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# **I/O Devices and Operations 1**

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**Minsoo Ryu**

**Real-Time Computing and Communications Lab.  
Hanyang University**

**msryu@hanyang.ac.kr**

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# Topics Covered

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- ☐ Character Devices
- ☐ Block Devices
- ☐ Network Devices
- ☐ Clocks and Timers

# CPU Execution and I/O

프로세스 실행될 때

CPU burst: Instruction 처리

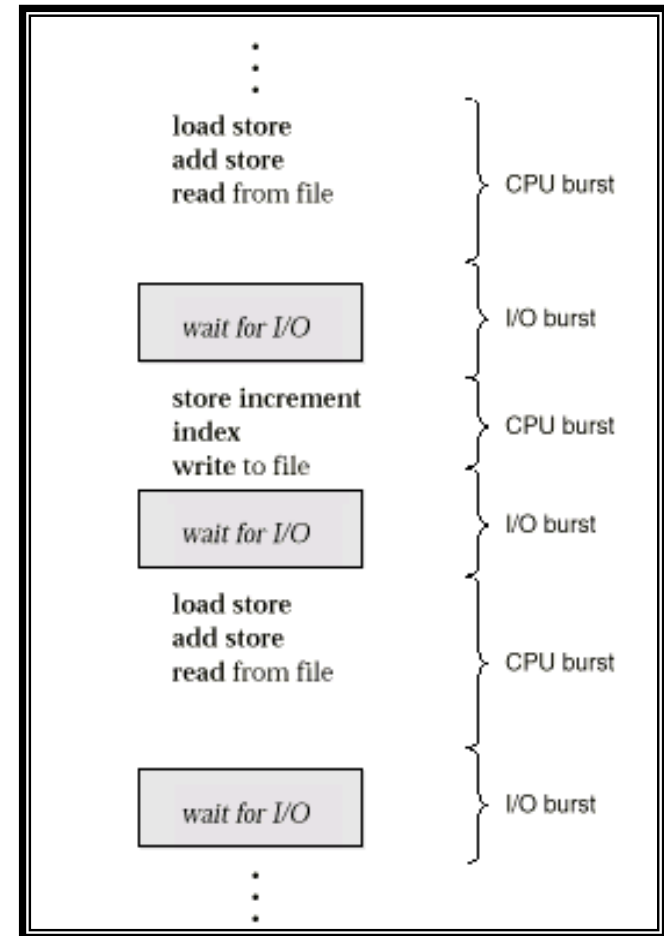
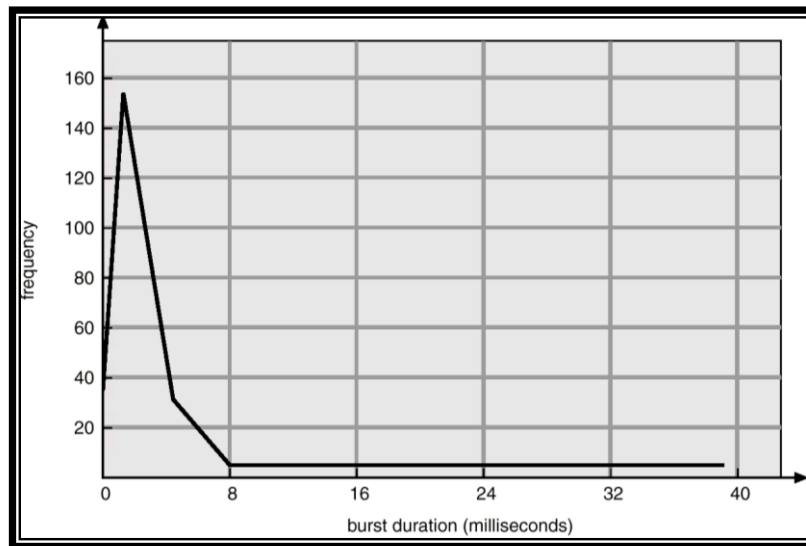
I/O burst: I/O 작업 수행

