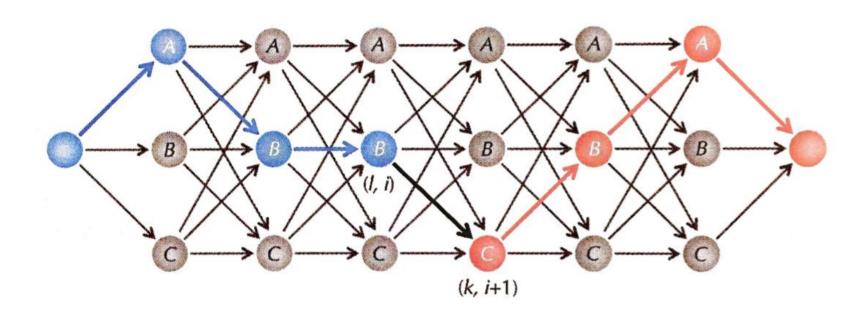
$$E_k^i(b)$$
 $Pr(\pi_i = k, x) = \sum_{\substack{all \ paths \ \pi \ with \ \pi_i = k}} Pr(x, \pi)$

$$= \sum_{all~paths~\pi~before}~Pr(\pi_{before})~\sum_{all~paths~\pi~after}~Pr(\pi_{after})$$

forward k,i

backward _{k,i}

learning HMM parameters by soft decision



EB(H) = ? = 앞부분 모든 path와 뒷牦 모든 path를 더한다 = B state에서 H가 emit 될 박물

learning HMM parameters without hidden state

$$E_k^i(b) = \begin{cases} 1 & \text{if } \pi_i = k \text{ and } x_i = b \\ 0 & \text{otherwise} \end{cases}$$

$$E_k^i(b) = \begin{cases} Pr(\pi_i = k|x) & if \quad x_i = b \\ 0 & otherwise \end{cases}$$

$$E_k(b) = \sum_{i=1}^n E_k^i(b)$$

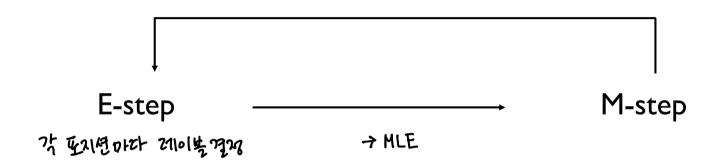
$$E_k(b) = \sum_{i=1}^n E_k^i(b)$$

for hard decision

for soft decision

$$emission_k(b) = \frac{E_k(b)}{\sum_{all \; symbols \; c \; in \; the \; alphabet} E_k(c)}$$

learning HMM parameters without hidden state



Estimate T and E for each position (and find optimal hidden path)

$$transition_{l.k} = \frac{T_{l,k}}{\sum_{all \; states \; j} T_{l,j}}$$

$$emission_k(b) = \frac{E_k(b)}{\sum_{all \ symbols \ c \ in \ the \ alphabet} E_k(c)}$$

learning HMM parameters without hidden state

- Forward-Backward algorithm
- Expectation Maximization algorithm
- Baum-Welch 알고리는

 → hidden state가 있는 시퀀스로

 HMM의 parameter를 estimate
- E-step: calculate the expected transition or emission is used
- M-step: estimate the parameters to maximize the likelihood of these expected values

```
「の見別」
- なのもちだ 号加
- なのもちだ 号加 - それがれ は切 のかり
- 相比もと 号加 - それがれ は切 のかり
- Mavkov ChaTu
- EM (k-means,)
- Hierarchical clustering,
- global/local alignment, DP
- Motif finding 号加 なる いけり
```