## □ The two main jobs of a computer

- CPU execution
- Input/Output

## □ Usually, the main job is I/O

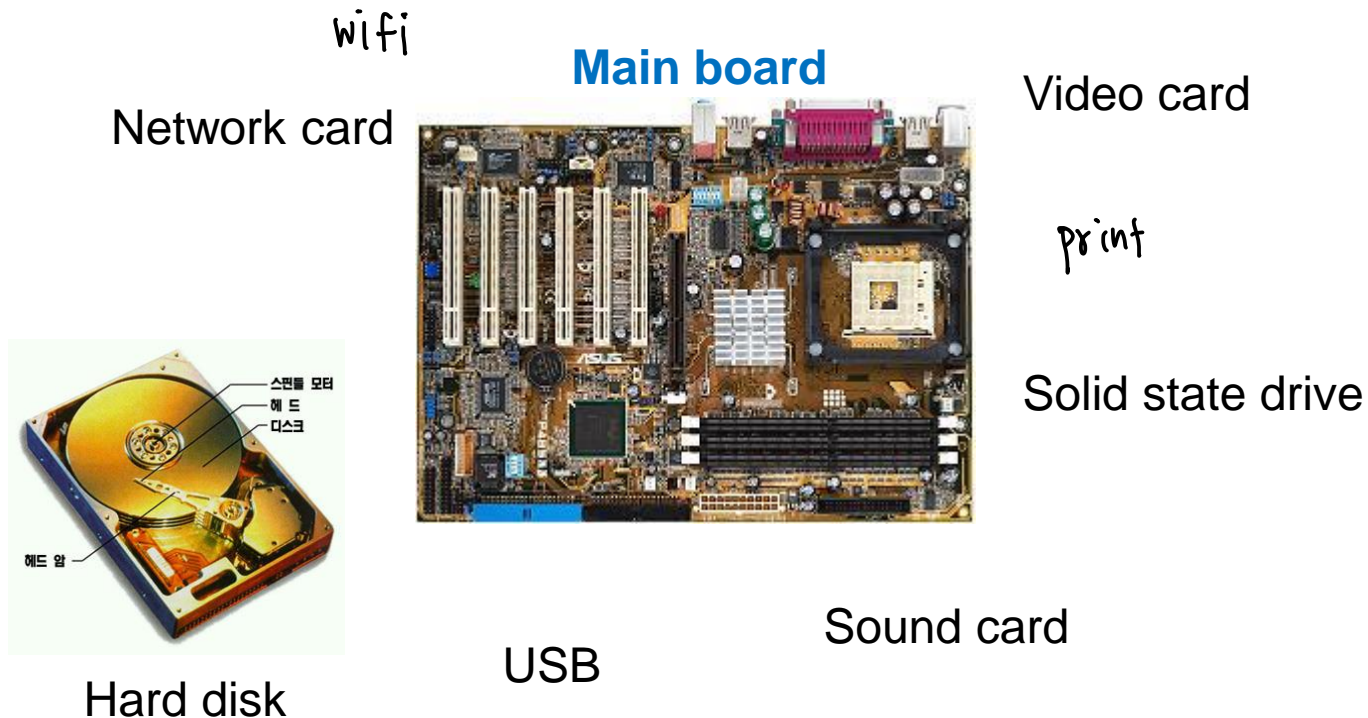
- The CPU execution is incidental



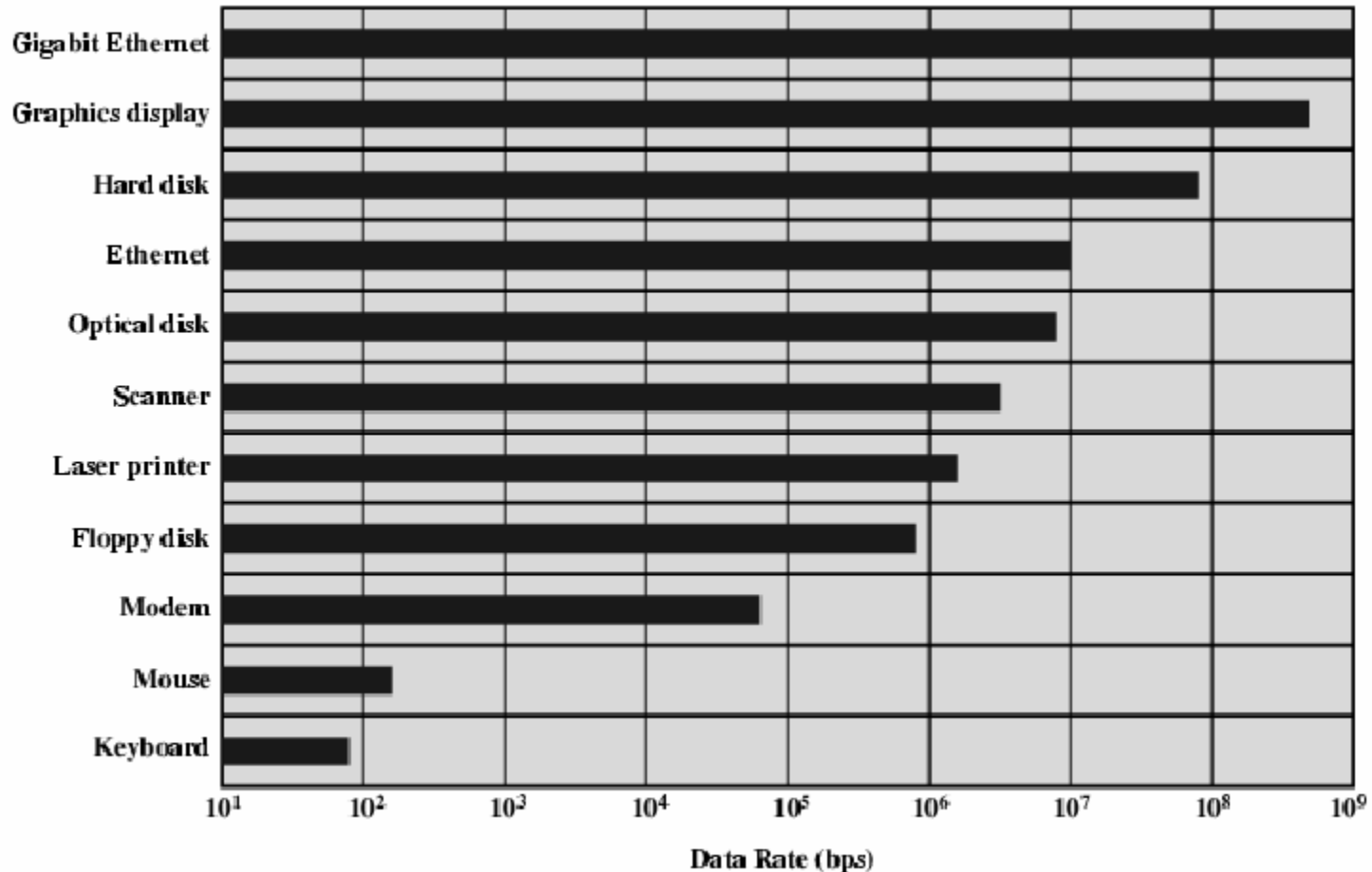
일반적으로 CPU burst는 실행 간격 짧음, I/O작업은 실행 시간이 더 김 → 사용자가 느끼는 컴퓨터의 성능은 I/O에 의해 결정 됨

# Variety of I/O Devices

- ❑ A computer is equipped with many I/O devices
  - VGA card, network card, disk controller, ...



# Typical I/O Data Rates



# Types of I/O Devices

## ❑ Character devices (mouse, terminal, etc)

- Commands include *get* and *put*

byte (char) 단위

## ❑ Block devices (disk drive, flash drive, etc)

- Commands include *read*, *write*, and *seek*
- Raw I/O or file-system access
- Memory-mapped file I/O access possible
  - `mmap()` function: convenient programming interface
  - `mmap` is faster than `read`, because of single copy operation

block 단위  
(byte들의 묶음)

## ❑ Network devices

- NIC (network interface card)

packet 단위  
(byte의 stream)

# Character Device: Mouse (1)

## □ Brief history

- **First mechanical mouse with a roller ball**
  - Bill English at Xerox PARC in the early 1970s
- **Introduced by Apple Macintosh in 1984**
  - They have helped to completely redefine the way we use computers since then
- **Became the PC-human interface of choice quickly when Windows 3.1 made Graphical User Interface (GUI) a standard**
- **Optical Mouse**
  - Gary Gordon at Agilent Laboratories in 1999



# Character Device: Mouse (2)

## ❑ Optical mouse

- Tiny camera takes **1500-7080 images** per second
  - **Camera** = laser + a CMOS sensor
- Images sent for analysis to a **DSP** operating typically at 18 MIPS
- DSP detects patterns in images and thus estimates **motion**
- Data ports are used for two-way communication
- Upon mouse movement, a 3/5-byte packet is sent to the port
  - Typical description of the data
    - ✓  $(x_s, y_s), (x_d, y_d)$ , mouse-up/down
- This data packet is decoded by the mouse driver and its internal co-ordinates are updated



# Character Device: Mouse (3)

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- ❑ **Data transfer with optical mouse**
  - **Sensors (CMOS)**
  - **Mouse Controller (DSP)**
  - **Communication link (Cable/Wireless)**
  - **Data interface (Serial, PS/2, USB)**
  - **Device driver**
  - **Application**

# Character Device: Terminal (1)

## □ Example

- DEC VT100, Heathkit Z19



# Character Device: Terminal (2)

## ❑ Terminal = keyboard + display

- Keyboard and display are handled **independent** in most systems (no automatic echo, full duplex serial link)

## ❑ I/O registers are connected to host via serial line

- **Keyboard data/status registers**
  - KBDR (Keyboard Data Register), KBSR (Keyboard Status Register)
- **Display data/status registers**
  - DDR (Display Data Register), DSR (Display Status Register)

# Character Device: Terminal (3)

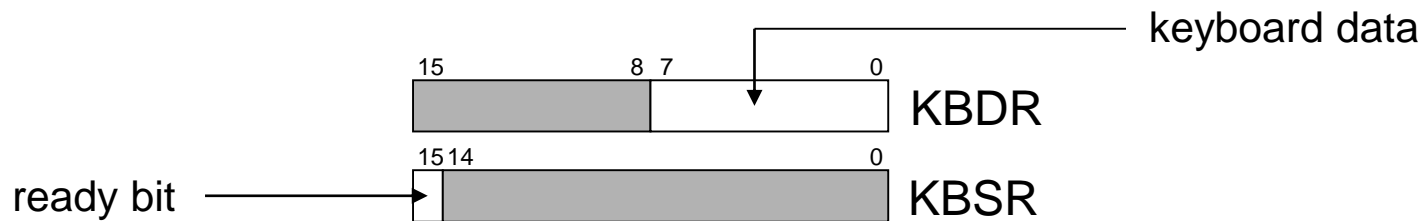
## ❑ Keyboard input handling

- **One interrupt per character**
  - One character (8-bit data or control function) is sent at a time
  - **ASCII** encoding is used: 'A' is 0x65
- **Slow speed**
  - **10-1800** characters per second
  - Measure: **Baud rate** (bits per second)

# Character Device: Terminal (4)

## □ When a character is typed:

- Its ASCII code is placed in bits [7:0] of keyboard data register
- The “ready bit” of keyboard status register is set to **zero**
- **Generate interrupt and disable keyboard**
  - Any typed characters will be ignored



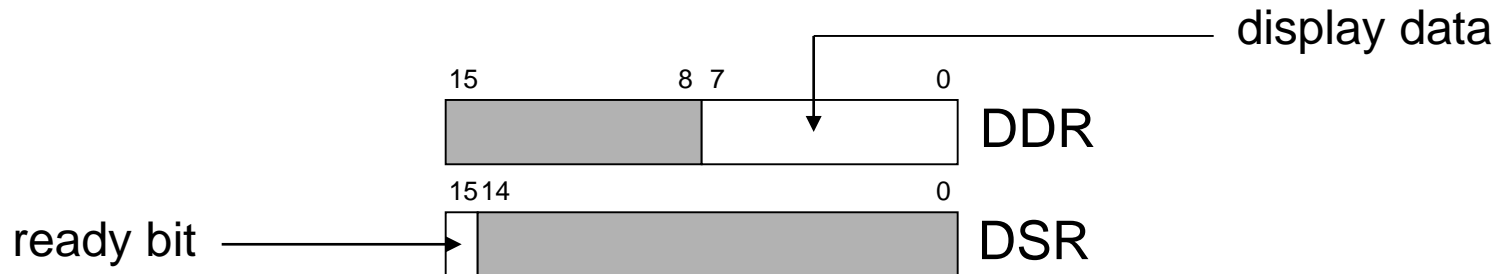
## □ When KBDR is read:

- The “ready bit” of KBSR is set to one
- Enable keyboard

# Character Device: Terminal (5)

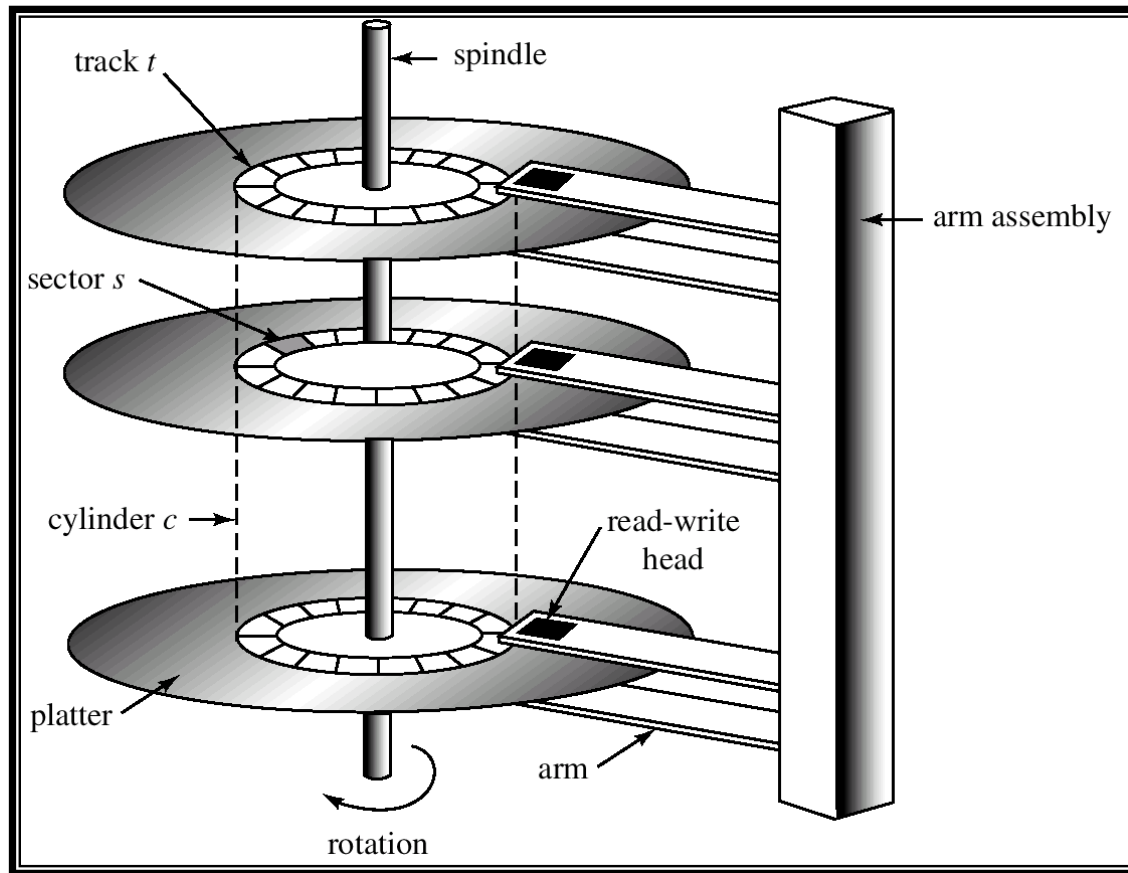
## □ Display output handling

- When monitor is ready to display another character
  - The “ready bit” of display status register is set to one



- When data is written to DDR:
  - The “ready bit” of DSR is set to zero
  - Character in DDR is displayed
  - Any other character data written to DDR is ignored

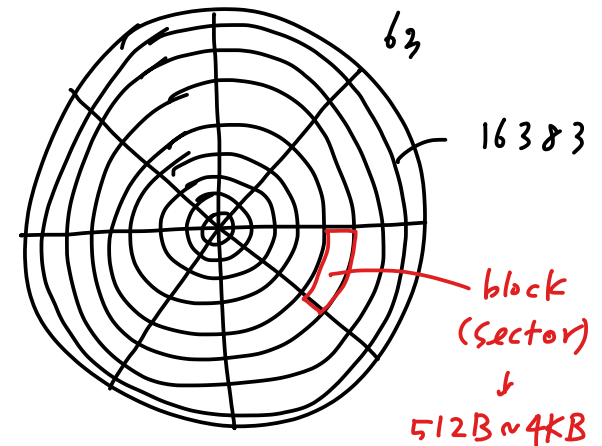
# Block Device: Disk Drive (1)



# Block Device: Disk Drive (2)

## □ Example disk characteristics

- 2-6 heads (platters x 2)
- Platter diameter between 0.8" and 8"
- 16,383 tracks (cylinders) per surface
- 63 blocks (sectors) per track
- Block (sector) size of 512 to 4096 bytes
  - 4KB physical emulated at 512-byte sectors
- Capacity ranges up to 4 TB

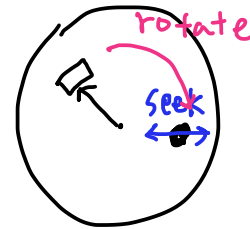




# Block Device: Disk Drive (3)

## □ Disk operation

- Select desired read/write head
- Move heads to the correct track (“seek”)
  - Seek time
- Wait for disk to “rotate” desired block into position
  - Rotational delay
- Read from or write to the block
  - Transfer latency



## □ Disk performance

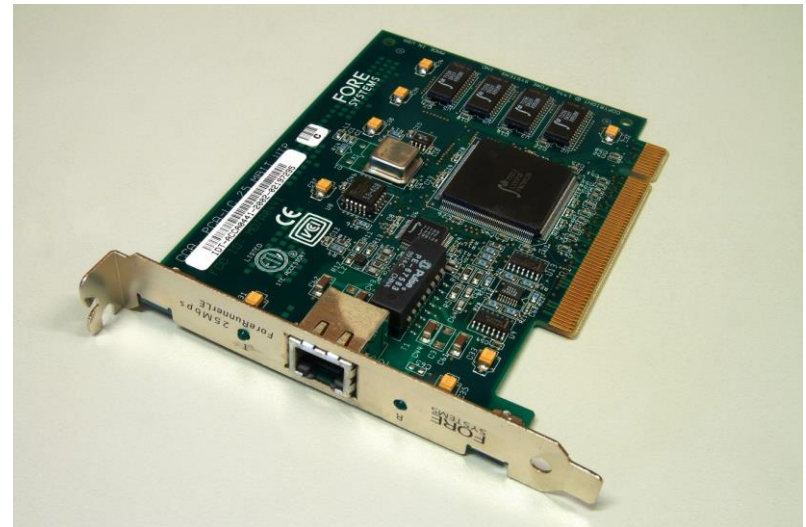
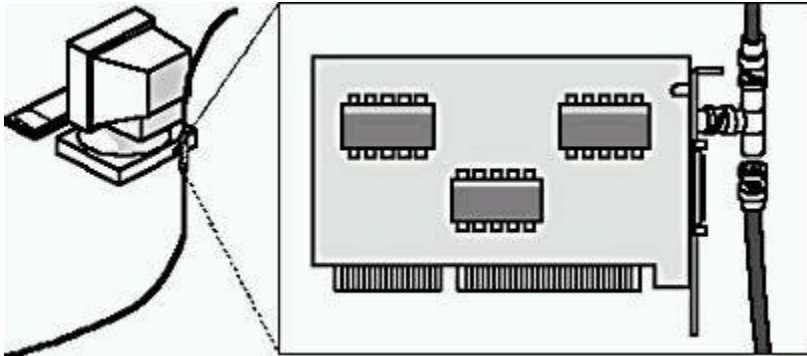
- Seek time: 0-50 ms (average 10-20 ms)
- Rotational delay: 0-16 ms
- Typical drive spins at 3600-5400 RPM

하드디스크의  
분당 회전 속도

# Network Interfaces

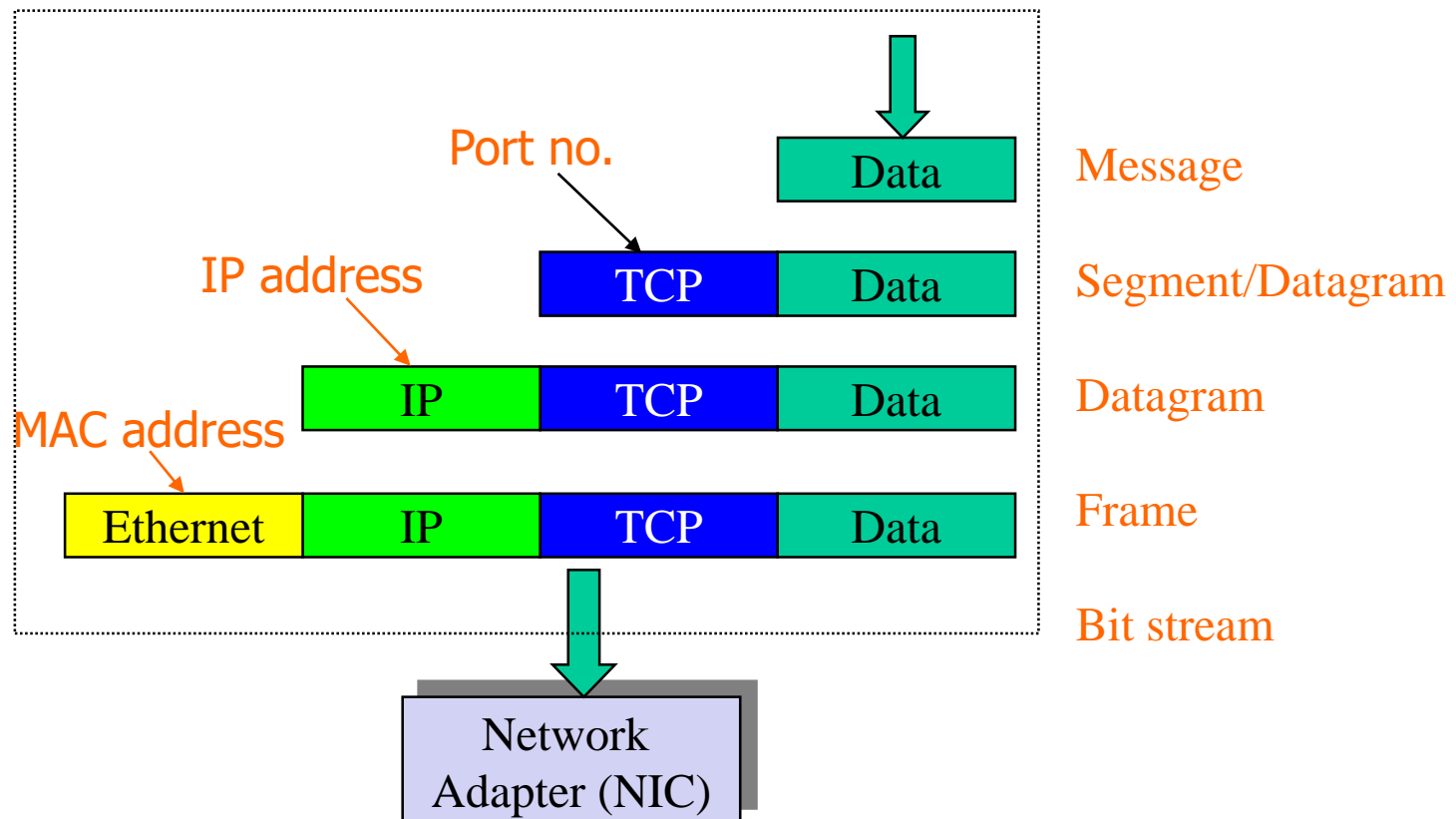
## □ Network interfaces

- UART and RS-232, USB, ethernet, etc

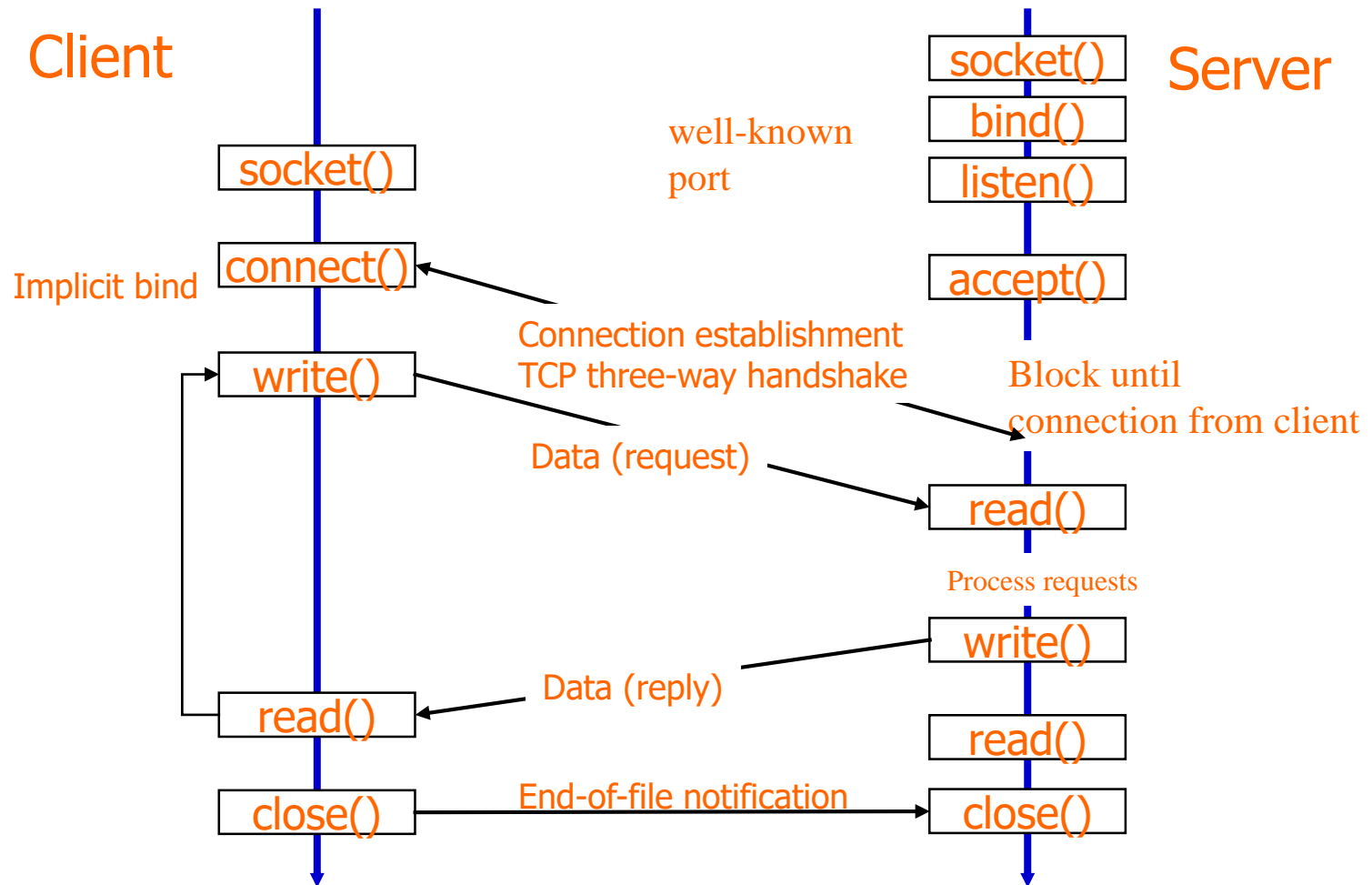


# Layering (Protocol Stack)

- ❑ Network I/O is more complex than other types of I/O
  - Complex network protocols and layered processing



# TCP Socket Programming Flow



# Clocks and Timers

## ☐ Provide three basic functions

- Give the **current time**
- Give the **elapsed time**
- **Set a timer to trigger** operation X at time Y

## ☐ Programmable interval timer

- The hardware for last two functions
- Wait and generate an interrupt
- CPU scheduler uses this

## ☐ Unfortunately, the system calls for timer functions are not standardized across operating systems

- `alarm()` in UNIX
- `timer_create()` and `timer_settime()` in POSIX

# Unix Time Values

## ❑ Two different time values

### ▪ Calendar time

- Counts the number of seconds since the Epoch (Jan 1, 1970)
- UTC (coordinated Universal Time, Greenwich Mean Time)

### ▪ Process time

- Measures the CPU time used by a process
- Process time is measured in clock ticks
  - ✓ Usually, 50, 60, or 100 ticks per second
- CPU time = User CPU time + System CPU time

## ❑ Lack of timer support on Unix

### ▪ We can get around by using `alarm()` system call

- It generates a SIGALRM signal after the number of real-time seconds (specified by `seconds`) has elapsed

### ▪ `ioctl` on UNIX covers odd aspects of I/O such as clocks and timers (catchall for I/O operations)

# Linux

## ❑ The timer interrupt is set to a default frequency

- “linux/param.h”
- 100 Hz for most hardware platforms

## ❑ Jiffies

- The number of clock ticks since the operating system was booted
- When the timer interrupt occurs, the jiffies value is incremented



thank you!